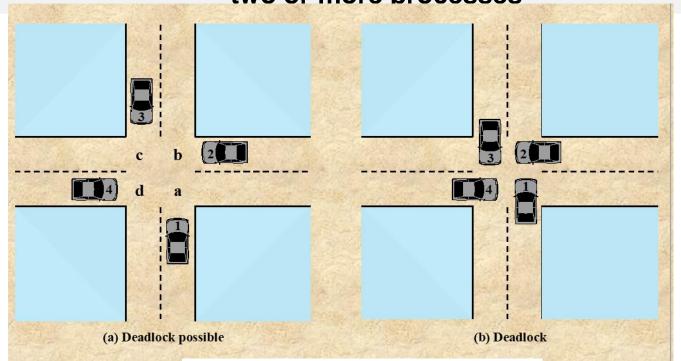
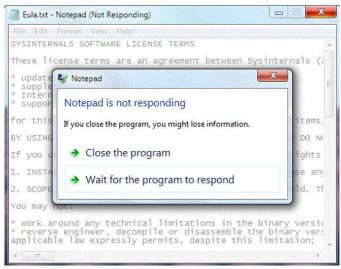
Chapter 8: Deadlocks



Deadlock: All deadlocks involve conflicting needs for resources by two or more processes









Chapter 8: Deadlocks

- System Model
- Deadlock Characterization
- Methods for Handling Deadlocks
- Deadlock Prevention
- Deadlock Avoidance
- Deadlock Detection
- Recovery from Deadlock





Chapter Objectives

- To develop a description of deadlocks, which prevent sets of concurrent processes from completing their tasks
- To present a number of different methods for preventing or avoiding deadlocks in a computer system





System Model

- System consists of resources
- Resource types R_1 , R_2 , . . . , R_m *CPU cycles, memory space, I/O devices*
- Each resource type R_i has W_i instances.
- Each process utilizes a resource as follows:
 - request
 - use
 - release





Deadlock Characterization

Deadlock can arise if four conditions hold simultaneously.

- Mutual exclusion: only one process at a time can use a resource
- Hold and wait: a process holding at least one resource is waiting to acquire additional resources held by other processes
- No preemption: a resource can be released only voluntarily by the process holding it, after that process has completed its task
- Circular wait: there exists a set $\{P_0, P_1, ..., P_n\}$ of waiting processes such that P_0 is waiting for a resource that is held by P_1 , P_1 is waiting for a resource that is held by P_2 , ..., P_{n-1} is waiting for a resource that is held by P_n , and P_n is waiting for a resource that is held by P_0 .





Deadlock with Mutex Locks

- file locks: When two processes lock different files and attempt to lock each other's file.
- process synchronization (wait(), mutex()): Multiple processes or threads waiting on resources in circular dependencies can lead to deadlock.
- memory management (malloc()): If memory resources are exhausted and processes need additional memory, deadlocks can occur.
- Difficult to detect and prevent, but techniques like deadlock detection algorithms, resource allocation graphs, or implementing protocols like the Banker's Algorithm can help manage or avoid deadlocks.





Resource-Allocation Graph

A set of vertices **V** and a set of edges **E**.

- V is partitioned into two types:
 - $P = \{P_1, P_2, ..., P_n\}$, the set consisting of all the processes in the system
 - $R = \{R_1, R_2, ..., R_m\}$, the set consisting of all resource types in the system
- request edge directed edge $P_i \rightarrow R_j$
- **assignment edge** directed edge $R_i \rightarrow P_i$





Resource-Allocation Graph (Cont.)

