Logout 3 regression Last Checkpoint: 5 hours ago (autosaved) Menu Python 2 • File New Notebook Python 2 Python 3 Open... 0 Make a Copy... • Rename... Save and Checkpoint Revert to Checkpoint Saturday, February 25, 2017 5:19 PM 0 Print Preview Download as Notebook (.ipynb) Python (.py) HTML (.html) Markdown (.md) reST (.rst) PDF via LaTeX (.pdf) **Trusted Notebook** Close and Halt • Edit Cut Cells Copy Cells Paste Cells Above Paste Cells Below Paste Cells & Replace Delete Cells Undo Delete Cells 0

- Split Cell
- Merge Cell Above
- Merge Cell Below

0

- Move Cell Up
- Move Cell Down

0

Edit Notebook Metadata

c

- Find and Replace
- View
 - Toggle Header
 - Toggle Toolbar
 - Cell Toolbar
 - None
 - Edit Metadata
 - Raw Cell Format
 - Slideshow
- Insert
 - Insert Cell Above
 - Insert Cell Below
- <u>Cell</u>
 - Run Cells
 - Run Cells and Select Below
 - Run Cells and Insert Below
 - Run All
 - Run All Above
 - Run All Below

C

- Cell Type
 - Code
 - Markdown
 - Raw NBConvert

0

- Current Outputs
 - <u>Toggle</u>
 - Toggle Scrolling
 - Clear
- All Output
 - Toggle
 - Toggle Scrolling
 - Clear

- Kernel
 - Interrupt
 - Restart
 - Restart & Clear Output
 - Restart & Run All
 - Reconnect
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 - Python 2
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- Help
 - User Interface Tour
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 - Notebook Help
 - Markdown

 - Python
 - <u>IPython</u>
 - NumPy
 - SciPy
 - Matplotlib
 - SymPy
 - pandas

 - About



Code

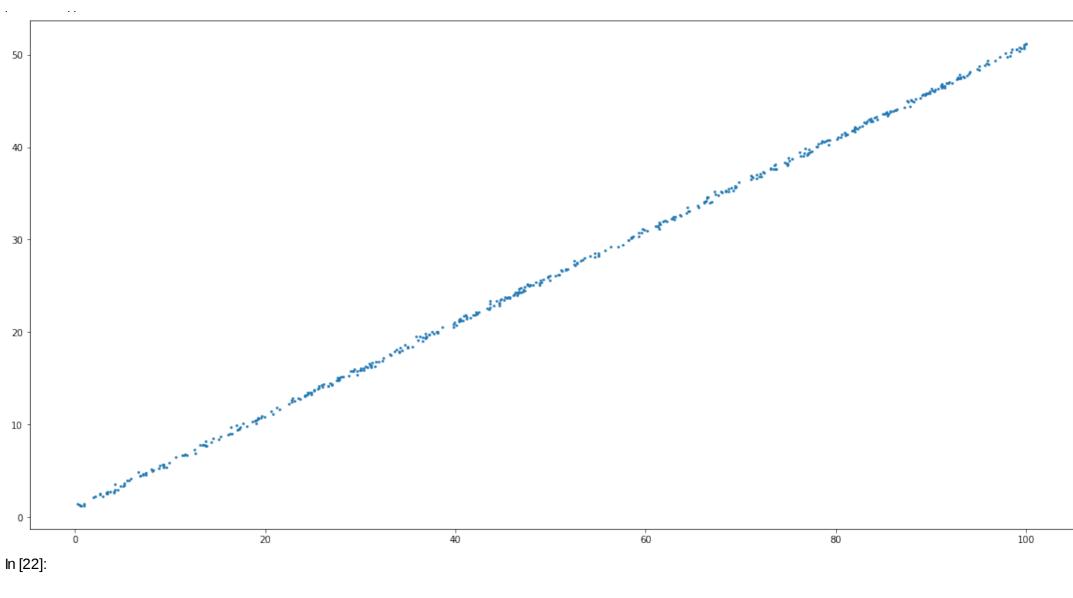
CellToolbar

In [16]:

import scipy.stats as sps

import numpy as np

```
import matplotlib.pyplot as plt
%matplotlib inline
In [12]:
bounds = (0, 100)
size_of_sample = 500
X = sps.uniform.rvs(bounds[0], bounds[1], size_of_sample)
noise = sps.norm.rvs(0, 0.2, size_of_sample)
Y = 0.5 * X + noise + 1
plt.figure(figsize=(20, 10))
plt.scatter(X, Y, s=3)
plt.show()
```

