

Context and issues

Objectives

- Accurate modelisation and simulation of seismo-acoustic waves **through heterogeneous domains with complex geometries**
- Treatment of realistic cases of interest
 - **High Performance Computing (HPC)**

Issues

- Difficulty to mesh complex geometries
- High-order precision needed to accurately capture waves
 - **Hybrid discontinuous methods (HDG/HHO)**

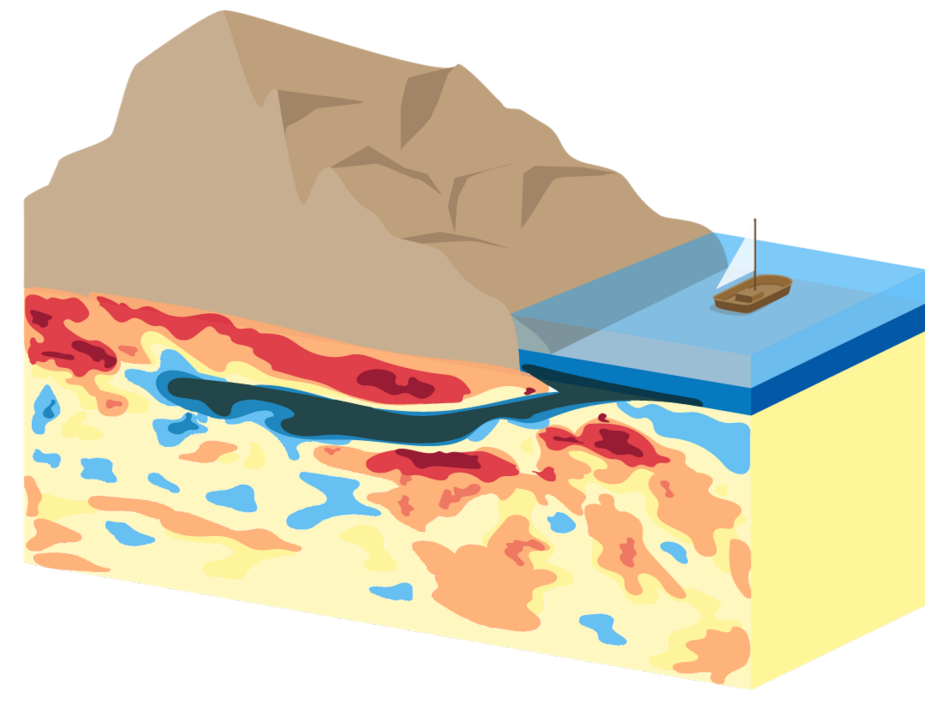


Fig. 1: Lateral heterogeneities near the earth's surface.

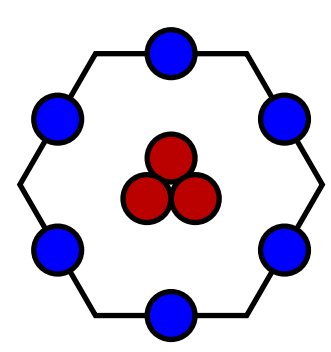
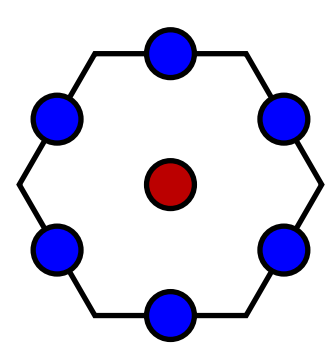
Coupling of the acoustic and elastic wave equations

- **Elastic wave equation:**
$$\begin{cases} \partial_t \varepsilon(t) - \nabla^s v^S(t) = 0 \\ \rho_S \partial_t v^S(t) - \nabla \cdot (\mathcal{C} : \varepsilon(t)) = f(t) \end{cases}$$
- **Acoustic wave equation:**
$$\begin{cases} \frac{1}{\kappa} \partial_t p(t) + \nabla \cdot v^F(t) = g \\ \rho_F \partial_t v^F(t) + \nabla p(t) = 0 \end{cases}$$
- **Coupling condition:**
$$\begin{cases} \llbracket v(t) \cdot n_\Gamma \rrbracket_\Gamma = 0 \\ (\mathcal{C} : \varepsilon(t)) \cdot n_\Gamma = p(t) n_\Gamma \end{cases}$$

