

Unsupervised pre-training for images

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Reading material

- Chapter 19.2.4 in Probabilistic ML by K Murphy
- Papers

Motivation

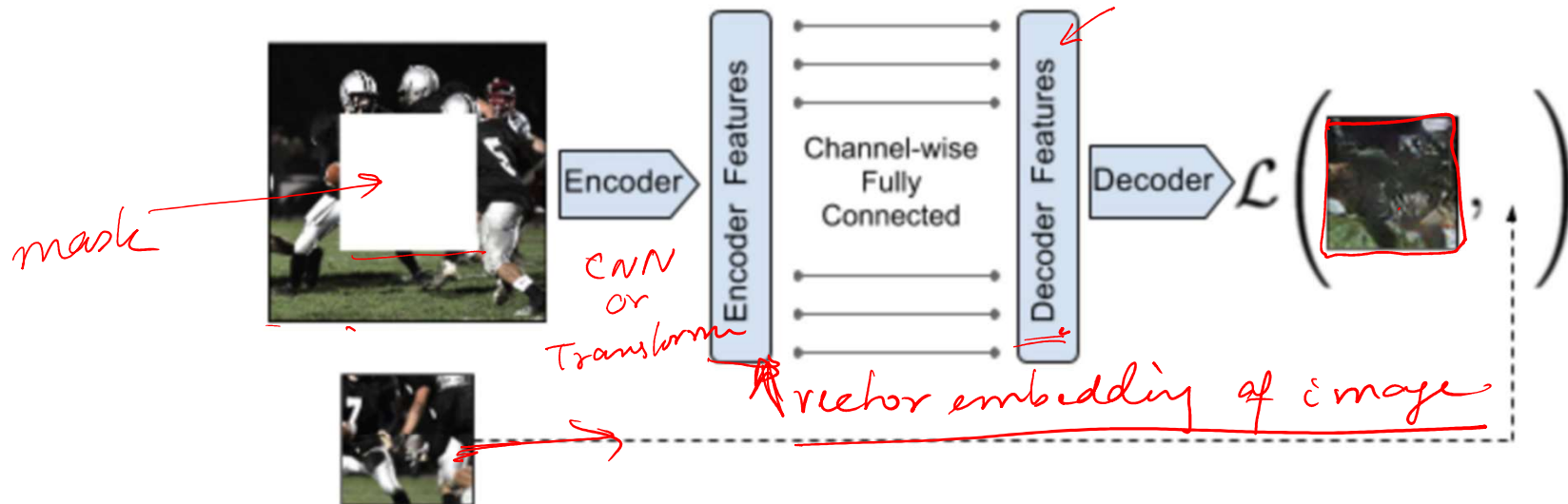
- ML models have more parameters than the amount of labelled data available for training them well
 - Labeled data: e.g.
 - Images along with labels of objects in them
 - Images with caption
- ResNET CNN with 50 layers has 23 million parameters
- Unlabelled data:
 - Large collection of images but without any labels or captions.
 - Can we harness these for pre-training a CNN for image classification or captioning?

Unsupervised → self-supervised

- Starting from unlabeled data e.g. collection of images, use a set of scripts to automatically create supervised tasks out of them.
- Example, for text data next-token prediction.
- Three types of self-supervised tasks for images:
 - • Imputation
 - Mask part of image and generate that
 - Proxy or pretext tasks
 - Create image pairs and use Siamese networks to generate representations that can predict relationship between them
 - Contrastive learning
 - Like metric learning, but create similar pairs on your own.

