

Solution 1  
Introduction to LMIs and Optimization Toolboxes  
Alexandre Didier and Jérôme Sieber

---

## 1 Exercise

### Linear Matrix Inequalities

1. Consider the set of matrices

$$\mathcal{F} = \{F(x) \in \mathbb{R}^{n \times n}, x \in \mathbb{R}^m \mid F(x) = F_0 + \sum_{i=1}^m F_i x_i, F(x) \succeq 0\},$$

where  $F_i \in \mathbb{R}^{n \times n}$ . Show that this set is convex.

2. Consider the ellipsoid  $\mathcal{E} = \{x \in \mathbb{R}^n \mid (x - x_c)^T P (x - x_c) \leq 1\}$ , which  $P$  symmetric and  $P \succeq 0$ . Rewrite the inequality  $(x - x_c)^T P (x - x_c) \leq 1$  as an LMI in the variable  $P^{-1}$  using Schur's complement. Can you also formulate the LMI in the variable  $P$ ?

### Semi-definite Programming

1. Write down an SDP which computes the largest ellipsoid  $\mathcal{E} = \{x \in \mathbb{R}^n \mid x^T P x \leq 1\}$  fully contained in the polytope  $\mathbb{X} = \{x \in \mathbb{R}^n \mid A_x x \leq b_x\}$ , with  $A_x \in \mathbb{R}^{n_x \times n}$ ,  $b_x \in \mathbb{R}^{n_x}$ .  
*Hint:* The volume of  $\mathcal{E}$  is proportional to  $\log \det(P^{-1})$ , where  $\log \det$  is concave.  
*Hint:* An ellipsoid is contained within a halfspace  $a^T x \leq b$  if  $a^T P^{-1} a \leq b^2$ .
2. Complete the provided MATLAB template to solve the SDP in 1. using YALMIP.

## 2 Solution

### Linear Matrix Inequalities

1. Note that a set  $\mathcal{A}$  is convex if it holds for all  $x, y \in \mathcal{A}$  and  $\lambda \in [0, 1]$ , that  $\lambda x + (1 - \lambda)y \in \mathcal{A}$ . Using the definition of  $\mathcal{F}$ , we have

$$\begin{aligned}
 F(\lambda x + (1 - \lambda)y) &= F_0 + \sum_{i=1}^m (\lambda x_i + (1 - \lambda)y_i) F_i \\
 &= \lambda F_0 + (1 - \lambda)F_0 + \lambda \sum_{i=1}^m x_i F_i + (1 - \lambda) \sum_{i=1}^m y_i F_i \\
 &= \lambda F(x) + (1 - \lambda)F(y) \\
 &\succeq 0
 \end{aligned}$$

2. We have

$$\begin{aligned}
 (x - x_c)^T P (x - x_c) &\leq 1 \\
 \Leftrightarrow 1 - (x - x_c)^T P (x - x_c) &\geq 0 \\
 \Leftrightarrow \begin{bmatrix} 1 & (x - x_c)^T \\ (x - x_c) & P^{-1} \end{bmatrix} &\succeq 0
 \end{aligned}$$

By defining  $E = P^{-1}$ , we have

$$\Leftrightarrow \begin{bmatrix} 1 & (x - x_c)^T \\ (x - x_c) & E \end{bmatrix} \succeq 0.$$

Alternatively, we can write

$$\begin{aligned}
 1 - (x - x_c)^T P (x - x_c) &\geq 0 \\
 \Leftrightarrow 1 - (x - x_c)^T P P^{-1} P (x - x_c) &\geq 0 \\
 \Leftrightarrow \begin{bmatrix} 1 & (x - x_c)^T P \\ P (x - x_c) & P \end{bmatrix} &\succeq 0
 \end{aligned}$$

### Semi-definite Programming

1. By using  $E = P^{-1}$ , we can write the SDP as

$$\begin{aligned}
 \min_E & -\log \det E \\
 \text{s.t. } & \forall i = 0, \dots, n_x \\
 & E \succeq 0 \\
 & [A_x]_i E [A_x]_i^T \leq [b_x]_i^2
 \end{aligned}$$

2. The MATLAB Code for this question can be found on Moodle.