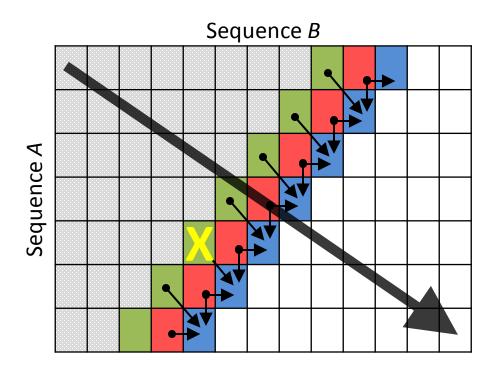
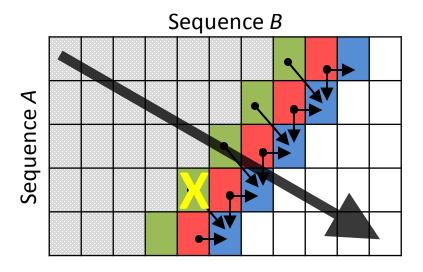
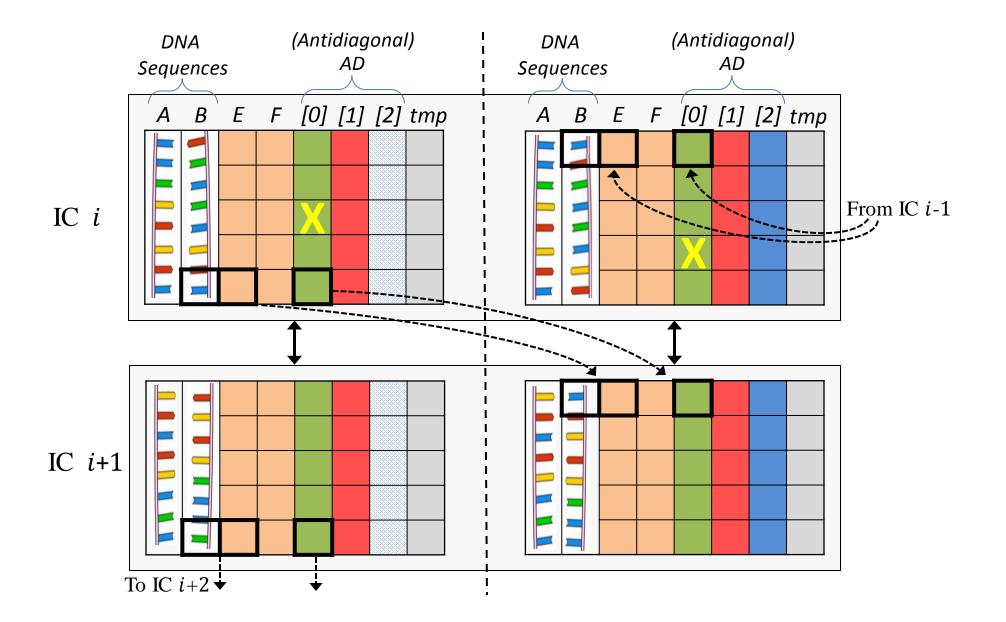
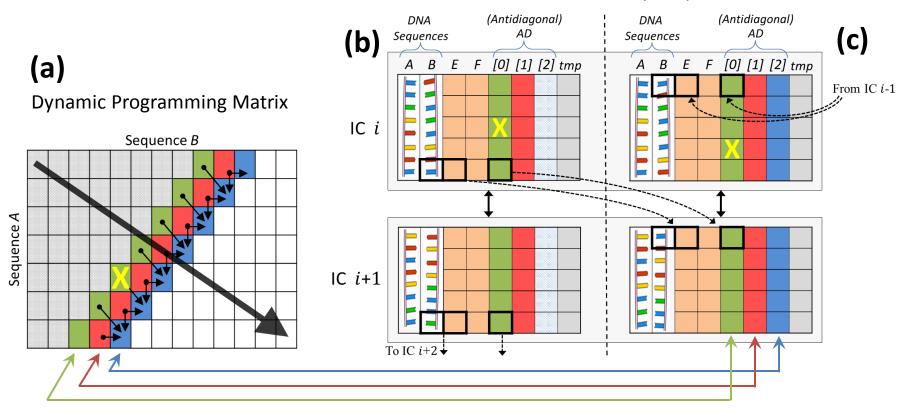
Fig 2

