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## From Point Forecasts to Distributional Forecasts

- A forecast  $\hat{y}_{T+h|T}$  is (usually) the mean of the conditional distribution:  $Y_{T+h}|Y_1, \dots Y_T$
- Most models produces Gaussian distributed forecast
- Because models assumes Gaussian residuals: remember that the residuals are the stochastic components that are determining the distribution of both the estimators and the forecasts
- The forecast distribution describes the probability to forecast any future value

# Distributional Forecasts

Assuming the **residuals are uncorrelated** with variance  $\hat{\sigma}^2$ , and with an estimate  $\hat{\sigma}^2$ 

# Model Typology

- Mean:  $Y_{T+h|T} = \mathcal{N}(\overline{Y}, (1 + \frac{1}{T})\hat{\sigma^2})$
- Naive:  $Y_{T+h|T} = \mathcal{N}(Y_T, h\hat{\sigma^2})$
- Seasonal Naive:  $Y_{T+h|T} = \mathcal{N}(Y_{T+h-m(k+1)}, (k+1)\hat{\sigma^2})$
- Drift:  $Y_{T+h|T} = \mathcal{N}(Y_T + \frac{h}{T-1}(Y_T Y_1), h\frac{T+h}{T}\hat{\sigma^2})$
- where k is the integer part of  $\frac{h-1}{m}$
- Note that when h=1 and T is large, these all give the same approximate variance  $\hat{\sigma^2}$

# Prediction Intervals

#### Definition

A prediction interval gives a **region** within which we expect  $Y_{T+h}$  to lie with a **specified probability** 

• Assuming that the forecasting errors are normally distributed, then a 95% prediction interval is:

$$Y_{T+h|T} \pm 1.96\hat{\sigma_h}$$

- where  $\hat{\sigma}_h$  is the standard deviation of the h-step distribution
- when h = 1,  $\hat{\sigma}_h$  can be estimated from the residuals

## Prediction Interval Fit

```
brick_fc %>% hilo(level = 95)
    A tsibble: 80 x 5 [10]
##
  # Kev:
               .model [4]
##
      .model
                    Quarter Bricks .mean
                                                      95%
     <chr>>
                               <dist> <dbl>
                                                     <hilo>
##
                      <atr>
   1 Seasonal naive 2005 Q3 N(428, 2336) 428 [333, 523]95
##
   2 Seasonal_naive 2005 Q4 N(397, 2336) 397 [302, 492]95
##
   3 Seasonal naive 2006 01 N(355, 2336) 355 [260, 450]95
##
##
   4 Seasonal naive 2006 02 N(435, 2336)
                                           435 [340, 530]95
   5 Seasonal_naive 2006 Q3 N(428, 4672)
                                           428 [294, 562]95
##
##
   6 Seasonal_naive 2006 Q4 N(397, 4672)
                                           397 [263, 531]95
##
   7 Seasonal naive 2007 01 N(355, 4672)
                                           355 [221, 489]95
##
   8 Seasonal naive 2007 Q2 N(435, 4672)
                                           435 [301, 569]95
   9 Seasonal_naive 2007 Q3 N(428, 7008)
                                           428 [264, 592]95
##
```

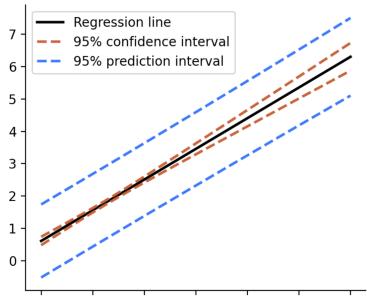
# Why Prediction Intervals Matter

- Point forecasts are often useless without a measure of uncertainty (such as prediction intervals)
- Prediction intervals require a **stochastic model** (with random errors, etc.)
- For most models, prediction intervals get wider as the forecast horizon increases
- The degree of confidence (the probability) impacts the width of the prediction interval
- Usually too narrow due to unaccounted uncertainty: pay attention