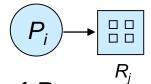
Process



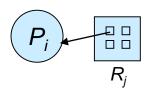
Resource Type with 4 instances



 \blacksquare P_i requests instance of R_i



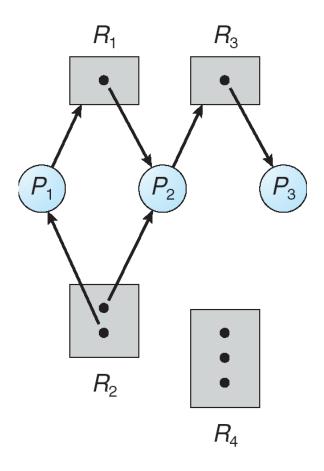
 \blacksquare P_i is holding an instance of R_j







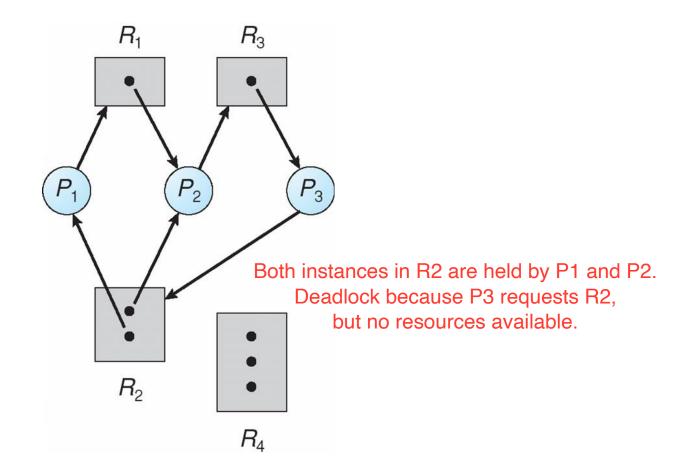
Example of a Resource Allocation Graph







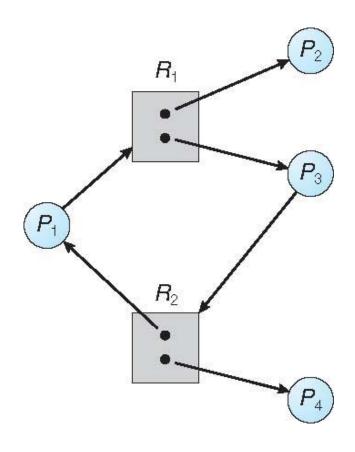
Resource Allocation Graph With A Deadlock







Graph With A Cycle But No Deadlock



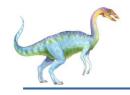




Basic Facts

- If graph contains no cycles ⇒ no deadlock
- If graph contains a cycle ⇒
 - if only one instance per resource type, then deadlock
 - if several instances per resource type, possibility of deadlock





Methods for Handling Deadlocks

- Ensure that the system will never enter a deadlock state:
 - Deadlock prevention
 - Deadlock avoidance
- Allow the system to enter a deadlock state and then recover
- Ignore the problem and pretend that deadlocks never occur in the system; used by most operating systems, including UNIX





Deadlock Prevention

Restrain the ways request can be made

- Mutual Exclusion not required for sharable resources (e.g., read-only files); must hold for non-sharable resources
 - **Example**: If multiple processes want to read from the same file, they can all do so simultaneously without conflict (no mutual exclusion is needed). However, if a process wants to write to the file, mutual exclusion is necessary since writing can't be done by multiple processes at the same time
 - Prevention Rule: Allow sharing of resources when possible (e.g., multiple readers), but enforce mutual exclusion for non-sharable resources (e.g., writing to a file).





Deadlock Prevention

Restrain the ways request can be made

- Hold and Wait must guarantee that whenever a process requests a resource, it does not hold any other resources
 - Require process to request and be allocated all its resources before it begins execution, or allow process to request resources only when the process has none allocated to it.
 - Low resource utilization; starvation possible:
 - It wastes resources because they are locked up by processes that don't need them right away.
- **Example**: a process wants to print a document and needs both a printer and a scanner. Acquire the scanner first and wait for the printer to become available, possible deadlock if another process holds the printer and waits for the scanner. To prevent this, the process must either:
 - Request both the scanner and printer at the same time before starting, or
 - Release the scanner if the printer is not available and retry later.
- Prevention Rule: A process must request all its resources at once or hold none while waiting for additional resources.



Deadlock Prevention (Cont.)

