



## Experiment - 8

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**Subject Name:** Design and Analysis of Algorithms

**Subject Code:** 23CSH-301

1. **Aim:** Develop a program and analyze complexity to find shortest paths in a graph with positive edgeweights using Dijkstra's algorithm.
2. **Objective:** Code and analyze to find shortest paths in a graph with positive edge weights using Dijkstra's
3. **Input/Apparatus Used:** Graph (  $G=(V,E)$  ) is taken as input for this problem.

### 4. Procedure:

Follow the steps below to solve the problem:

- Create a set sptSet (shortest path tree set) that keeps track of vertices included in the shortest- path tree, i.e., whose minimum distance from the source is calculated and finalized. Initially, this set is empty.
- Assign a distance value to all vertices in the input graph. Initialize all distance values as INFINITE. Assign the distance value as 0 for the source vertex so that it is picked first.
- While sptSet doesn't include all vertices
- Pick a vertex u which is not there in sptSet and has a minimum distance value.
- Include u to sptSet.
- Then update distance value of all adjacent vertices of u.
- To update the distance values, iterate through all adjacent vertices.

- For every adjacent vertex  $v$ , if the sum of the distance value of  $u$  (from source) and weight of edge  $u-v$ , is less than the distance value of  $v$ , then update the distance value of  $v$ .

## 5. Algorithm

- **Step 1:** SET STATUS = 1 (ready state) for each node in  $G$
- **Step 2:** Push the starting node  $A$  on the stack and set its STATUS = 2 (waiting state)
- **Step 3:** Repeat Steps 4 and 5 until STACK is empty
- **Step 4:** Pop the top node  $N$ . Process it and set its STATUS = 3 (processed state)
- **Step 5:** Push on the stack all the neighbours of  $N$  that are in the ready state (whose STATUS = 1) and set their STATUS = 2 (waiting state)  
[END OF LOOP]
- **Step 6:** EXIT

## 6. Code and Output:

```
#include <bits/stdc++.h>

using namespace std;

#define INF INT_MAX

int minDistance(vector<int>& dist, vector<bool>& sptSet, int V) {

    int minVal = INF, minIndex = -1;

    for (int v = 0; v < V; v++) {

        if (!sptSet[v] && dist[v] <= minVal) {

            minVal = dist[v];

            minIndex = v;

        }

    }
```



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```
    }

    return minIndex;
}

void printSolution(vector<int>& dist, int V) {

    cout << "\nVertex\tDistance from Source\n";

    for (int i = 0; i < V; i++)

        cout << i << "\t\t" << dist[i] << "\n";

}

void dijkstra(vector<vector<int>>& graph, int src, int V) {

    vector<int> dist(V, INF);

    vector<bool> sptSet(V, false);

    dist[src] = 0;

    for (int count = 0; count < V - 1; count++) {

        int u = minDistance(dist, sptSet, V);

        sptSet[u] = true;

        for (int v = 0; v < V; v++) {

            if (!sptSet[v] && graph[u][v] && dist[u] != INF &&
```



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```
        dist[u] + graph[u][v] < dist[v]) {  
            dist[v] = dist[u] + graph[u][v];  
        }  
    }  
}  
  
printSolution(dist, V);  
  
}  
  
int main() {  
    cout << "DIJKSTRA'S ALGORITHM - SHORTEST PATH FINDER\n\n";  
    int V;  
    cout << "Enter number of vertices: ";  
    cin >> V;  
  
    vector<vector<int>> graph(V, vector<int>(V, 0));  
    cout << "\nEnter the adjacency matrix (0 for no edge):\n";  
    for (int i = 0; i < V; i++) {  
        for (int j = 0; j < V; j++)  
            cin >> graph[i][j];  
    }
```

```
int src;  
  
cout << "\nEnter source vertex (0 to " << V - 1 << "): ";  
  
cin >> src;  
  
dijkstra(graph, src, V);  
  
return 0;  
  
}
```

Output	
DIJKSTRA'S ALGORITHM - SHORTEST PATH FINDER	
Enter number of vertices: 5	
Enter the adjacency matrix (0 for no edge):	
0	10 0 5 0
0	0 1 2 0
0	0 0 0 4
0	3 9 0 2
7	0 6 0 0
Enter source vertex (0 to 4): 0	
Vertex	Distance from Source
0	0
1	8
2	9
3	5
4	7