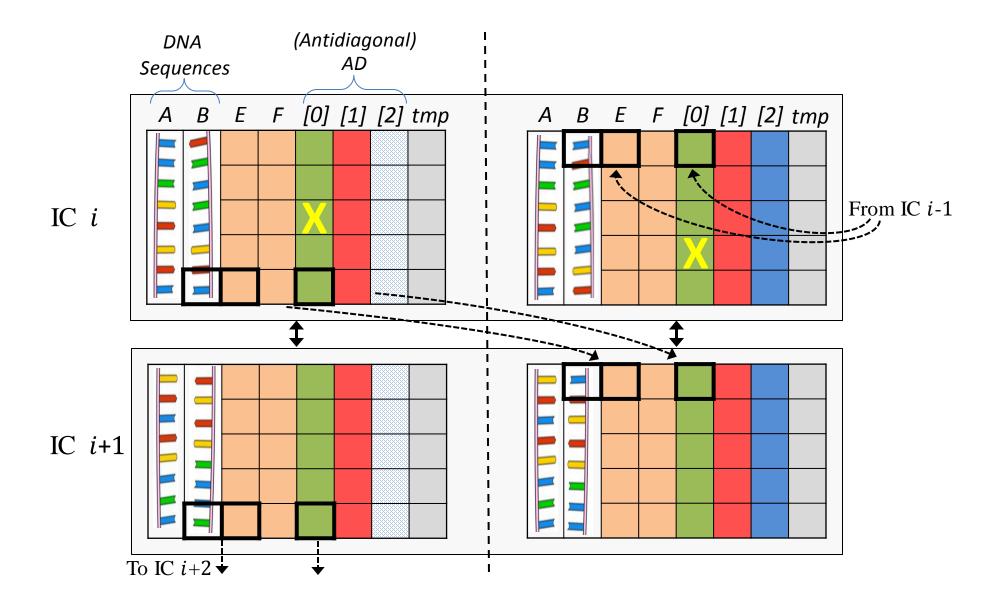




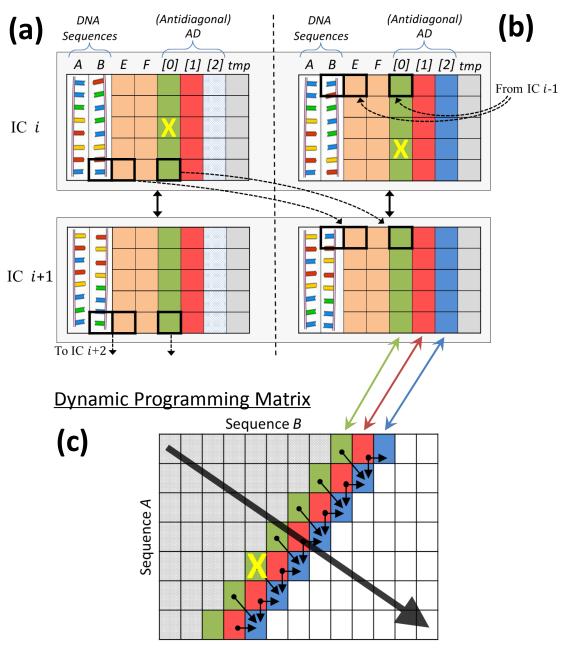


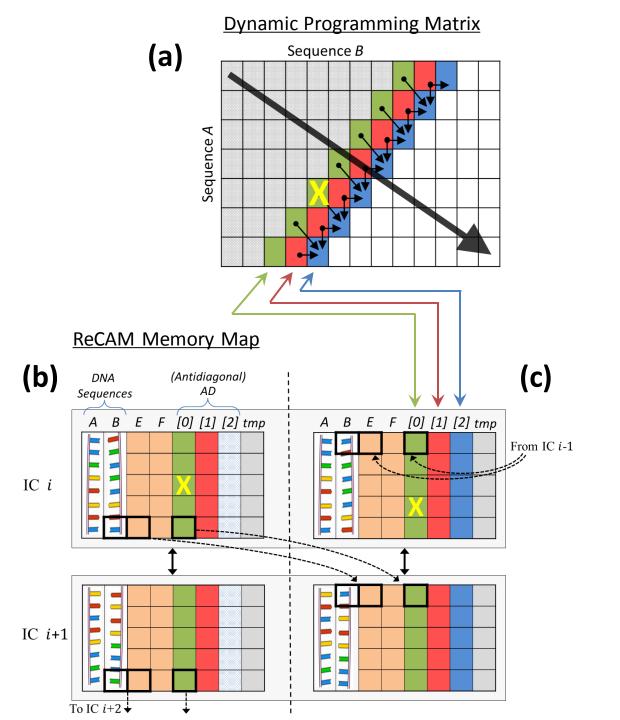
#### ReCAM Memory Map

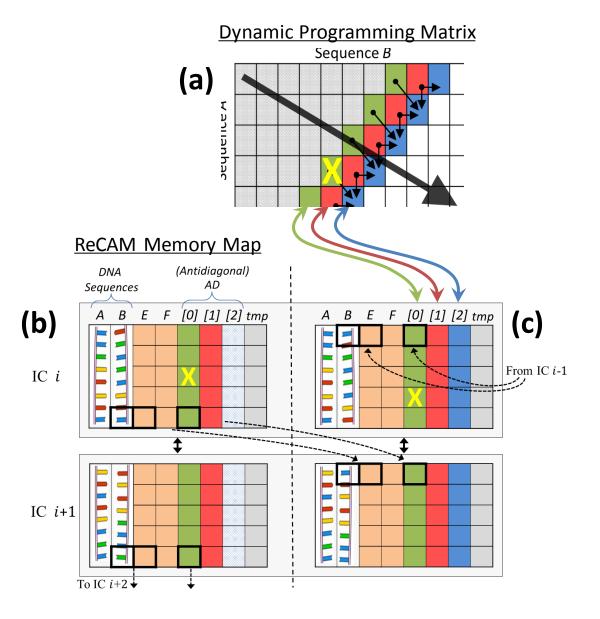


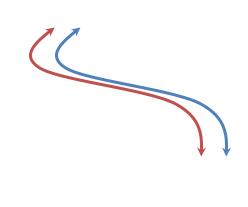


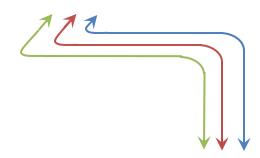
#### **ReCAM Memory Map**

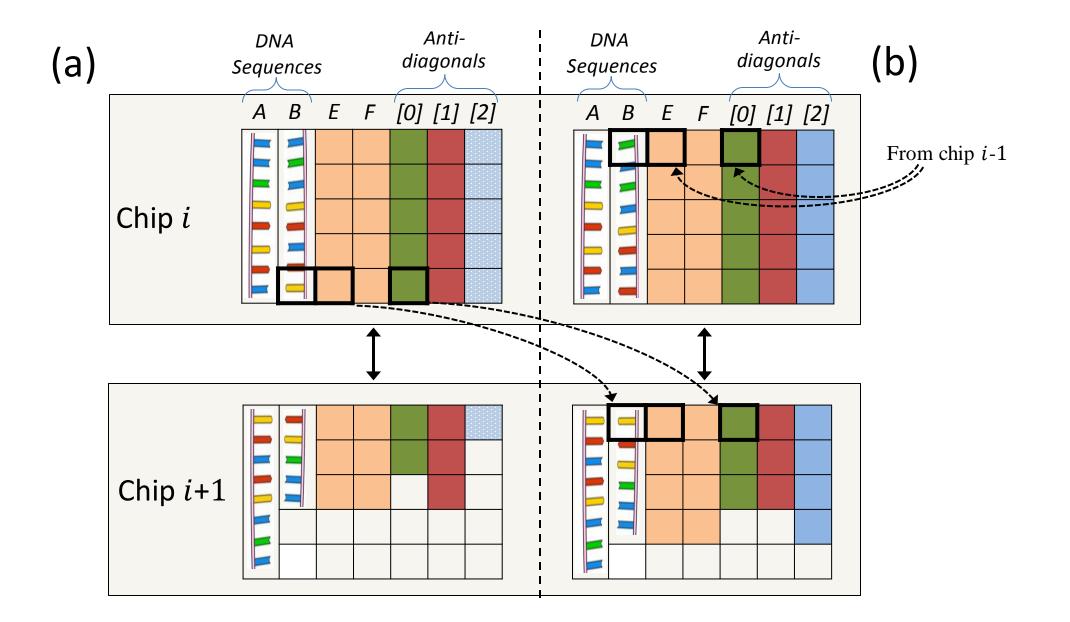












