Support Vector Machines

Non-probabilistic models for classification of the form:

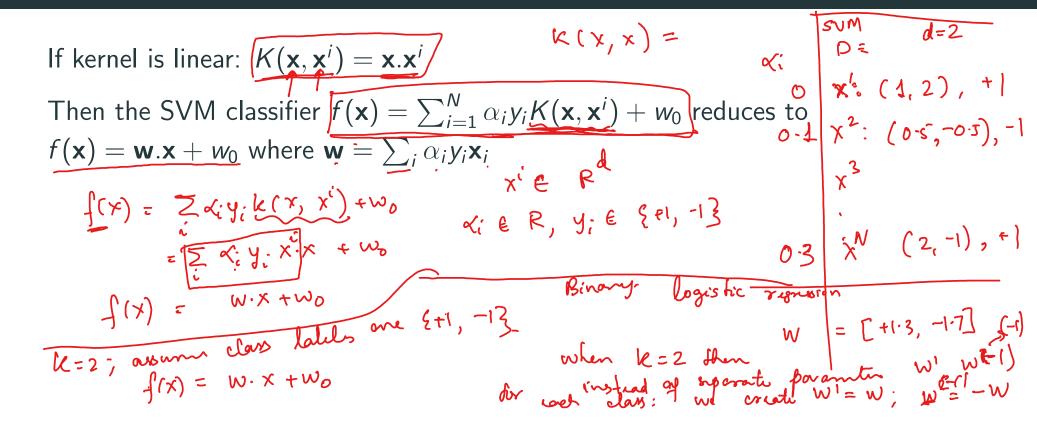
$$f(\mathbf{x}) = \sum_{i=1}^{N} \alpha_i y_i K(\mathbf{x}, \mathbf{x}^i) + w_0$$

Learning fixes values of α_i . These are chosen in such a way that only a few *i*s have non-zero α_i . These are called support vectors.

Assume $y_i \in \{-1, +1\}$, binary classification model.

Predicted class label = $sign(f(\mathbf{x}))$

When Kernel is linear

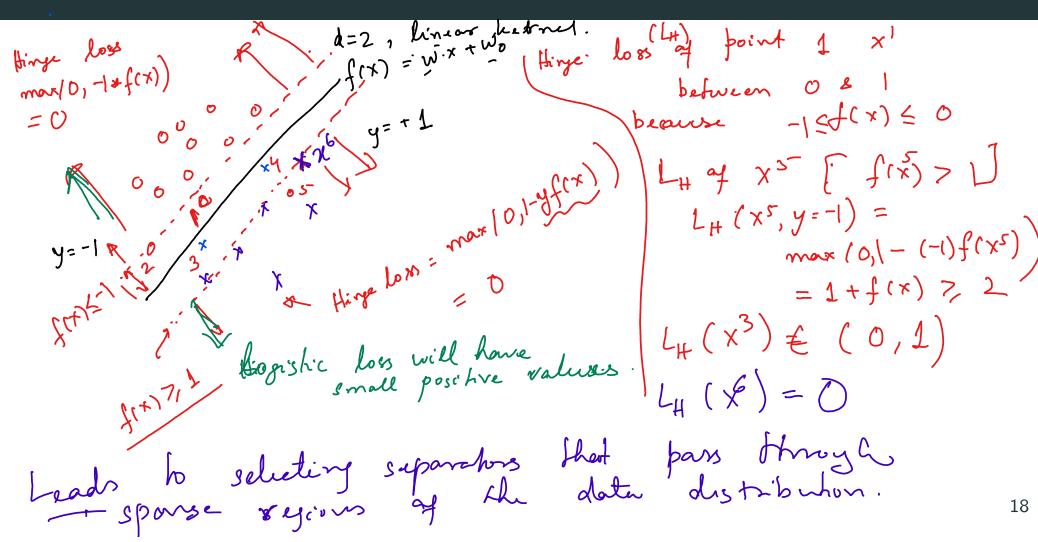


Training SVMs

Given a training dataset, find α_i s and w_0 so as to minimize a new margin loss called the Hinge loss. For correct prediction: yf(x) > 0 for a tool (x, y) Hinge loss: $L_H(y, f(x)) = \max(0, 1 - yf(x))$ Loss is 0 iff $yf(x) \ge 1$.

To minimal 0(1 prediction) which $yf(x) \ge 0$ minimal $yf(x) \ge$

Understanding Hinge Loss geometrically



Comparing Hinge loss and logistic loss.

