ELEC6027: VLSI Design Project Part 1: Microprocessor Research Topic: Subroutines

Ashley Robinson Team: R4 Course Tutor: Mr B. Iain McNally

13th February, 2014

Contents

1	Introduction			
2	Research			
	2.1	Subro	outine Context Save	
	2.2	Opera	ation of Stack Frames	
		2.2.1	8086	
		2.2.2	ARM7TDMI using Arm Thumb	
3	Cor	clusio	on	

1 Introduction

Subroutines, also known as procedures, methods, functions or just routines, are smaller sections of code inside larger program designed to perform certain tasks which is described in [2]. The motivation for subroutines is to produce code which is more efficient in size, easy to adapt and above all else maintain. They help form the foundations of third generation programming languages.

Designing hardware such that it is capable of executing subroutines only requires available memory and access to the program counter. Designing hardware to call and return from subroutines efficiently can vastly improve the performance of a processor.

2 Research

2.1 Subroutine Context Save

Context save allows a microprocessor to switch execution focus but retain data such that the previous focus can be fully restored.

2.2 Operation of Stack Frames

A stack, as discussed in [3], is a Last-In-First-Out (LIFO) data structure which is used as store when the immediately accessible register do not provide enough memory. The stack can be thought of to grow in size where a register called a *stack pointer* (SP) holds the address of the top most element in main memory. Two operations can be performed on the stack; *push*, which adds an item to the stack and increments the stack pointer, together with *pull*, which performs the reverse therefore shrinking the stack.

One of the main

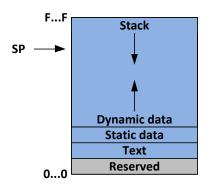


Figure 1: Allocation of the stack in main memory. Based on a MIPS architecture adapted from [3].

2.2.1 8086

The assembler held in listing 1 and 2 is written for the Intel 8086 microprocessor. A basic example of how stack frames are built to pass parameters to and from a subroutine. The main program in listing 1 loads two immediate values into registers then begins building a stack frame by pushing them to the stack. The subroutine is called to act upon the arguments passed via the stack. When control is passed back to these set of instructions and the return value is extracted by using relative addressing from the base pointer then finally two stack pops completely destroy the stack frame.

```
main:
                       ; Main loop
      MOV
                          ; Init base ptr
             bp, sp
      MOV
             ax, 42
                            Load arg1
      MOV
             bx,69
                            Load arg2
      PUSH
                            Push arg1 to stack
      PUSH
             ax
                          ; Push arg2 to stack
      CALL
                          ; Call the subroutine
             adder
      MOV
             cx, [bp-12]
                          ; Access return value
      POP
                          : Restore all registers
      POP
             bx
      JMP
             main
```

Listing 1: 8086Caller.asm

When the subroutine, in listing 2, is called the return address is pushed onto the stack. This built-in support for the stack handles branching and next line address storage using a call function. To start the base pointer is placed on the stack so stack pointer has value to which to be restored. Reducing the value of the stack pointer allocates space for local variables. The first argument is placed in memory as local variable; this is unnecessary

but serves as example. The second argument is loaded into a working register. The first local variable is added to the working register which is then placed in to the memory for the second local variable. Finally the stack pointer and the base pointer are restored and a return instruction hands control over the caller. This is all part of the calling convention for subroutines using stack frames on the 8086 [1].

```
adder PROC
                      ; Subroutine
                           Push base ptr to stack
      PUSH
            bp
      MOV
                           Set base ptr to stack ptr
            bp, sp
            sp,4
      SUB
                           Allocate local variable space (2 ints)
      MOV
            ax, [bp+4]
                           Load arg1 into Working
      MOV
            [bp-2], ax
                          ; Load arg1 into Local1
      MOV
            ax, [bp+6]
                          ; Load arg2 into Working
      ADD
            ax, [bp-2]
                           Add to contents of working reg
      MOV
            [bp-4], ax
                           Write Local2 with result
      MOV
            sp, bp
                           Return stack ptr
      POP
            bp
                           Restore base ptr
      RET
                           Done
adder ENDP
```

Listing 2: 8086Callee.asm

This code was tested upon an 8086 emulator [6]. The emulator provides a complete overview of the flow of data within the processor including the stack. Figure 2a shows the emulator during the execution of the subroutine just before the stack pointer is overwritten with the base pointer. Figure 2b is an abstraction of the stack with data label corresponding to the subroutine.