Imputation

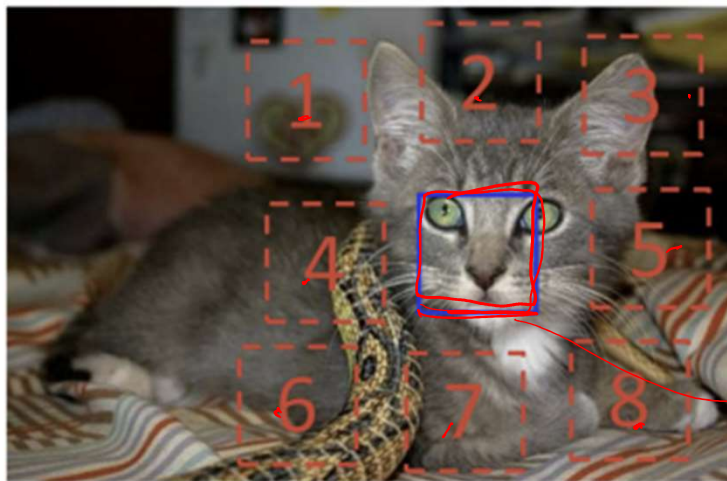
Learning to inpaint by reconstruction



Learning to reconstruct the missing pixels

Source: [Pathak et al., 2016](#)

Pretext task: predict relative patch locations



$$X = (\text{cat face patch}, \text{cat ear patch}); Y = 3$$

Example:



Question 1:



Question 2:



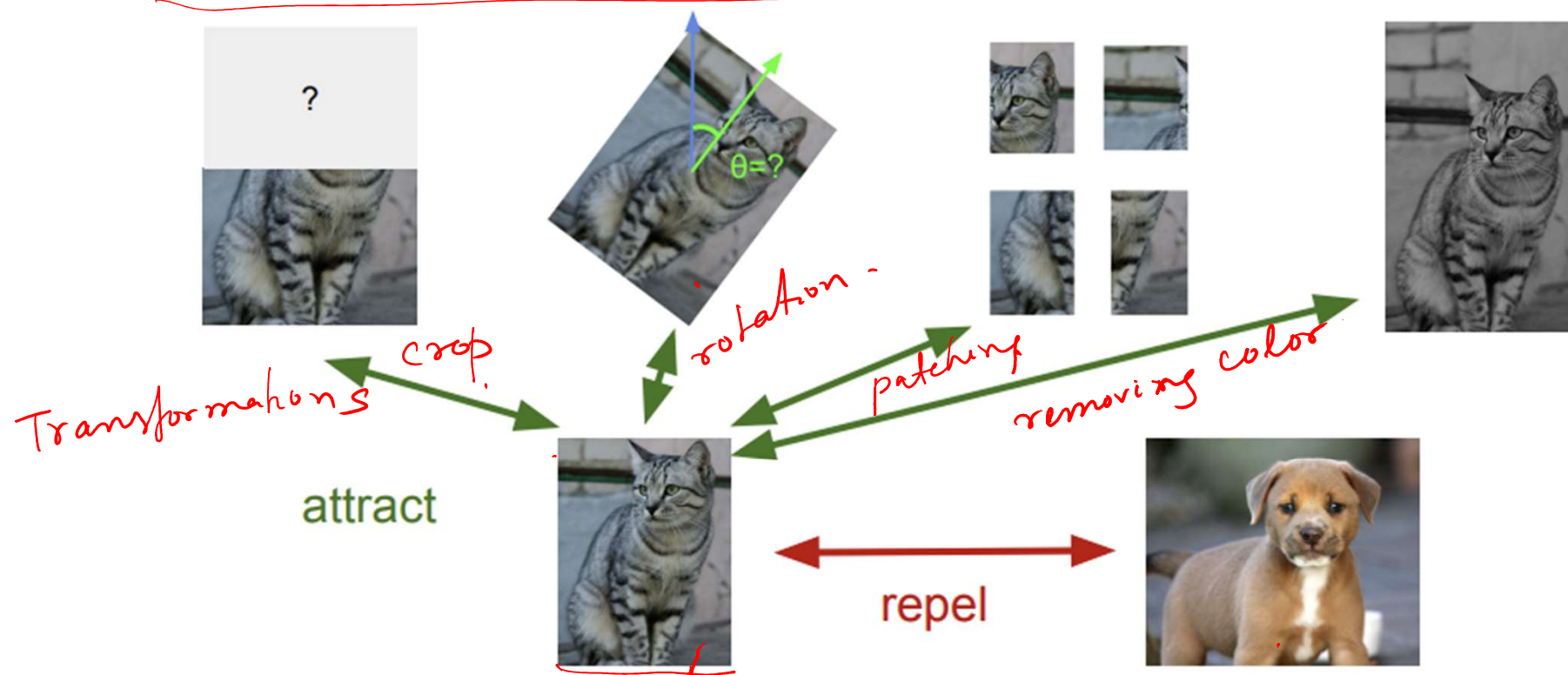
center patch
neighboring patch

orientation of
neighbor
1 of 8
possible
values:
classification
task

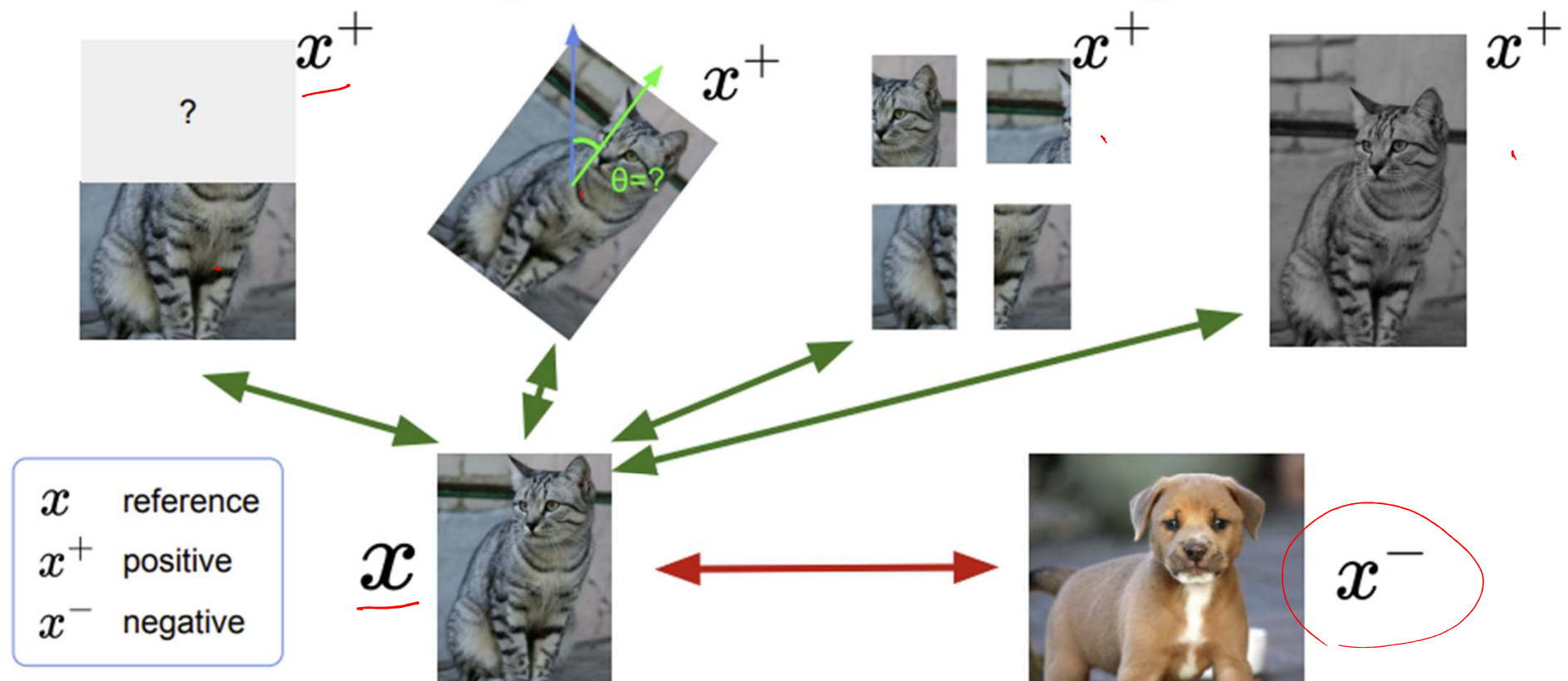
one of the 8 possible neighboring patches