The HHO method

Degrees of freedom

- **Principle:** Polynomial unknowns located in the cells and on the faces



HHO unknowns:

$$\hat{u}_h := (u_{\mathcal{T}}, u_{\mathcal{F}})$$

- Cell unknowns of degree k'
- Face unknowns of degree k

Fig. 2: Left panel: Equal-order discretization ($k' = k = 0$).
Right panel: Mixed-order discretization ($k' = k + 1 = 1$).

Operators

- **Gradient reconstruction operator:** $\nabla u \rightarrow G(\hat{u}_h)$
- **Stabilization operator:** $s(\hat{u}_h, \hat{w}_h)$
 - Penalization at the element level to ensure stability while preserving the approximation properties of the reconstruction.

Advantages

- **Mesh flexibility:**
 - Complex geometries
 - Unstructured and polyhedral meshes
 - Local mesh refinement
- **Local conservativity**
- **Optimal error estimates for smooth solutions**
- **Attractive computational costs:**
 - Global problem couples only face dofs
 - Cell dofs recovered by local post-processing

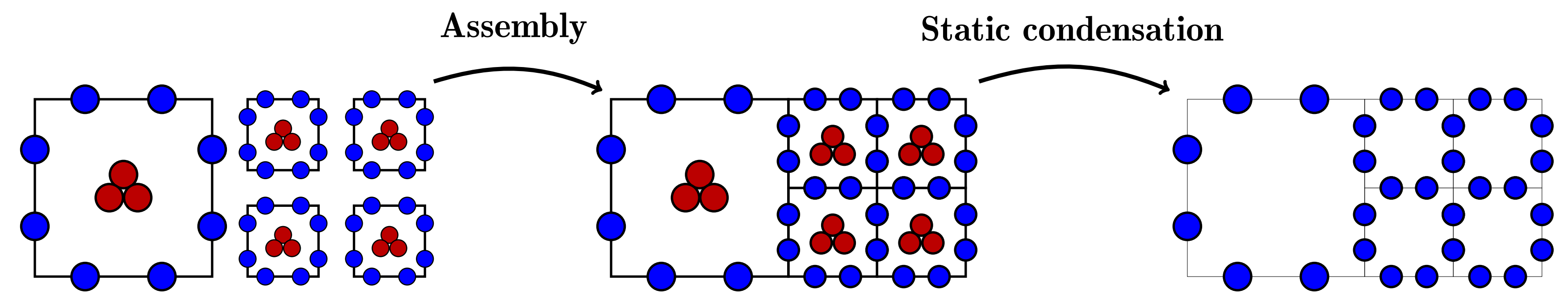


Fig. 3: Static condensation procedure.

HHO space semi-discretization

Approximation spaces:

Fluid domain:

$$\mathbf{V}_{\mathcal{T}_h}^k := \bigotimes_{T \in \mathcal{T}_h^F} \mathbb{P}^k(T; \mathbb{R}^d), \quad \hat{\mathbf{V}}_h^F := \bigotimes_{T \in \mathcal{T}_h^F} \mathbb{P}^{k'}(T; \mathbb{R}) \times \bigotimes_{F \in \mathcal{F}_h^F} \mathbb{P}^k(F; \mathbb{R})$$

Elastic domain:

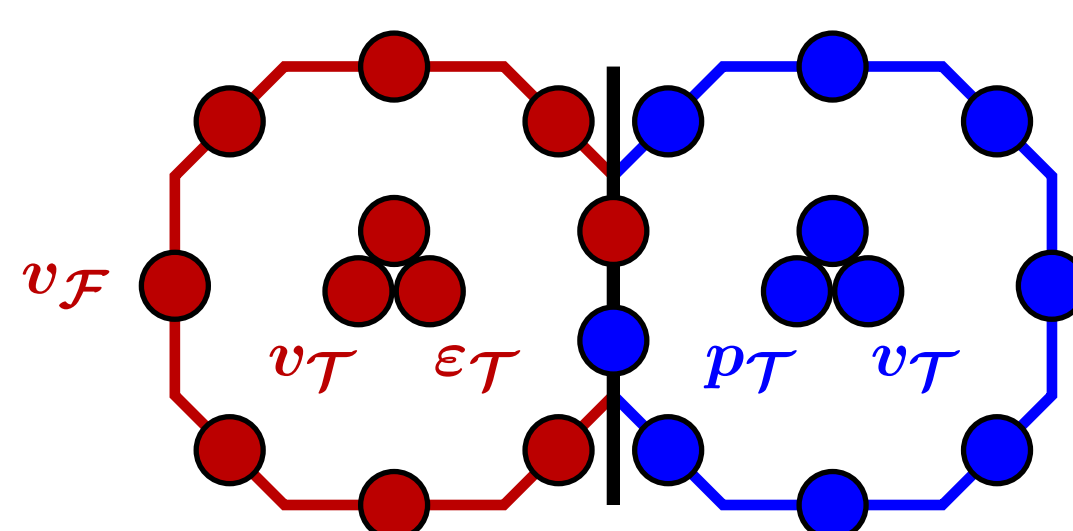
$$\mathbf{Z}_{\mathcal{T}_h}^k := \bigotimes_{T \in \mathcal{T}_h^S} \mathbb{P}^k(T; \mathbb{R}^{d \times d}_{\text{sym}}), \quad \hat{\mathbf{V}}_h^S := \bigotimes_{T \in \mathcal{T}_h^S} \mathbb{P}^{k'}(T; \mathbb{R}^d) \times \bigotimes_{F \in \mathcal{F}_h^S} \mathbb{P}^k(F; \mathbb{R}^d)$$

Elasto-acoustic coupling:

$$\begin{cases} (\partial_t v_{\mathcal{T}}^F(t), r_{\mathcal{T}})_{L^2(\rho_F; \Omega_F)} + (G_{\mathcal{T}}(\hat{p}_h(t)), r_{\mathcal{T}})_{L^2(\Omega_F)} = 0 \\ (\partial_t p_{\mathcal{T}}(t), q_{\mathcal{T}})_{L^2(\frac{1}{\kappa}; \Omega_F)} - (v_{\mathcal{T}}^F(t), G_{\mathcal{T}}(\hat{q}_h))_{L^2(\Omega_F)} + s_h^F(\hat{p}_h(t), \hat{q}_h) - (v_{\mathcal{F}}^S(t) \cdot n_\Gamma, q_{\mathcal{F}})_{L^2(\Gamma)} = (g(t), q_{\mathcal{T}})_{L^2(\Omega_F)} \\ (\partial_t \varepsilon_{\mathcal{T}}(t), z_{\mathcal{T}})_{L^2(\Omega_S)} - (E_{\mathcal{T}}(\hat{v}_h(t)), z_{\mathcal{T}})_{L^2(\Omega_S)} = 0 \\ (\partial_t v_{\mathcal{T}}(t), w_{\mathcal{T}})_{L^2(\rho; \Omega_S)} + (\varepsilon_{\mathcal{T}}, E_{\mathcal{T}}(\hat{w}_h))_{L^2(\mathcal{C}; \Omega_S)} + s_h^S(\hat{v}_h^S(t), \hat{w}_h) + (p_{\mathcal{F}}(t), w_{\mathcal{F}} \cdot n_\Gamma)_{L^2(\Gamma)} = (f(t), w_{\mathcal{T}})_{L^2(\Omega_S)} \end{cases}$$

