

Quantifying the Latency and Possible Throughput of External Interrupts on Cyber-Physical Systems



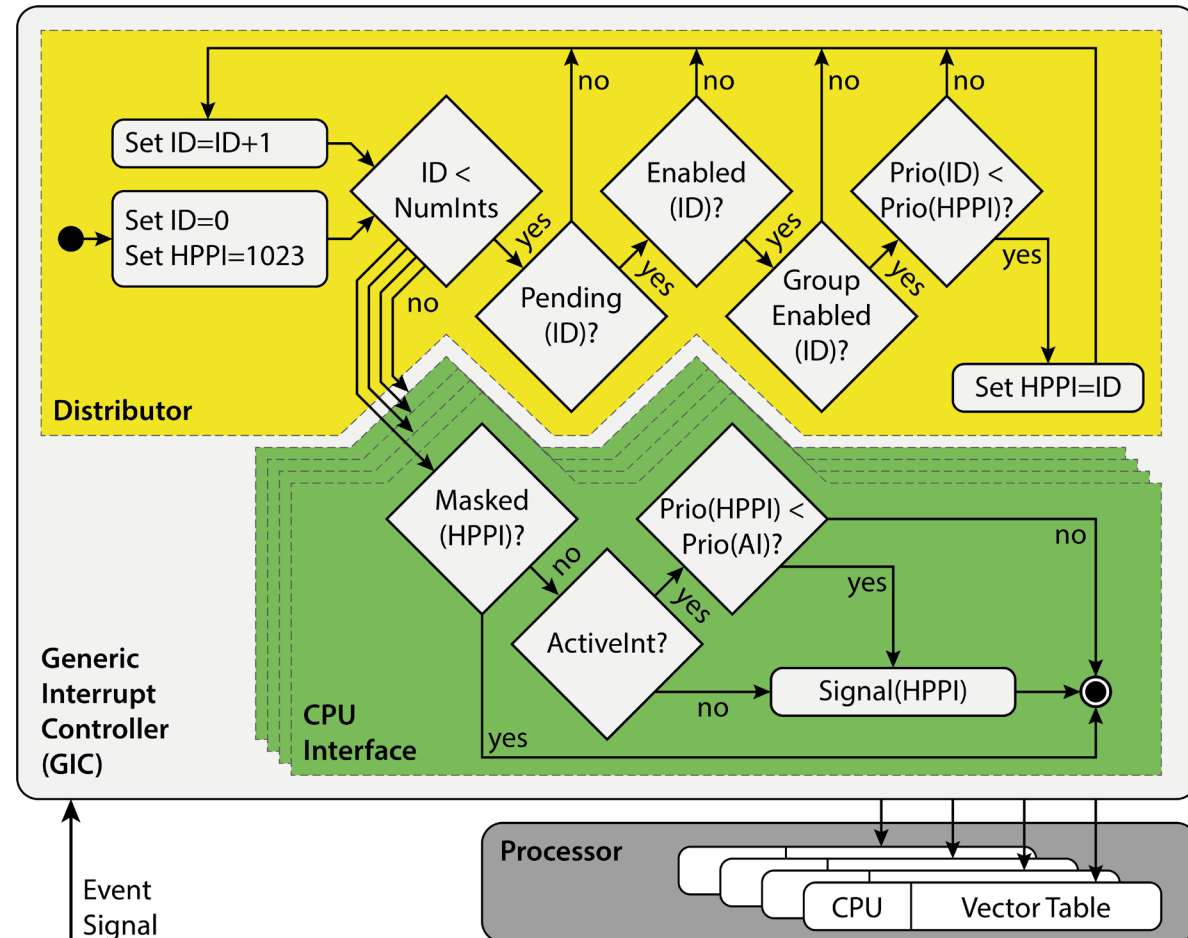
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Introduction