No Preemption –

- If a process that is holding some resources requests another resource that cannot be immediately allocated to it, then all resources currently being held are released
- Preempted resources are added to the list of resources for which the process is waiting
- Process will be restarted only when it can regain its old resources, as well as the new ones that it is requesting
- Example: Process holds a printer and requests a scanner. If the scanner is unavailable, the system will force the process to release the printer. The process will then be put back in a waiting queue until both the printer and scanner are available at the same time.





Deadlock Prevention (Cont.)

- Circular Wait impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration
 - Example: Suppose we have two resources: R1 (printer) and R2 (scanner). To avoid deadlock, we assign a total ordering, such as R1 < R2. A process that needs both the printer and the scanner must always request the printer (R1) first and then the scanner (R2). If a process is holding the scanner and then tries to request the printer, it will violate the rule, so it won't be allowed to proceed.</p>
 - May avoid any possibility of a circular wait:
 - It may require processes to request resources they don't need yet, which can lead to low resource utilization. Also requires careful planning of resource ordering to avoid inefficiencies.





Deadlock Example

```
import threading
import time
# Define two semaphores (representing resources)
resource1 = threading.Semaphore(1)
resource2 = threading.Semaphore(1)
 Thread 1 function
def process 1():
    print ("Process 1: Trying to acquire Resource 1...")
    resource1.acquire()
    print("Process 1: Acquired Resource 1")
    # Simulate some work
    time.sleep(1)
    print ("Process 1: Trying to acquire Resource 2...")
    resource2.acquire() # Deadlock happens here
    print("Process 1: Acquired Resource 2")
    # Release resources
    resource2.release()
    resource1.release()
```

```
# Thread 2 function
def process 2():
    print ("Process 2: Trying to acquire Resource 2...")
    resource2.acquire()
    print("Process 2: Acquired Resource 2")
    # Simulate some work
    time.sleep(1)
    print ("Process 2: Trying to acquire Resource 1...")
    resource1.acquire() # Deadlock happens here
    print("Process 2: Acquired Resource 1")
                               rocess 1: Trying to acquire Resource 1...Process 2: Trying to acquire Resource
    # Release resources
    resource1.release()
                               Process 1: Acquired Resource 1Process 2: Acquired Resource 2
    resource2.release()
                               Process 1: Trying to acquire Resource 2...Process 2: Trying to acquire Resource
# Create two threads
thread1 = threading.Thread(target=process 1)
thread2 = threading.Thread(target=process 2)
# Start both threads
thread1.start()
thread2.start()
# Join the threads to ensure the main program waits for them to finish
thread1.join()
thread2.join()
```

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Deadlock Avoidance

Requires that the system has some additional a priori information available

- Simplest and most useful model requires that each process declare the *maximum number* of resources of each type that it may need
- The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition
- Resource-allocation state is defined by the number of available and allocated resources, and the maximum demands of the processes





Safe State

- When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state
- System is in safe state if there exists a sequence $\langle P_1, P_2, ..., P_n \rangle$ of ALL the processes in the systems such that for each P_i , the resources that P_i can still request can be satisfied by currently available resources + resources held by all the P_i , with j < l
- That is:
 - If P_i resource needs are not immediately available, then P_i can wait until all P_j have finished
 - When P_j is finished, P_i can obtain needed resources, execute, return allocated resources, and terminate
 - When P_i terminates, P_{i+1} can obtain its needed resources, and so on





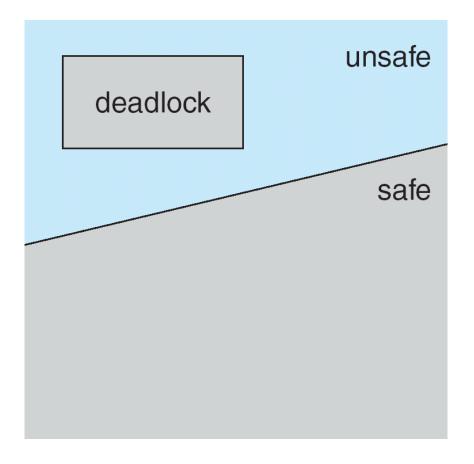
Basic Facts

- If a system is in safe state ⇒ no deadlocks
- If a system is in unsafe state ⇒ possibility of deadlock
- Avoidance ⇒ ensure that a system will never enter an unsafe state.