Algebraic realization:

$$\begin{bmatrix} M_{\mathcal{T}\mathcal{T}}^V & 0 & 0 & 0 & 0 & 0 \\ 0 & M_{\mathcal{T}\mathcal{T}}^F & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & M_{\mathcal{T}\mathcal{T}}^E & 0 & 0 \\ 0 & 0 & 0 & 0 & M_{\mathcal{T}\mathcal{T}}^S & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \partial_t V_{\mathcal{T}}^F \\ \partial_t P_{\mathcal{T}} \\ \partial_t P_{\mathcal{F}} \\ \partial_t S_{\mathcal{T}} \\ \partial_t V_{\mathcal{T}} \\ \partial_t V_{\mathcal{F}} \end{bmatrix} + \begin{bmatrix} 0 & -G_{\mathcal{T}} & -G_{\mathcal{F}} & 0 & 0 & 0 \\ G_{\mathcal{T}}^\dagger \Sigma_{\mathcal{T}\mathcal{T}}^F & \Sigma_{\mathcal{T}\mathcal{T}}^F & \Sigma_{\mathcal{T}\mathcal{F}}^F & 0 & 0 & 0 \\ G_{\mathcal{F}}^\dagger \Sigma_{\mathcal{F}\mathcal{T}}^F & \Sigma_{\mathcal{F}\mathcal{T}}^F & \Sigma_{\mathcal{F}\mathcal{F}}^F & 0 & 0 & C_\Gamma \\ 0 & 0 & 0 & 0 & -E_{\mathcal{T}} & -E_{\mathcal{F}} \\ 0 & 0 & 0 & E_{\mathcal{T}}^\dagger \Sigma_{\mathcal{T}\mathcal{T}}^S & \Sigma_{\mathcal{T}\mathcal{T}}^S & \Sigma_{\mathcal{T}\mathcal{F}}^S \\ 0 & 0 & -C_\Gamma^\dagger & E_{\mathcal{F}}^\dagger \Sigma_{\mathcal{F}\mathcal{T}}^S & \Sigma_{\mathcal{F}\mathcal{T}}^S & \Sigma_{\mathcal{F}\mathcal{F}}^S \end{bmatrix} \begin{bmatrix} V_{\mathcal{T}}^F \\ P_{\mathcal{T}} \\ P_{\mathcal{F}} \\ S_{\mathcal{T}} \\ V_{\mathcal{T}}^S \\ V_{\mathcal{F}}^S \end{bmatrix} = \begin{bmatrix} 0 \\ G_{\mathcal{T}} \\ 0 \\ 0 \\ F_{\mathcal{T}} \\ 0 \end{bmatrix}$$



- Elastic unknowns
- Elasto-acoustic interface Γ
- Acoustic unknowns

Fig. 4: Elasto-acoustic unknowns with a mixed-order ($k' = k + 1 = 1$) discretization.

Numerical results

Verification of convergence rates on analytical solutions:

- $\mathcal{O}(h^{k+1})$ in H^1 -norm
- $\mathcal{O}(h^{k+2})$ in L^2 -norm (superconvergence)