# Difference between Confidence Interval and Prediction Interval

- A confidence interval informs about where the true parameter of a model can be
  - Confidence interval quantifies the uncertainty about the model, or the distance between the model and reality
  - Confidence interval are associated with a wide range of parameters, values, etc.
  - They inform about how the model represents well the reality
  - Wide confidence intervals are associated with a less accurate model, and/or a very volatile model
- The prediction interval predicts in what range a future individual observation will fall
  - Prediction interval quantifies the uncertainty about the future, or the distance between today and the future
  - Prediction interval are not about the parameters of the model, but about the dependent variable  $(y_t)$
  - The problem is that prediction intervals tend to neglect the uncertainty about the parameters used to generate the forecasts...

# Difference between Confidence Interval and Prediction Interval



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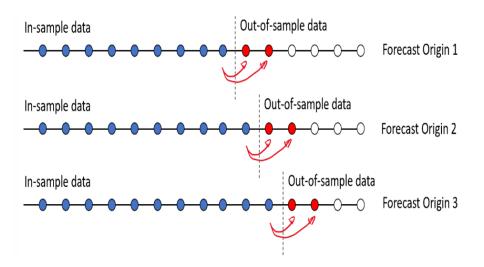
# Fitting and Forecasting

#### Be careful

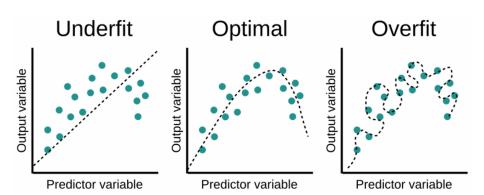
A model that fits the data well (in sample) might not necessarily forecast well

- A perfect in-sample fit can always be obtained by using a model with with enough parameters
- Over-fitting a model to data is just as bad as failing to identify a systematic pattern in the data
- Need to split the model between
- The test set must no be used to *any* aspect of model development or calculation of forecasts
- Forecast accuracy is only based on the test set

### Train and Test Set



# Underfit, Optimal, Overfit



# Forecast Errors

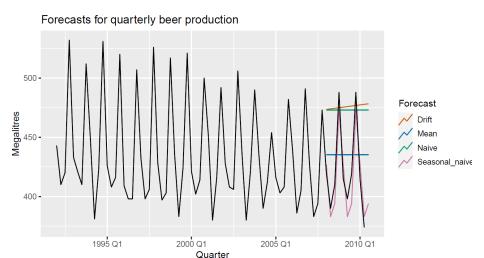
#### Definition: Forecast Errors

A forecast error is the difference between an observed value and its forecast

$$e_{T+h} = y_{T+h} - \hat{y}_{T+h} | Y_T, \dots, Y_1$$

- The conditional set  $Y_T, \ldots, Y_1$  should only be taken from the training dataset
- The true value  $y_{T+h}$  is taken from the test set
- Unlike residuals, forecast errors on the test involve multi-step forecasts
- These are the **true** forecast error, as the test data is not used to compute  $\hat{y}_{T+h}$

# Example: Forecasting Beer Production



# Measures of Forecast Accuracy

#### Main Metrics

- MAE: mean absolute errors  $\frac{1}{S} \sum_{s \in S} |e_{s,T+h}|$
- MSE: mean squared errors  $\frac{1}{S} \sum_{s \in S} (e_{s,T+h})^2$
- MAPE: mean absolute percentage errors  $\frac{1}{S}100 * \sum_{s \in S} \frac{|e_{s,T+h}|}{|y_{s,t+h}|}$
- RMSE: root mean squared errors:  $\sqrt{\frac{1}{S}\sum_{s\in S}(e_{s,T+h})^2}$

#### With:

- $y_{T+h}$ : T+h observation, h being the horizon (h = 1, 2, ..., H)
- $\hat{y}_{T+h|T}$ : the forecast based on data up to time T
- $e_{T+h} = y_{T+h} \hat{y}_{T+h|T}$ : The forecast errors
- $\bullet$  S is the testing sample

#### Note:

• MAE, MSE and RMSE are all scale dependent