- ▶ Cyber-physical systems demand both, timely and predictable responses to physical events
- ▶ The interrupt handling process makes up a large part of this
- ▶ Previous studies focused on external measurements that are not applicable to modern, complex SoC, due to occurring inaccuracies
- ▶ Hence, we propose a flexible measurement procedure for ARMv8-A IP-core based platforms that provide a trace port
- ▶ We see a wide applicability of our measurement procedure, due to the increased market share of ARM and the wide adoption of ARM-based systems in the automotive industry (e.g., Mercedes MBUX, Continental Body Computers, and Tesla Autonomous Driving Platform)
- ▶ Precise measurements on the interrupt performance are beneficiary for the design of virtualization solutions, operating system, and runtime environments for time-critical systems

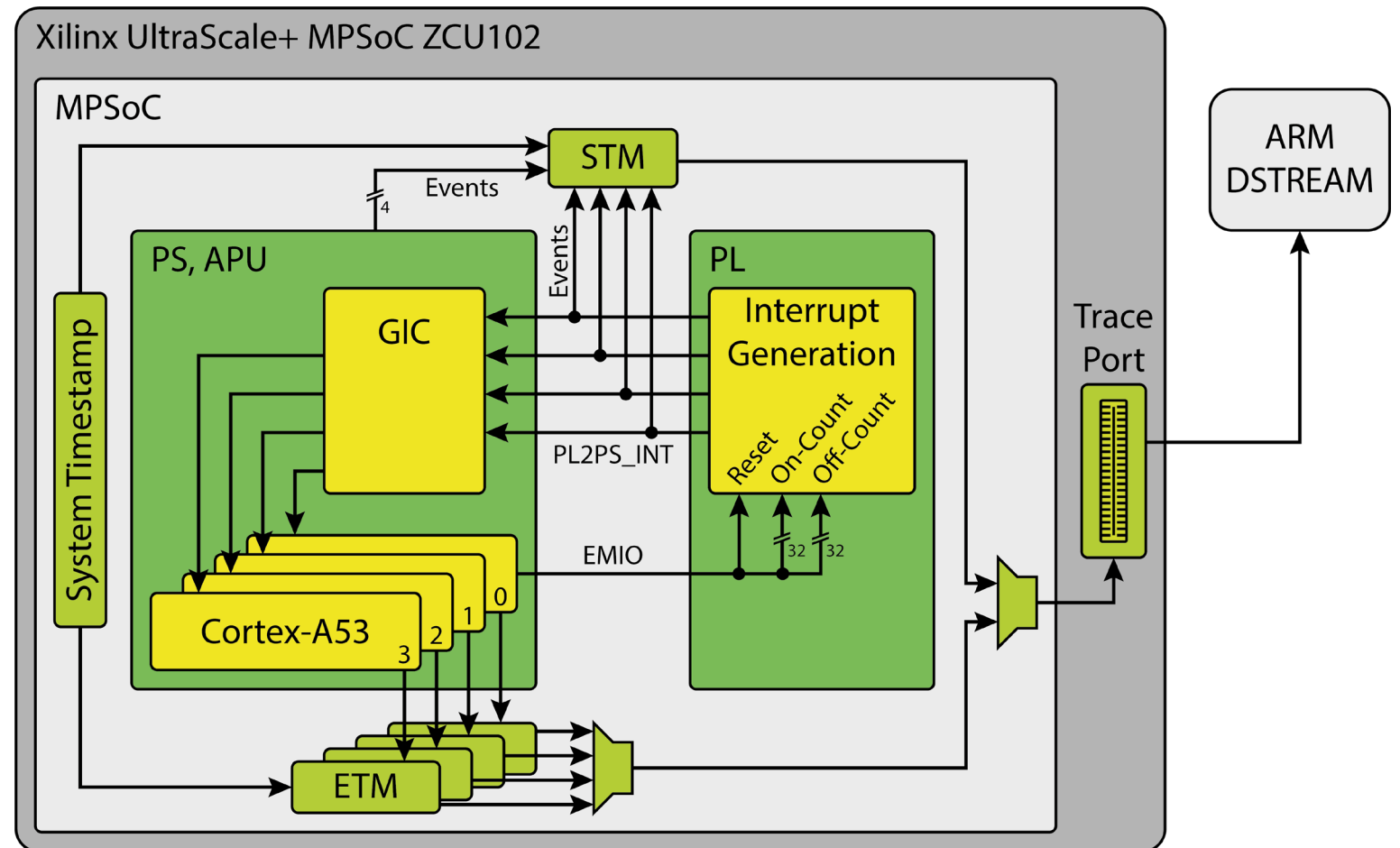
ARMv8-A Interrupt Handling Procedure

- ▶ 4 types of interrupts:
 - Peripheral
 - Software generated
 - Virtual
 - Maintenance
- ▶ 2 processing schemes:
 - Regular (IRQ)
 - Fast (FIQ)
- ▶ We focus on peripheral interrupts, triggered by an external stimuli, processed in the regular way (IRQ)



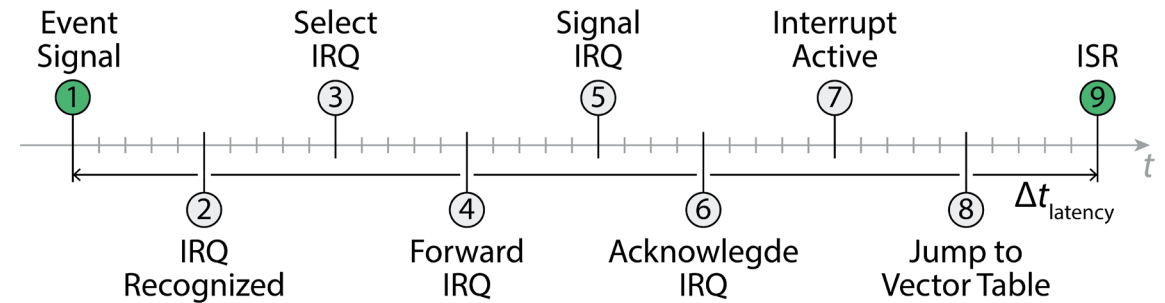
Measurement Setup

- ▶ Xilinx ZCU102 evaluation board with 4x A53-, 2x R5-cores, and an on-chip FPGA
