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# Problem no.13 - Chaotic Magnetic Pendulum IPT 2022

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#### Official Problem Statement

Consider a pendulum consisting of a magnetic bob attached to a string. If the pendulum is allowed to swing over a structure of permanent magnets, it will display complex motion. Study the pendulum dynamics and its dependence on the number of permanent magnets and their arrangement.

#### Hypotheses

For certain initial parameters pendulum will display chaotic motion.

## Theory

- For continuous dynamical systems, the Poincaré–Bendixson theorem shows that chaos only exist in 3 dimensions described by non-linear equations.
- Dynamical chaos can exist in systems starting with effective 3/2 (1/2 for no explicit time dependence) degrees of freedom.
- Integrals of motion (conserved) restrict the solution and make dynamical chaos less likely:

$$N_F = \frac{1}{2}(N - N_{int})$$

## Theory

Chaotic pendulum:

$$N = 4$$
,  $N_{int} = 1 \Rightarrow N_F = 3/2$ 

In the presence of dissipation, a mechanical system relaxes down to one of its local energy minima. Generally, dissipation tends to make chaotic motion regular.

## Theoretical Description

We approximate magnets by magnetic dipoles.

Coordinate system origin at the top of the string.

Force between two dipoles:

$$\mathbf{F}_{\mathbf{m}}(\mathbf{r}', \mathbf{m}_{1}, \mathbf{m}_{2}) = \frac{3\mu_{0}}{4\pi r'^{5}} \left[ (\mathbf{m}_{1} \cdot \mathbf{r}') \mathbf{m}_{2} + (\mathbf{m}_{2} \cdot \mathbf{r}') \mathbf{m}_{1} + (\mathbf{m}_{1} \cdot \mathbf{m}_{2}) \mathbf{r}' - \frac{5(\mathbf{m}_{1} \cdot \mathbf{r}')(\mathbf{m}_{2} \cdot \mathbf{r}')}{r'^{2}} \mathbf{r}' \right]$$
(1)

$$\mathbf{r} = (x, y, -l - h + \sqrt{l^2 - x^2 - y^2})$$
 (2)

All forces:

$$\mathbf{F} = \mathbf{F_g} + \mathbf{F_{mi}} - \mathbf{F_v} \tag{3}$$

$$\mathbf{F} = \mathbf{F_g} + \mathbf{F_{mi}} - \langle \mathbf{F_g} + \mathbf{F_{mi}}, \frac{\mathbf{r}}{r} \rangle \frac{\mathbf{r}}{r}$$
(4)

## Theoretical Description

#### Dimensionless:

$$\{x, y, z\} = L\{\chi, \gamma, \zeta\}, \qquad \boldsymbol{r} = L\boldsymbol{\rho}, \qquad t = T\tau$$
 (5)

$$\|\mathbf{m_1}\| = \|\mathbf{m_2}\| \tag{6}$$

$$L = \sqrt[4]{\frac{\mu_0 \|\mathbf{m_1}\|^2}{mg}}, \qquad T = \sqrt{\frac{L}{g}}$$
 (7)

$$\mathcal{F}_{\mathbf{mi}}(\boldsymbol{\rho}, \boldsymbol{\rho}_i') = \frac{3}{4\pi\rho_i'^5} \left[ (-\frac{\boldsymbol{\rho}}{\rho} \cdot \boldsymbol{\rho}_i') \hat{\mathbf{e}}_z + (\hat{\mathbf{e}}_z \cdot \boldsymbol{\rho}_i') - \frac{\boldsymbol{\rho}}{\rho} + (-\frac{\boldsymbol{\rho}}{\rho} \cdot \hat{\mathbf{e}}_z) \boldsymbol{\rho}_i' - \frac{5(-\frac{\boldsymbol{\rho}}{\rho} \cdot \boldsymbol{\rho}_i')(\hat{\mathbf{e}}_z \cdot \boldsymbol{\rho}_i')}{\rho_i'^2} \boldsymbol{\rho}_i' \right]$$
(8)