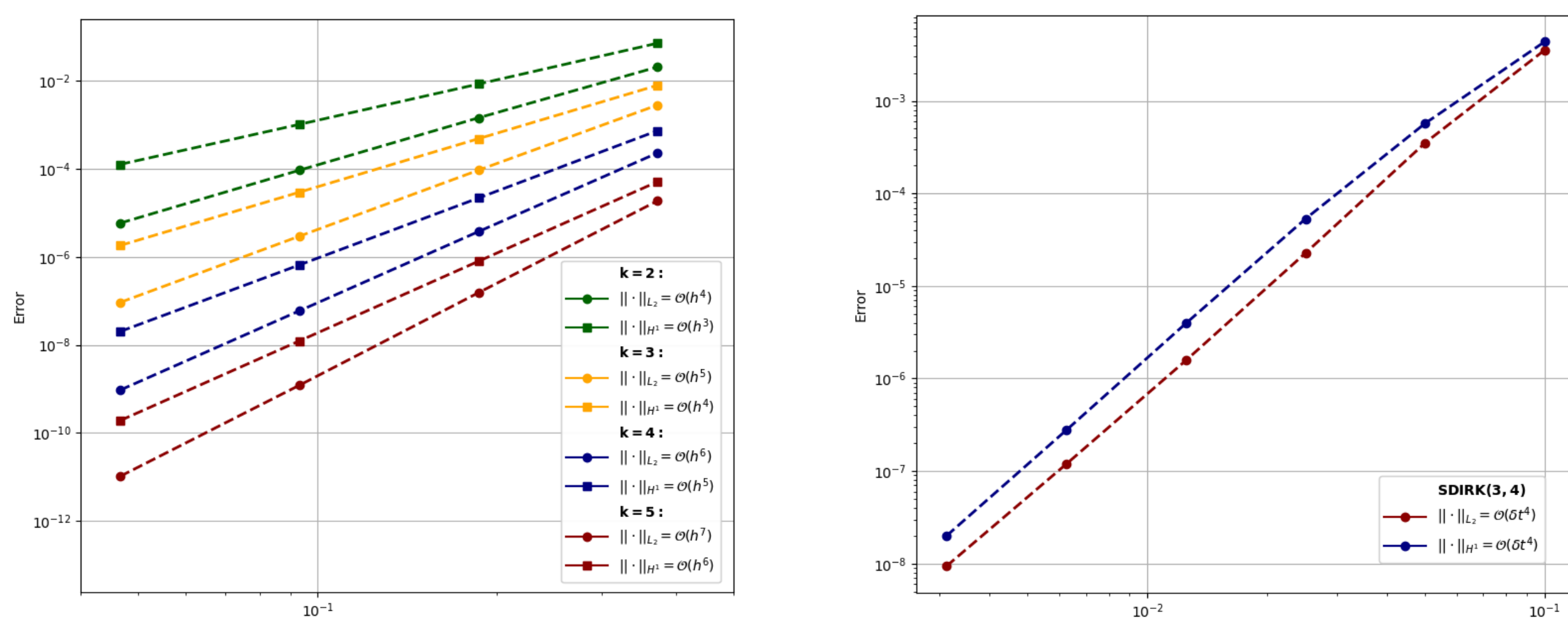


Fig. 5: Left panel: Errors as a function of the mesh size with $\Delta t = 0.1 \times 10^{-5}$. Right panel: Errors as a function of the time-step with $k' = k + 1 = 6$ and $dx = 2^{-5}$.

Realistic test case

- **Computational domain:**
 - Acoustic region on the upper side
 - Elastic region on the lower side
- **Homogeneous Dirichlet conditions**
- **Initial condition:** pressure Ricker wavelet

$$p_0(x, y) := -\frac{4}{10} \sqrt{\frac{10}{3}} (1600r^2 - 1) \pi^{-1/4} e^{-800r^2}$$

$$v_0^F := 0, \quad v_0^S := 0, \quad \varepsilon_0 := 0.$$
- **Time integration scheme:** SDIRK(s,s+1)