- ▶ ARM DSTREAM hardware trace
- ▶ Verilog based interrupt generation block controlled by the APU
- ▶ ARM CoreSight ETM and STM based measurements provide a common time-line for internal and external events



Measurement Procedure

- ▶ Measurements on 2 platforms
 - Baremetal (unoptimized)
 - FreeRTOS
- ▶ Based on the open-source build- and test platform *toki* with the same low-level interrupt dispatching routine provided by Xilinx
- ▶ Easily extensible to Linux based systems
- ▶ Measurements on APU core 0, stimulation by all cores
- ▶ Designed for and tested on GICv2 but applicable to v3 and v4 as well



- ▶ Latency Measurements
 - 1ms interrupt trigger, 4ms pause
 - 30s trace capture (i.e., 2.400 stimulation phases)
- ▶ Throughput Measurements
 - 9.75s interrupt trigger, 250ms pause
 - 120s trace capture (i.e., 20 stimulation phases)

Precision, Limitations & Benefits

Precision

- ▶ Measurement precision is bounded by the timestamp clock, configured to 250 MHz
 - ⇒ 4ns time resolution
 - ⇒ An order of magnitude below the measured latency
- ▶ Modern oscilloscopes can reach up to 20 GSa/s, i.e., a 0.05ns time resolution, but their measurements are imprecise

Limitations

- ▶ Only applicable to ARM based systems with JTAG- and trace-port
 - ARM IP designs have a 40% market share
 - Wide availability of evaluation boards

