



# DD2437 – Artificial Neural Networks and Deep Architectures (annda)

## Lecture 5: **Radial basis function NN and introduction to competitive learning**

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- Interpolation problem and RBFs
- RBF networks – hybrid learning
- Weight interpretation in the input space
- Competitive mechanisms for unsupervised learning

## Lecture overview

- Interpolation problem and radial-basis functions (RBFs)
- RBF networks – hybrid learning
- Weight interpretation
- Competitive mechanisms for unsupervised learning

- **Interpolation problem and RBFs**
- RBF networks – hybrid learning
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# The separability of patterns

## *Cover's theorem*

*“A complex pattern classification problem, projected nonlinearly to a high-dimensional space, is more likely to be linearly separable than in low dimensional space, especially if it is not populated too densely.”*

Cover, 1965

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# The separability of patterns

## *Cover's theorem*

*“A complex pattern classification problem, projected nonlinearly to a high-dimensional space, is more likely to be linearly separable than in low dimensional space, especially if it is not populated too densely.”*

Cover, 1965

So, we need to have:

- 1) Many nonlinear mappings  $\varphi_i(\mathbf{x} \in \mathbb{R}^M): \mathbb{R}^M \rightarrow \mathbb{R}^1$ , where  $i = 1, \dots, N$  (large)
- 2) Linear function for separability in high  $N$ -dimensional space

- **Interpolation problem and RBFs**
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# The radial-basis-function (RBF) technique

Nonlinear mapping with the use of *radial-basis-functions* (RBFs):

$$\varphi_i \left( \left\| \mathbf{x} - \mathbf{x}_i \right\| \right)$$

$\mathbf{x}_i$  – RBF centre

$\|\cdot\|$  – vector norm, often Euclidean

$\varphi_i(r)$  – kernel function, often Gaussian

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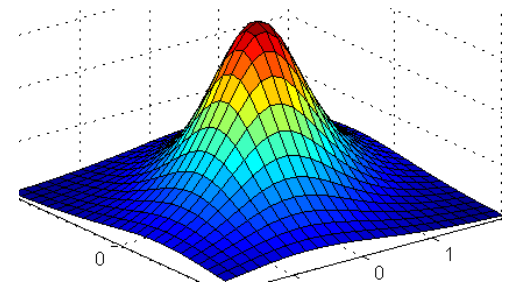
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$$\varphi_i \left( r = \left\| \mathbf{x} - \mathbf{x}_i \right\| \right) = \exp \left( -\frac{r^2}{2\sigma^2} \right)$$



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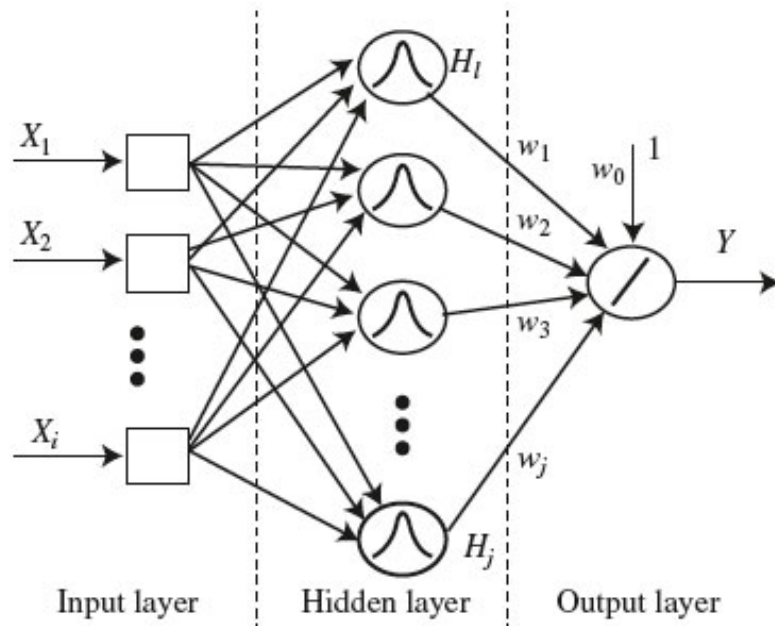
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Linear operation in  $N$ -dimensional space:

$$F(\mathbf{x}) = \sum_{i=1}^N w_i \varphi_i \left( \left\| \mathbf{x} - \mathbf{x}_i \right\| \right)$$

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# The RBF neural network concept

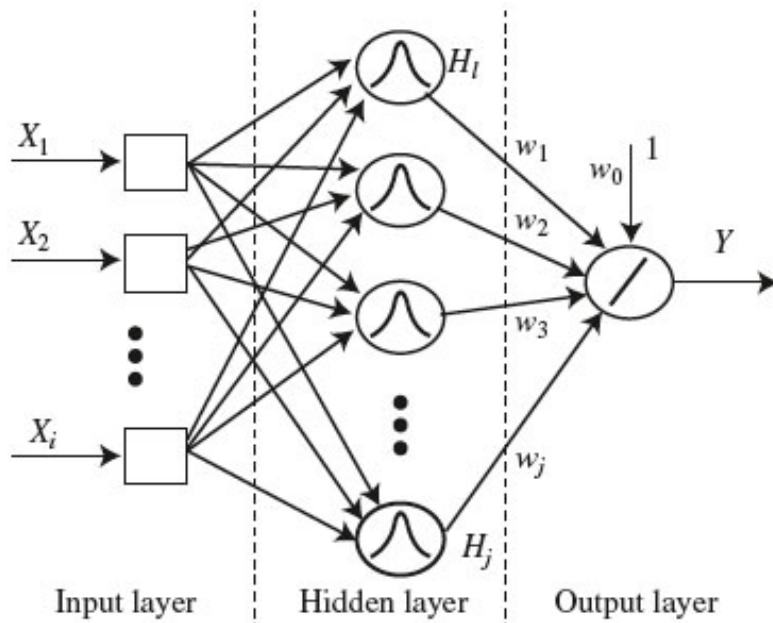


In the *exact interpolation*, the size of the hidden layer,  $N$ , is equal to the number of samples  $n$



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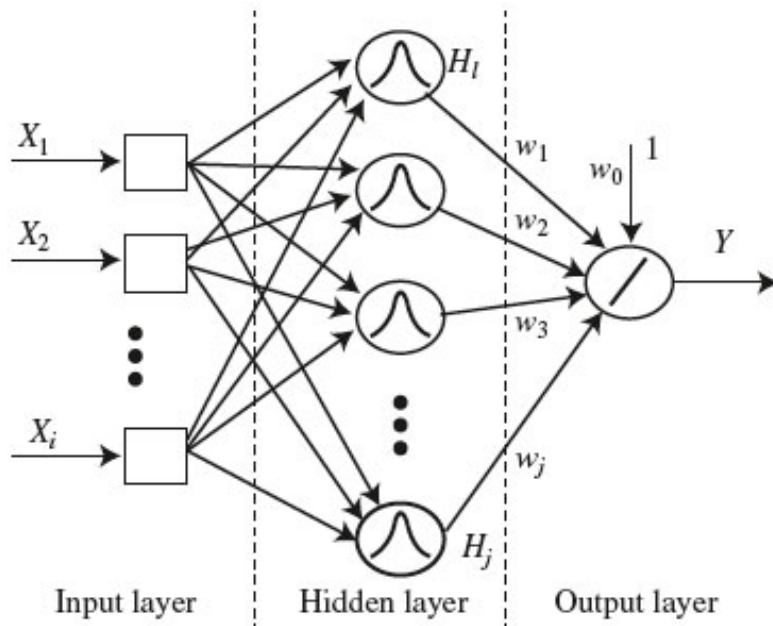


In the *exact interpolation*, the size of the hidden layer,  $N$ , is equal to the number of samples  $n$

**BUT** this is not robust especially if a lot of samples are corrupted with noise!

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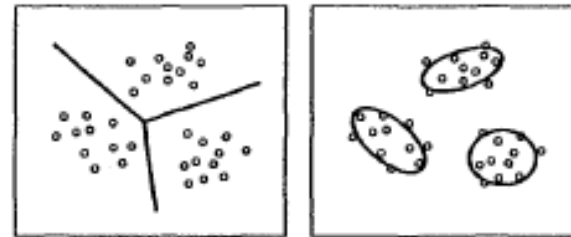
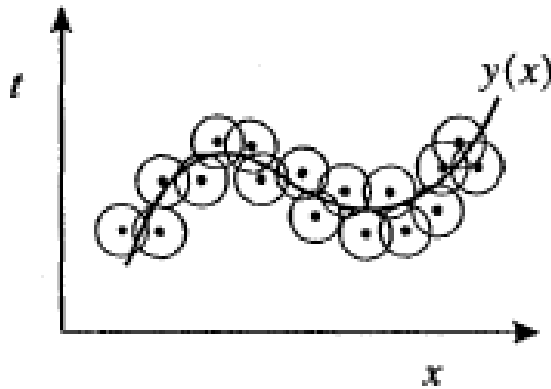
**BUT** this is not robust especially if a lot of samples are corrupted with noise!