# How it works in Parallel

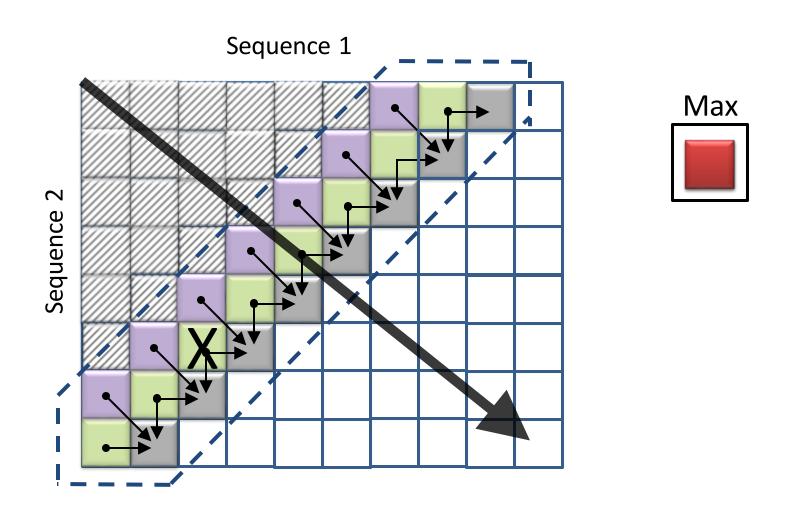


Fig 2

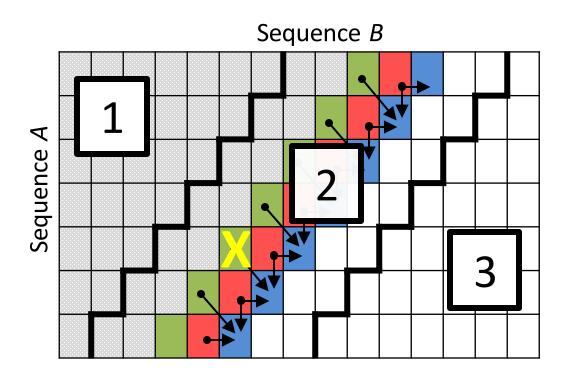
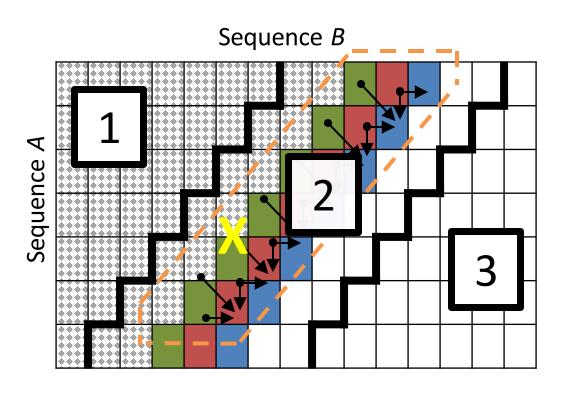
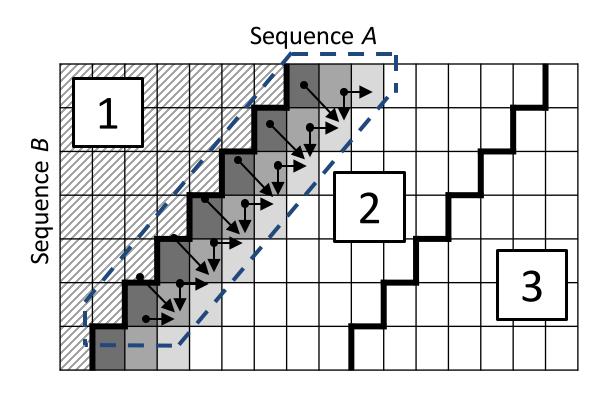


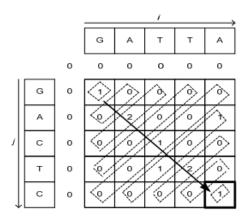
Fig 2

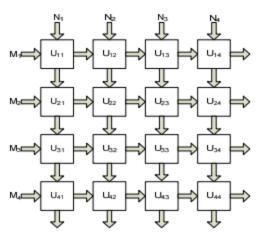