Benefits

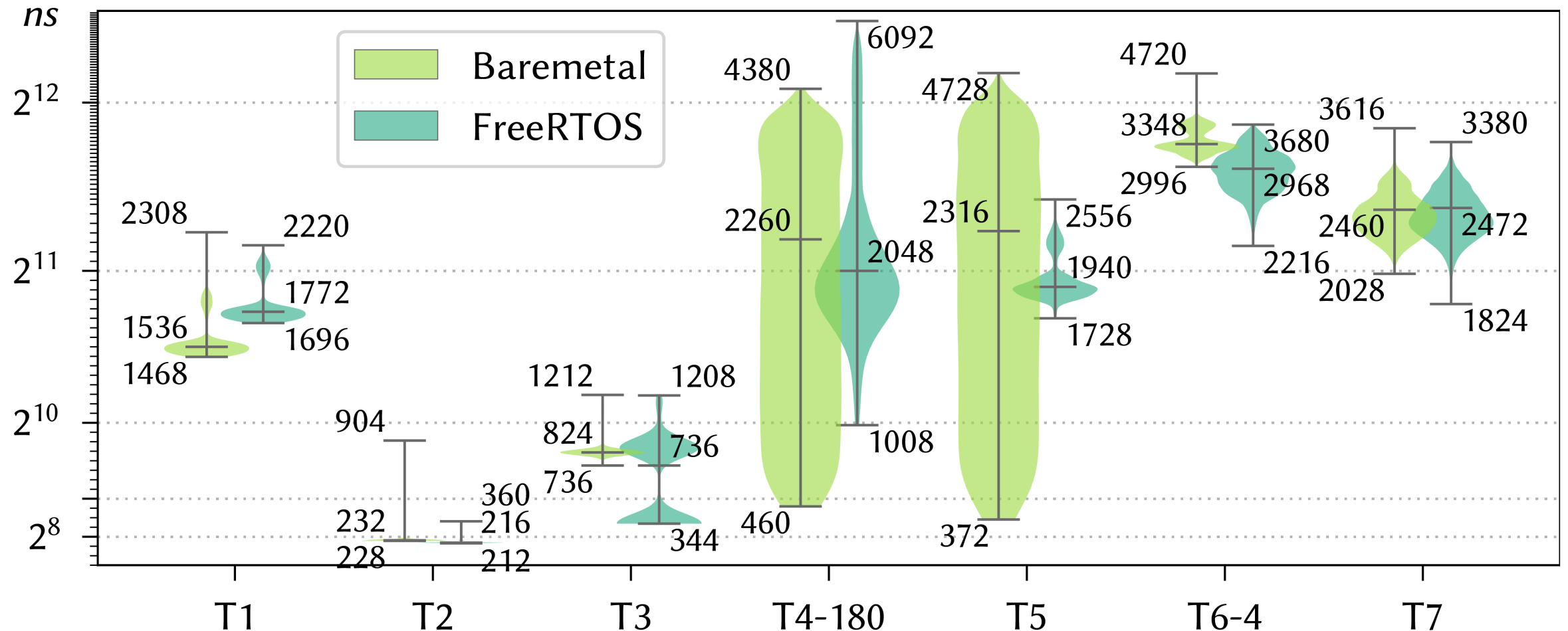
- ▶ No in-depth knowledge about the hardware platform needed
- ▶ Measurement procedure applicable to other software stacks as well

Analyzed Test-cases

Description	Targeted Comp.	Measurements		Enabled Interrupts	Cache Config	Enabled Cores	Benchmarks		
		L	T				L _{min}	L _{max}	T _{max}
T1: Baseline	-	X	X	1	Disabled	1			
T2: Caches Enabled	Cache	X	X	1	Enabled	1	X		X
T3: Caches Invalid.	Cache	X		1	Invalidated	1			
T4: Enabled Int.	GIC	X		2-181	Disabled	2		X	
T5: Order of Prio.	GIC	X		15	Disabled	2			
T6: Parallel Int. Hdl.	GIC	X	X	1	Disabled	2, 3, 4		X	X
T7: Rnd Mem Access	Memory	X		1	Disabled	4			

