## From Toeplitz to Cauchy matrices

Let 
$$Z = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & \ddots & \ddots & 0 \\ 0 & \ddots & \ddots & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$
 be the displacement matrix that acts as

$$ZA = A\downarrow$$
,  $Z^tA = A\uparrow$ ,  $AZ = A \leftarrow$ ,  $AZ^t = A \rightarrow$ .

Toeplitz and Cauchy matrices are introduced in the paper. To fix the notations, denote  $V_u$ ,  $\bar{V}_u$ ,  $W_u$  and  $\bar{W}_u$  be the following "Vandermonde" matrices

$$\begin{aligned} \mathbf{V}_{\mathbf{u}} = & \begin{pmatrix} 1 & u_1 & \cdots & u_1^{n-1} \\ \vdots & \vdots & & \vdots \\ 1 & u_n & \cdots & u_n^{n-1} \end{pmatrix} , & & & \bar{\mathbf{V}}_{\mathbf{u}} = & \begin{pmatrix} u_1^{n-1} & \cdots & u_1 & 1 \\ \vdots & & \vdots & \vdots \\ u_n^{n-1} & \cdots & u_n & 1 \end{pmatrix} , \\ \mathbf{W}_{\mathbf{u}} = & \begin{pmatrix} u_1^{n-1} & \cdots & u_n^{n-1} \\ \vdots & & \vdots \\ u_1 & \cdots & u_n \\ 1 & \cdots & 1 \end{pmatrix} , & & \bar{\mathbf{W}}_{\mathbf{u}} = & \begin{pmatrix} 1 & \cdots & 1 \\ u_1 & \cdots & u_n \\ \vdots & & \vdots \\ u_1^{n-1} & \cdots & u_n^{n-1} \end{pmatrix} . \end{aligned}$$

I keep the paper notations for  $V_u$ ,  $W_u$  and introduce  $\bar{V}_u$ ,  $\bar{W}_u$  which are the correct matrices in my opinion (see below).

We have the following relations

$$\begin{array}{lll} \mathsf{D}_{\mathsf{u}}\,\mathsf{V}_{\mathsf{u}} \; = \; \mathsf{V}_{\mathsf{u}}\,\mathsf{Z} + \left( \begin{array}{ccc} 0 \; \cdots \; 0 \; u_{1}^{n} \\ \vdots & \vdots \; \vdots \\ 0 \; \cdots \; 0 \; u_{n}^{n} \end{array} \right) \\ \mathsf{D}_{\mathsf{u}}\,\bar{\mathsf{V}}_{\mathsf{u}} \; = \; \bar{\mathsf{V}}_{\mathsf{u}}\,\mathsf{Z}^{t} + \left( \begin{array}{ccc} u_{1}^{n} \; 0 \; \cdots \; 0 \\ \vdots \; \vdots \; & \vdots \\ u_{n}^{n} \; 0 \; \cdots \; 0 \end{array} \right) \\ \mathsf{W}_{\mathsf{u}}\,\mathsf{D}_{\mathsf{u}} \; = \; \mathsf{Z}\,\mathsf{W}_{\mathsf{u}} + \left( \begin{array}{ccc} u_{1}^{n} \; \cdots \; u_{n}^{n} \\ 0 \; \cdots \; 0 \\ \vdots & \vdots \\ 0 \; \cdots \; 0 \end{array} \right) \\ \bar{\mathsf{W}}_{\mathsf{u}}\,\mathsf{D}_{\mathsf{u}} \; = \; \mathsf{Z}^{t}\,\bar{\mathsf{W}}_{\mathsf{u}} + \left( \begin{array}{ccc} 0 \; \cdots \; 0 \\ \vdots \; & \vdots \\ 0 \; \cdots \; 0 \\ u_{1}^{n} \; \cdots \; u_{n}^{n} \end{array} \right) \end{array}$$