We need modifications:

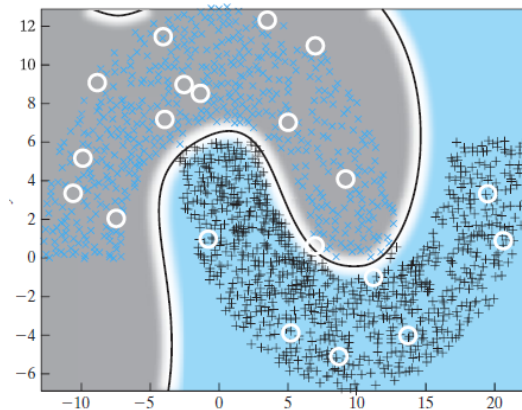
- 1)  $N < n$
- 2) centres  $\mathbf{x}_i$  different from samples
- 3) widths,  $\sigma$ , also differ across RBF nodes
- 4) it is possible to include biases

- Interpolation problem and RBFs
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# Examples

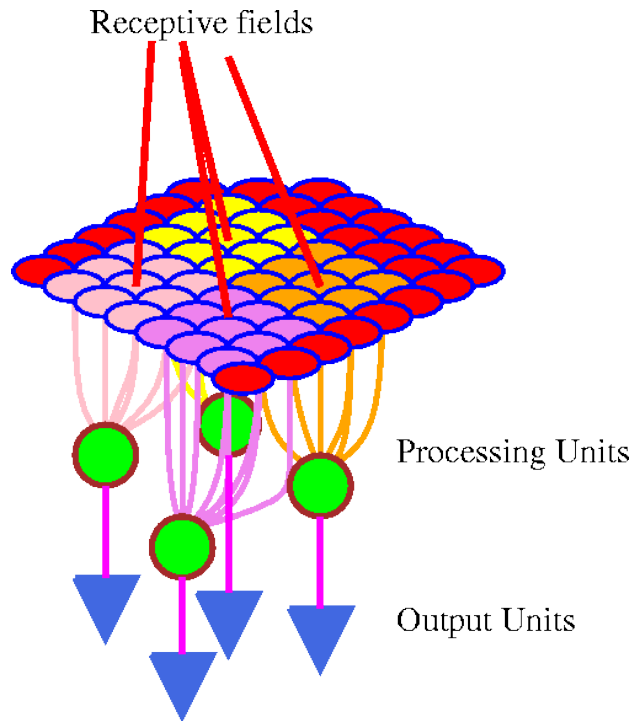


See *Bishop (1995)* for Bayesian interpretation of classification with RBF networks



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# Analogy with receptive fields

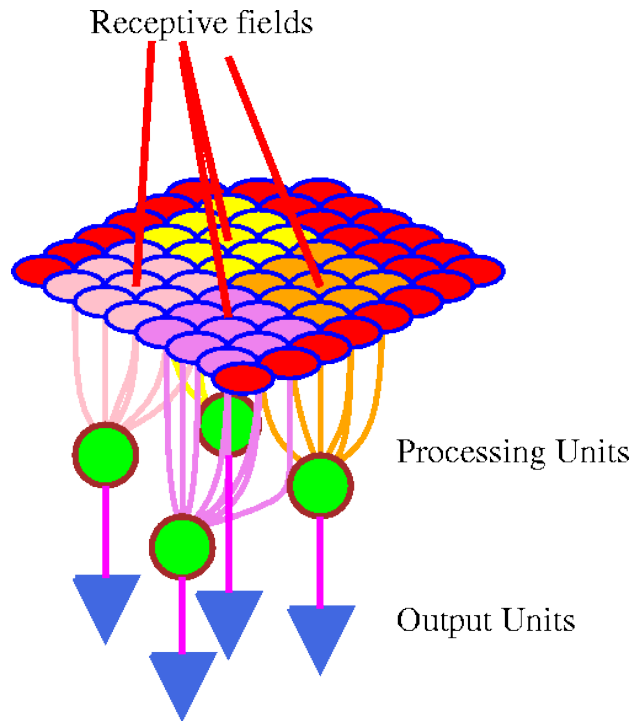


The **receptive field** of a unit is the region of the input space from which a stimulus pattern evokes a response.

Haykin, 2009

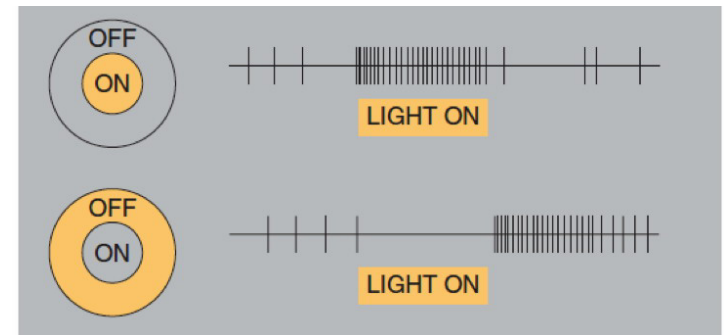
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# Analogy with receptive fields



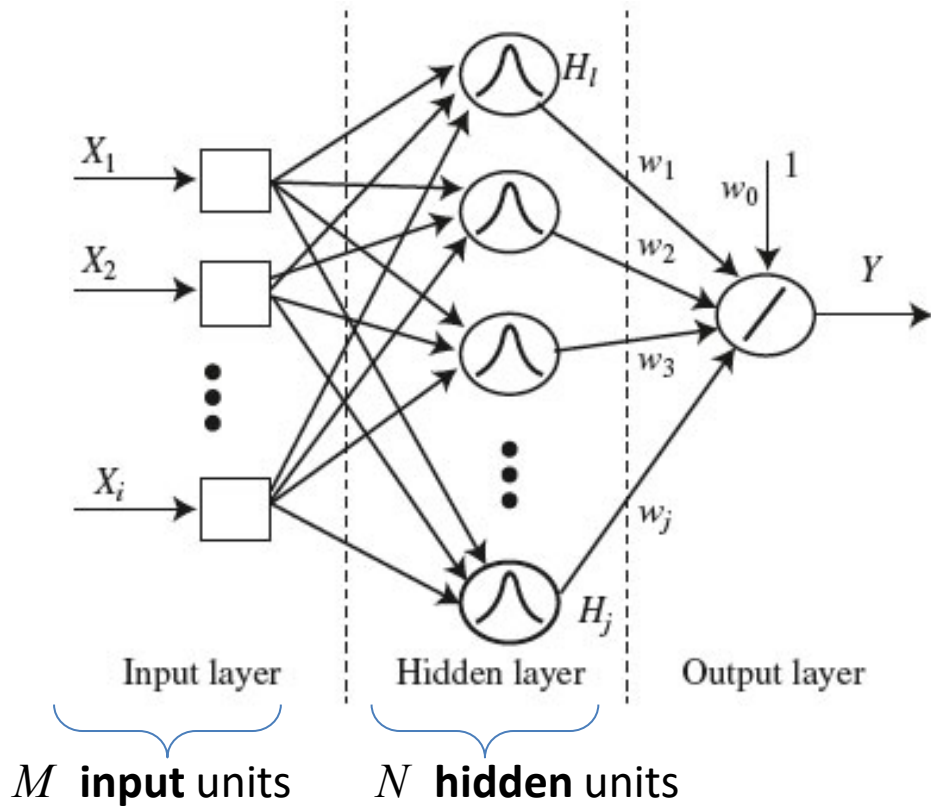
## ***Example:***

Retinal ON-centre and OFF-centre cells



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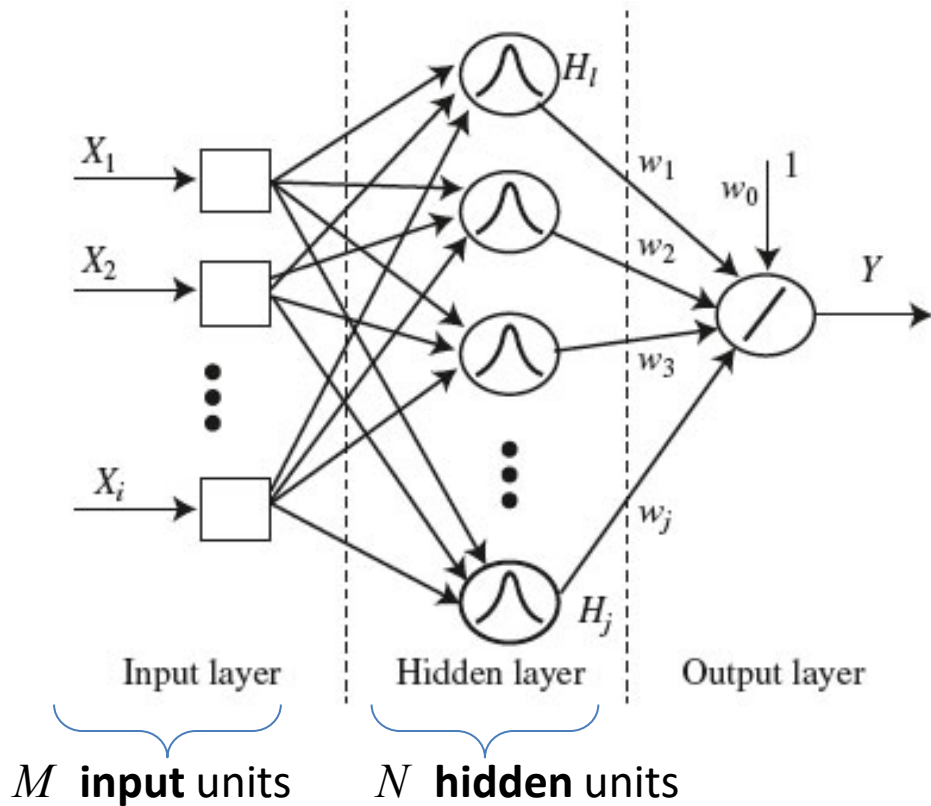
# Hybrid learning algorithm



$n$  **training** samples (each sample is  $N$ -dimensional)

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# Hybrid learning algorithm

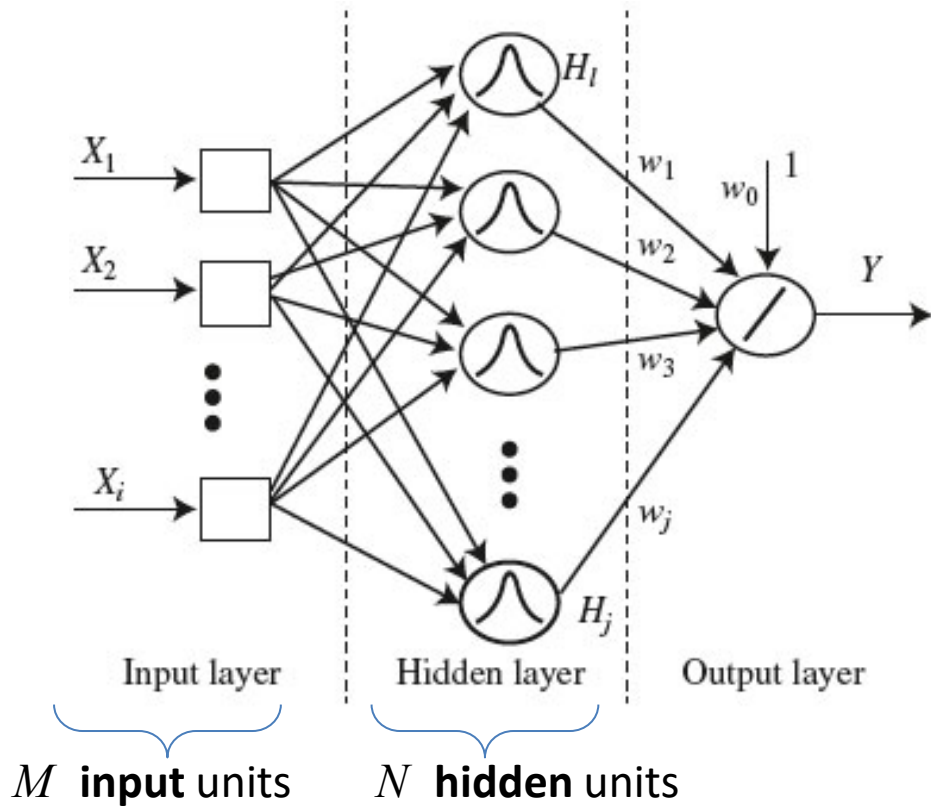


Size of the **input layer** determined by the dimensionality of the input.