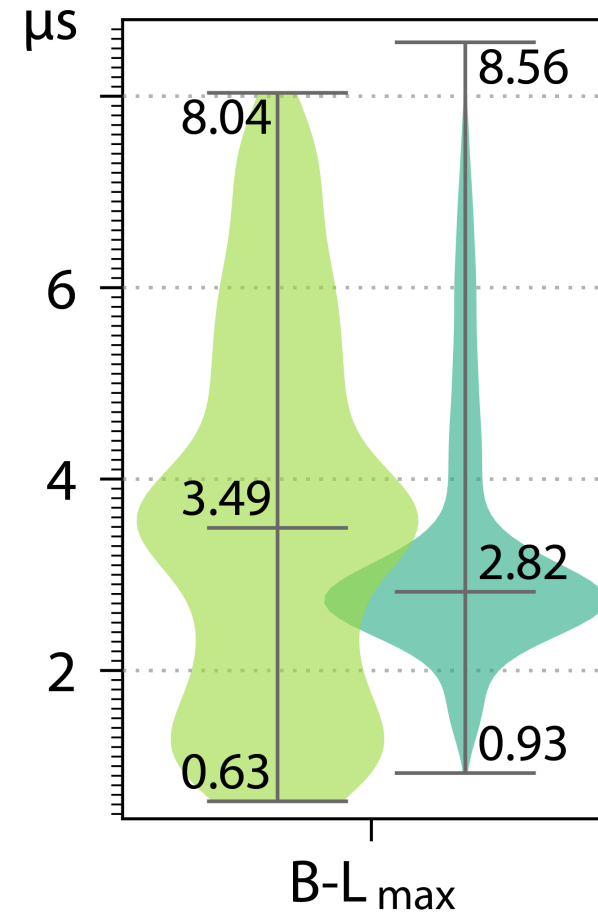
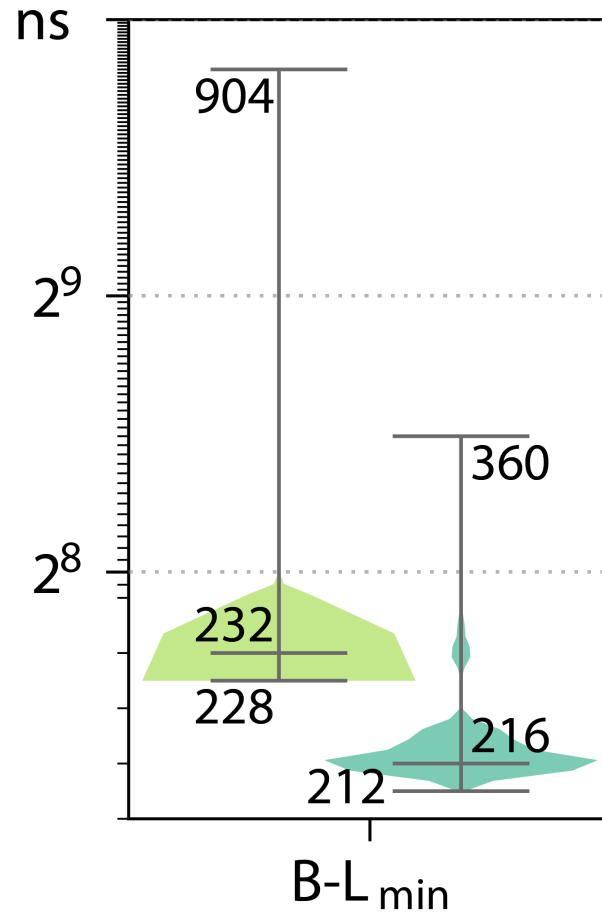
Measurement Results

Latency Measurements (1/2)