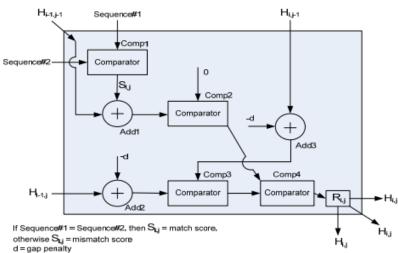
# How it works in Parallel



# Systolic Implementation





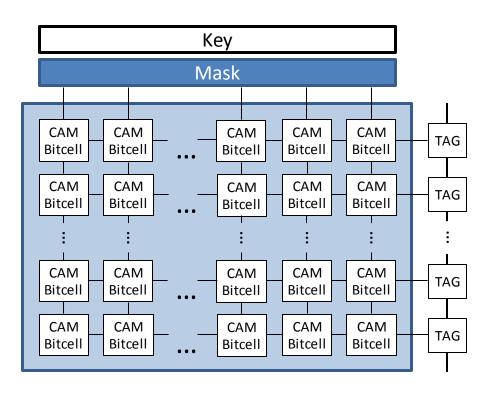


<sup>(1)</sup> Yu, Chi Wai, et al. "A Smith-Waterman systolic cell." New Algorithms, Architectures and Applications for Reconfigurable Computing. Springer US, 2005. 291-300.