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# Hybrid learning algorithm



Size of the **input layer** determined by the dimensionality of the input.

## Hidden layer

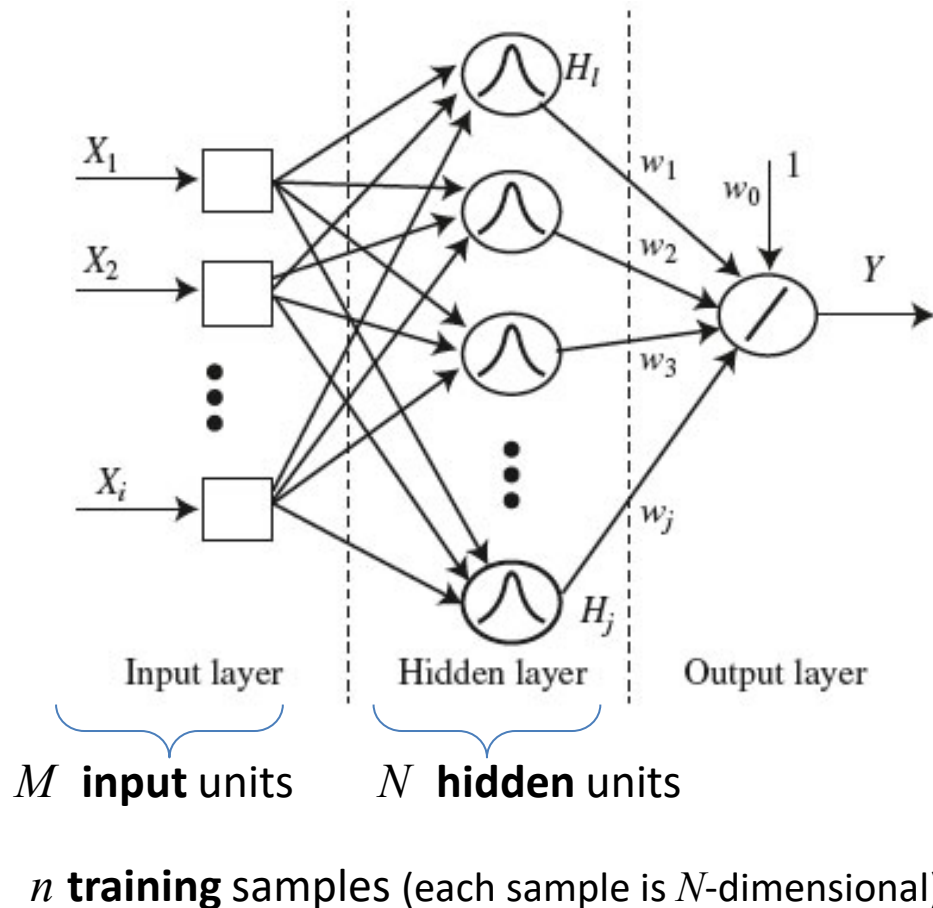
- $N$  has to be decided
- centres and widths of hidden units have to be identified

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# Hybrid learning algorithm



Size of the **input layer** determined by the dimensionality of the input.

## Hidden layer

- $N$  has to be decided
- centres and widths of hidden units have to be identified

**Output layer** performs a linear mapping – e.g., training with least square methods

$$\begin{bmatrix} \varphi_{11} & \varphi_{12} & \dots & \varphi_{1N} \\ \varphi_{21} & \varphi_{22} & \dots & \varphi_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ \varphi_{n1} & \varphi_{n2} & \dots & \varphi_{nN} \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_N \end{bmatrix} = \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_n \end{bmatrix}$$

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## Hybrid learning – RBF layer

- Clustering algorithms
  - k-means clustering
  - clustering with Kohonen feature maps (SOMs), vector quantization (VQ)
  - estimate of the cluster width (variance problem)
- Gaussian mixture models: expectation-maximization (EM) alg.

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- Supervised tuning of the RBF parameters with gradient descent

$$\frac{\partial E}{\partial \mu_{ji}} = \sum_n \sum_k \{y_k(\mathbf{x}^n) - t_k^n\} w_{kj} \exp\left(-\frac{\|\mathbf{x}^n - \mu_j\|^2}{2\sigma_j^2}\right) \frac{(x_i^n - \mu_{ji})}{\sigma_j^2}$$

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Bishop, 1995

- Subset selection with orthogonal least squares

- Interpolation problem and RBFs
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# Hybrid learning – output layer

- Least-squares fitting – batch approach

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- Recursive least-squares estimation (see *Haykin*, RLS algorithm)

delta rule:

$$\begin{aligned} \Delta \mathbf{w} &= -\eta \nabla_{\mathbf{w}} \hat{\xi} \\ &= -\eta \frac{1}{2} \nabla_{\mathbf{w}} (f(x_k) - \Phi(x_k)^\top \mathbf{w})^2 \\ &= \eta (f(x_k) - \Phi(x_k)^\top \mathbf{w}) \Phi(x_k) \\ &= \eta e \Phi(x_k) \end{aligned} \quad \Phi(x_k) = \begin{pmatrix} \phi_1(x_k) \\ \phi_2(x_k) \\ \vdots \\ \phi_n(x_k) \end{pmatrix}$$

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## RBF NN vs MLP

- Hidden units in MLP rely on weighted linear summations of inputs (a matter of interpretation)
  - RBFs rely on distance to prototype vectors

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## RBF NN vs MLP

- Hidden units in MLP rely on weighted linear summations of inputs (a matter of interpretation)
  - RBFs rely on distance to prototype vectors
- In MLPs, function approximation is defined as by a nested sum of weighted summations
  - In RBFs, the approximation is defined by a single weighted sum



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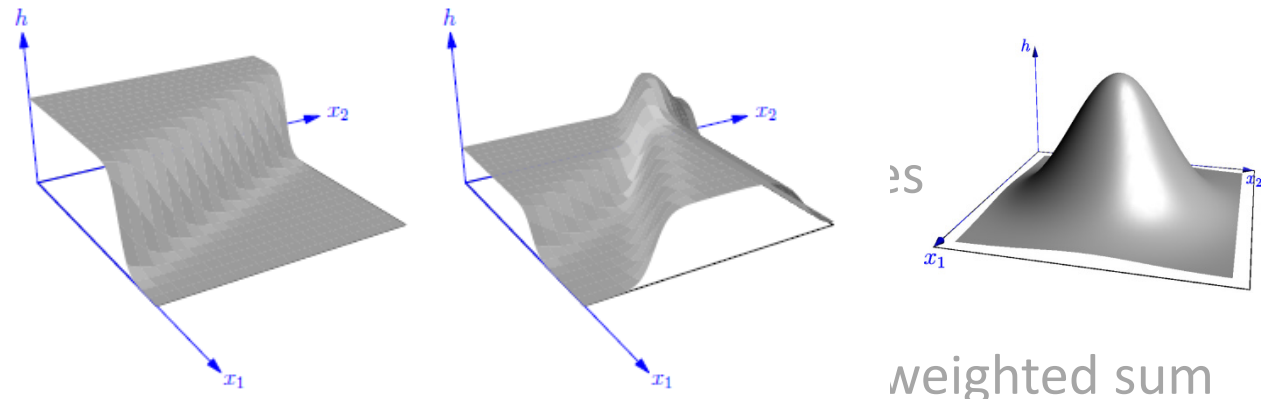
# RBF NN vs MLP

- Hidden units in MLP rely on weighted linear summations of inputs  
(a matter of  $\sum w_i x_i$ )

➤ RBFs rely

- In MLPs, fun  
weighted su

➤ In RBFs,  $f(\sum w_i x_i)$



- MLPs form distributed activations (many hidden units contribute to the output for a given input, which partly leads to local minima etc.)
  - In RBFs, very few local basis functions (wrt. input) are activated for a given input

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- In MLPs, usually all parameters/weights are trained at the same time
  - In RBFs, hybrid two-stage training is used

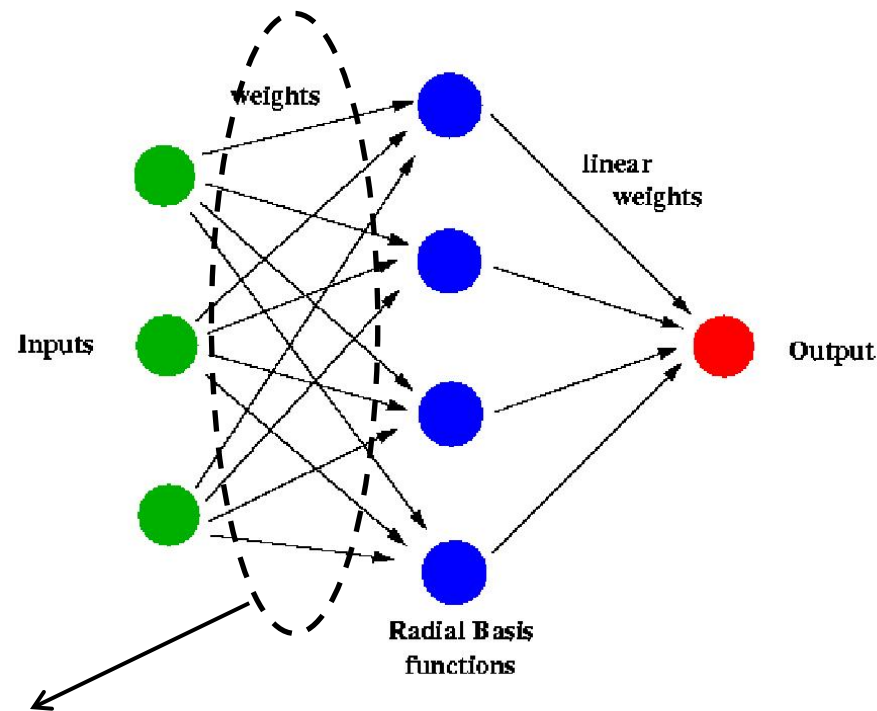
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## RBF NN vs MLP

- In MLPs, usually all parameters/weights are trained at the same time
  - In RBFs, hybrid two-stage training is used
- MLPs rely on complex multi-layer architecture
  - RBF NNs have simple one-hidden-layer architecture