Safe, Unsafe, Deadlock State







Avoidance Algorithms

- Single instance of a resource type
 - Use a resource-allocation graph

- Multiple instances of a resource type
 - Use the banker's algorithm





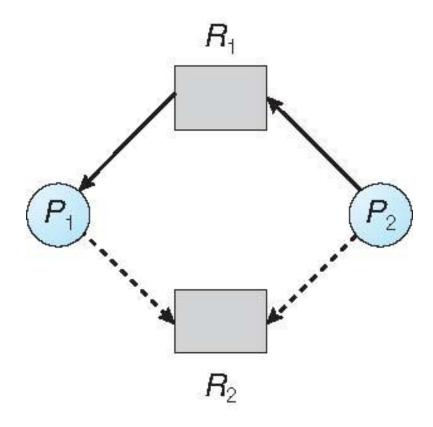
Resource-Allocation Graph Scheme

- Claim edge $P_i \rightarrow R_j$ indicated that process P_j may request resource R_j ; represented by a **dashed line**
- Claim edge converts to request edge when a process requests a resource
- Request edge converted to an assignment edge when the resource is allocated to the process
- When a resource is released by a process, assignment edge reconverts to a claim edge
- Resources must be claimed a priori in the system





Resource-Allocation Graph

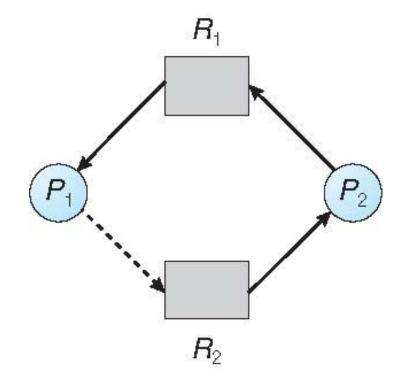






Unsafe State In Resource-Allocation Graph

- Suppose that process P_i requests a resource R_i
- The request can be granted only if converting the request edge to an assignment edge does not result in the formation of a cycle in the resource allocation graph





Resource Allocation Graph - Algorithm

Draw the "Avoidance Graph"

Suppose that process P_i requests a resource R_i

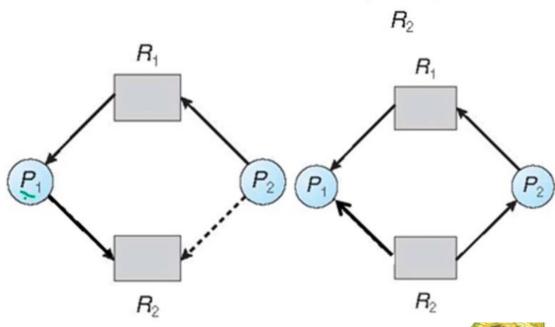
Convert the claim edge $(P_i \rightarrow R_i)$ to request edge $(P_i \rightarrow R_i)$

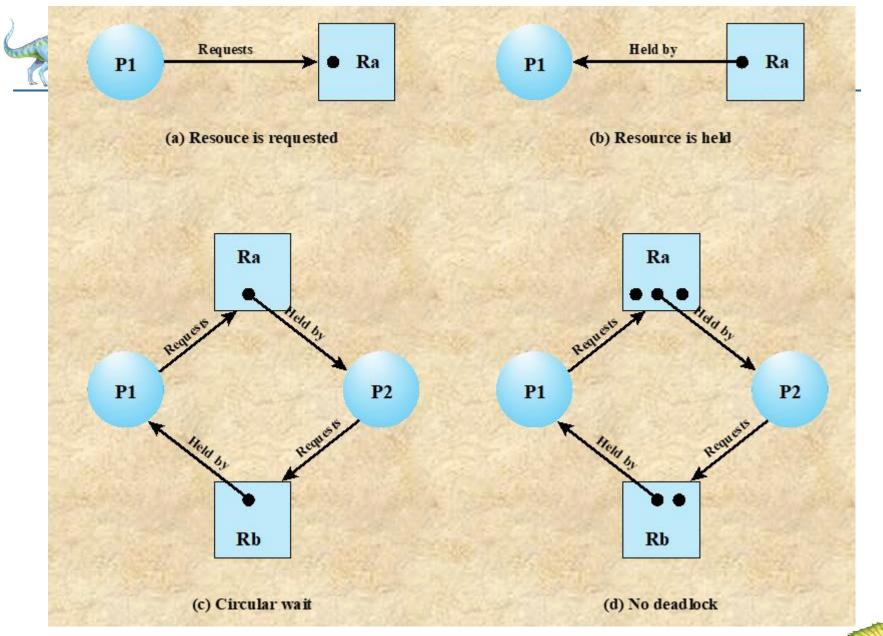
Temporarily convert this request edge $(P_i \rightarrow R_i)$ to assignment edge

