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& Ronaldo  
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# Computation Tree Logic

Luis Tertulino & Ronaldo Silveira

October 21, 2015

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# Previously on Temporal Logic Week...

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# Motivation

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- Needing of uncertainty;

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- Needing of uncertainty;
- Different paths of the future;

# Intuition

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In Computation Tree Logic (CTL) the model of time is a tree-like structure. This way, we cannot use Linear Temporal Logic (LTL) to express the existence of a certain path of time in which some event occurs.

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The syntax of CTL consists on the syntax of temporal logic plus some path operators. The class of formulas can be defined in Backus-Naur form. If  $\phi$  is a formula:

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$$\phi ::= \perp \mid \top \mid p \mid \neg\phi \mid \phi \wedge \phi \mid \phi \vee \phi \mid \phi \rightarrow \phi \mid \mathbf{AX}\phi \mid \mathbf{EX}\phi \mid$$

$$\mathbf{AF}\phi \mid \mathbf{EF}\phi \mid \mathbf{AG}\phi \mid \mathbf{EG}\phi \mid \mathbf{A}[\phi\mathbf{U}\phi] \mid \mathbf{E}[\phi\mathbf{U}\phi]$$



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With  $p$  as a literal (atomic formula), AX, EX, AF, EF, AG e EG unary operators.

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The propositional operators:  $\neg, \vee, \wedge, \rightarrow$  have the same meaning of in the propositional logic.

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The path-specific operators can be read, considering  $\varphi$  and  $\psi$  formulas, as:

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- $G\varphi$ : Globally (in all future states)  $\varphi$  is true;
- $\varphi U\psi$ :  $\varphi$  is true at least until  $\psi$  becomes true;

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- Notice that, in CTL, the combination of path specific operators and temporal operators are atomic, i.e.,  $AF$  is a operator that can be read as “In all paths in the future there is some state where...”

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- Notice as well that the binary operators  $A[\varphi U \psi]$  and  $E[\varphi U \psi]$  can be represented as  $AU$

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- We assume that, similarly to the  $\neg$  operator, the “new” unary operators ( $AX$ ,  $EX$ ,  $AF$ ,  $EF$ ,  $AG$ , and  $EG$ ) have the first precedence. Next comes the  $\wedge$  and  $\vee$  operators. And at last the  $\rightarrow$ ,  $AU$  and  $EU$

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- Examples of well-formed formulas:
  - $AG(p \vee EFq)$

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- Examples of well-formed formulas:
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  - $EFEGp \rightarrow AFr$  Note that this is binded as  $(EFEGp) \rightarrow AFr$ ,  
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- Example of formulas that are not well-formed:
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  - $A[pUs \wedge qUs]$

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## Definition of model

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Different from usual logics, CTL formulas are interpreted by a transition system. Given an set of atoms:

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Different from usual logics, CTL formulas are interpreted by a transition system. Given an set of atoms:

### Definition (1)

A **transition system**  $\mathcal{M}$  is a triple  $\mathcal{M} = (S, \rightarrow, L)$  in which  $S$  is a set of states,  $\rightarrow$  is a binary relation over  $S$  ( $\rightarrow \subseteq S \times S$ ) and  $L : S \rightarrow \mathcal{P}(Atoms)$  is a labelling function.

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A **model** is a duple  $\mathcal{M}, s$  in which  $\mathcal{M}$  is a transition system and  $s$  is a state.

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**Notation:** we will use  $\mathcal{M}, s \models \varphi$  to say that the model  $\mathcal{M}, s$  satisfies the formula  $\varphi$



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Take an arbitrary model  $\mathcal{M}$ . Let  $s, s_1, s_2, s_3$  be states in  $S$ . Let  $\varphi, \varphi_1, \varphi_2$  be well-formed formulas of CTL. And let  $p$  be an atom. The satisfaction of CTL formulas can be defined as follows:

- $\mathcal{M}, s \models \top$  and  $\mathcal{M}, s \not\models \perp$  for all  $s \in S$

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- $\mathcal{M}, s \models \varphi_1 \wedge \varphi_2$  iff  $\mathcal{M}, s \models \varphi_1$  AND  $\mathcal{M}, s \models \varphi_2$

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- $\mathcal{M}, s \models \varphi_1 \wedge \varphi_2$  iff  $\mathcal{M}, s \models \varphi_1$  AND  $\mathcal{M}, s \models \varphi_2$
- $\mathcal{M}, s \models \varphi_1 \vee \varphi_2$  iff  $\mathcal{M}, s \models \varphi_1$  OR  $\mathcal{M}, s \models \varphi_2$

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Take an arbitrary model  $\mathcal{M}$ . Let  $s, s_1, s_2, s_3$  be states in  $S$ . Let  $\varphi, \varphi_1, \varphi_2$  be well-formed formulas of CTL. And let  $p$  be an atom. The satisfaction of CTL formulas can be defined as follows:

- $\mathcal{M}, s \models \top$  and  $\mathcal{M}, s \not\models \perp$  for all  $s \in S$
- $\mathcal{M}, s \models p$  iff  $p \in L(S)$
- $\mathcal{M}, s \models \neg\varphi$  iff  $\mathcal{M}, s \not\models \varphi$
- $\mathcal{M}, s \models \varphi_1 \wedge \varphi_2$  iff  $\mathcal{M}, s \models \varphi_1$  AND  $\mathcal{M}, s \models \varphi_2$
- $\mathcal{M}, s \models \varphi_1 \vee \varphi_2$  iff  $\mathcal{M}, s \models \varphi_1$  OR  $\mathcal{M}, s \models \varphi_2$
- $\mathcal{M}, s \models \varphi_1 \rightarrow \varphi_2$  iff  $\mathcal{M}, s \not\models \varphi_1$  OR  $\mathcal{M}, s \models \varphi_2$

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 $s = s_1$ , for all  $s_i$ ,  $\mathcal{M}, s_i \models \varphi$ . Thus, AG says: “In all possible  
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- $\mathcal{M}, s \models \text{EG}\varphi$  iff exists some path  $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow \dots$  in which  $s = s_1$ , for all  $s_i$ ,  $\mathcal{M}, s_i \models \varphi$ . Thus, EG says: “Exists a path from now on in all next states...”

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- $M, s, \models \text{AF}\varphi$  iff for all paths  $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow \dots$  in which  $s = s_1$ , exists  $s_i$ ,  $M, s_i \models \varphi$ . Thus, AF says: “In all possible paths from now on, in some next state...”

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- $M, s, \models \text{A}[\varphi_1 \text{U} \varphi_2]$  iff for all paths  $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow \dots$  in which  $s = s_1$ , this path satisfies  $\varphi_1 \text{U} \varphi_2$ , i.e., exists  $s_i$  in the path such that  $\mathcal{M}, s_i \models \varphi_2$  and, for all  $j < i$ ,  $M, s_j \models \varphi_1$ . Thus, AU says: “For all paths from now on, until some state...”

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- “It’s possible to get to a state where something has started but it’s not ready”:  $EF(started \wedge \neg ready)$



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- “It’s possible to get to a state where something has started but it’s not ready”:  $EF(started \wedge \neg ready)$
- “A certain process is enabled infinitely often on every computation path”:  $AG(AF enabled)$

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- “It’s possible to get to a state where something has started but it’s not ready”:  $EF(started \wedge \neg ready)$
- “A certain process is enabled infinitely often on every computation path”:  $AG(AF enabled)$
- “An upwards travelling lift at the second floor does not change its direction when it has passengers wishing to go to the fifth floor”:  
 $AG(floor2 \wedge directionUp \wedge button5 \rightarrow A[directionUp U floor5])$