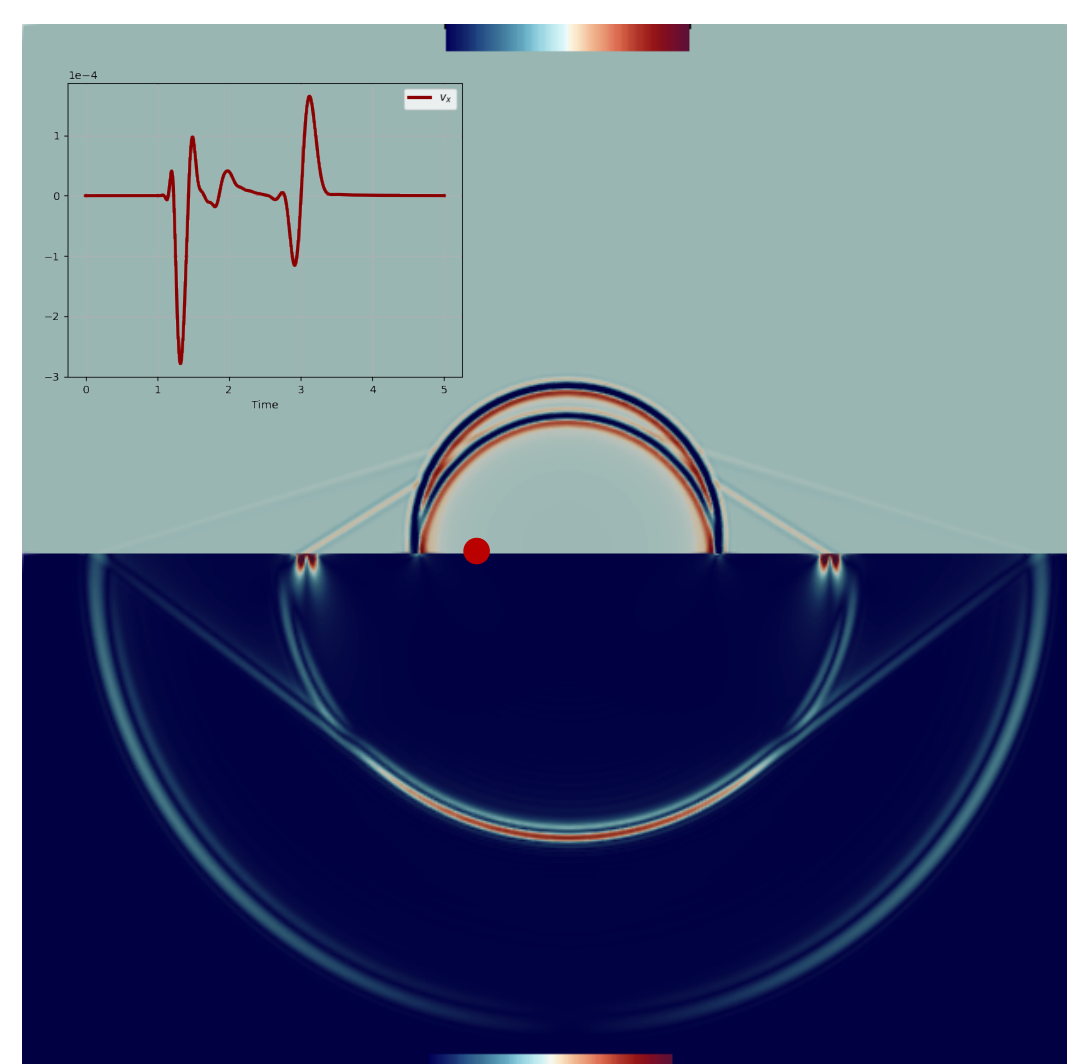


Fig. 6: Two-dimensional distribution of the acoustic pressure (upper side) and elastic velocity norm (lower side), predicted by the HHO-SDIRK(3,4) at $t = 5$ s. Simulation parameters: $k' = k + 1 = 2$, $dx = 2^{-8}$ and $\Delta t = 0.1 \times 2^{-8}$.

Energy conservation of the scheme

Mechanical energy of the scheme: $\mathcal{E}_h(t) := \mathcal{E}_h^S(t) + \mathcal{E}_h^F(t)$ with

$$\mathcal{E}_h^F(t) := \frac{1}{2} \|v_{\mathcal{T}}^F(t)\|_{L^2(\rho_F; \Omega_F)}^2 + \frac{1}{2} \|p_{\mathcal{T}}(t)\|_{L^2(\frac{1}{\kappa}; \Omega_F)}^2, \quad \mathcal{E}_h^S(t) := \frac{1}{2} \|v_{\mathcal{T}}^S(t)\|_{L^2(\rho_S; \Omega_S)}^2 + \frac{1}{2} \|\varepsilon_{\mathcal{T}}(t)\|_{L^2(\mathcal{C}; \Omega_S)}^2$$