<sup>(2)</sup> Zhang, Peiheng, Guangming Tan, and Guang R. Gao. "Implementation of the Smith-Waterman algorithm on a reconfigurable supercomputing platform."

Proceedings of the 1st international workshop on High-performance reconfigurable computing technology and applications: held in conjunction with SCO7. ACM, 2007.

<sup>(3)</sup> Hasan, Laiq, Yahya M. Khawaja, and Abdul Bais. "A Systolic Array Architecture for the Smith-Waterman Algorithm with High Performance Cell Design." IADIS European Conf. Data Mining. 2008.



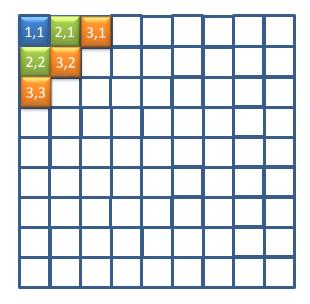
AD[2] AD[1] AD[0] EF seqA seqB

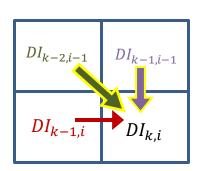
$DI_{3,1}$	1,i-1	1,i-2	$a_1$	$b_i$
$DI_{3,2}$	1,i−1		$a_2$	$b_{i-1}$
$DI_{3,3}$			$a_3$	$b_{i-2}$
			$a_{i-2}$	$b_3$
			$a_{i-2}$ $a_{i-1}$	

$DI_3$	,1		$a_1$	$b_3$
DI	7772,1	$\nu_{I_{1,1}}$	$a_2$	$b_2$
$DI_3$	,,,,2		$a_3$	$b_1$
			$a_4$	
			$a_5$	
			$a_6$	
			$a_7$	

# How it works

## Dynamic Programming Matrix



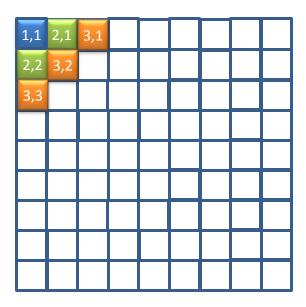


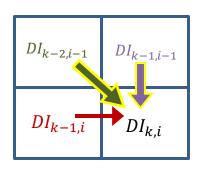
# ReCAM (iteration start)

	$DI_{3,1}$	$DI_{2,1}$	$DI_{1,1}$	$a_1$	$b_3$
	$DI_{3,2}$	$DI_{2,2}$		$a_2$	$b_2$
	$DI_{3,3}$			$a_3$	$b_1$
				$a_4$	
				$a_5$	
				$a_6$	
				$a_7$	

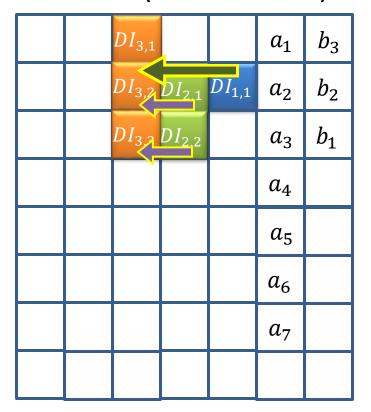
# How it works

### **Dynamic Programming Matrix**



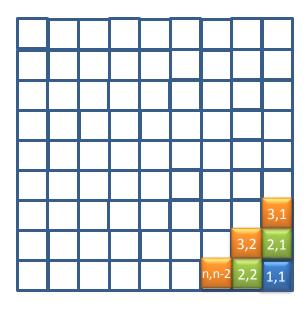


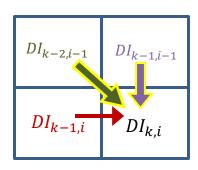
## ReCAM (iteration end)



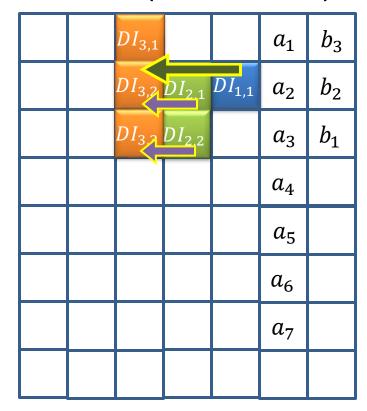
# How it works

### **Dynamic Programming Matrix**



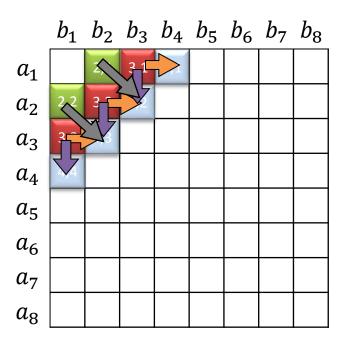


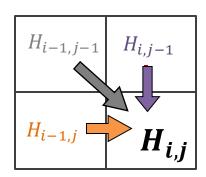
# ReCAM (iteration end)