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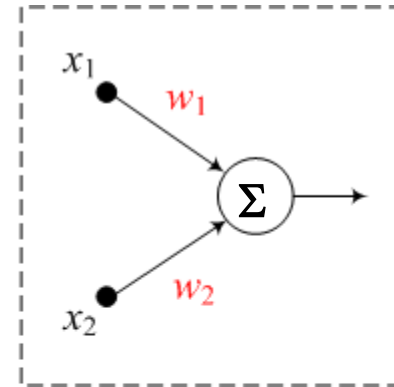
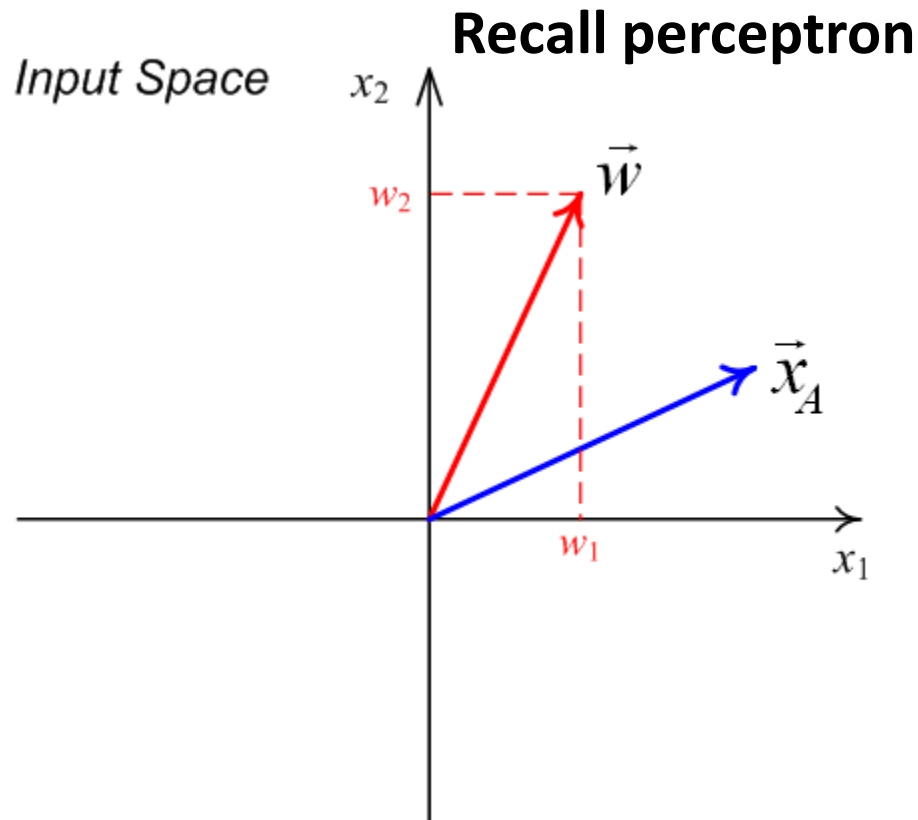
# Interpretation of the weights to hidden layer



Do these connections have weights?

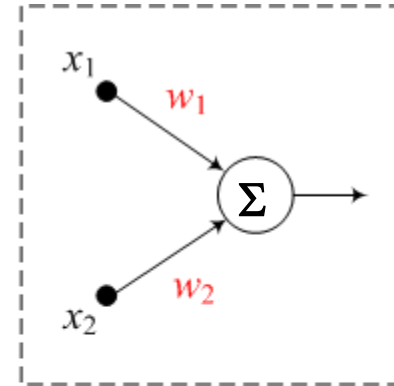
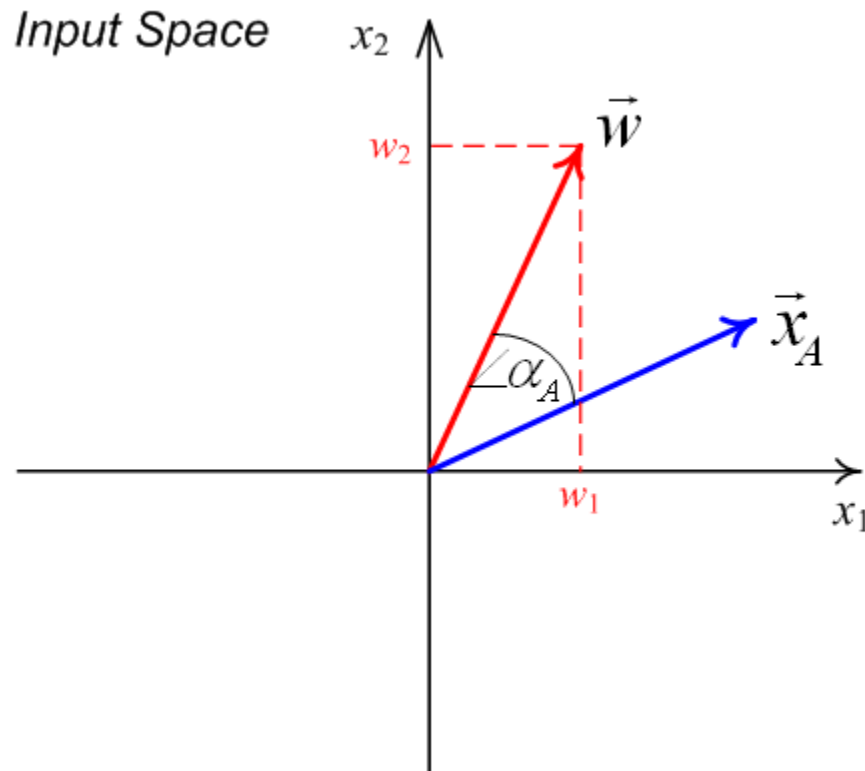
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# Weights in the input space



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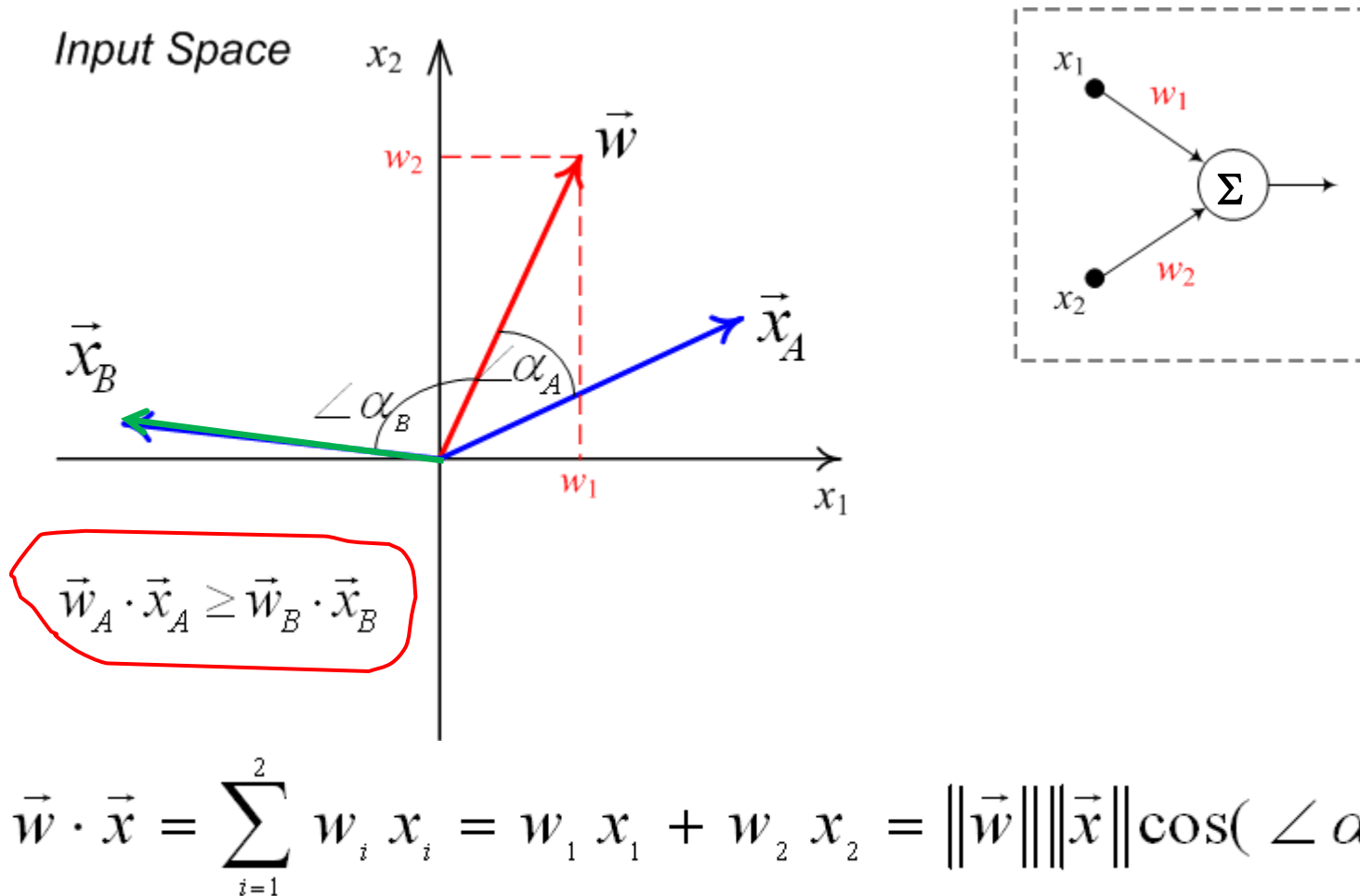
# Weights in the input space – scalar product



$$\vec{w} \cdot \vec{x} = \sum_{i=1}^2 w_i x_i = w_1 x_1 + w_2 x_2 = \|\vec{w}\| \|\vec{x}\| \cos(\angle \alpha)$$

