

Multi-armed Bandits in Practice

Alexandr Vorobyev

Yandex

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- 1 Classic Multi-Armed Bandit Problem
- 2 Contextual Multi-Armed Bandit Problem

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Multi-Armed Bandit Problem



Multi-Armed Bandit Problem: Formalization

Setting

- A finite set of **arms** $\{a_1, a_2, \dots, a_k\}$
- We have T **steps (trials)**. At each step t :
 - We choose an arm $a_{j(t)}$.
 - We observe a **reward** $R_{j(t)}$ – **random** value, $ER_{j(t)} = r_{j(t)}$ ($R_{j(1)}, \dots, R_{j(T)}$ are independent).

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Objective

Maximize the expectation of **cumulative reward** $\sum_{t=1}^T R_{j(t)}$.

Multi-Armed Bandit Problem: Intuition

Let's try to play

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The problem of balancing between these two goals is known as **exploration–exploitation dilemma**.

Most important case

which often arises in practice:

- Reward R_j is a **Bernoulli random variable**:

$$P(R_j = 1) = r_j, P(R_j = 0) = 1 - r_j, ER_j = r_j.$$

- Parameter r_j has **uniform prior distribution** on $[0, 1]$.

Advertisement

- Problem setting: to **choose an ad** from the database to **show to a user in some known context**.
- Step = appearance of the context.
- Arm = ad.
- $R_{j(t)} = 1$, if the user clicked the ad $a_{j(t)}$, $= 0$ otherwise.
- r_j is known as CTR (click-through rate).

Multi-Armed Bandit Problem: practical examples

Information retrieval

- Problem setting: to **choose a document** from the database **to show to a user at the top position to some known query**.
- Step = an issue of the query.
- Arm = document.
- $R_{j(t)} = 1$, if the user clicked the document, = 0 otherwise.
- r_j is known as CTR at position 1.

Multi-Armed Bandit Problem: algorithms

Algorithms for Bernoulli R_j

Define an appropriate scoring $S_t(a)$, choose $j(t) = \operatorname{argmax}_j S_t(a_j)$.

- **UCB-1:** $S_t(a_j) = \widehat{r}_{t,j} + \alpha \sqrt{\frac{2 \ln t}{N_{t-1,j}}}$, where
 - $\widehat{r}_{a_j,t} = \frac{S_{t-1,j}}{N_{t-1,j}}$, $S_{t-1,j}$ ($N_{t-1,j}$) is the number of succesful (all) trials of a_j .
 - α is an exploration parameter (to be fitted to T).

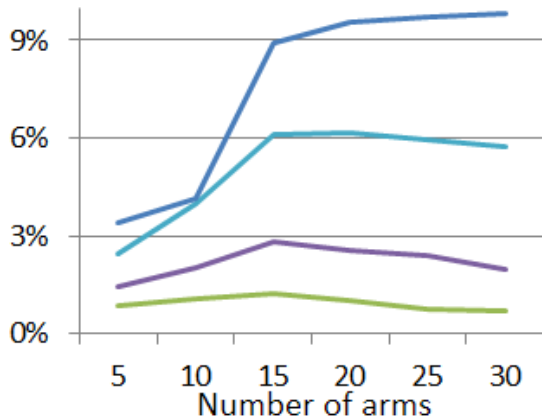
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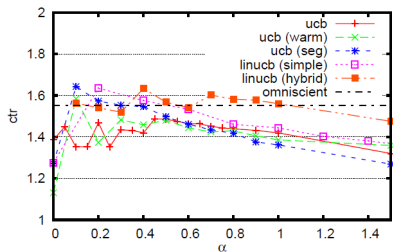
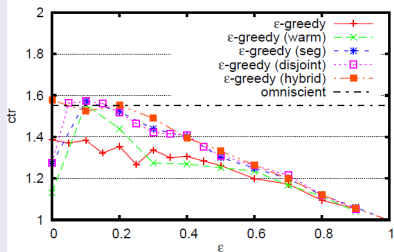
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 - α is an exploration parameter (to be fitted to T).
- **Bayesian approach**
 - Calculate posterior distribution of r_j :
 $p_{t,j}(r) \propto r^{S_{t-1,j}} (1-r)^{N_{t-1,j}-S_{t-1,j}} p_{0,j}(r)$
 - **Thompson sampling** algorithm: $S_t(a_j)$ is a sample from $p_{t,j}(r)$.
 - **Bayesian-UCB** algorithm: $S_t(a_j)$ is a $\alpha(t)$ -quantile of $p_{t,j}(r)$, $\alpha(t)$ is an exploration parameter (to be fitted to T).