# Mapping the Algorithm to Device

### **Dynamic Programming Matrix**

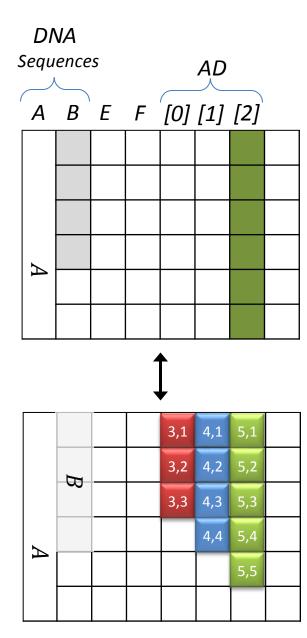


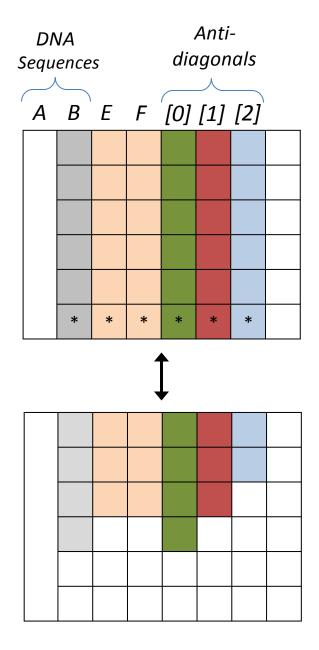


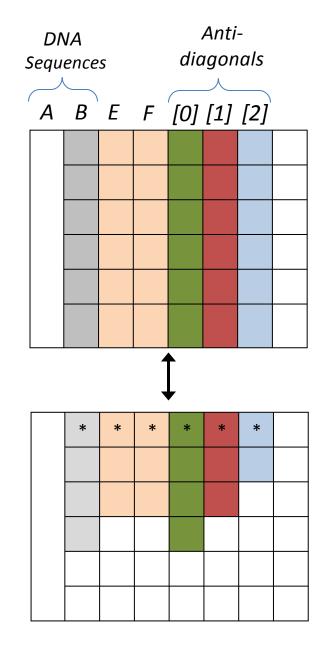
#### **ReCAM**

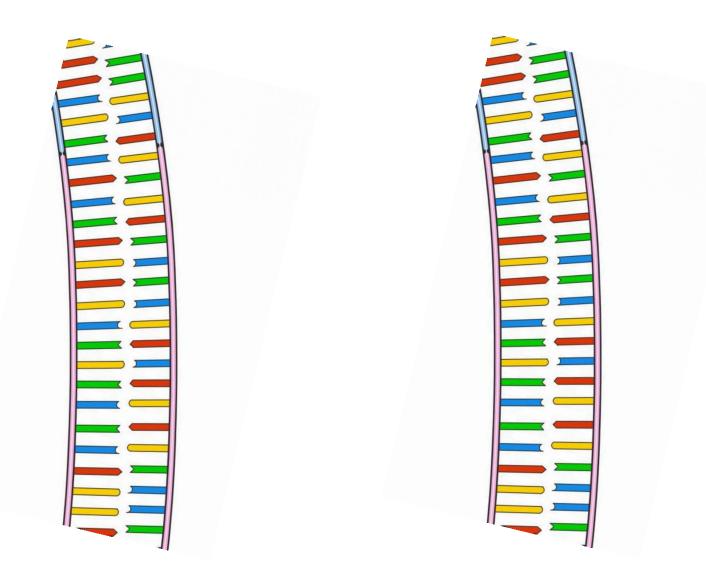
A B

$a_1$	$b_3$	4	J,1	
$a_2$	$b_2$	4	<del></del> ,2	
$a_3$	$b_1$	-	,3	
$a_4$		7		
$a_5$				
$a_6$				
$a_7$				
$a_8$				









(a) AD[2] AD[1] AD[0] Ε seqA seqB  $H_{1,i-3} | H_{1,i-1} | H_{1,i-2} | F_{1,i-1} | E_{1,i-1} | A_1 | B_{i-1}$  $\left| H_{2,i-4} \right| H_{2,i-2} \left| H_{2,i-3} \right| F_{2,i-2} \left| E_{2,i-2} \right| A_2 \left| B_{i-2} \right|$  $|H_{1,i-5}|H_{3,i-3}|H_{3,i-4}|F_{3,i-3}|E_{3,i-3}|A_3|B_{i-3}$  $|H_{i-2,2}|H_{i-2,1}|F_{i-2,2}|E_{i-2,2}|A_{i-2}|B_2$  $H_{i-1,1}$  $|F_{i-1,1}|E_{i-1,1}|A_{i-1}|B_1$  $A_i$  $A_{i+1}$ 