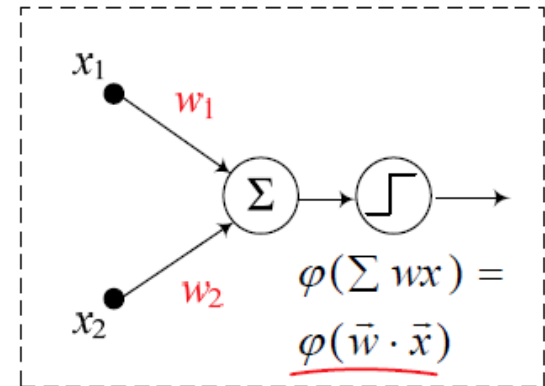
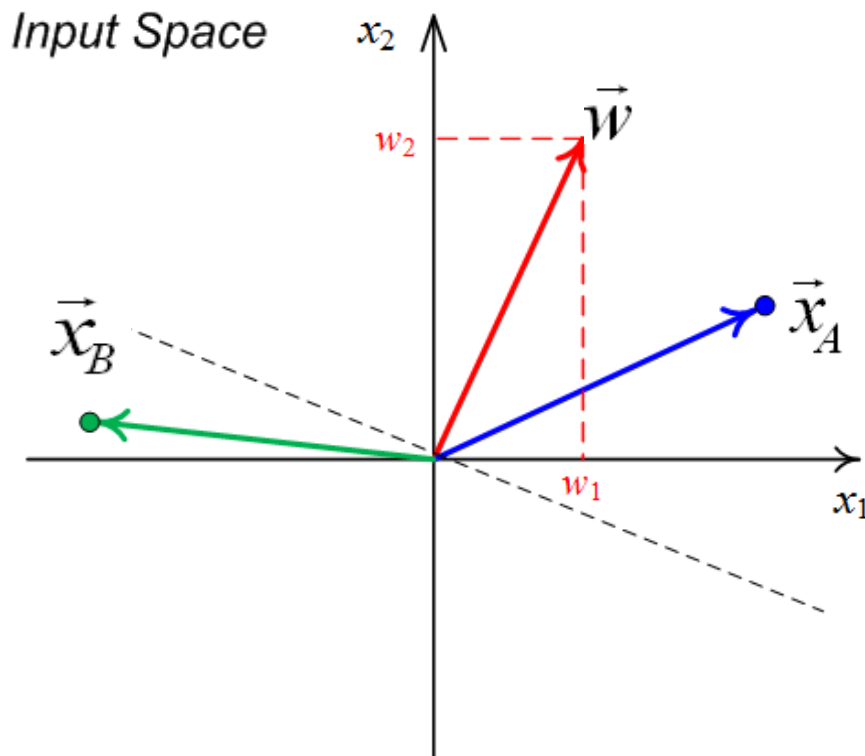
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# Weights in the input space – scalar product



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# Weights in the input space – perceptron classifier

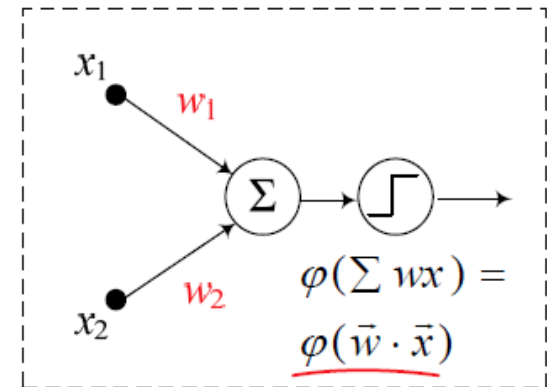
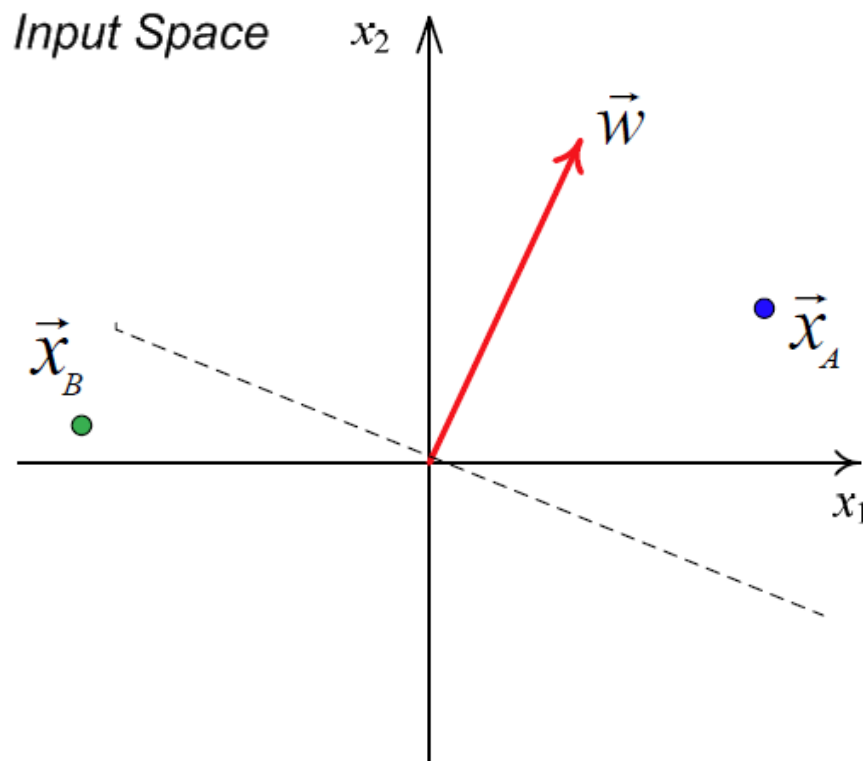


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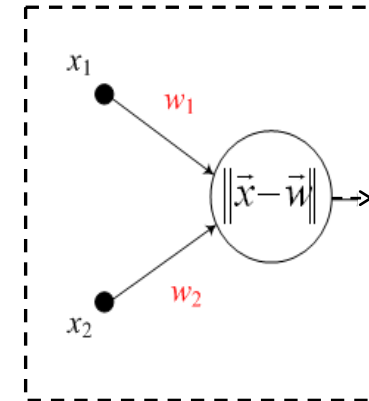
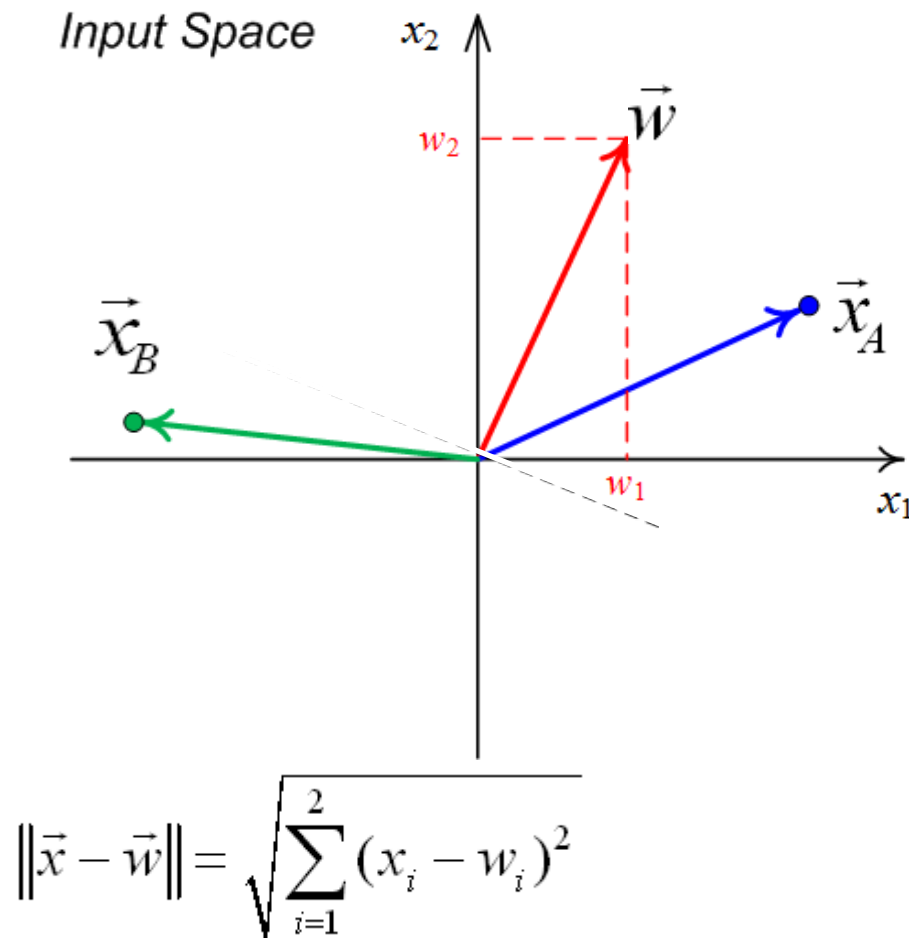


based on scalar product

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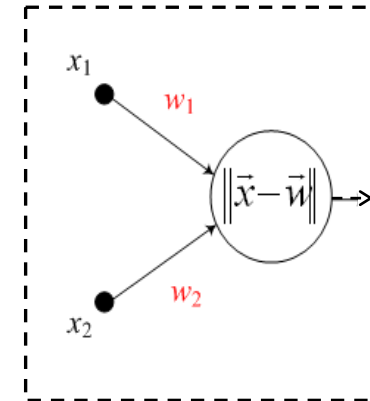
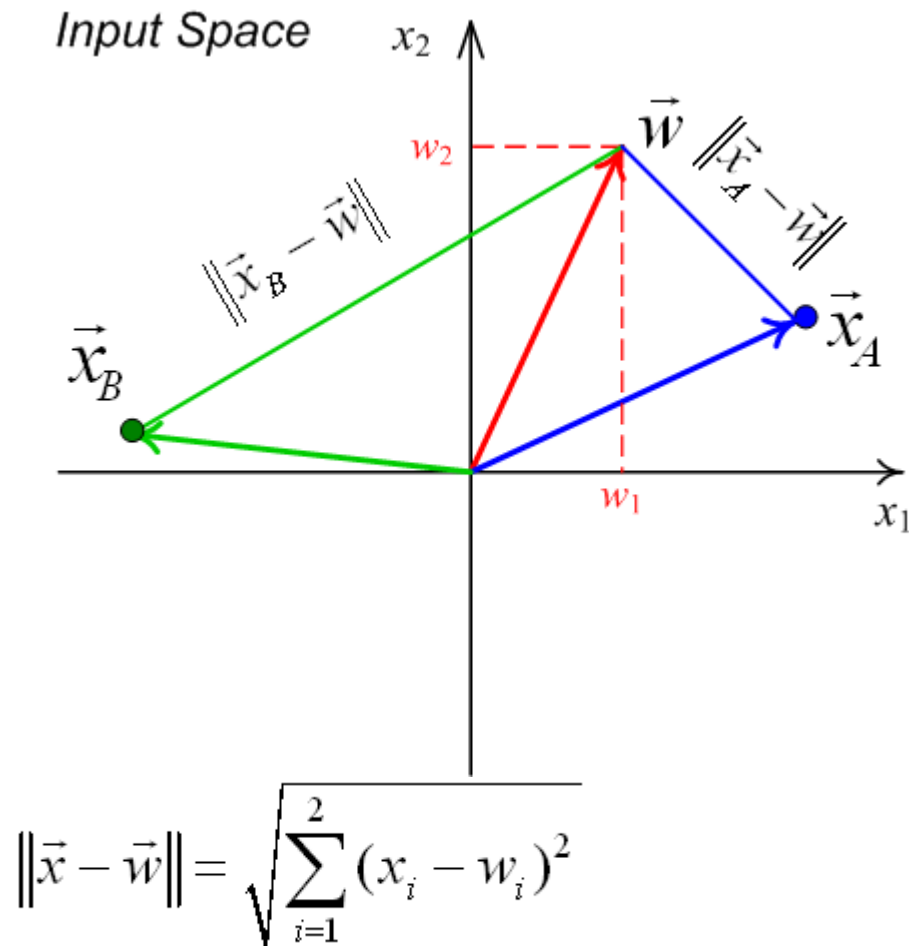
# Weights in the input space – Euclidean distance