If still there is "no cycle" formed; allocate the resource

Otherwise revert the change

- P1 requested for R2
- Safe State
- Request Accepted





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Banker's Algorithm

- Multiple instances
- Each process must a priori claim maximum use
- When a process requests a resource it may have to wait
- When a process gets all its resources it must return them in a finite amount of time
 - When a process (or program) gets all the resources it needs (like memory, files, or a printer), it should use them and then give them back within a reasonable amount of time. This ensures that other processes can also get access to those resources and prevents them from waiting forever.



Data Structures for the Banker's Algorithm

Let n = number of processes, and m = number of resources types.

- **Available**: **Vector** of length m. If available [j] = k, there are k instances of resource type R_i available
- Max: $n \times m$ matrix. If Max[i,j] = k, then process P_i may request at most k instances of resource type R_i
- Allocation: $n \times m$ matrix. If Allocation[i,j] = k then P_i is currently allocated k instances of R_i
- **Need**: $n \times m$ **matrix**. If Need[i,j] = k, then P_i may need k more instances of R_j to complete its task

$$Need[i,j] = Max[i,j] - Allocation[i,j]$$





Safety Algorithm

 Let Work and Finish be vectors of length m and n, respectively. Initialize:

Work = Available
Finish
$$[i]$$
 = false for $i = 0, 1, ..., n-1$

- 2. Find an *i* such that both:
 - (a) *Finish* [*i*] = *false*
 - (b) $Need_i \leq Work$ If no such i exists, go to step 4
- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- 4. If *Finish* [*i*] == *true* for all *i*, then the system is in a safe state





Resource-Request Algorithm for Process P_i

 $Request_i = request \ vector for process P_i$. If $Request_i[j] = k$ then process P_i wants k instances of resource type R_i

- 1. If *Request_i* ≤ *Need_i* go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim
- 2. If $Request_i \leq Available$, go to step 3. Otherwise P_i must wait, since resources are not available
- 3. Pretend to allocate requested resources to P_i by modifying the state as follows:

Available = Available - Request_i; Allocation_i = Allocation_i + Request_i; Need_i = Need_i - Request_i;

- If safe ⇒ the resources are allocated to P_i
- If unsafe $\Rightarrow P_i$ must wait, and the old resource-allocation state is restored





Example of Banker's Algorithm

• 5 processes P_0 through P_4 ;

3 resource types:

A (10 instances), B (5instances), and C (7 instances)

Snapshot at time T_0 :

	<u>Allocation</u>	<u>Max</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	753	3 3 2
P_1	200	322	
P_2	302	902	
P_3	211	222	
P_4	002	433	



Example 01

- 1. Let *Work* and *Finish* be vectors of length m and n, respectively. Initialize Work = Available and Finish[i] = false for i = 0, 1, ..., n 1.
- 2. Find an index i such that both
 - a. Finish[i] == false
 - b. $Need_i \leq Work$

If no such i exists, go to step 4.

After each process finishes, update Available and check from P0 again.

- Work = Work + Allocation_i
 Finish[i] = true
 Go to step 2.
- 4. If Finish[i] == true for all i, then the system is in a safe state.