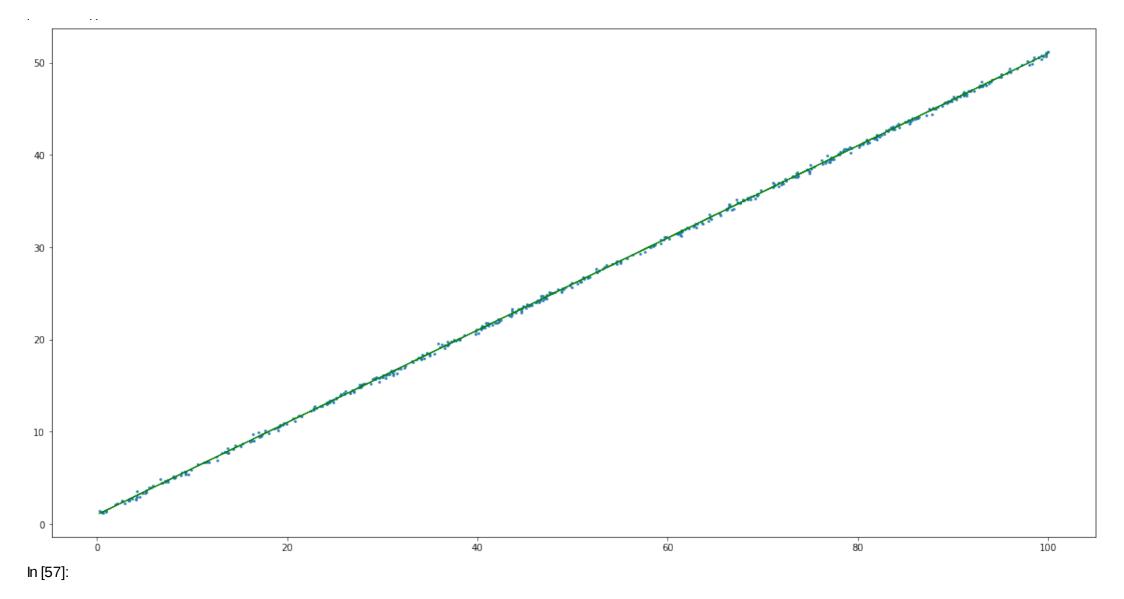


from scipy.optimize import minimize In [28]:

def model(k):
 return k[0] * X + k[1]

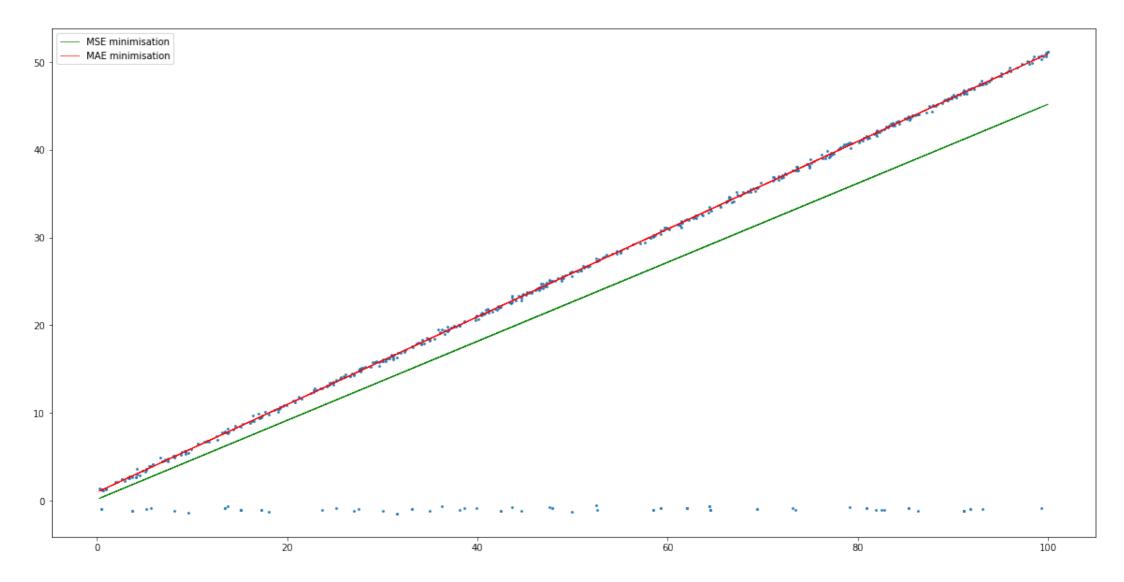
def fun(k):

```
return np.sum((model(k) - Y)**2)
res = minimize(fun, [0, 1.5])
In [37]:
print "MSE has a result as k = \%f, b = \%f and a value of minimised func as : \%f" \% (res.x[0], res.x[1], fun(res.x)) MSE has a result as k = 0.500146, b = 0.994311 and a value of minimised func as : 18.800026
In [35]:
plt.figure(figsize=(20, 10))
plt.scatter(X, Y, s=3)
plt.plot(X, model(res.x), c='g', linewidth=0.7)
plt.show()
```



blowout_size = 75
blowout_id = np.array(map(int,sps.uniform.rvs(bounds[0],bounds[1], blowout_size)))
X_blowout = X[blowout_id]
noise_blowout = noise[blowout_id]
Y_blowout = -1 + noise_blowout

```
X_{new} = np.array(list(X) + list(X_blowout))
Y_new = np.array(list(Y) + list(Y_blowout))
def model_new(k):
    return k[0] * X_new + k[1]
def MSE_fun_new(k):
    return np.sum((model_new(k) - Y_new)**2)
def MAE_fun_new(k):
    return np.sum(np.abs(model_new(k) - Y_new))
res = minimize(MSE_fun_new, [0, 1.5])
res_MAE = minimize(MAE_fun_new, [0, 1.5])
print "MSE has a result as k = \%f, b = \%f and a value of minimised func as : \%f\n" % (res.x[0], res.x[1], MSE_fun_new(res.x))
print "MAE has a result as k = \%f, b = \%f and a value of minimised func as : \%f" \% (res_MAE.x[0], res_MAE.x[1], MAE_fun_new(res.x))
plt.figure(figsize=(20, 10))
plt.scatter(X_new, Y_new, s=3)
plt.plot(X, model(res.x),c='g',linewidth=0.7, label="MSE minimisation")
plt.plot(X, model(res_MAE.x),c='r',linewidth=0.7,label="MAE minimisation")
plt.legend()
plt.show()
MSE has a result as k = 0.450598, b = 0.145170 and a value of minimised func as : 57719.779273
MAE has a result as k = 0.500168, b = 0.953347 and a value of minimised func as : 3413.043402
```



Функция ошибки в виде суммы абсолютной ошибки более устойчива к выбросам Функция ошибки в виде суммы абсолютной ошибки более устойчива к выбросам