Euclidean distance  
measure:  $\|\vec{x} - \vec{w}\|$

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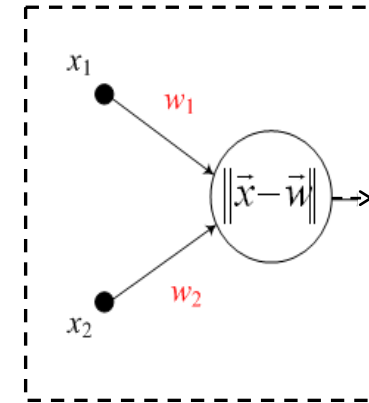
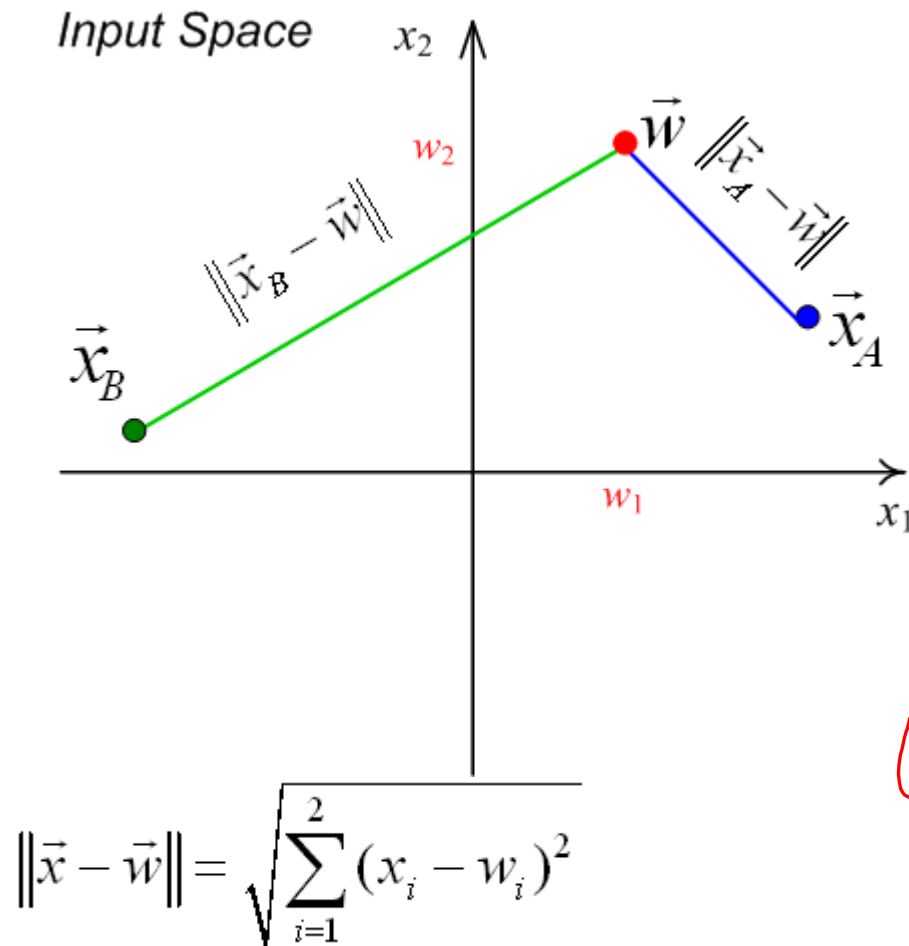
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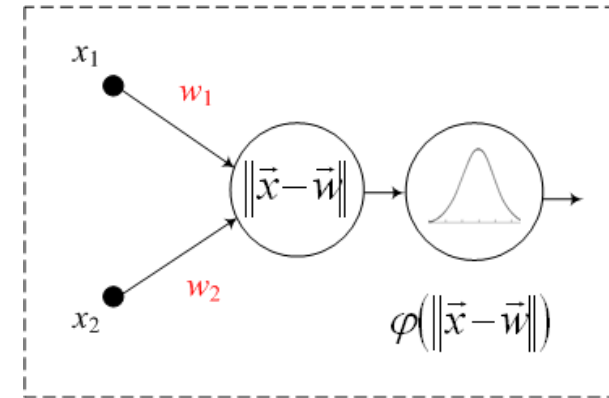
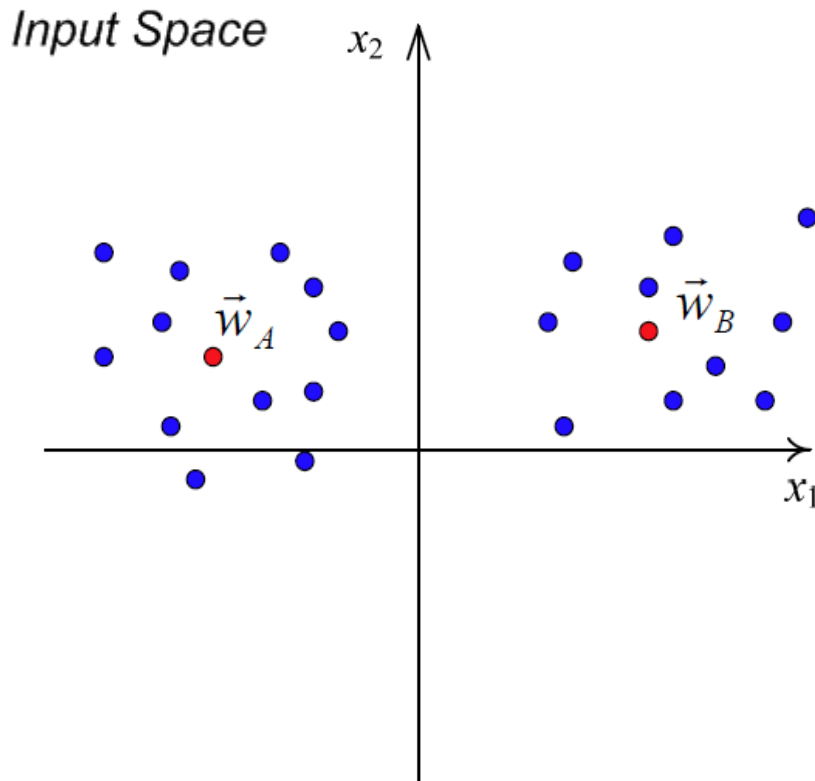


Euclidean distance  
measure:  $\|\vec{x} - \vec{w}\|$

$$\|\vec{x}_A - \vec{w}\| < \|\vec{x}_B - \vec{w}\|$$

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# Weights in the input space – proximity measure

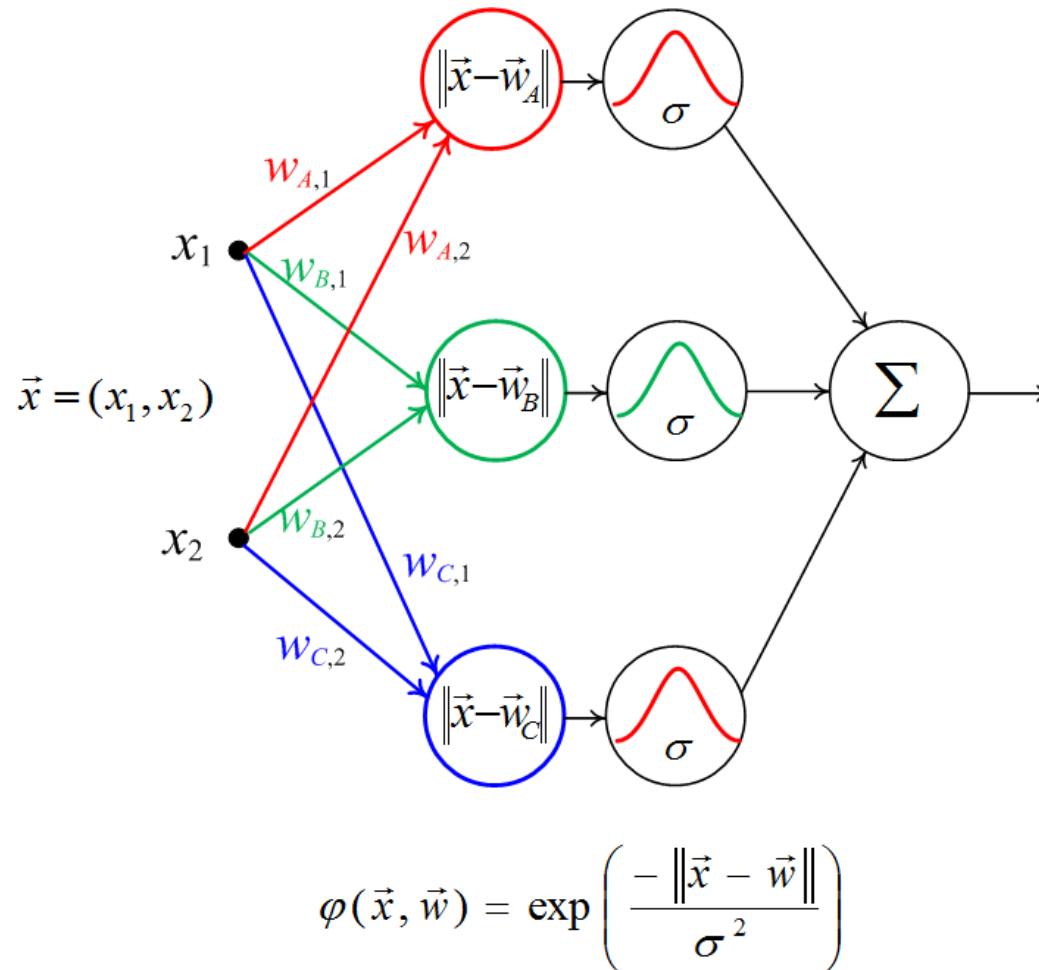


based on Euclidean distance

$$\varphi(\|\vec{x} - \vec{w}\|) = \exp\left(-\frac{\|\vec{x} - \vec{w}\|^2}{\sigma^2}\right)$$