				<u>Allocation</u>	<u>Max</u>		Need	<u>Available</u>
				ABC	ABC		ABC	ABC
			P_{0}	010	753		743	3 3 2
Work		P_1	200	3 2 2		1 2 2		
Α	В	С	P_2	302	902		600	
			P_3	2 1 1	222		011	
Finish			P_4	002	4 3 3		431	
0			1	2		3	4	

Safe Sequence



- 1. Let *Work* and *Finish* be vectors of length m and n, respectively. Initialize Work = Available and Finish[i] = false for i = 0, 1, ..., n 1.
- 2. Find an index i such that both
 - a. Finish[i] == false
 - b. $Need_i \leq Work$

- Work = Work + Allocation_i
 Finish[i] = true
 Go to step 2.
- 4. If *Finish*[*i*] == *true* for all *i*, then the system is in a safe state.

				<u>Allocation</u>	<u>Max</u>		Need	<u>Available</u>
				ABC	ABC		ABC	ABC
Monte			P_{0}	010	753		743	3 3 2
Work	·		<i>P</i> ₁	200	3 2 2		1 2 2	
Α	В	С	P_2	302	902		600	
5	3	2	P ₃	2 1 1	222		011	
Finisi	h		P_4	002	4 3 3		431	
	0		1	2		3	4	
F			Т	F		F	F	

Safe Sequence

- 1. Let Work and Finish be vectors of length m and n, respectively. Initialize Work = Available and Finish[i] = false for i = 0, 1, ..., n - 1.
- 2. Find an index i such that both
 - a. Finish[i] == false
 - b. $Need_i < Work$

If no such *i* exists, go to step 4.

3. Work = Work + Allocation; Finish[i] = trueGo to step 2.

If Finish[i] == true for all i, then the system is in a safe state.

			<u>Allocation</u>	Max	<u> </u>	Need	<u>Available</u>	
				ABC	ABO	С	ABC	ABC
Monte			P_{0}	010	75	3	743	3 3 2
Work			P_1	200	3 2 2		1 2 2	
A	В	С	P_2	302	90	2	600	
7	4	3	P_3	2 1 1	2 2	2	011	
Finish			P_4	002	4 3	3	4 3 1	
0			1	2		3	4	
00	_ F		Т	F		Т	F	

Safe Sequence

- 1. Let Work and Finish be vectors of length m and n, respectively. Initialize Work = Available and Finish[i] = false for i = 0, 1, ..., n 1.
- 2. Find an index *i* such that both
 - a. Finish[i] == false
 - b. $Need_i \leq Work$

- Work = Work + Allocation_i
 Finish[i] = true
 Go to step 2.
- **4.** If Finish[i] == true for all i, then the system is in a safe state.

			<u>Allocation</u>	<u>Max</u>		Need	<u>Available</u>	
				ABC	ABC		ABC	ABC
Monte			P_{0}	010	753		7 4 3	3 3 2
Work		<i>P</i> ₁	200	3 2 2		1 2 2		
Α	В	С	P_2	302	902		600	
7	5	3	P ₃	2 1 1	222	011		
Finis	h		P_4	002	4 3 3		431	
0			1	2		3	4	
	Т		Т	F	•	Т	F	

Safe Sequence

< P1, P3, P0, P2>

- 1. Let *Work* and *Finish* be vectors of length m and n, respectively. Initialize Work = Available and Finish[i] = false for i = 0, 1, ..., n 1.
- 2. Find an index i such that both
 - a. Finish[i] == false
 - b. $Need_i \leq Work$

- Work = Work + Allocation_i
 Finish[i] = true
 Go to step 2.
- 4. If *Finish*[*i*] == *true* for all *i*, then the system is in a safe state.