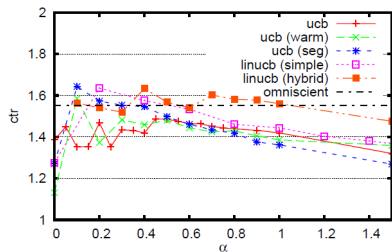
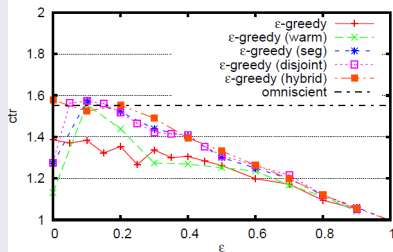
Number of arms



Exploration rate



Exploration rate



Bayes UCB: $\alpha(t) = 1 - \frac{1}{t \cdot (\log n)^c}$

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Contextual Multi-Armed Bandit Problem

Setting

- A set **A** of **arms**
 - finite: documents, objects for recommendation;
 - continuum: vectors of formula's coefficients.
- A set **C** of **contexts** (query, user, location, position, upper documents) with a distribution P_C on it.
- Arm-context pair $(a, c) \longleftrightarrow$ a feature vector $x_{a,c} \in \mathbb{R}^d$.

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 - We choose an arm $a(t) \in \mathbf{A}$.
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Contextual Multi-Armed Bandit Problem

What is new?

- We believe that $r(x)$ is continuous, Lipschitzian or smooth function on \mathbb{R}^d .
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General Idea

At step t , for each arm a_j , try to **estimate** $r(a(t), c(t))$ and **confidence** in this estimate (variance, confidence bounds) on the features $x_{a(t), c(t)}$ and the history of observations $\{x_{j(\tau), c(\tau)}, R_t\}_{\tau=1, \dots, T}$.

Adaptation of the classical MAB (for contexts)

[Hoffman; Radlinski; Sloan, Wang; our paper on WWW'15...]

- Divide \mathbf{C} into regions:
region=query (web search), region=user (recommendations).
- Run a separate bandit for each region.

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Analysis

- + The smaller region – the more specific feedback.
- The smaller region – more information ignored, the lower learning rate.

Effective for **small regions with a lot of feedback** (frequent queries, active users).

Context tree

[Slivkins, Radlinski, “zooming algorithm”]

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 - Choose one of nodes, choose an arm from it arbitrary, refer reward to the node.
 - Collected sufficient information for a node \implies substitute it by its children, use the information as prior for them.

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Analysis

- + Adaptive width of regions.
- Threshold-based aggregation of feedback.
- No approach to **construct a tree reflecting proximity of $r(a, c)$ over (a, c)** .

LinUCB: linear regression

[Lihong Li, Langford, Schapire]

- Linear regression for $r_{a,c}$
 - Disjoint model — aggregate over contexts:
$$E(r_{a,c}|x_{a,c}) = x_{a,c}^T \theta_a.$$

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 - Hybrid model — aggregate over contexts and arms:
$$E(r_{a,c}|x_{a,c}) = x_{a,c}^T \theta_a + x_{a,c}^T \xi.$$

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 $E(r_{a,c}|x_{a,c}) = x_{a,c}^T \theta_a + x_{a,c}^T \xi.$
 - Add $x_{a,c}^T \eta_g$ for any division of $\mathbf{A} \times \mathbf{C}$ into regions g ?
- $R_{a,c} = E(r_{a,c}|x_{a,c}) + \epsilon, E\epsilon = 0, |\epsilon| < b.$

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- At each step, obtain an upper confidence bound for $r_{a,c}$

