

1. Обратное распространение ошибки из оригинальной статьи про

Batch normalisation (<https://arxiv.org/pdf/1502.03167.pdf>) :

$$\frac{\partial l}{\partial \hat{x}_i} = \frac{\partial l}{\partial y_i} \cdot \gamma$$

$$\frac{\partial l}{\partial \sigma_B^2} = \sum_{i=1}^m \frac{\partial l}{\partial \hat{x}_i} \cdot (x_i - \mu_B) \cdot \left(-\frac{1}{2}\right) (\sigma_B^2 + \epsilon)^{-3/2}$$

$$\frac{\partial l}{\partial \mu_B} = \left( \sum_{i=1}^m \frac{\partial l}{\partial \hat{x}_i} \cdot \left(-\frac{1}{\sqrt{\sigma_B^2 + \epsilon}}\right) \right) + \frac{\partial l}{\partial \sigma_B^2} \cdot \frac{\sum_{i=1}^m -2(x_i - \mu_B)}{m}$$

$$\frac{\partial l}{\partial x_i} = \frac{\partial l}{\partial \hat{x}_i} \cdot \frac{1}{\sqrt{\sigma_B^2 + \epsilon}} + \frac{\partial l}{\partial \sigma_B^2} \cdot \frac{2(x_i - \mu_B)}{m} + \frac{\partial l}{\partial \mu_B^2} \cdot \frac{1}{m}$$

$$\frac{\partial l}{\partial \gamma} = \sum_{i=1}^m \frac{\partial l}{\partial y_i} \cdot \hat{x}_i$$

$$\frac{\partial l}{\partial \beta} = \sum_{i=1}^m \frac{\partial l}{\partial y_i}$$

2. Соберем наиболее важные обозначения из оригинальной статьи :

$$\hat{x}_i = \frac{x_i - \mu_B}{\sigma_B + \epsilon} \quad - \quad z\text{-score для } x_i$$

$$y_i = \gamma x_i + \beta$$

$$\frac{\partial l}{\partial \hat{x}_i} = \frac{\partial l}{\partial y_i} \cdot \gamma$$

3. Разберем  $\frac{\partial l}{\partial x_i}$  для упрощения вычислений обратного распространения ошибки :

$$\frac{\partial l}{\partial x_i} = \frac{\partial l}{\partial \hat{x}_i} \cdot \frac{1}{\sqrt{\sigma_B^2 + \epsilon}} + \frac{\partial l}{\partial \sigma_B^2} \cdot \frac{2(x_i - \mu_B)}{m} + \frac{\partial l}{\partial \mu_B^2} \cdot \frac{1}{m} \quad \left( \text{Развернём } \frac{\partial l}{\partial \sigma_B^2} \right)$$

$$\frac{\partial l}{\partial x_i} = \frac{\partial l}{\partial \hat{x}_i} \cdot \frac{1}{\sqrt{\sigma_B^2 + \epsilon}} + \left[ \sum_{i=1}^m \frac{\partial l}{\partial \hat{x}_i} \cdot (x_i - \mu_B) \cdot \left(-\frac{1}{2}\right) (\sigma_B^2 + \epsilon)^{-3/2} \right] \cdot \frac{2(x_i - \mu_B)}{m} + \frac{\partial l}{\partial \mu_B^2} \cdot \frac{1}{m}$$

$$\frac{\partial l}{\partial x_i} = \frac{\partial l}{\partial \hat{x}_i} \cdot \frac{1}{\sqrt{\sigma_B^2 + \epsilon}} - \left[ \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} \cdot (x_j - \mu_B) \cdot \frac{1}{(\sqrt{\sigma_B^2 + \epsilon})^3} \right] \cdot \frac{(x_i - \mu_B)}{m} + \frac{\partial l}{\partial \mu_B^2} \cdot \frac{1}{m}$$

$$\frac{\partial l}{\partial x_i} = \frac{\partial l}{\partial \hat{x}_i} \cdot \frac{1}{\sqrt{\sigma_B^2 + \epsilon}} - \left[ \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} \cdot \frac{(x_j - \mu_B)}{\sqrt{\sigma_B^2 + \epsilon}} \cdot \frac{1}{(\sqrt{\sigma_B^2 + \epsilon})^2} \right] \cdot \frac{(x_i - \mu_B)}{m} + \frac{\partial l}{\partial \mu_B^2} \cdot \frac{1}{m}$$



$$\frac{\partial l}{\partial x_i} = \frac{1}{\sqrt{\sigma_B^2 + \epsilon}} \left( \frac{\partial l}{\partial \hat{x}_i} - \frac{\hat{x}_i}{m} \left[ \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} \hat{x}_j \right] - \frac{1}{m} \left[ \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} \right] \right) + 0$$

$$\frac{\partial l}{\partial x_i} = \frac{1}{\sqrt{\sigma_B^2 + \epsilon}} \left( \frac{\partial l}{\partial \hat{x}_i} - \frac{\hat{x}_i}{m} \left[ \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} \hat{x}_j \right] - \frac{1}{m} \left[ \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} \right] \right)$$

$$\frac{\partial l}{\partial x_i} = \frac{1}{\sqrt{\sigma_B^2 + \epsilon}} \left( \frac{m}{m} \frac{\partial l}{\partial \hat{x}_i} - \frac{\hat{x}_i}{m} \left[ \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} \hat{x}_j \right] - \frac{1}{m} \left[ \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} \right] \right)$$

$$\frac{\partial l}{\partial x_i} = \frac{1}{m \sqrt{\sigma_B^2 + \epsilon}} \left( m \frac{\partial l}{\partial \hat{x}_i} - \hat{x}_i \left[ \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} \hat{x}_j \right] - \left[ \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} \right] \right)$$

Последнее выражение является упрощенной версией вычисления  $\frac{\partial l}{\partial x_i}$ .

Полезные материалы :



[https://kevinzakka.github.io/2016/09/14/batch\\_normalization/](https://kevinzakka.github.io/2016/09/14/batch_normalization/)  
<http://cthorey.github.io./backpropagation/>