#### Computation Tree Logic

Luis Tertulino & Ronaldo Silveira

October 19, 2015

#### In previous chapters... Temporal Logic

Motivation and Intuition Motivation Intuition

How to communicate Syntax of CTL Semanthics of CTL

#### In previous chapters... Temporal Logic

Motivation and Intuition Motivation Intuition

How to communicate
Syntax of CTL
Semanthics of CTL

Previously on Temporal Logic Week...

Temporal Logic

### In previous chapters... Temporal Logic

# Motivation and Intuition Motivation

How to communicate Syntax of CTL Semanthics of CTL

#### Motivation

Needing of uncertainty;

#### Motivation

Needing of uncertainty; Different paths of the future;

### In previous chapters... Temporal Logic

## Motivation and Intuition Motivation

Intuition

How to communicate
Syntax of CTL
Semanthics of CTL

#### Intuition

In Computation Tree Logic (CTL) the model of time is a tree-like structure. This way, we cannot use Linear Temporal Logic (LTL) to express the existence of a certain path of time in which some event occurs.

### In previous chapters.. Temporal Logic

Motivation and Intuition Motivation Intuition

How to communicate Syntax of CTL Semanthics of CTL Syntax Definition

The syntax of CTL consists on the syntax of temporal logic plus some path operators. The class of formulas can be defined in Backus-Naur form. If  $\phi$  is a formula:

### Syntax Definition

The syntax of CTL consists on the syntax of temporal logic plus some path operators. The class of formulas can be defined in Backus-Naur form. If  $\phi$  is a formula:

$$\phi ::= \bot \mid \top \mid p \mid \neg \phi \mid \phi \land \phi \mid \phi \lor \phi \mid \phi \rightarrow \phi \mid \mathsf{AX}\phi \mid \mathsf{EX}\phi \mid$$
 
$$\mathsf{AF}\phi \mid \mathsf{EF}\phi \mid \mathsf{AG}\phi \mid \mathsf{EG}\phi \mid \mathsf{A}[\phi\mathsf{U}\phi] \mid \mathsf{E}[\phi\mathsf{U}\phi]$$

### Syntax Definition

The syntax of CTL consists on the syntax of temporal logic plus some path operators. The class of formulas can be defined in Backus-Naur form. If  $\phi$  is a formula:

$$\begin{split} \phi ::= \bot \mid \top \mid \rho \mid \neg \phi \mid \phi \land \phi \mid \phi \lor \phi \mid \phi \to \phi \mid \mathsf{AX}\phi \mid \mathsf{EX}\phi \mid \\ \mathsf{AF}\phi \mid \mathsf{EF}\phi \mid \mathsf{AG}\phi \mid \mathsf{EG}\phi \mid \mathsf{A}[\phi \mathsf{U}\phi] \mid \mathsf{E}[\phi \mathsf{U}\phi] \end{split}$$

With p as a literal (atomic formula), AX, EX, AF, EF, AG e EG unary operators.

## Syntax Intuition

The propositional operators:  $\neg, \vee, \wedge, \to$  have the same meaning of in the propositional logic.

## Syntax

The propositional operators:  $\neg, \lor, \land, \rightarrow$  have the same meaning of in the propositional logic.

The temporal operators can be read (if  $\varphi$  is a formula) as follows:

## Syntax Intuition

The propositional operators:  $\neg, \lor, \land, \rightarrow$  have the same meaning of in the propositional logic.

The temporal operators can be read (if  $\varphi$  is a formula) as follows:

 $A\phi$ :  $\varphi$  is true in all possible paths;

#### Syntax Intuition

The propositional operators:  $\neg, \lor, \land, \rightarrow$  have the same meaning of in the propositional logic.

The temporal operators can be read (if  $\varphi$  is a formula) as follows:

 $A\phi$ :  $\varphi$  is true in all possible paths;

 $\mathsf{E}\phi$ :  $\varphi$  exists a path in which  $\phi$  is true;

#### Syntax Intuition

The propositional operators:  $\neg, \lor, \land, \rightarrow$  have the same meaning of in the propositional logic.