## Theoretical Description

Dimensionless:

$$\boldsymbol{\rho} = \left(\chi, \gamma, -\lambda - \eta + \sqrt{\lambda^2 - \chi^2 - \gamma^2}\right) \tag{9}$$

$$\mathcal{F} = \mathcal{F}_{\mathbf{g}} + \mathcal{F}_{\mathbf{mi}} - \mathcal{F}_{\mathbf{v}} \tag{10}$$

$$\mathcal{F} = \mathcal{F}_{\mathbf{g}} + \mathcal{F}_{\mathbf{mi}} - \langle \mathcal{F}_{\mathbf{g}} + \mathcal{F}_{\mathbf{mi}}, \frac{\boldsymbol{\rho}}{\rho} \rangle \frac{\boldsymbol{\rho}}{\rho}$$
 (11)

Projection on x, y plane.

$$\begin{pmatrix} \ddot{\chi} \\ \ddot{\gamma} \end{pmatrix} = \begin{pmatrix} \langle \mathcal{F}, \, \hat{e}_x \rangle \\ \langle \mathcal{F}, \, \hat{e}_y \rangle \end{pmatrix} \tag{12}$$

We solve for  $\chi, \gamma$ .



## Experiment

- We used different magnetic configurations.
- We filmed throws at different initial parameters.

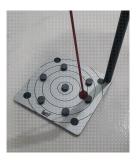


Figure 1: Example of an experiment.

Residual flux density on surface  $B_r$ 

$$m_1 = \frac{B_r V}{\mu_0} \approx 0.1 \text{Am}^2, \quad l = 0.18 \text{cm}, \quad h = 0.02 \text{cm}, \quad m \approx 3 \text{g}$$

## Experiment

#### We found three regimes.

- High kinetic energy: pendulum swings sinusoidally in a regular way.
- Medium kinetic energy: pendulum swings chaotically.
- Low kinetic energy: perturbed sinusoidal swinging in a minimum (spherical pendulum).

## Experiment videos Animation $\rightarrow$

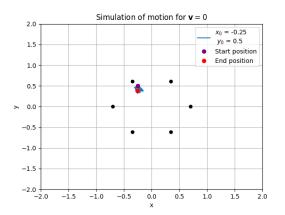


Figure 2: Example of stationary point.

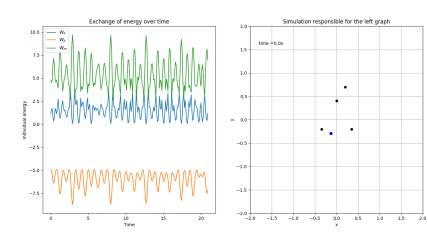


Figure 3: Exchange of energy over time.

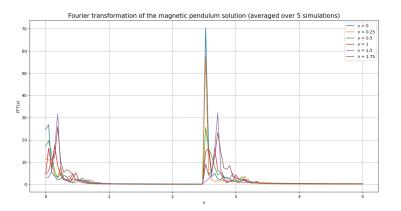


Figure 4: Fourier transformation, eigen frequencies. For higher energies motion is more chaotic. Second peak is redundant, arises form discrete model.

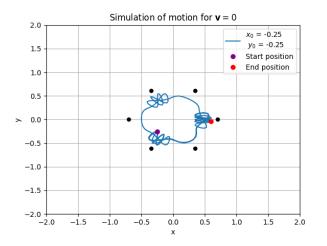


Figure 5: Motion looks like a random walk. Swinging in a minimum and jumping to other minimums.

#### Conclusion

- We found regular and chaotic regimes of motion in experiment.
- We showed in simulation that for certain initial parameters motion is chaotic.

### References

[1] D. Garanin. *Dynamical Chaos*. (2008). https://www.lehman.edu/faculty/dgaranin/Mechanics/Dynamical\_Chaos.pdf