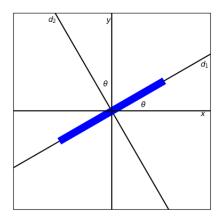
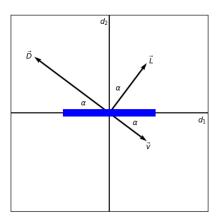
## 02-Airbounce: Ideje in rešitve

## Stabilen frizbi 1

Frizbi zaradi vrtenja ohranja orientacijo.





Slika 1: Graf osi, koordinatni sistem N

Slika 2: Koordinatni sistem frizbija D

V sistemu frizbija (D):

$$L = \frac{1}{2}A\rho C_L v^2 \qquad D = \frac{1}{2}A\rho C_D v^2 \tag{1}$$

$$C_L = C_{L0} + C_{L\alpha}\alpha \qquad C_D = C_{D0} + C_{D\alpha}\alpha^2 \tag{2}$$

$$K = \frac{A\rho}{2m} \qquad \tan \alpha = \frac{-v_2}{v_1} \tag{3}$$

$$L = \frac{1}{2}A\rho C_L v^2 \qquad D = \frac{1}{2}A\rho C_D v^2$$

$$C_L = C_{L0} + C_{L\alpha}\alpha \qquad C_D = C_{D0} + C_{D\alpha}\alpha^2$$

$$K = \frac{A\rho}{2m} \qquad \tan \alpha = \frac{-v_2}{v_1}$$

$$L = mKv^2 C_L \begin{pmatrix} \sin \alpha \\ \cos \alpha \end{pmatrix} = mKv^2 C_L \begin{pmatrix} -v_2 \\ v_1 \end{pmatrix}$$

$$(1)$$

$$(2)$$

$$(3)$$

$$\mathbf{D} = mKv^2 C_D \begin{pmatrix} -\cos\alpha\\ \sin\alpha \end{pmatrix} = mKv^2 C_D \begin{pmatrix} -v_1\\ -v_2 \end{pmatrix}$$
 (5)

$$\mathbf{F_g} = -mg \begin{pmatrix} \sin \theta \\ \cos \theta \end{pmatrix} \tag{6}$$

(7)

$$m\mathbf{a} = \mathbf{L} + \mathbf{D} + \mathbf{F_g} \tag{8}$$

$$v = \sqrt{v_1^2 + v_2^2} \tag{9}$$

$$a_1 = -K(C_{L0} + C_{L\alpha}\alpha)vv_2 - K(C_{D0} + C_{D\alpha}\alpha^2)vv_1 - g\sin\theta$$
 (10)

$$a_2 = K(C_{L0} + C_{L\alpha}\alpha)vv_1 - K(C_{D0} + C_{D\alpha}\alpha^2)vv_2 - g\cos\theta$$
 (11)

Rešimo:  $d_1, d_2, v_1, v_2$ . Zarotiramo v N sistem.

$$R = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \tag{12}$$

$$\begin{pmatrix} x \\ y \end{pmatrix}_{N} = R \begin{pmatrix} d_{1} \\ d_{2} \end{pmatrix}_{D}$$

$$\begin{pmatrix} v_{x} \\ v_{y} \end{pmatrix}_{N} = R \begin{pmatrix} v_{1} \\ v_{2} \end{pmatrix}_{D}$$
(13)

$$\begin{pmatrix} v_x \\ v_y \end{pmatrix}_N = R \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}_D$$
 (14)