Known approaches

LinUCB: linear regression

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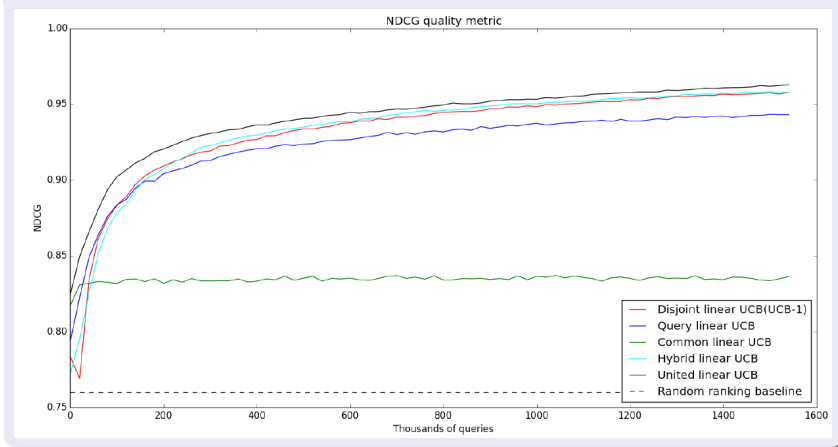
- + Learning dependence between clicks and features.
- Linearity.
- An upper bound is not in $[0, 1]$, logistic model is more preferable:

$$E(r_{a,c}|x_{a,c}) = \frac{1}{1 + e^{-x_{a,c}^T \theta_a}}$$

Disjoint LinUCB algorithm

```
0: Inputs:  $\alpha \in \mathbb{R}_+$ 
1: for  $t = 1, 2, 3, \dots, T$  do
2:   Observe features of all arms  $a \in \mathcal{A}_t$ :  $\mathbf{x}_{t,a} \in \mathbb{R}^d$ 
3:   for all  $a \in \mathcal{A}_t$  do
4:     if  $a$  is new then
5:        $\mathbf{A}_a \leftarrow \mathbf{I}_d$  ( $d$ -dimensional identity matrix)
6:        $\mathbf{b}_a \leftarrow \mathbf{0}_{d \times 1}$  ( $d$ -dimensional zero vector)
7:     end if
8:      $\hat{\boldsymbol{\theta}}_a \leftarrow \mathbf{A}_a^{-1} \mathbf{b}_a$ 
9:      $p_{t,a} \leftarrow \hat{\boldsymbol{\theta}}_a^\top \mathbf{x}_{t,a} + \alpha \sqrt{\mathbf{x}_{t,a}^\top \mathbf{A}_a^{-1} \mathbf{x}_{t,a}}$ 
10:   end for
11:   Choose arm  $a_t = \arg \max_{a \in \mathcal{A}_t} p_{t,a}$  with ties broken arbitrarily, and observe a real-valued payoff  $r_t$ 
12:    $\mathbf{A}_{a_t} \leftarrow \mathbf{A}_{a_t} + \mathbf{x}_{t,a_t} \mathbf{x}_{t,a_t}^\top$ 
13:    $\mathbf{b}_{a_t} \leftarrow \mathbf{b}_{a_t} + r_t \mathbf{x}_{t,a_t}$ 
14: end for
```

Experiments in web search



Gaussian process

[Vanchinathan, Nicolic, De Bona]

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- At each step, obtain normal posterior distribution for $f(x_{a,c})$.

$$\mu_t(\mathbf{s}, \mathbf{z}) = \mathbf{k}_t(\mathbf{s}, \mathbf{z})^T (\mathbf{K}_t + \mathbb{I})^{-1} \bar{\mathbf{y}}_t, \quad (3)$$

$$\sigma_t^2(\mathbf{s}, \mathbf{z}) = \kappa((\mathbf{s}, \mathbf{z}), (\mathbf{s}, \mathbf{z})) - \mathbf{k}_t(\mathbf{s}, \mathbf{z})^T (\mathbf{K}_t + \mathbb{I})^{-1} \mathbf{k}_t(\mathbf{s}, \mathbf{z}), \quad (4)$$

where $\mathbf{k}_t(\mathbf{s}, \mathbf{z}) = [\kappa((\mathbf{s}_1, \mathbf{z}_1), (\mathbf{s}, \mathbf{z})), \dots, \kappa((\mathbf{s}_t, \mathbf{z}_t), (\mathbf{s}, \mathbf{z}))]^T$ and \mathbf{K}_t is the positive semi-definite kernel matrix such that $\mathbf{K}_{t,i,j} = [\kappa((\mathbf{s}_i, \mathbf{z}_i), (\mathbf{s}_j, \mathbf{z}_j))]$.

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Analysis

- + General model (despite two normality assumptions).
- No approach to set $k(x, x')$.

Interesting? Have ideas how to do better?



You are welcome:

yandex.ru/jobs/vacancies/interns/intern_researcher