

Toy Car Using Raspberry Pi, Bluetooth & Arduino

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Abstract—A Toy car is controlled using a keyboard and bluetooth where the keyboard is connected to a raspberry pi.

1 HARDWARE SETUP

- 1) Assemble the motors, chassis and wheels to build the toy car.
- 2) Stick the breadboard to the chassis of the toy car.
- 3) Stick a 9V battery to the breadboard and connect the positive and negative terminals to extreme ends of the breadboard.
- 4) Stick a 9V battery to the breadboard and connect the positive and negative terminals to extreme ends of the breadboard.
- 5) Provide 9V to the supply pin of the Arduino.
- 6) Plug the L293D motor driver IC in Fig. 1 on the breadboard.

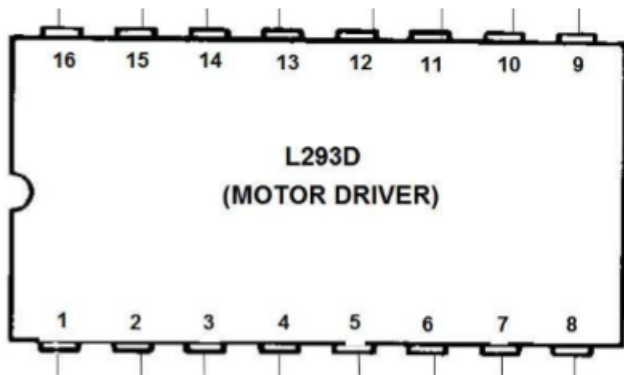


Fig. 1: Pin out of L293D

- 7) Connect the L293D pins according to Fig.3.

2 SETTING UP ARDUINO AND BLUETOOTH MODULE

- 1) Connect the HC05 pins i.e., bluetooth module pins according to Fig.2.

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Power	L293D			
9V	1	8	9	16
GND	4	5	12	13

Arduino	D2	D3	D4	D5
L293D	2	7	10	15

Motor	+		-	
L293D	3	11	6	14

Fig. 2: Arduino to L293D connection

Arduino	D0	D1	5V	GND
HC05	TX	RX	Vcc	GND

Fig. 3: Arduino to bluetooth connection

- 2) Dump the following code in Arduino using its IDE.

```
https://github.com/rohithreddy0087/toy-car-using-bluetooth-raspberry-pi/tree/master/codes./Arduino code
```

- 3) The HC-05 bluetooth module looks as shown in the figure

3 CONFIGURING BLUETOOTH OF PI

- 1) The following commands will install graphical interface for the bluetooth of the Pi

```
sudo apt-get update
sudo apt-get install bluetooth bluez
blueman
sudo reboot
```

- 2) After rebooting the pi, under the menu option scroll down to preferences and click

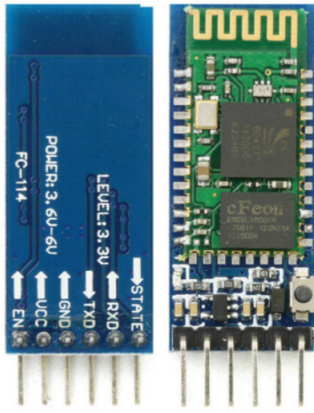


Fig. 4: HC-05 Bluetooth Module

textbfBluetooth Manager. From there, connect to bluetooth device that is connected to the arduino.

- 3) The snap shot of the bluetooth settings in raspberry pi looks as shown in the figure Fig. 4.

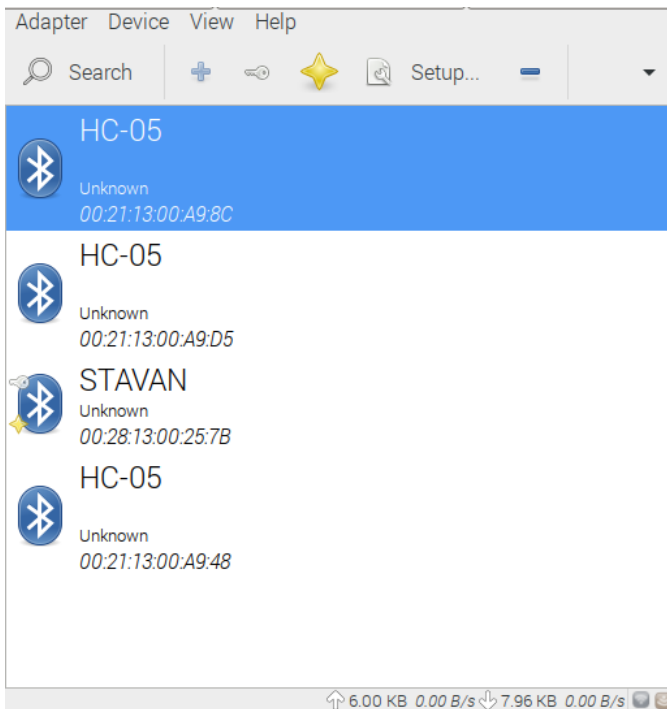


Fig. 5: Bluetooth settings in raspberry pi

[https://github.com/rohithreddy0087/toy-car-using-bluetooth-raspberry-pi/blob/master/codes./python code](https://github.com/rohithreddy0087/toy-car-using-bluetooth-raspberry-pi/blob/master/codes./python%20code)

- b) Run the program using following command.
python bluetooth.py
- c) The num keypad on the keyboard is used to control the toy car.
The controls are shown in the Table 0.

Number	direction
8	Forward
2	Back
4	Right
6	Left
5	Stop

TABLE 0: Keyboard controls

5 EXPLANATION

Raspberry Pi and the bluetooth devices are connected to send/recieve the information through serial communication

As keyboard is used to control the toy car, serial information is sent from the raspberry pi to HC-05 bluetooth device. To send the information from raspberry pi we implemented a python code where we used a function called serial.Serial with necessary baud rate.

The function getch() is used to take continous input from the user without pressing enter key.

4 IMPLEMENTATION

- a) Save the following code in a file called bluetooth.py .