• • •

(b) D[2] AD[1] AD[0] F E

AD[2]	AD[1]	AD[0]	F	Ε	seqA	seqB
$H_{1,i}$	$H_{1,i-1}$	1 	$F_{1,i}$	$E_{1,i}$	$A_1$	$B_i$
$H_{2,i-1}$	$H_{2,i-2}$	$H_{1,i-2}$	$F_{2,i-1}$	$E_{2,i-1}$	$A_2$	$B_{i-1}$
$H_{3,i-2}$	$H_{3,i-3}$	$H_{2,i-3}$	$F_{3,i-2}$	$E_{3,i-2}$	$A_3$	$B_{i-2}$
			• • •			
$H_{i-2,3}$	$H_{i-2,2}$	$H_{i-3,2}$	$F_{i-2,3}$	$E_{i-2,3}$	$A_{i-2}$	$B_3$
$H_{i-1,2}$	$H_{i-1,1}$	$H_{i-2,1}$	$F_{i-1,2}$	$E_{i-1,2}$	$A_{i-1}$	$B_2$
$H_{i,1}$	1 	1 	$F_{i,1}$	$E_{i,1}$	$A_i$	$B_1$
	 	 	 	 	$A_{i+1}$	 
			•••			

(a)

F segA

AD[1]	AD[0]	F	Ε	seqA	seqB
$H_{1,i-1}$	$H_{1,i-2}$	$F_{1,i-1}$	$E_{1,i-1}$	$a_1$	$b_{i-1}$
$H_{2,i-2}$	$H_{2,i-3}$	$F_{2,i-2}$	$E_{2,i-2}$	$a_2$	$b_{i-2}$
$H_{3,i-3}$	$H_{3,i-4}$	$F_{3,i-3}$	$E_{3,i-3}$	$a_3$	$b_{i-3}$
		•••			
$H_{i-2,2}$	$H_{i-2,1}$	$F_{i-2,2}$	$E_{i-2,2}$	$a_{i-2}$	$b_2$
$H_{i-1,1}$	 	$F_{i-1,1}$	$E_{i-1,1}$	$a_{i-1}$	$b_1$
1 	 	1 	 	$a_i$	1 
 	 	I I I	 	$a_{i+1}$	 
	$H_{1,i-1}$ $H_{2,i-2}$ $H_{3,i-3}$	$H_{1,i-1}$ $H_{1,i-2}$ $H_{2,i-3}$ $H_{3,i-3}$ $H_{3,i-4}$ $H_{i-2,2}$ $H_{i-2,1}$	$H_{1,i-1}$ $H_{1,i-2}$ $F_{1,i-1}$ $H_{2,i-2}$ $H_{2,i-3}$ $F_{2,i-2}$ $H_{3,i-3}$ $H_{3,i-4}$ $F_{3,i-3}$	$H_{1,i-1}$ $H_{1,i-2}$ $F_{1,i-1}$ $E_{1,i-1}$ $H_{2,i-2}$ $H_{2,i-3}$ $F_{2,i-2}$ $E_{2,i-2}$ $H_{3,i-3}$ $H_{3,i-4}$ $F_{3,i-3}$ $E_{3,i-3}$	$a_i$

• • •

(b)

AD[2]	AD[1]	AD[0]	F	Ε	seqA	seqB
$H_{1,i}$	$H_{1,i-1}$		$F_{1,i}$	$E_{1,i}$	$a_1$	$b_i$
$H_{2,i-1}$	$H_{2,i-2}$	$H_{1,i-2}$	$F_{2,i-1}$	$E_{2,i-1}$	$a_2$	$b_{i-1}$
$H_{3,i-2}$	$H_{3,i-3}$	$H_{2,i-3}$	$F_{3,i-2}$	$E_{3,i-2}$	$a_3$	$b_{i-2}$
			• • •			
$H_{i-2,3}$	$H_{i-2,2}$	$H_{i-3,2}$	$F_{i-2,3}$	$E_{i-2,3}$	$a_{i-2}$	$b_3$
$H_{i-1,2}$	$H_{i-1,1}$	$H_{i-2,1}$	$F_{i-1,2}$	$E_{i-1,2}$	$a_{i-1}$	$b_2$
$H_{i,1}$	 	 	$F_{i,1}$	$E_{i,1}$	$a_i$	$b_1$
	 	 	 	 	$a_{i+1}$	 
			•••			
•						