The temporal operators can be read (if  $\varphi$  is a formula) as follows:

 $A\phi$ :  $\varphi$  is true in all possible paths;

 $\mathrm{E}\phi$ :  $\varphi$  exists a path in which  $\phi$  is true;

The path-specific operators can be read, considering  $\varphi$  and  $\psi$  formulas, as:

#### Syntax Intuition

The propositional operators:  $\neg, \lor, \land, \rightarrow$  have the same meaning of in the propositional logic.

The temporal operators can be read (if  $\varphi$  is a formula) as follows:

 $A\phi$ :  $\varphi$  is true in all possible paths;

 $\mathbf{E}\phi$ :  $\varphi$  exists a path in which  $\phi$  is true;

The path-specific operators can be read, considering  $\varphi$  and  $\psi$  formulas, as:

 $X\phi: \varphi$  is true until next state;

### Syntax

The propositional operators:  $\neg, \lor, \land, \rightarrow$  have the same meaning of in the propositional logic.

The temporal operators can be read (if  $\varphi$  is a formula) as follows:

 $A\phi$ :  $\varphi$  is true in all possible paths;

 $\mathbf{E}\phi$ :  $\varphi$  exists a path in which  $\phi$  is true;

The path-specific operators can be read, considering  $\varphi$  and  $\psi$  formulas, as:

 $X\phi: \varphi$  is true until next state;

 ${
m F} \varphi$  : There is some state in the future where  $\varphi$  is true;

## Syntax Intuition

The propositional operators:  $\neg, \lor, \land, \rightarrow$  have the same meaning of in the propositional logic.

The temporal operators can be read (if  $\varphi$  is a formula) as follows:

 $A\phi$ :  $\varphi$  is true in all possible paths;

 $\mathsf{E}\phi$ :  $\varphi$  exists a path in which  $\phi$  is true;

The path-specific operators can be read, considering  $\varphi$  and  $\psi$  formulas, as:

 $X\phi: \varphi$  is true until next state;

 ${
m F} \varphi$  : There is some state in the future where  $\varphi$  is true;

 $G\varphi$ : Globally (in all future states)  $\varphi$  is true;

## Syntax Intuition

The propositional operators:  $\neg, \lor, \land, \rightarrow$  have the same meaning of in the propositional logic.

The temporal operators can be read (if  $\varphi$  is a formula) as follows:

 $A\phi$ :  $\varphi$  is true in all possible paths;

 $\mathbf{E}\phi$ :  $\varphi$  exists a path in which  $\phi$  is true;

The path-specific operators can be read, considering  $\varphi$  and  $\psi$  formulas, as:

 $X\phi: \varphi$  is true until next state;

 ${
m F} \varphi$  : There is some state in the future where  $\varphi$  is true;

 $G\varphi$ : Globally (in all future states)  $\varphi$  is true;

 $\varphi U \psi$ :  $\varphi$  is true at least until  $\psi$  becomes true;

Notice that, in CTL, the combination of path specific operators and temporal operators are atomic, i.e., AF is a operator that can be read as "In all paths in the future there is some state where..."

Notice as well that the binary operators A[ $\varphi$ U $\psi$ ] and E[ $\varphi$ U $\psi$ ] can be represented as AU

We assume that, similarly to the  $\neg$  operator, the "new" unary operators (AX, EX, AF, EF, AG, and EG) have the first precedence. Next comes the  $\land$  and  $\lor$  operators. And at last the  $\rightarrow$ , AU and EU

Examples of well-formed formulas:  $AG(p \lor EFq)$ 

Examples of well-formed formulas:

$$\mathtt{AG}(p \lor \mathtt{EF}q) \ \mathtt{AX}(q \to \mathtt{E}[(p \lor q)\mathtt{U}r])$$

Examples of well-formed formulas:

$$\begin{array}{l} \operatorname{AG}(p \vee \operatorname{EF}q) \\ \operatorname{AX}(q \to \operatorname{E}[(p \vee q)\operatorname{U}r]) \\ \operatorname{EFEG}p \to \operatorname{AF}r \text{ Note that this is binded as} \\ (\operatorname{EFEG}p) \to \operatorname{AF}r, \text{ not as } \operatorname{EFEG}(p \to \operatorname{AF}r) \end{array}$$