Advantage of hinge-loss: sparsity. Perceptron loss: max(0, -yf(x))

High loss: LH = max(0, 1-yf(x)) bream of not impossing

mangin Alogistic loss: loss und in losgustices: regression elarnifices: -yf(x)) (for k=2) Le = log(1+e) If yf(x)>1 then LH =0 Logishe else LH = 1-yf(x) 95 yf(x) = 0 the Le = log(1+1) = log 2

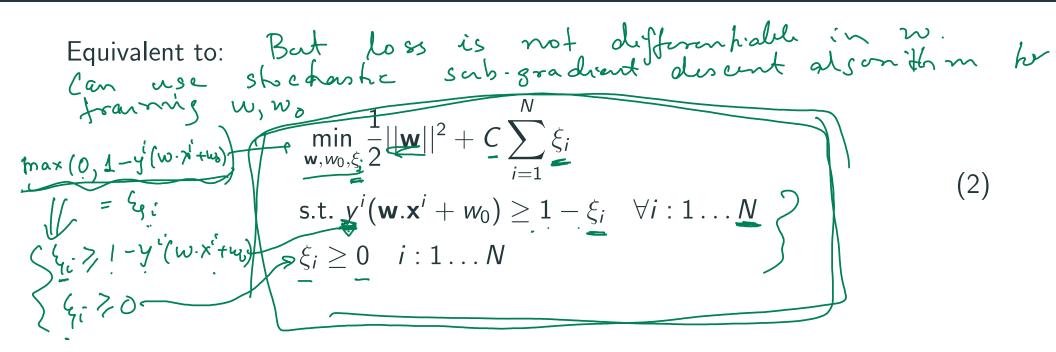
Comparing Hinge loss and logistic loss.

Advantage of hinge-loss: sparsity.

Training SVMs

First consider the linear case:

Training objective as a constrained program.



Show

Training objective in dual form

$$\max_{\alpha_{1},...,\alpha_{N}} \left\{ \sum_{i=1}^{N} \alpha_{i} - \frac{1}{2} \left(\sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} \mathbf{x}^{i} . \mathbf{x}^{j} \right) \right\}$$

$$\sum_{i=1}^{N} \alpha_{i} y_{i} = 0$$

$$0 <= \alpha_{i} <= C, \quad i:1...N \quad [box constraint]$$

$$(3)$$

Training algorithm for SVMs

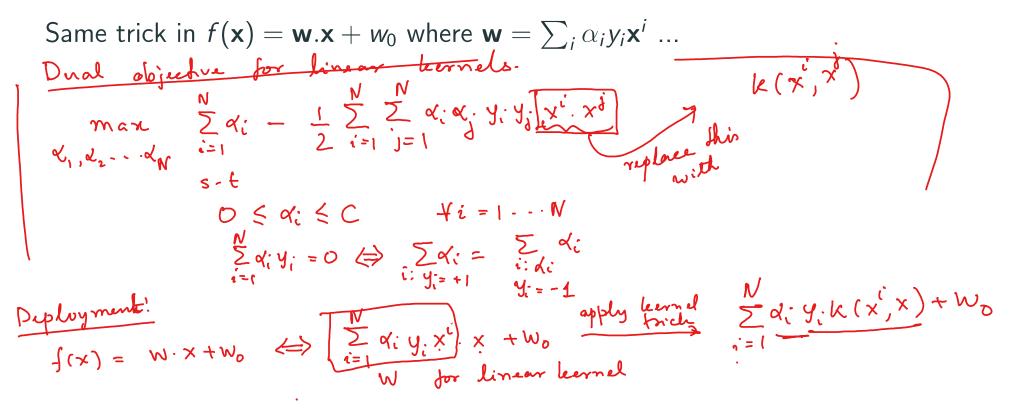
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3 Objective is concave in x-s
2) constraints are eary: box-combant bolancing comban.
=) (an solve with projected gradient ascent algorithm.
=) one popular mithod 13: SMO alsonithm:
   √°·· √° & 10· - - 0] €=0
   while no change: (t=1--.co)

pick tovo xi, xi
             attle di - D = ensures that \( \frac{tel}{2} = 0 \)
        find change 1 s.t.
             √3 + √3 - ▷ ((√3, √3)) C3 -1 if √3 = √3.
              D so as to kause maximum assent in objective.

and los diff < Ci o salt < C.
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Kernel Trick: extending to non-linear kernels

In the dual objective replace $\mathbf{x}^i.\mathbf{x}^j$ with $K(\mathbf{x}^i,\mathbf{x}^j)$.



Demo

Training Wo

1) Prick any example j set $y \neq C$ Now, solve for w_0 set: $y_i f(x^i) = 1$ $f(x) = \sum_{i=1}^{N} d_i y_i k(x^i, x) + w_0$

https://drive.google.com/file/d/1LihEFle5fyFbWPS342PA9NZdy2Kxjkvy/view?usp=sharing

Summary

- Kernel methods provide a new way to represent data and build models based purely on comparision of two points.
- Various kernels are available, each with its own characteristics.
- Kernel methods find applications in several ML algorithms: classifiers (Nearest neighbor, few-shot classification, SVMs) and regression (Kernel regression, support vector regression, Gaussian processes)