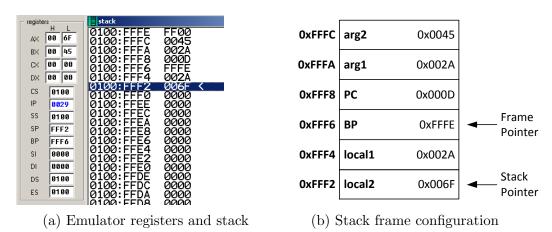


Figure 2: 8086 stack operation

2.2.2 ARM7TDMI using Arm Thumb

The ARM7TDMI is a 32-bit RISC microprocessor with an emphasis on low-power design and pipelining for high throughput [4]. It has two instruction sets one of which is Arm Thumb, a low density 16-bit subset of the ARM assembly language [5]. A user selectable flag is set to switch between instruction sets therefore drawing on each sets advantages.

This architecture does not have built-in support for calling subroutines using the stack. When the branch instruction is used, as seen in listing 3, the program counter is overwritten with the address of the corresponding label. The address of the next line of code, which should be returned to after the subroutine, is placed into the link register. Calling conventions suggests leaving this register untouched and simply moving the data back into the program counter on a return.

```
MOV
            r0, #42
                      ; Load arg1
main
      MOV
                        Load arg2
            r1,#69
            r0
      PUSH
                        Push arg1 to stack
      PUSH
                        Push arg2 to stack
            r1
            adder
      BL
                        Branch to subroutine
      POP
                        This line is held in the link register
            r0
      POP
            r0
                        Result pop from arg1 spot
      BL
            main
```

Listing 3: ArmCaller.asm

In this case the link register is pushed onto the stack from the subroutine therefore requiring the subroutine to pop the value into the program counter in order to return. Listing 4 holds the subroutine and handles placing the return address on the stack. Relative addressing on the stack is required to draw the two arguments out and replace the first with the output of the function.

```
adder PUSH
            lr
                            ; Link register holds return address
      LDR
            r0, [sp, #12]
                              Get arg1 off stack
      LDR
            r1, [sp, #8]
                              Get arg2 off stack
      ADD
            r0, r1
                              Do the add
            [sp, #12], r0
                              Replace arg1 on the stack
      STR
      POP
                              Restore program counter and return
```

Listing 4: ArmCallee.asm

3 Conclusion

References

- [1] James Archibald. The c calling convention and the 8086: Using the stack frame. http://ece425web.groups.et.byu.net/stable/labs/StackFrame.html, 2013. Online. Acessed Feb 2014.
- [2] Allison June Barlow Chaney. Subroutine. https://www.princeton.edu/~achaney/tmve/wiki100k/docs/Subroutine.html, Oct 2013. Online. Acessed Feb 2014.
- [3] David A. Patterson and John L. Hennessy. Computer Organization and Design, Fourth Edition, Fourth Edition: The Hardware/Software Interface (The Morgan Kaufmann Series in Computer Architecture and Design). Morgan Kaufmann, 4th edition, 2008. pp114–121.
- [4] ARM Holdings plc. Arm7tdmi data sheet. http://www.ndsretro.com/download/ARM7TDMI.pdf, Aug 1995. Online. Acessed Feb 2014.
- [5] ARM Holdings plc. Thumb instruction set quick reference card. http://www.eng.auburn.edu/~nelson/courses/elec5260_6260/Thumb%20Instructions.pdf, Oct 2003. Online. Acessed Feb 2014.
- [6] Daniel B. Sedory, Randall Hyde, Eric Isaacson, Barry Allyn, Tomasz Grysztar, Saul Coval, Bob Brodt, Jordan Russell, and Jeremy Gordonii. emu8086. http://www.emu8086.com/, 2013. Online. Acessed Feb 2014.

Bibliography

[1] Patterson D A and Hennessy J L, Computer Organisation and Design: The Hardware/Software Interface. Morgan Kaufman, 4th Edition, 2009.
- Lots of processor concepts and MIPS examples