Examples of well-formed formulas:

$$\begin{array}{l} \operatorname{AG}(p \vee \operatorname{EF}q) \\ \operatorname{AX}(q \to \operatorname{E}[(p \vee q)\operatorname{U}r]) \\ \operatorname{EFEG}p \to \operatorname{AF}r \text{ Note that this is binded as} \\ (\operatorname{EFEG}p) \to \operatorname{AF}r, \text{ not as } \operatorname{EFEG}(p \to \operatorname{AF}r) \end{array}$$

Example of formulas that are not well-formed:

$$A \neg G \neg p$$

Examples of well-formed formulas:

$$AG(p \lor EFq)$$
 $AX(q \to E[(p \lor q)Ur])$ 
 $EFEGp \to AFr$  Note that this is binded as  $(EFEGp) \to AFr$ , not as  $EFEG(p \to AFr)$ 

Example of formulas that are not well-formed:

$$A \neg G \neg p$$
 $F[pUs]$ 

Examples of well-formed formulas:

$$\begin{array}{l} \operatorname{AG}(p \vee \operatorname{EF}q) \\ \operatorname{AX}(q \to \operatorname{E}[(p \vee q)\operatorname{U}r]) \\ \operatorname{EFEG}p \to \operatorname{AF}r \text{ Note that this is binded as} \\ (\operatorname{EFEG}p) \to \operatorname{AF}r, \text{ not as } \operatorname{EFEG}(p \to \operatorname{AF}r) \end{array}$$

Example of formulas that are not well-formed:

$$A \neg G \neg p$$
 $F[pUs]$ 
 $A[pUs \land qUs]$ 

### In previous chapters... Temporal Logic

Motivation and Intuition Motivation Intuition

How to communicate
Syntax of CTL
Semanthics of CTL

Definition of model

Different from usual logics, CTL formulas are interpreted by a transition system. Given an set of atoms:

Definition of model

Different from usual logics, CTL formulas are interpreted by a transition system. Given an set of atoms:

#### Definition (1)

A transition system  $\mathcal{M}$  is a triple  $\mathcal{M}=(S,\to,L)$  in which S is a set of states,  $\to$  is a binary relation over S ( $\to\subseteq S\times S$ ) and  $L:S\to\mathcal{P}(Atoms)$  is a labelling function.

Definition of model

Different from usual logics, CTL formulas are interpreted by a transition system. Given an set of atoms:

#### Definition (1)

A transition system  $\mathcal{M}$  is a triple  $\mathcal{M}=(S,\to,L)$  in which S is a set of states,  $\to$  is a binary relation over S ( $\to\subseteq S\times S$ ) and  $L:S\to\mathcal{P}(Atoms)$  is a labelling function.

#### Definition (2)

A model is a duple  $\mathcal{M}, s$  in which  $\mathcal{M}$  is a transition system and s is a state.

Definition of model

Different from usual logics, CTL formulas are interpreted by a transition system. Given an set of atoms:

#### Definition (1)

A transition system  $\mathcal{M}$  is a triple  $\mathcal{M}=(S,\to,L)$  in which S is a set of states,  $\to$  is a binary relation over S ( $\to\subseteq S\times S$ ) and  $L:S\to\mathcal{P}(Atoms)$  is a labelling function.

#### Definition (2)

A model is a duple  $\mathcal{M}, s$  in which  $\mathcal{M}$  is a transition system and s is a state.

**Notation:** we will use  $\mathcal{M}, s \vDash \varphi$  to say that the model  $\mathcal{M}, s$  satisfies the formula  $\varphi$ 

Satisfaction

$$\mathcal{M}, s \vDash \top$$
 and  $\mathcal{M}, s \not\vDash \bot$  for all  $s \in S$ 

Satisfaction

$$\mathcal{M}, s \vDash \top$$
 and  $\mathcal{M}, s \not\vDash \bot$  for all  $s \in S$   
 $\mathcal{M}, s \vDash p$  iff  $p \in L(S)$ 