			<u>A</u>	<u>llocation</u>	Mo	ax	Need	Ava	<u>iilable</u>	
				ABC	A B	С	ABC	Α	BC	
14//			P_{0}	010	7	5 3	743	3	3 2	
Work			P ₁ .	200	3 2	2 2	122			
Α	В	С	P_2	302	9 (0 2	600			
10	5	5	P_3	2 1 1	2 2	2 2	011			
Finisl	h		P_4	002	4	3 3	431			
	0		1	2		3	4			
	Т		Т	F		Т	F			

Safe Sequence

< P1, P3, P0, P2, P4>

- 1. Let *Work* and *Finish* be vectors of length m and n, respectively. Initialize Work = Available and Finish[i] = false for i = 0, 1, ..., n 1.
- 2. Find an index i such that both
 - a. Finish[i] == false
 - b. Need_i ≤ Work

If no such i exists, go to step 4.

Work = Work + Allocation_i
 Finish[i] = true
 Go to step 2.



Safe State

If Finish[i] == true for all i, then the system is in a safe state.

				<u>Allocation</u>	<u>Max</u>		Need	<u>Available</u>
				ABC	ABC		ABC	ABC
Work			P_{0}	010	753		743	3 3 2
		P ₁		200	200 322		122	
Α	В	С	P_2	302	902		600	
10	5	7	P ₃	211	222		011	
Finish			P_4	002	4 3 3		4 3 1	
0			1	2		3	4	
	Т		Т	T		Т	Т	

P₁ requests (1, 0, 2)

- If Request_i ≤ Need_i, go to step 2. Otherwise, raise an error condition, since the process has exceeded its maximum claim.
- If Request_i ≤ Available, go to step 3. Otherwise, P_i must wait, since the resources are not available.
- 3. Have the system pretend to have allocated the requested resources to process P_i by modifying the state as follows:

Safe Sequence

<>

 $Available = Available - Request_i;$ $Allocation_i = Allocation_i + Request_i;$ $Need_i = Need_i - Request_i;$

				<u>Allocation</u>	<u>Max</u>	Need	<u>Available</u>
				ABC	ABC	ABC	ABC
144			P_{0}	010	753	743	332
Worl	·		<i>P</i> ₁	302	3 2 2	020	230
Α	В	С	P_2	302	902	600	
			P_3	2 1 1	222	011	
Finis	h		P_4	002	4 3 3	4 3 1	
	0		1	2		3 4	
			P.			1.00	

200



3 2 2

P₁ requests (1, 0, 2)

Safe Sequence

<>

- 1. Let *Work* and *Finish* be vectors of length m and n, respectively. Initialize Work = Available and Finish[i] = false for i = 0, 1, ..., n 1.
- 2. Find an index i such that both
 - a. Finish[i] == false
 - b. $Need_i \leq Work$

- Work = Work + Allocation_i
 Finish[i] = true
 Go to step 2.
- 4. If *Finish*[*i*] == *true* for all *i*, then the system is in a safe state.

			4	Allocation	N	<u>lax</u>		Need	A	vailable	2
				ABC	Α	ВС		ABC		ABC	
1471	-		P_{0}	010	7	5 3		743		230	
Work			<i>P</i> ₁	302	3	2 2		020			
Α	В	С	P_2	302	9	0 2		600			
2	3	0	P_3	211	2	2 2		011			
Finisi	Finish		P_4	002	4	3 3		431			
	0		1	2			3	4			
	F		F	F			F	F			

P₁ requests (1, 0, 2)

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Safe Sequence

< P1,>

1. Let Work and Finish be vectors of length m and n, respectively. Initialize Work = Available and Finish[i] = false for i = 0, 1, ..., n - 1.

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- 2. Find an index i such that both
 - a. Finish[i] == false
 - b. $Need_i \leq Work$

If no such *i* exists, go to step 4.

- Work = Work + Allocation_i
 Finish[i] = true
 Go to step 2.
- **4.** If Finish[i] == true for all i, then the system is in a safe state.