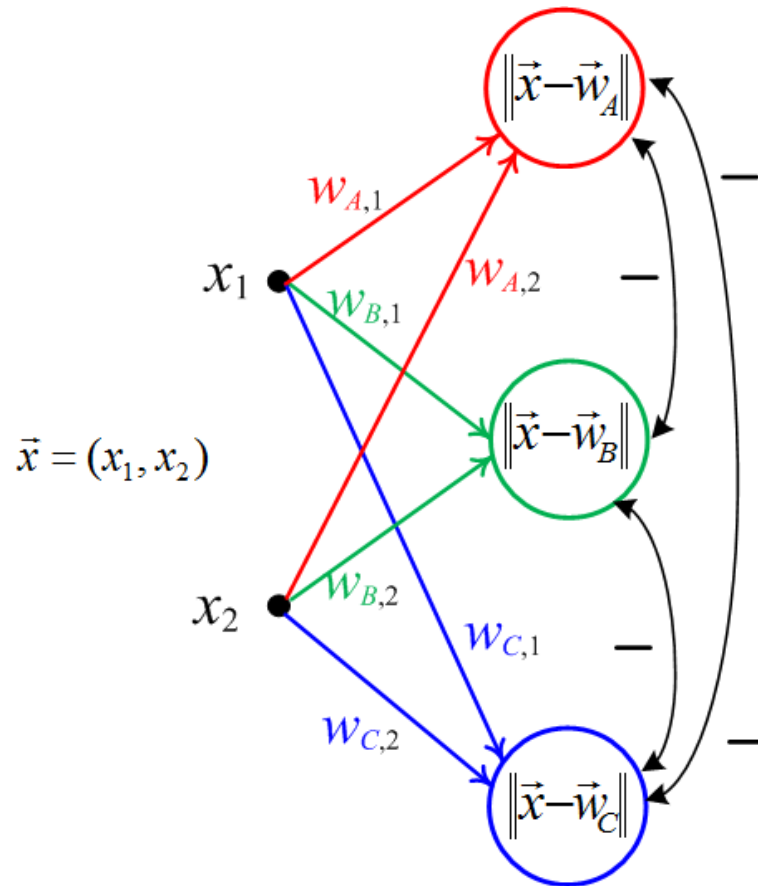
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# RBF network – interpretation of the input weights



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# Competition and winner-take-all mechanism



Competition  
between nodes  
– Winner  
Takes All  
(WTA)

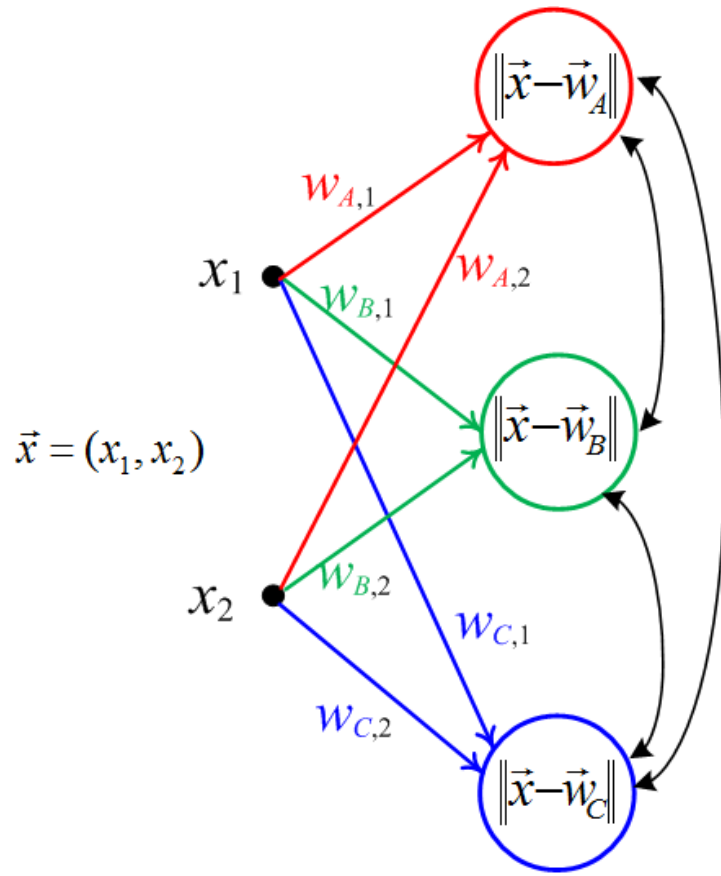
$$\vec{w}_A = (w_{A,1}, w_{A,2})$$

$$\vec{w}_B = (w_{B,1}, w_{B,2})$$

$$\vec{w}_C = (w_{C,1}, w_{C,2})$$

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# Competitive mechanisms



If the **red** node  $w_A$  wins, then:

$$\Delta \vec{w}_A = \eta \vec{x}$$

OR

$$\Delta \vec{w}_A = \eta (\vec{x} - \vec{w}_A)$$

$$\vec{w}_A = (w_{A,1}, w_{A,2})$$

$$\vec{w}_B = (w_{B,1}, w_{B,2})$$

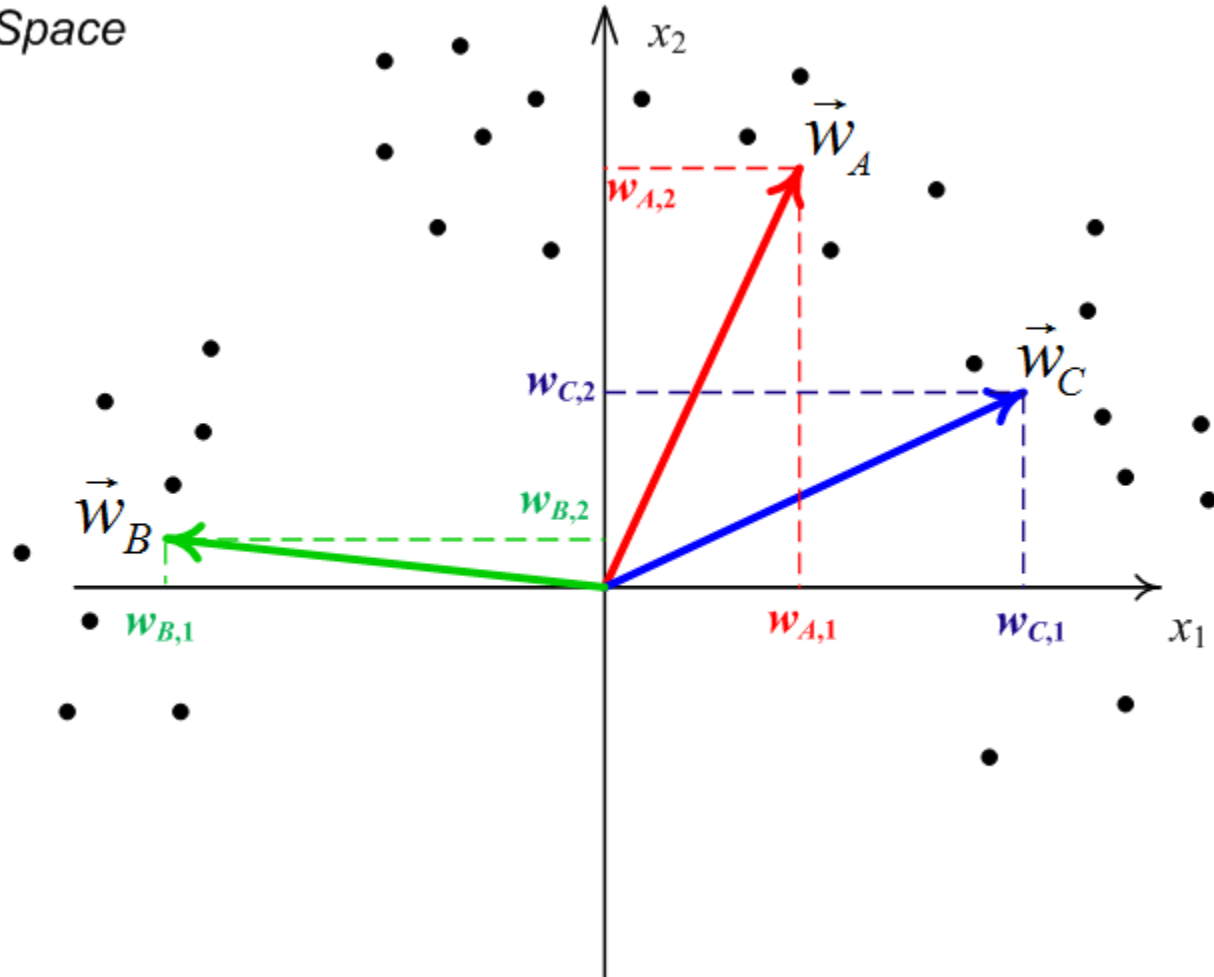
$$\vec{w}_C = (w_{C,1}, w_{C,2})$$



- Interpolation problem and RBFs
- RBF networks – hybrid learning
- Weight interpretation in the input space
- **Competitive mechanisms for unsupervised learning**