Satisfaction

$$\mathcal{M}, s \vDash \top$$
 and  $\mathcal{M}, s \not\vDash \bot$  for all  $s \in S$   
 $\mathcal{M}, s \vDash p$  iff  $p \in L(S)$   
 $\mathcal{M}, s \vDash \neg \varphi$  iff  $\mathcal{M}, s \not\vDash \varphi$ 

#### Satisfaction

$$\mathcal{M}, s \vDash \top$$
 and  $\mathcal{M}, s \not\vDash \bot$  for all  $s \in S$   
 $\mathcal{M}, s \vDash p$  iff  $p \in L(S)$   
 $\mathcal{M}, s \vDash \neg \varphi$  iff  $\mathcal{M}, s \not\vDash \varphi$   
 $\mathcal{M}, s \vDash \varphi_1 \land \varphi_2$  iff  $\mathcal{M}, s \vDash \varphi_1$  AND  $\mathcal{M}, s \vDash \varphi_2$ 

#### Satisfaction

$$\begin{split} \mathcal{M},s &\vDash \top \text{ and } \mathcal{M},s \not\vDash \bot \text{ for all } s \in S \\ \mathcal{M},s &\vDash \rho \text{ iff } \rho \in L(S) \\ \mathcal{M},s &\vDash \neg \varphi \text{ iff } \mathcal{M},s \not\vDash \varphi \\ \mathcal{M},s &\vDash \varphi_1 \land \varphi_2 \text{ iff } \mathcal{M},s \vDash \varphi_1 \text{ AND } \mathcal{M},s \vDash \varphi_2 \\ \mathcal{M},s &\vDash \varphi_1 \lor \varphi_2 \text{ iff } \mathcal{M},s \vDash \varphi_1 \text{ OR } \mathcal{M},s \vDash \varphi_2 \end{split}$$

#### Satisfaction

$$\begin{split} \mathcal{M},s &\vDash \top \text{ and } \mathcal{M},s \not\vDash \bot \text{ for all } s \in S \\ \mathcal{M},s &\vDash p \text{ iff } p \in L(S) \\ \mathcal{M},s &\vDash \neg \varphi \text{ iff } \mathcal{M},s \not\vDash \varphi \\ \mathcal{M},s &\vDash \varphi_1 \land \varphi_2 \text{ iff } \mathcal{M},s \vDash \varphi_1 \text{ AND } \mathcal{M},s \vDash \varphi_2 \\ \mathcal{M},s &\vDash \varphi_1 \lor \varphi_2 \text{ iff } \mathcal{M},s \vDash \varphi_1 \text{ OR } \mathcal{M},s \vDash \varphi_2 \\ \mathcal{M},s &\vDash \varphi_1 \to \varphi_2 \text{ iff } \mathcal{M},s \not\vDash \varphi_1 \text{ OR } \mathcal{M},s \vDash \varphi_2 \end{split}$$

Satisfaction

Take an arbitrary model  $\mathcal{M}$ . Let  $s, s_1, s_2, s_3$  be states in S. Let  $\varphi, \varphi_1, \varphi_2$  be well-formed formulas of CTL. And let p be an atom. The satisfaction of CTL formulas can be defined as follows:

 $\mathcal{M}, s \vDash \mathtt{AX}\varphi$  iff for all  $s_1$  that  $s \to s_1$  and  $\mathcal{M}, s_1 \vDash \varphi$ . Thus,  $\mathtt{AX}$  says: "in every next state..."

Satisfaction

Take an arbitrary model  $\mathcal{M}$ . Let  $s, s_1, s_2, s_3$  be states in S. Let  $\varphi, \varphi_1, \varphi_2$  be well-formed formulas of CTL. And let p be an atom. The satisfaction of CTL formulas can be defined as follows:

 $\mathcal{M}, s \vDash \mathtt{AX}\varphi$  iff for all  $s_1$  that  $s \to s_1$  and  $\mathcal{M}, s_1 \vDash \varphi$ . Thus, AX says: "in every next state..."

 $\mathcal{M}, s \vDash \mathtt{EX}\varphi$  iff exists  $s_1$  that  $s \to s_1$  and  $M, s_1 \vDash \varphi$ . This, EX says: "in some next state..."