Semi-discrete energy conservation of the scheme

$$\mathcal{E}_h(t) = \mathcal{E}_h(0) + \int_0^t \left[(f(\alpha), v_{\mathcal{T}}^S(\alpha))_{L^2(\Omega_S)} + (g(\alpha), p_{\mathcal{T}}(\alpha))_{L^2(\Omega_F)} - s_h^S(\hat{v}_h^S(\alpha), \hat{v}_h^S(\alpha)) - s_h^F(\hat{p}_h(\alpha), \hat{p}_h(\alpha)) \right] d\alpha$$

Validation on analytic test cases

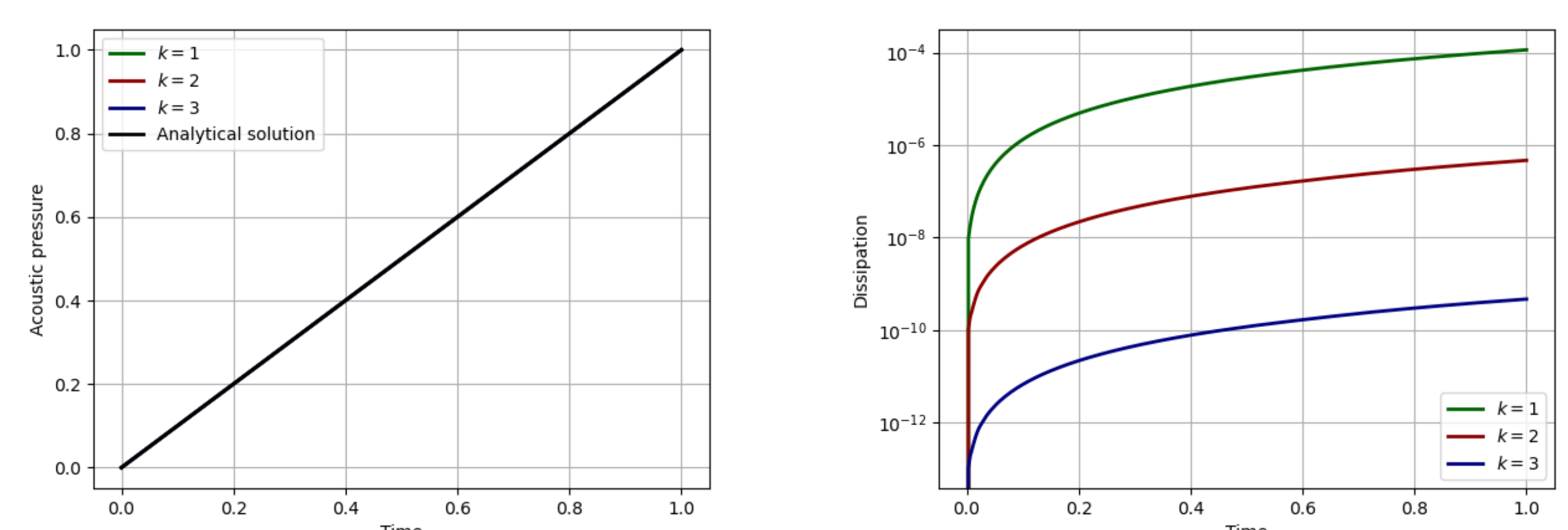


Fig. 7: Demonstration of the negligible nature of the energy dissipation introduced by the HHO scheme.

Some references

- [1] Di Pietro and Ern. "A hybrid high-order locking-free method for linear elasticity on general meshes". In: *Comput. Meth. Appl. Mech. Engrg.* 283 (2015), pp. 1–21.
- [2] Burman, Duran, and Ern. "Hybrid high-order methods for the acoustic wave equation in the time domain". In: *Comm. App. Math. Comp. Sci.* 4.2 (2022), pp. 597–633.
- [3] Burman, Duran, Ern, and Steins. "Convergence Analysis of Hybrid High-Order Methods for the Wave Equation". In: *J. Sci. Comput.* 87.3 (2021), p. 91.
- [4] Terrana, Vilotte, and Guillot. "A spectral hybridizable discontinuous Galerkin method for elastic-acoustic wave propagation". In: *Geophys. J. Int.* 213.1 (2017), pp. 574–602.