

ADVANCED REGRESSION TOPICS

- Training Data Set can be written as following:

Sl. No.	x_0	x_1	...	x_k	y
1	1	$x_1^{(1)}$...	$x_k^{(1)}$	$y^{(1)}$
2	1	$x_1^{(2)}$...	$x_k^{(2)}$	$y^{(2)}$
⋮	⋮	⋮	...	⋮	⋮
m	1	$x_1^{(m)}$...	$x_k^{(m)}$	$y^{(m)}$

- There are total k many features and m many training examples.
- Notice that we have added one extra feature column x_0 with all values 1 in the left.
- The training samples can now be written as $\langle \mathbf{x}^{(i)}, y^{(i)} \rangle_{i=1}^m$
Where $\mathbf{x}^{(i)} = [x_0^{(i)}, x_1^{(i)}, x_2^{(i)}, \dots, x_k^{(i)}]^T$ is the vector of dimension $k + 1$.
- Now the equation $y = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_k x_k$ can be written in vector form as $y = \Theta^T \mathbf{x}$.
- Where $\Theta = [\theta_0, \theta_1, \theta_2, \dots, \theta_k]^T$ is the vector of parameters of the model. Θ is of dimension $k + 1$.

- In linear regression we are trying to estimate the model parameter vector from the given set of data. Let the estimated parameter vector be $\hat{\Theta}$ and the corresponding predicted values be $\hat{\mathbf{y}}$. Then in vector-matrix notation:

$$\hat{\mathbf{y}} = \begin{bmatrix} \hat{y}^{(1)} \\ \hat{y}^{(2)} \\ \vdots \\ \hat{y}^{(m)} \end{bmatrix} = \begin{bmatrix} 1 & x_1^{(1)} & \dots & x_k^{(1)} \\ 1 & x_1^{(2)} & \dots & x_k^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_1^{(m)} & \dots & x_k^{(m)} \end{bmatrix} \begin{bmatrix} \hat{\theta}_0 \\ \hat{\theta}_1 \\ \vdots \\ \hat{\theta}_k \end{bmatrix} \quad \text{or} \quad \hat{\mathbf{y}} = \mathbf{X}\hat{\Theta}, \quad \text{Where } \mathbf{X} \text{ is the matrix:}$$

x_0	x_1	\dots	x_k
1	$x_1^{(1)}$	\dots	$x_k^{(1)}$
1	$x_1^{(2)}$	\dots	$x_k^{(2)}$
\vdots	\vdots	\dots	\vdots
1	$x_1^{(m)}$	\dots	$x_k^{(m)}$

- The mean square error cost function in vector-matrix notation is following:

$$J(\hat{\Theta}) = \frac{1}{2m} (\mathbf{X}\hat{\Theta} - \mathbf{y})^T (\mathbf{X}\hat{\Theta} - \mathbf{y})$$

where $\hat{\mathbf{y}} = \mathbf{X}\hat{\Theta}$ is the vector of predicted values and \mathbf{y} is vector of the actual values.

- Simplified cost function is:

$$\begin{aligned} J(\hat{\Theta}) &= \frac{1}{2m} (\mathbf{X}\hat{\Theta} - \mathbf{y})^T (\mathbf{X}\hat{\Theta} - \mathbf{y}) = \frac{1}{2m} \left((\mathbf{X}\hat{\Theta})^T - \mathbf{y}^T \right) (\mathbf{X}\hat{\Theta} - \mathbf{y}) = \\ &= \frac{1}{2m} \left((\mathbf{X}\hat{\Theta})^T \mathbf{X}\hat{\Theta} - \mathbf{y}^T (\mathbf{X}\hat{\Theta}) - (\mathbf{X}\hat{\Theta})^T \mathbf{y} + \mathbf{y}^T \mathbf{y} \right) = \frac{1}{2m} (\hat{\Theta}^T \mathbf{X}^T \mathbf{X} \hat{\Theta} - 2\hat{\Theta}^T \mathbf{X}^T \mathbf{y} + \mathbf{y}^T \mathbf{y}) \end{aligned}$$

Because $\mathbf{y}^T (\mathbf{X}\hat{\Theta})$ and $(\mathbf{X}\hat{\Theta})^T \mathbf{y}$ are scalars and $\mathbf{y}^T (\mathbf{X}\hat{\Theta}) = (\mathbf{X}\hat{\Theta})^T \mathbf{y} = \hat{\Theta}^T \mathbf{X}^T \mathbf{y}$

- After differentiating $J(\hat{\Theta})$ with respect to $\hat{\Theta}$ and setting the derivative to zero:

$$\frac{\partial J(\hat{\Theta})}{\partial \hat{\Theta}} = \frac{1}{m} (\mathbf{X}^T \mathbf{X} \hat{\Theta} - \mathbf{X}^T \mathbf{y}) = 0 \quad \text{or} \quad \mathbf{X}^T \mathbf{X} \hat{\Theta} = \mathbf{X}^T \mathbf{y} \quad \text{or}$$

$$\hat{\Theta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}, \text{ assuming } \mathbf{X}^T \mathbf{X} \text{ is invertible}$$