(Image source: [Doersch et al., 2015](#))

Contrastive Representation Learning



Contrastive Representation Learning



A formulation of contrastive learning

Loss function given 1 positive sample and N - 1 negative samples:

$$L = -\mathbb{E}_X \left[\log \frac{\exp(\underline{s(f(x), f(x^+))})}{\exp(s(f(x), f(x^+))) + \sum_{j=1}^{N-1} \exp(s(f(x), f(x_j^-)))} \right]$$

Handwritten notes:
 - similarity function (pointing to s)
 - representation or embedding of input (pointing to f)
 - input (pointing to x)



x



x^+

$y = 1$



x



x_1^-



x_2^-



x_3^-

...

SimCLR: A Simple Framework for Contrastive Learning

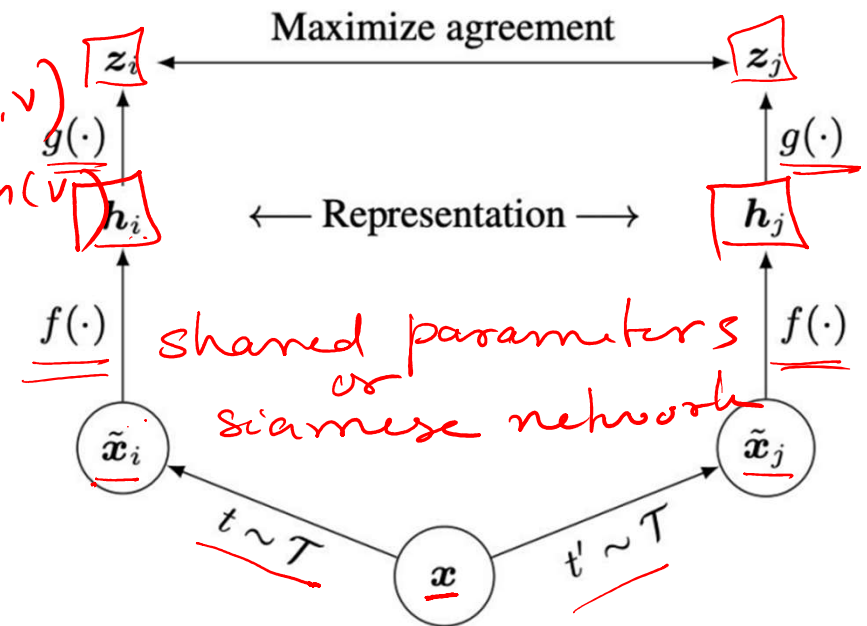
Cosine similarity as the score function:

$$\underline{s(u, v)} = \frac{u^T v}{\|u\| \|v\|} = \frac{\text{dot product}(u, v)}{\text{norm}(u) \text{norm}(v)}$$

Use a projection network $g(\cdot)$ to project features to a space where contrastive learning is applied

Generate positive samples through data augmentation:

- random cropping, random color distortion, and random blur.



Source: [Chen et al., 2020](#)

SimCLR: generating positive samples from data augmentation



(a) Original



(b) Crop and resize



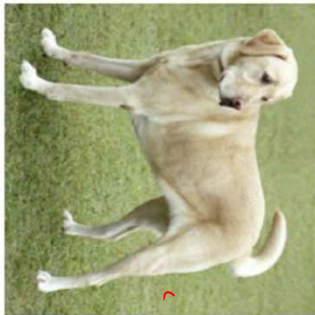
(c) Crop, resize (and flip)



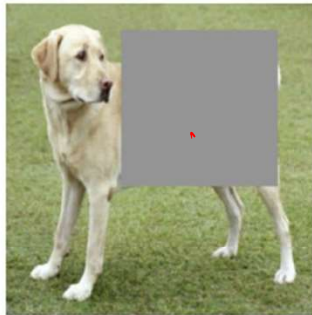
(d) Color distort. (drop)



