# Modelling Meta-awareness & Attentional control using deep parametric active inference framework<sup>1</sup>

Modeling in Neuroscience & elsewhere Supervised by Jean-Pierre Nadal

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Master MVA ● 2021-2022

<sup>&</sup>lt;sup>1</sup>Sandved-Smith et al., 2021

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Principles for modeling Meta-awaress and Attentional control in the brain Regulatory control strategy Computational modeling of mental action Active Inference (AI) Generative model Variational free energy (VFE)

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 Conclusion and perspectives Applications Conclusion Idea : Propose a formal model of awareness & attentional control through mental action

# Model particularities :

- relies on active inference framework
- casts mental action <sup>a</sup> as policy selection over higher-level cognitive states
- adds hierarchical level: model meta-awareness
  - $\Rightarrow$  modulates precision<sup>b</sup> mapping between observations & cognitive processes

agoal-directed internal behavior

bexpected confidence

# Simulation of cycle of attention & its regulation during an attentional task

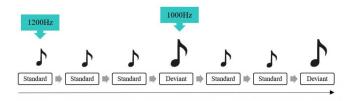


Figure 1: Example of auditory oddball paradigm task

Task: Detection deviant stimuli

⇒ involves sustained selective attention on a perceptual object

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# Meta-awareness (MA)

Ability to 'explicitly' notice current content of conscious episode.

### Enable effective self-regulation (of attention) by providing:

- Knowledge about objects & processes of experience (ACCESS )
- Revision of beliefs (EVALUATION)
- Increased control over cognitive processes (CONTROL)

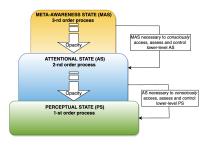


Figure 2: The 3 states as hierarchical levels. Higher order levels enable process to become aware of lower levels, i.e 'opaque' to the system.

# State accessibility : Opacity & transparency

# State accessibility

The capacity of a system to access some subset of its own states has been theorized under the rubric of 'opacity' versus 'transparency' <sup>2</sup>.

#### Mental states can be decomposed into:

- Opaque states: Cognitive processes constructing these states perceptible as such, available to awareness.
- Transparent states: Cognitive processes constructing these states imperceptible as such. Only aware of the content they make available.

<sup>&</sup>lt;sup>2</sup> Metzinger, T. (2003). Phenomenal transparency and cognitive self-reference

# Assumptions of the project

- Conscious mental action is grounded in higher-level access to cognitive states
- Distinction between opaque vs transparent states & processes can be formalized under deep active inference framework
- Understanding inferential architecture ⇒ advanced for formal, computational neurophenomenological account of cognitive control

# Goals of the project

- Explicitly model meta-awareness (MA) states (as a 3rd order level)
- Account for the computational & phenomenal consequences of MA and attentional states on cognitive control
- Provide a computational account of mental (covert) action
- Extend the work from Sandved-Smith et al., (2021) to simulate ADHD condition

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# Regulatory cognitive control strategy

# Computational architecture

Agent seeks to control/regulate their mental states by becoming aware of the state as a cognitive process (opacity <sup>3</sup>)

⇒ need notion of confidence/reliability in effective self regulation :

#### Precision

Quantifies confidence/reliability of implicit (posterior Bayesian) beliefs :

- knowledge about states of the world
- their relation to sensory observations
- how they change over time

 $<sup>^3</sup>$ gives access new source of data, allowing for further processing & action over state

# Computational modeling of mental action

#### Goals

- 1 Implementation self-reflective, hierarchically structured inferences
- 2 Simulate attentional control dynamics linked with :
  - cognitive opacity
  - mental action selection

# Implementation: parametrically deep active inference framework

#### Active inference

- neurocognitive & behavioral modeling framework
- knowledge driven action & perception
- adaptation in dynamical & embodied environment
- $\Rightarrow$  gather evidences for embodied and enactive generative model