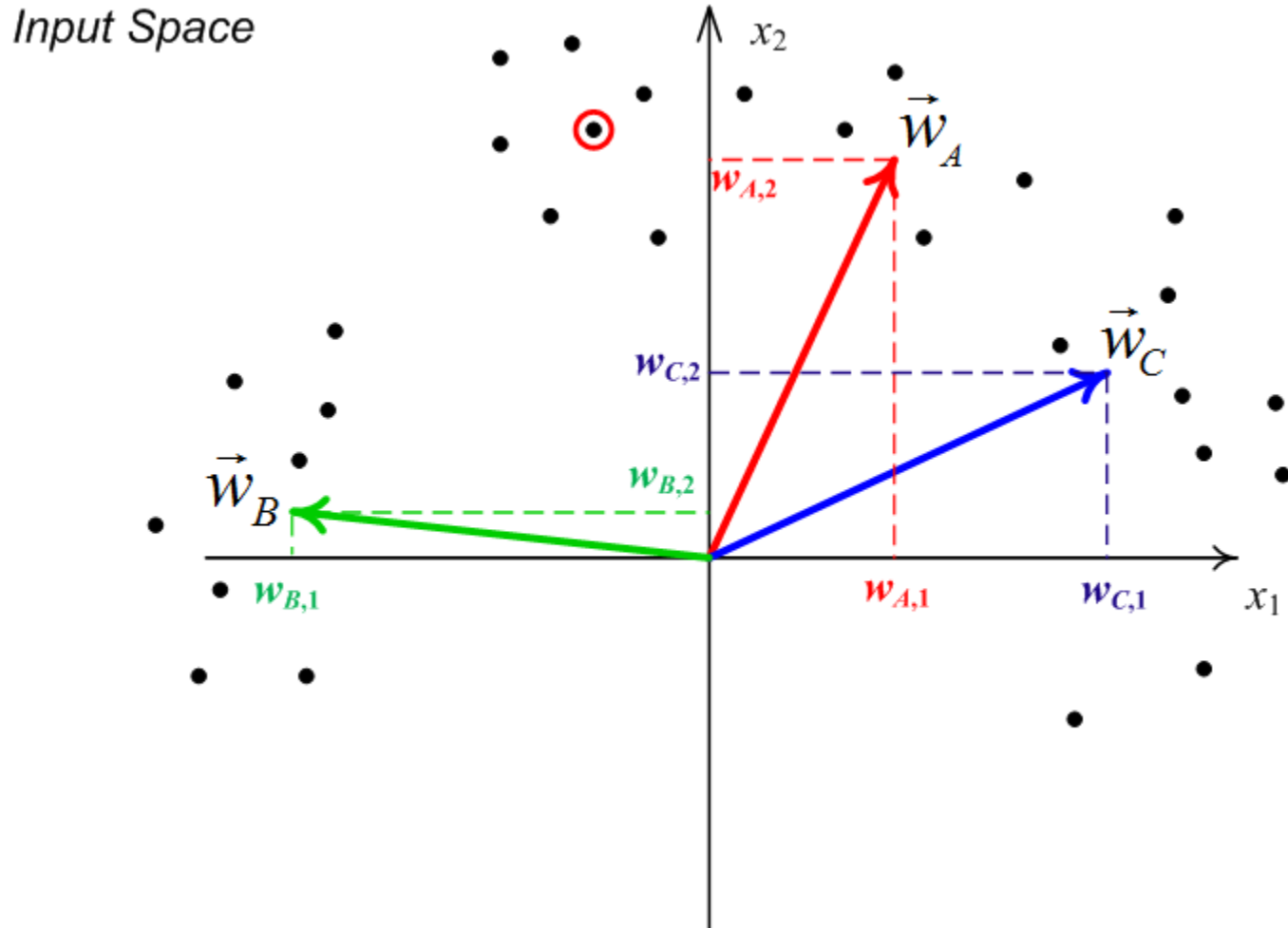
# Competition – update of the input weights, example

*Input Space*



- Interpolation problem and RBFs
- RBF networks – hybrid learning
- Weight interpretation in the input space
- **Competitive mechanisms for unsupervised learning**

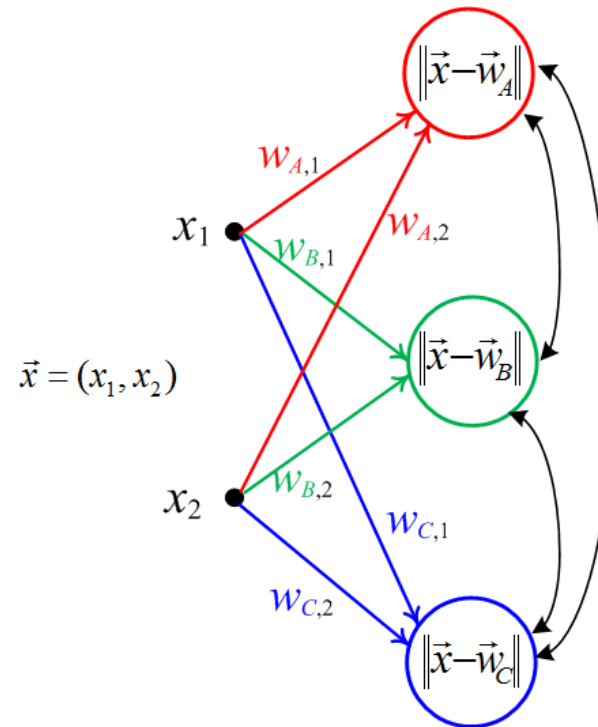
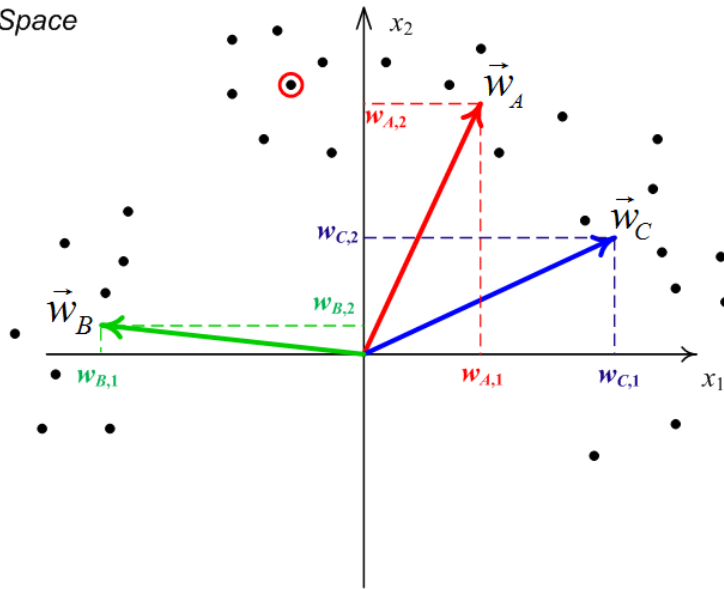
## Competition – update of the input weights



- Interpolation problem and RBFs
- RBF networks – hybrid learning
- Weight interpretation in the input space
- **Competitive mechanisms for unsupervised learning**

# Competition – update of the input weights

Input Space



If the **red** node  $w_A$  wins, then:

$$\Delta \vec{w}_A = \eta \vec{x}$$

OR

$$\Delta \vec{w}_A = \eta (\vec{x} - \vec{w}_A)$$

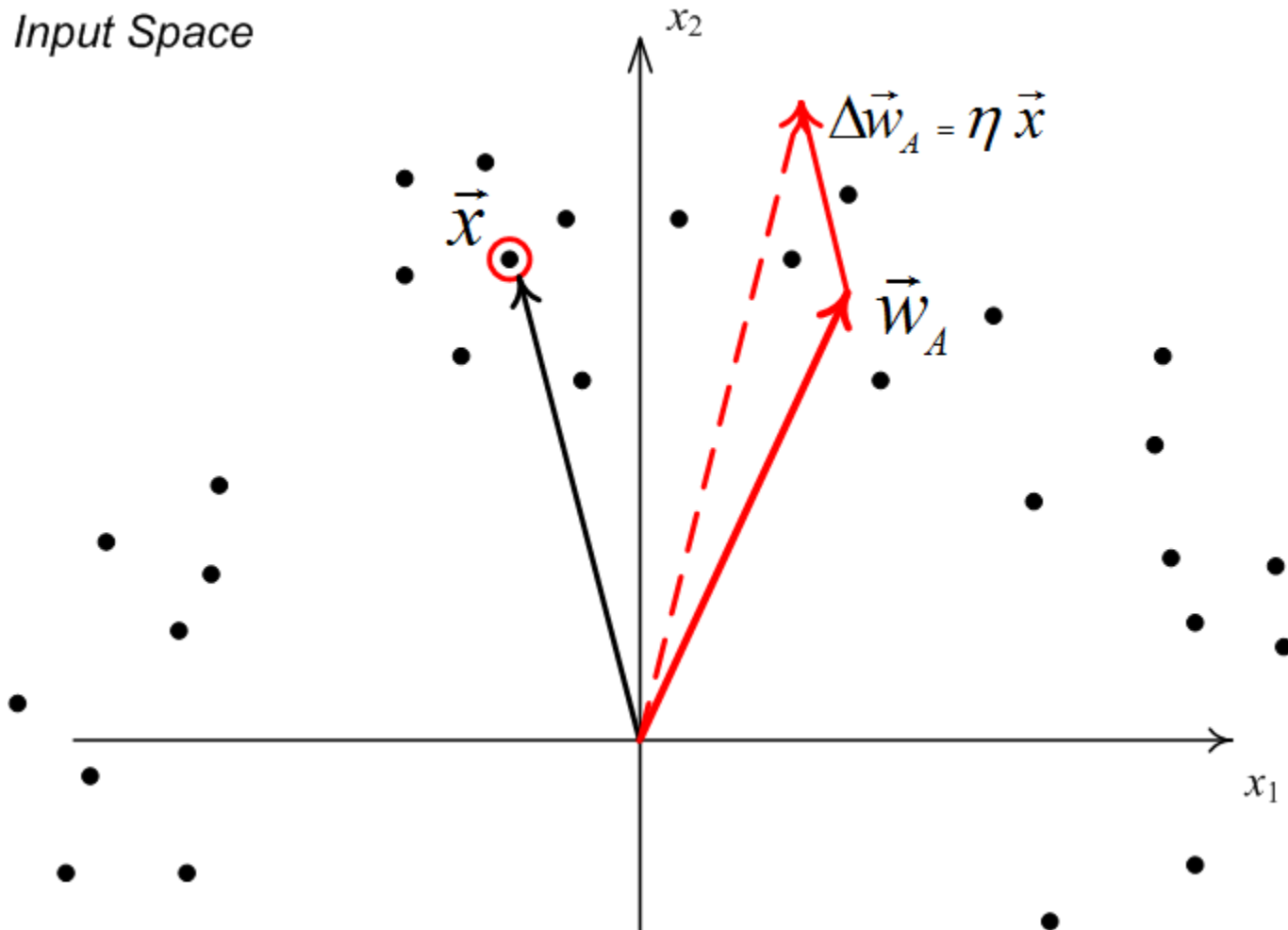
$$\vec{w}_A = (w_{A,1}, w_{A,2})$$

$$\vec{w}_B = (w_{B,1}, w_{B,2})$$

$$\vec{w}_C = (w_{C,1}, w_{C,2})$$

- Interpolation problem and RBFs
- RBF networks – hybrid learning
- Weight interpretation in the input space
- **Competitive mechanisms for unsupervised learning**

# Competition – update of the input weights, ver. 1



- Interpolation problem and RBFs
- RBF networks – hybrid learning
- Weight interpretation in the input space
- **Competitive mechanisms for unsupervised learning**

## Competition – update of the input weights, ver. 2