(e) Color distort. (jitter)



(f) Rotate $\{90^\circ, 180^\circ, 270^\circ\}$



(g) Cutout



(h) Gaussian noise



(i) Gaussian blur



(j) Sobel filtering

Source: [Chen et al., 2020](#)

SimCLR

Algorithm 1 SimCLR's main learning algorithm.

input: batch size N , constant τ , structure of f, g, \mathcal{T} .
for sampled minibatch $\{\mathbf{x}_k\}_{k=1}^N$ **do**
 for all $k \in \{1, \dots, N\}$ **do**
 draw two augmentation functions $t \sim \mathcal{T}, t' \sim \mathcal{T}$
 # the first augmentation
 $\tilde{\mathbf{x}}_{2k-1} = t(\mathbf{x}_k)$
 $\mathbf{h}_{2k-1} = f(\tilde{\mathbf{x}}_{2k-1})$ # representation
 $\mathbf{z}_{2k-1} = g(\mathbf{h}_{2k-1})$ # projection
 # the second augmentation
 $\tilde{\mathbf{x}}_{2k} = t'(\mathbf{x}_k)$
 $\mathbf{h}_{2k} = f(\tilde{\mathbf{x}}_{2k})$ # representation
 $\mathbf{z}_{2k} = g(\mathbf{h}_{2k})$ # projection
 end for
 for all $i \in \{1, \dots, 2N\}$ and $j \in \{1, \dots, 2N\}$ **do**
 $s_{i,j} = \mathbf{z}_i^\top \mathbf{z}_j / (\|\mathbf{z}_i\| \|\mathbf{z}_j\|)$ # pairwise similarity
 end for
 define $\ell(i, j)$ as $\ell(i, j) = -\log \frac{\exp(s_{i,j}/\tau)}{\sum_{k=1}^{2N} \mathbb{1}_{[k \neq i]} \exp(s_{i,k}/\tau)}$
 $\mathcal{L} = \frac{1}{2N} \sum_{k=1}^N [\ell(2k-1, 2k) + \ell(2k, 2k-1)]$
 update networks f and g to minimize \mathcal{L}
end for
return encoder network $f(\cdot)$, and throw away $g(\cdot)$

*We use a slightly different formulation in the assignment. You should follow the assignment instructions.

Generate a positive pair by sampling data augmentation functions

Iterate through and use each of the $2N$ sample as reference, compute average loss

InfoNCE loss: Use all non-positive samples in the batch as \mathbf{x}^-

Source: [Chen et al., 2020](#)

Semi-supervised learning on SimCLR features

Method	Architecture	Label fraction	
		1%	10%
		— Top 5	
Supervised baseline	ResNet-50	48.4	80.4
<i>Methods using other label-propagation:</i>			
Pseudo-label	ResNet-50	51.6	82.4
VAT+Entropy Min.	ResNet-50	47.0	83.4
UDA (w. RandAug)	ResNet-50	-	88.5
FixMatch (w. RandAug)	ResNet-50	-	89.1
S4L (Rot+VAT+En. M.)	ResNet-50 (4×)	-	91.2
<i>Methods using representation learning only:</i>			
InstDisc	ResNet-50	39.2	77.4
BigBiGAN	RevNet-50 (4×)	55.2	78.8
PIRL	ResNet-50	57.2	83.8
CPC v2	ResNet-161(*)	77.9	91.2
SimCLR (ours)	ResNet-50	75.5	87.8
SimCLR (ours)	ResNet-50 (2×)	83.0	91.2
SimCLR (ours)	ResNet-50 (4×)	85.8	92.6

Table 7. ImageNet accuracy of models trained with few labels.

Train feature encoder on ImageNet (entire training set) using SimCLR.

Finetune the encoder with 1% / 10% of labeled data on ImageNet.

Source: [Chen et al., 2020](#)

Self-supervised multi-modal pre-training

- Learning to jointly encode image and text

<https://icml.cc/media/icml-2021/Slides/9193.pdf>