# Parametric depth

- cognitive architecture property
- nested beliefs/knowledge structures
- inferential results as data for further processings
- ⇒ access to self-states & meta awareness

# Active Inference framework (AI)

# Offers a unified mathematical framework for modeling cognitive processes (perception, learning, decision making)

 $\Rightarrow$  treats each of these psychological processes, and their interactions, as interdependent forms of inference :

Idea: cognitive agents are assumed to infer the probability of different external states and events in the environment

#### The inferences are:

- Created by combining prior beliefs with sensory (internal or external) inputs
- Active: the agent infers the actions most likely to generate preferred sensory input
- $\Rightarrow$  Leads to preference towards actions optimizing trade-off between reward and information gain

# Active Inference framework (AI)

#### Based on 2 concepts

- Agent actively engage with their environments to gather information, seek out 'preferred' observations, and avoid non-desired observations
- Bayesian inference: statistical procedure describing the optimal way to update one's beliefs (i.e probability distributions) when making new observations (i.e new sensory input) based on the rules of probability

 $\Rightarrow$  Beliefs updated in light of observations using Baye's theorem : Variational inference : find the posterior distribution p(s|o) to infer how the states s of the world have changed based on new observations o. This corresponds to finding the posterior distribution p(s|o). However, the calculation of the marginal likelihood p(o) is

#### Generative models

**Active inference agents**: must deploy inference and action to guesstimate their generative processes and structure

Generative model: probabilistic model of the process that generated this (sensory) data <sup>4</sup>

⇒ capture dynamics of how the environment generates observations.

### Variational free energy

#### Quantifies:

- how much evidence for the model is provided by the data
- discrepancy between observed outcomes (i.e. the sensory states of organism) & outcomes predicted under statistical (generative) model

<sup>&</sup>lt;sup>4</sup>Friston et al. 2016

# Basic Generative models of perception

#### Parameters:

• D: initial state vector  $p(S_1)$   $\Rightarrow$  Encodes prior beliefs about initial hidden states  $S_t$ 

S : Hidden state

 $\Rightarrow$  causing O• A: likelihood mapping  $p(O_t|S_t)$   $\Rightarrow$  Encodes beliefs about the relationship hidden states  $(S_t)$ 

and observable outcomes  $(O_t)$ 

- O : Observable outcomes  $\Rightarrow$  caused by S
- $\bar{S}$  : Approximated most probable state  $p(S|\bar{o})$ .

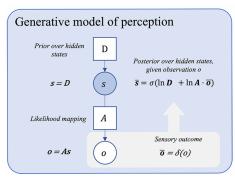


Figure 3: Basic generative model of perception.

# Markovian Active inference generative model

#### Implements beliefs about state transitions, noted B

 $\Rightarrow$  controls observations through selection of actions (policy selection).

#### Additional parameters :

- C: prior preference mapping  $p(S_1)$   $\Rightarrow$  prior beliefs about sensory outcomes  $\hat{o}$
- ullet E: prior over policies
- B (matrices): serries of beliefs about state transitions
- π : policy selection
   ⇒ selecting the sequence of B
   associated with least expected free
   energy min(G) (i.e minimizes
   'ambiguity' and 'risk')
- G: expected free energy.

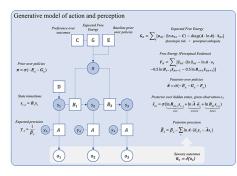


Figure 4: Generative model of action & perception.

# Markovian Generative models: Functional anatomy overview

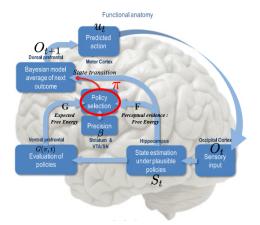


Figure 5: Overview of belief updates for discrete Markovian models and processes assignment to functional anatomy.<sup>5</sup> Sensory evidence  $(O_t)$  is accumulated to optimise expectations about the current state  $(S_t)$ , which are constrained by expectations of past  $(S_{t-1})$  & future  $(S_{t+1})$  states. Corresponds to state estimation under each policy the agent entertainments. Once an action has been selected, it generates a new observation  $(O_{t+1})$  and the cycle begins again.