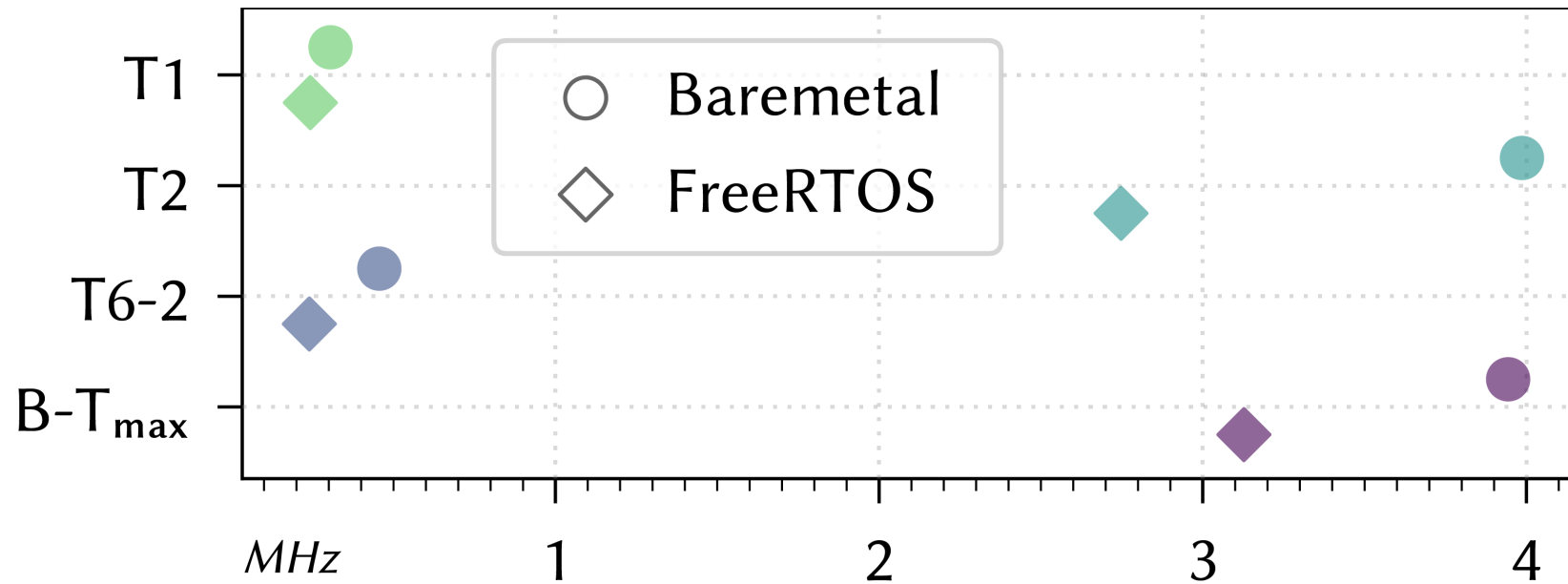
Measurement Results

Latency Measurements (2/2)



Measurement Results

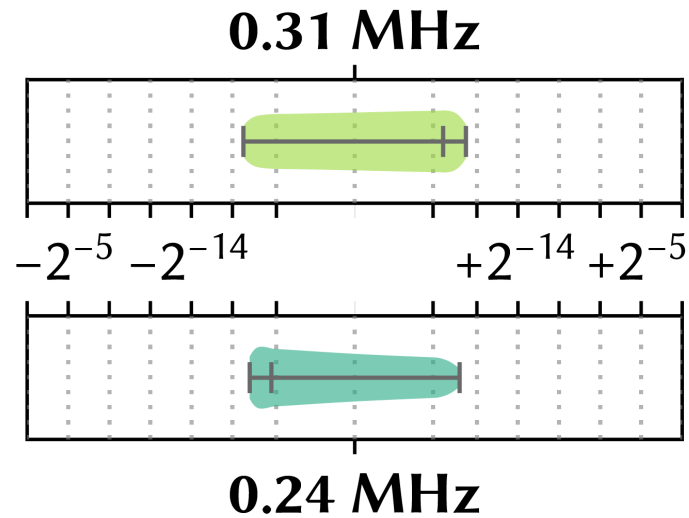
Throughput Measurements (1/3)