If  $A' = \bar{V}_u A \bar{W}_v$  then

$$\begin{split} \nabla_{\mathbf{u},\mathbf{v}}(\mathsf{A}') &= & \mathsf{D}_{\mathbf{u}}\,\bar{\mathsf{V}}_{\mathbf{u}}\,\mathsf{A}\,\bar{\mathsf{W}}_{\mathbf{v}} - \bar{\mathsf{V}}_{\mathbf{u}}\,\mathsf{A}\,\bar{\mathsf{W}}_{\mathbf{v}}\,\mathsf{D}_{\mathbf{v}} \\ &= & \bar{\mathsf{V}}_{\mathbf{u}}\,(\mathsf{Z}^t\,\mathsf{A} - \mathsf{A}\,\mathsf{Z}^t)\,\bar{\mathsf{W}}_{\mathbf{v}} + \left( \begin{array}{ccc} u_1^n & 0 & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ u_n^n & 0 & \cdots & 0 \end{array} \right) \mathsf{A}\,\bar{\mathsf{W}}_{\mathbf{v}} - \bar{\mathsf{V}}_{\mathbf{u}}\,\mathsf{A} \left( \begin{array}{ccc} 0 & \cdots & 0 \\ \vdots & & \vdots \\ 0 & \cdots & 0 \\ v_1^n & \cdots & v_n^n \end{array} \right). \end{split}$$

Or we can express it using the more common  $(A - ZAZ^t)$  displacement operator using

$$\bar{V}_{u} = D_{u} \bar{V}_{u} Z + \begin{pmatrix} 0 & \cdots & 0 & 1 \\ \vdots & & \vdots & \vdots \\ 0 & \cdots & 0 & 1 \end{pmatrix}$$

to get

$$\begin{split} \nabla_{u,v}(A') &= D_u \bar{V}_u \, A \, \bar{W}_v - \bar{V}_u \, A \, \bar{W}_v \, D_v \\ &= D_u \bar{V}_u \, A \, \bar{W}_v - \left[ D_u \bar{V}_u \, Z + \begin{pmatrix} 0 & \cdots & 0 & 1 \\ \vdots & \vdots & \vdots & \vdots \\ 0 & \cdots & 0 & 1 \end{pmatrix} \right] A \, \bar{W}_v \, D_v \\ &= D_u \bar{V}_u \, A \, \bar{W}_v - D_u \bar{V}_u \, Z \, A \, \bar{W}_v \, D_v - \begin{pmatrix} 0 & \cdots & 0 & 1 \\ \vdots & & \vdots & \vdots \\ 0 & \cdots & 0 & 1 \end{pmatrix} A \, \bar{W}_v \, D_v \\ &= D_u \bar{V}_u \, A \, \bar{W}_v - D_u \bar{V}_u \, Z \, A \left[ Z^t \, \bar{W}_v + \begin{pmatrix} 0 & \cdots & 0 \\ \vdots & & \vdots \\ 0 & \cdots & 0 \\ v_1^n & \cdots & v_n^n \end{pmatrix} \right] - \begin{pmatrix} 0 & \cdots & 0 & 1 \\ \vdots & & \vdots & \vdots \\ 0 & \cdots & 0 & 1 \end{pmatrix} A \, \bar{W}_v \, D_v \\ &= D_u \bar{V}_u \, (A - Z \, A \, Z^t) \, \bar{W}_v - D_u \bar{V}_u \, Z \, A \begin{pmatrix} 0 & \cdots & 0 \\ \vdots & & \vdots \\ 0 & \cdots & 0 \\ v_1^n & \cdots & v_n^n \end{pmatrix} - \begin{pmatrix} 0 & \cdots & 0 & 1 \\ \vdots & & \vdots & \vdots \\ 0 & \cdots & 0 & 1 \end{pmatrix} A \, \bar{W}_v \, D_v. \end{split}$$

## Old stuff

Displacement operators :

1. Toeplitz:

$$\phi^+$$
:  $A \mapsto A - Z A Z^t = A - (A \text{ shifted down and right by one place})$   
 $\phi$ :  $A \mapsto Z^t A - A Z^t = (A \text{ shifted up by one place}) - (A \text{ shifted right by one place})$ 

2. Cauchy:

$$\nabla_{\mathsf{u},\mathsf{v}}:\mathsf{A}\mapsto\mathsf{D}_\mathsf{u}\,\mathsf{A}-\mathsf{A}\,\mathsf{D}_\mathsf{v}$$

3. Vandermonde:

$$\varphi_{\mathbf{u}}^{+} : \mathbf{A} \mapsto \mathbf{D}_{\mathbf{u}} \mathbf{A} - \mathbf{A} \mathbf{Z}^{t}$$

$$\varphi_{\mathbf{u}} : \mathbf{A} \mapsto \mathbf{Z}^{t} \mathbf{A} - \mathbf{A} \mathbf{D}_{\mathbf{u}}$$