Computation Tree Logic

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In previous chapters... Temporal Logic

Motivation and Intuition Motivation Intuition

How to communicate Syntax of CTL Semanthics of CTL

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How to communicate
Syntax of CTL
Semanthics of CTL

Previously on Temporal Logic Week...

Temporal Logic

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Motivation and Intuition Motivation

How to communicate Syntax of CTL Semanthics of CTL

Motivation

Needing of uncertainty;

Motivation

Needing of uncertainty; Different paths of the future;

In previous chapters... Temporal Logic

Motivation and Intuition Motivation

Intuition

How to communicate
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Intuition

In Computation Tree Logic (CTL) the model of time is a tree-like structure. This way, we cannot use Linear Temporal Logic (LTL) to express the existence of a certain path of time in which some event occurs.

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Motivation and Intuition Motivation Intuition

How to communicate Syntax of CTL Semanthics of CTL Syntax Definition

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With p as a literal (atomic formula), AX, EX, AF, EF, AG e EG unary operators.

Syntax Intuition

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m F} \varphi$: There is some state in the future where φ is true;

 $G\varphi$: Globally (in all future states) φ is true;

 $\varphi U \psi$: φ is true at least until ψ becomes true;

Notice that, in CTL, the combination of path specific operators and temporal operators are atomic, i.e., AF is a operator that can be read as "In all paths in the future there is some state where..."

Notice as well that the binary operators A[φ U ψ] and E[φ U ψ] can be represented as AU

We assume that, similarly to the \neg operator, the "new" unary operators (AX, EX, AF, EF, AG, and EG) have the first precedence. Next comes the \land and \lor operators. And at last the \rightarrow , AU and EU

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A transition system \mathcal{M} is a triple $\mathcal{M}=(S,\to,L)$ in which S is a set of states, \to is a binary relation over S ($\to\subseteq S\times S$) and $L:S\to\mathcal{P}(Atoms)$ is a labelling function.

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Notation: we will use $\mathcal{M}, s \vDash \varphi$ to say that the model \mathcal{M}, s satisfies the formula φ

Satisfaction

Take an arbitrary model \mathcal{M} . Let s, s_1, s_2, s_3 be states in S. Let $\varphi, \varphi_1, \varphi_2$ be well-formed formulas of CTL. And let p be an atom. The satisfaction of CTL formulas can be defined as follows:

 $\mathcal{M}, s \vDash \top$ and $\mathcal{M}, s \not\vDash \bot$ for all $s \in S$

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 $\mathcal{M}, s \vDash \varphi_1 \land \varphi_2$ iff $\mathcal{M}, s \vDash \varphi_1$ AND $\mathcal{M}, s \vDash \varphi_2$

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$$\begin{split} \mathcal{M},s &\vDash \top \text{ and } \mathcal{M},s \not\vDash \bot \text{ for all } s \in S \\ \mathcal{M},s &\vDash \rho \text{ iff } \rho \in L(S) \\ \mathcal{M},s &\vDash \neg \varphi \text{ iff } \mathcal{M},s \not\vDash \varphi \\ \mathcal{M},s &\vDash \varphi_1 \land \varphi_2 \text{ iff } \mathcal{M},s \vDash \varphi_1 \text{ AND } \mathcal{M},s \vDash \varphi_2 \\ \mathcal{M},s &\vDash \varphi_1 \lor \varphi_2 \text{ iff } \mathcal{M},s \vDash \varphi_1 \text{ OR } \mathcal{M},s \vDash \varphi_2 \end{split}$$

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$$\begin{split} \mathcal{M},s &\vDash \top \text{ and } \mathcal{M},s \not\vDash \bot \text{ for all } s \in S \\ \mathcal{M},s &\vDash p \text{ iff } p \in L(S) \\ \mathcal{M},s &\vDash \neg \varphi \text{ iff } \mathcal{M},s \not\vDash \varphi \\ \mathcal{M},s &\vDash \varphi_1 \land \varphi_2 \text{ iff } \mathcal{M},s \vDash \varphi_1 \text{ AND } \mathcal{M},s \vDash \varphi_2 \\ \mathcal{M},s &\vDash \varphi_1 \lor \varphi_2 \text{ iff } \mathcal{M},s \vDash \varphi_1 \text{ OR } \mathcal{M},s \vDash \varphi_2 \\ \mathcal{M},s &\vDash \varphi_1 \to \varphi_2 \text{ iff } \mathcal{M},s \not\vDash \varphi_1 \text{ OR } \mathcal{M},s \vDash \varphi_2 \end{split}$$

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 $\mathcal{M}, s \vDash \mathtt{EX}\varphi$ iff exists s_1 that $s \to s_1$ and $M, s_1 \vDash \varphi$. This, \mathtt{EX} says: "in some next state..."

 $M, s, \vDash \mathtt{AG}\varphi$ iff for all paths $s_1 \to s_2 \to s_3 \to ...$