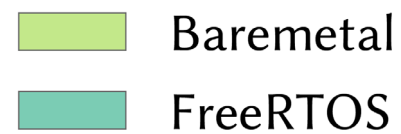
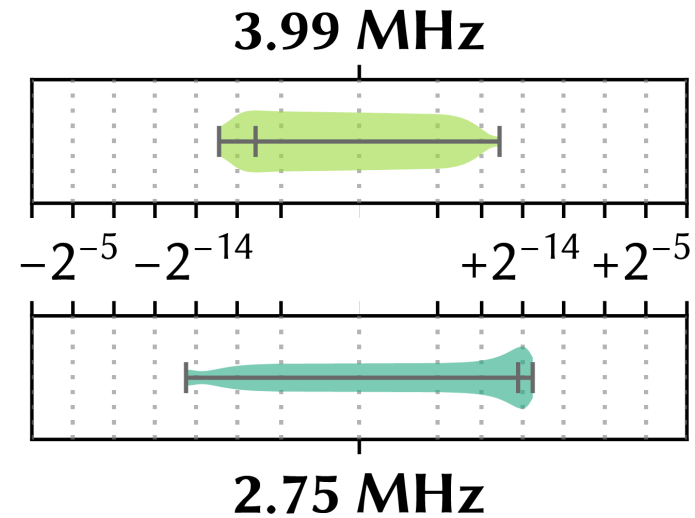
Measurement Results

Throughput Measurements (2/3)

► T1



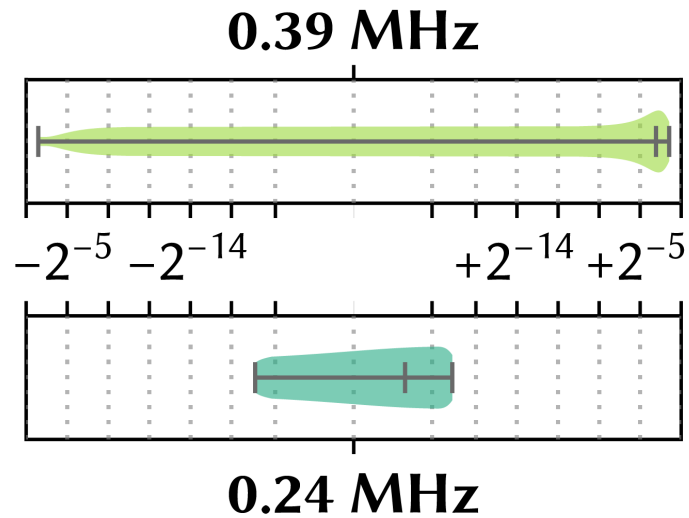
► T2



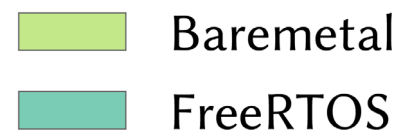
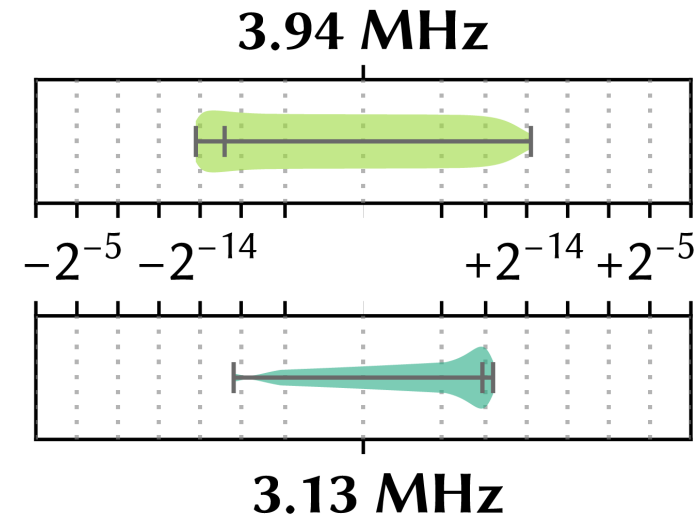
Measurement Results

Throughput Measurement (3/3)

► T6-2



► B-T_{max}



Conclusion & Outlook

- ▶ Precise method to measure the interrupt performance of complex ARM based SoCs without expert knowledge
- ▶ Set of benchmark functions that provoke the best and worst interrupt latency and maximal throughput
- ▶ Evaluation platform and test-cases are available open-source, check it out under <https://git.fortiss.org/toki>
- ▶ Software design can have large effects on the predictability of the interrupt latency and throughput
- ▶ Partially unexpected results require further investigation, we see two options:
 - Implementing a fully optimized, assembly-only bare-metal stack
 - Analyzing the hardware effects with a cycle accurate simulator

Thank you.



Questions?

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