<sup>&</sup>lt;sup>5</sup>adapted from (Friston et al., 2016)

# Variational free energy (VFE)

Variational free energy quantifies the discrepancy between observed outcomes (i.e. the sensory states of an organism) and the outcomes that would be predicted under a statistical (generative) model of how their sensory data were produced

Idea I: Al assumes that perception and learning can be understood as minimizing a quantity known as **Variational free energy (FE)** 

Idea II: The role of action selection (policy) is to minimize the **expected** free energy (EFE)

- $\Rightarrow$  EFE quantifies the VFE of various actions based on expected future outcomes
- $\Rightarrow$  Use Bayesian inference framework to use and derive these quantities

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# Parametrical deep active inference

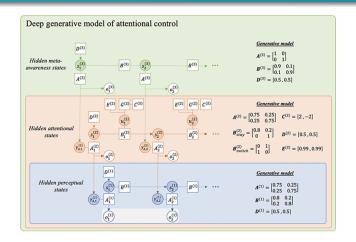
#### Limitation active inference:

Do not model agent's access, evaluation & control of its own attentional states (i.e no meta-awareness)

#### Extension

- deep, higher-level hierarchical architecture
- higher level policy selection over attentional states
- parametric depth : precision-dependant state inference

# Probabilistic Graphical Model of mental action : Active Inference architecture



- First-order level : perception of the external environment  $S^{(1)}$
- Second-order level : perception of internal attentional states  $S^{(2)}$
- ullet Third-order level : perception of meta-awareness states  $S^{(3)}$

Influence of attentional states on lower-order (perceptual) states - non-ADHD condition

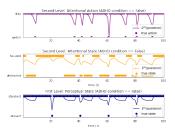


Figure 6: Replication in non-ADHD state. Attentional states during the first and second part of the experiment have been respectively set to "focus" and "distracted".

Influence of attentional states on lower-order (perceptual) states - non-ADHD condition

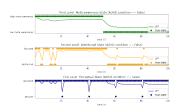


Figure 7: Replication in non-ADHD condition. Implementation of the 3-rd state level (meta-awareness level)

# Simulating Attentional Deficit condition

### Influence of attentional states on lower-order (perceptual) states - ADHD condition

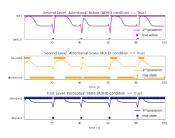


Figure 8: Replication in ADHD state. Attentional states during the first and second part of the experiment have been respectively set to "focus" and "distracted".

# Influence of attentional states on lower-order (perceptual) states - ADHD condition

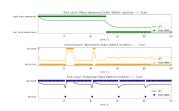


Figure 9: Replication in ADHD condition. Implementation of the 3-rd state level (meta-awareness level)

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# **Applications**

Control of cognitive (attentional) state through mental action involved in psychiatric conditions.

- ADHD
- Schizophrenia (Brown et al., 2013)
- Autism spectrum (Kiverstein et al., 2020)

Perceptual, mood, thinking dysfunctions:

- ⇒ Atypical inferences about higher-order states a control
- ⇒ Erroneous control associated processes

<sup>&</sup>lt;sup>a</sup>Higher-order: govern attribution of lower-level (eg perception) confidence

#### Conclusion

Computational implementation of **inferential architecture** enabling emergence of ability to access & control cognitive states.

- Interesting model to formalize specific phenomenal properties (here transparency and opacity of cognitive states, with respect to attention, and meta-cognition states)
- Framework presents as an interesting avenue to shed lights on the influence of priors in behavioral outcome.
- Particularly interesting for areas of research that are interested in studying variational properties of universal and individual features (e.g metacognitive skills) across states, cultures, conditions

# Thank you for your attention!

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Github of this project available here