(a)

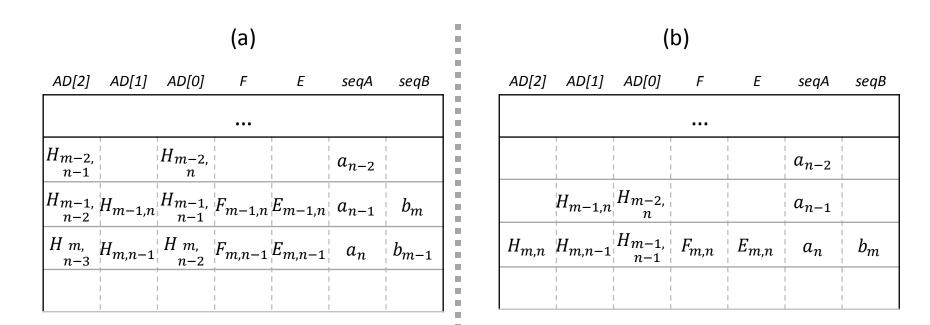
F AD[0] AD[1] AD[2]

Seq. A	Seq. B	Ε	F	AD[0]	AD[1]	AD[2]
$a_1$	$b_{i-1}$	$E_{1,i-1}$	$F_{1,i-1}$	$H_{1,i-2}$	$H_{1,i-1}$	$H_{1,i-3}$
$a_2$	$b_{i-2}$	$E_{2,i-2}$	$F_{2,i-2}$	$H_{2,i-3}$	$H_{2,i-2}$	$H_{2,i-4}$
$a_3$	$b_{i-3}$	$E_{3,i-3}$	$F_{3,i-3}$	$H_{3,i-4}$	$H_{3,i-3}$	$H_{1,i-5}$
			• • •			
$a_{i-2}$	$b_2$	$E_{i-2,2}$	$F_{i-2,2}$	$H_{i-2,1}$	$H_{i-2,2}$	 
$a_{i-1}$	$b_1$	$E_{i-1,1}$	$F_{i-1,1}$	 	$H_{i-1,1}$	 
$a_i$	 	 	 	 	 	 
$a_{i+1}$	 	 	 	 	 	 
			•••			

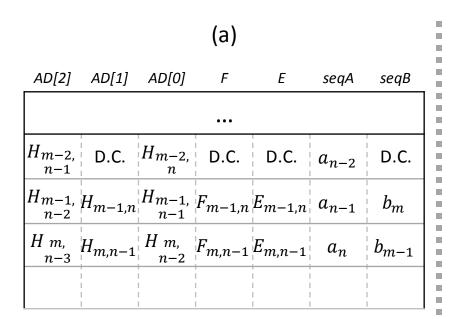
(b)

Seq. A	Seq. B	Ε	F	AD[0]	AD[1]	AD[2]
$a_1$	$b_i$	$E_{1,i}$	$F_{1,i}$	1 	$H_{1,i-1}$	$H_{1,i}$
$a_2$	$b_{i-1}$	$E_{2,i-1}$	$F_{2,i-1}$	$H_{1,i-2}$	$H_{2,i-2}$	$H_{2,i-1}$
$a_3$	$b_{i-2}$	$E_{3,i-2}$	$F_{3,i-2}$	$H_{2,i-3}$	$H_{3,i-3}$	$H_{3,i-2}$
			• • •			,
$a_{i-2}$	$b_3$	$E_{i-2,3}$	$F_{i-2,3}$	$H_{i-3,2}$	$H_{i-2,2}$	$H_{i-2,3}$
$a_{i-1}$	$b_2$	$E_{i-1,2}$	$F_{i-1,2}$	$H_{i-2,1}$	$H_{i-1,1}$	$H_{i-1,2}$
$a_i$	$b_1$	$E_{i,1}$	$F_{i,1}$	 	 	$H_{i,1}$
$a_{i+1}$	 	 	 	 	 	 
			• • •			

### Final iterations (last iteration)



#### Final iterations (last iteration)



(b)  $AD[2] \quad AD[1] \quad AD[0] \quad F \quad E \quad seqA \quad seqB$  ...D.C. D.C. D.C. D.C. D.C.  $a_{n-2}$  D.C.  $D.C. \quad H_{m-1,n} \stackrel{H_{m-2}}{\stackrel{n}{_{n-1}}} \quad D.C. \quad D.C. \quad a_{n-1} \quad D.C.$   $H_{m,n} \quad H_{m,n-1} \stackrel{H_{m-1}}{\stackrel{n-1}{_{n-1}}} \quad F_{m,n} \quad E_{m,n} \quad a_n \quad b_m$