Rollen D'Souza

rs2dsouz@edu.uwaterloo.ca • github.com/rollends

Publications

V. Joukov, R. D'Souza and D. Kulić, *Human pose estimation from imperfect sensor data via the Extended Kalman Filter*, International Symposium on Experimental Robotics, 2016. [Presented, In Print]

Academic Work Experience

Industry Work Experience