Normal Equation

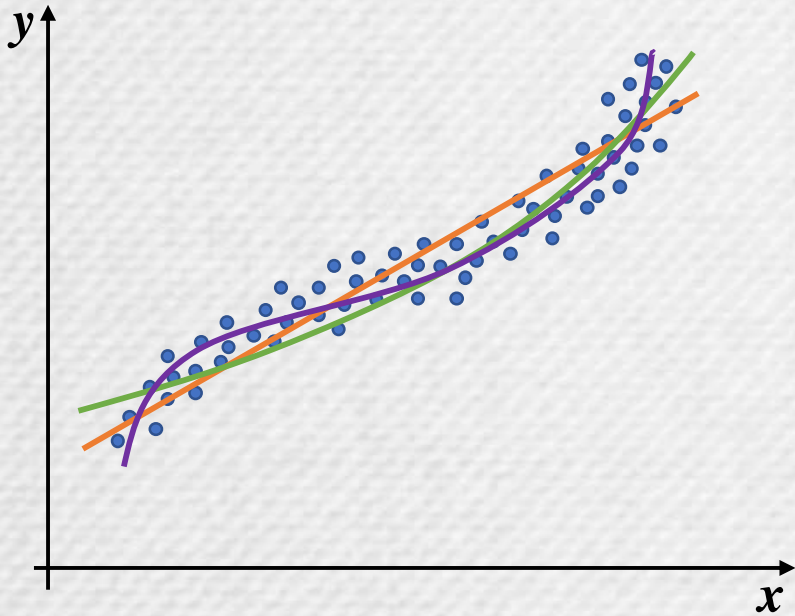
- Gradient Descent or Normal Equation which one is preferable?

Though normal equation directly gives solution without iteration like GD, it has many drawbacks. Like, for large dataset computing $(\mathbf{X}^T \mathbf{X})^{-1}$ is a costly operation. Moreover, if $\mathbf{X}^T \mathbf{X}$ is non-invertible we can't use normal equation directly as above.

The workaround in the case when $\mathbf{X}^T \mathbf{X}$ is non-invertible is to use pseudo-inverse.

Hence, gradient descent is more popular and good choice for solving linear regression problem.

- Consider the following example:



- We can fit a straight line through the datapoints of the form

$$y = \theta_0 + \theta_1 x$$

- But we can do better, if we fit second order polynomial of the form:

$$y = \theta_0 + \theta_1 x + \theta_2 x^2$$

- Or if we fit third order polynomial of the form:

$$y = \theta_0 + \theta_1 x + \theta_2 x^2 + \theta_3 x^3$$

- In general we can fit a n^{th} order polynomial through the datapoints:

$$y = \theta_0 + \theta_1 x + \theta_2 x^2 + \theta_3 x^3 + \dots + \theta_n x^n$$

- Smaller the value of n , the complexity of the model is less but the model may not fit the dataset appropriately. So we have to choose n accordingly such that we get reasonably good fit with less complexity.
- We can convert the polynomial regression problem into multiple linear regression problem just by assigning:
 $x_1 = x, x_2 = x^2, x_3 = x^3, \dots, x_n = x^n$ and then constructing multiple linear regression model $y = \theta_0 + \sum_{i=1}^n \theta_i x_i$
- For more than one predictor variables the polynomial regression becomes more complicated. For two predictor variables x_1 and x_2 the generalized form of second order polynomial is:
 $y = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_1 x_2 + \theta_4 x_1^2 + \theta_5 x_2^2$

To determine the “goodness” of the fit in a linear regression model we use a quantitative measure. That is “*Coefficient of Determination*” (R^2). It is defined as follows.

- Let there are m number of datapoints. $\mathbf{y} = [y_1, y_2, y_3, \dots, y_m]^T$ is the vector of the actual values of target variable and $\hat{\mathbf{y}} = [\hat{y}_1, \hat{y}_2, \hat{y}_3, \dots, \hat{y}_m]^T$ is the vector of predicted values of the target variable.
- Let, \bar{y} is the mean of the target variable. Then the *Total Sum of Squares (TSS)* is defined as follows:

$$TSS = \sum_{i=1}^m (y_i - \bar{y})^2$$

- TSS is proportional to the variance of the target variable.

- We already know the *Residual Sum of Squares* (RSS)

$$RSS = \sum_{i=1}^m (y_i - \hat{y}_i)^2$$

- Now the *Fraction of Unexplained Variance* (FUV) is defined as:

$$FUV = \frac{RSS}{TSS}$$

- Coefficient of Determination (R^2) also called *Fraction of Explained Variance* (FEV) is defined as:

$$R^2 = 1 - FUV = 1 - \frac{RSS}{TSS}$$

Properties of Coefficient of Determination:

- Coefficient of Determination (R^2) lies between 0 to 1
- Closer the value of R^2 to 1, Regression model fits better to our dataset and can better explain the observed variability of the target variable.
- Smaller value of R^2 implies that the regression model is not that good.
- It can be shown that for bivariate dataset
$$R^2 = \text{Square of the correlation coefficient between the predictor and target variable}$$