				<u>Allocation</u>	\underline{N}	<u>lax</u>	Need	Av	<u>ailable</u>
				ABC	Α	ВС	ABC	A	BC
1441			P_{0}	010	7	5 3	743	2	30
Work	·		P ₁	302	3	2 2	020		
Α	В	С	P_2	302	9	0 2	600		
5	3	2	P ₃	211	2	2 2	011		
Finisi	inish P ₄		002	433		431			
/1	0		1	2		3	4		
	F		Т	F		F	F		

8.44

P₁ requests (1, 0, 2)

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Safe Sequence

< P1, P3,>

- 2. Find an index i such that both
 - a. Finish[i] == false
 - b. $Need_i < Work$

If no such i exists, go to step 4.

- Work = Work + Allocation; Finish[i] = trueGo to step 2.
- If Finish[i] == true for all i, then the system is in a safe state.

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Let Work and Finish be vectors of length m and n, respectively. Initialize

Work = Available and Finish[i] = false for i = 0, 1, ..., n - 1.

				<u>Allocation</u>	<u>Max</u>	Need	<u>Available</u>
				ABC	ABC	ABC	ABC
144			P_{0}	010	753	743	230
Work		<i>P</i> ₁	302	3 2 2	020		
A	В	С	P_2	302	902	600	
7	4	3	P ₃	2 1 1	222	011	
Finis	h		P_4	002	4 3 3	4 3 1	
	0		1	2	:	3 4	
7	_		-	-	-		

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P₁ requests (1, 0, 2)

Safe Sequence

< P1, P3, P4,>

- 1. Let *Work* and *Finish* be vectors of length m and n, respectively. Initialize Work = Available and Finish[i] = false for i = 0, 1, ..., n 1.
- 2. Find an index *i* such that both
 - a. Finish[i] == false
 - b. $Need_i \leq Work$

- Work = Work + Allocation_i
 Finish[i] = true
 Go to step 2.
- 4. If *Finish*[*i*] == *true* for all *i*, then the system is in a safe state.

				<u>Allocation</u>	<u> </u>	<u>lax</u>	Need	<u>Available</u>	2
				ABC	A	ВС	ABC	ABC	
			P_{0}	010	7	5 3	743	230	
Work			<i>P</i> ₁	302	3	2 2	020		
Α	В	С	P ₂	302.	9	0 2	600		
7	4	5	P ₃	2 1 1	2	2 2	011		
Finisi	h		P_4	002	4	3 3	431		
	0		1	2		3	4		
	F		Т	F		Т	Т		

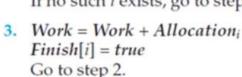
P₁ requests (1, 0, 2)

Safe Sequence

< P1, P3, P4, P0, P2>

- 1. Let *Work* and *Finish* be vectors of length m and n, respectively. Initialize Work = Available and Finish[i] = false for i = 0, 1, ..., n 1.
- 2. Find an index i such that both
 - a. Finish[i] == false
 - b. $Need_i \leq Work$

If no such i exists, go to step 4.





Safe State, ACCEPTED

4. If *Finish*[*i*] == *true* for all *i*, then the system is in a safe state.

				<u>Allocation</u>	<u>Max</u>		Need	<u>Available</u>
				ABC	ABC		ABC	ABC
			P_{0}	010	753		743	230
Worl	·		<i>P</i> ₁	302	3 2 2		020	
Α	В	С	P_2	302	902		600	
10	5	7	P ₃	211	222		011	
Finis	h		P_4	002	4 3 3		431	
	0		1	2		3	4	
	Т		T	Т		Т	T	Colvin and Co



Deadlock Detection

- Allow system to enter deadlock state
- Detection algorithm
- Recovery scheme





Single Instance of Each Resource Type

- Maintain wait-for graph
 - Nodes are processes
 - $P_i \rightarrow P_j$ if P_i is waiting for P_j
- Periodically invoke an algorithm that searches for a cycle in the graph.
 If there is a cycle, there exists a deadlock
- An algorithm to detect a cycle in a graph requires an order of n² operations, where n is the number of vertices in the graph

Consider four friends: A, B, C, and D. They invite each other in a cycle as follows:

- Friend A invites Friend B
- Friend B invites Friend C
- Friend C invites Friend D
- Friend D invites Friend A

This forms a cycle: $A \rightarrow B \rightarrow C \rightarrow D \rightarrow A$.

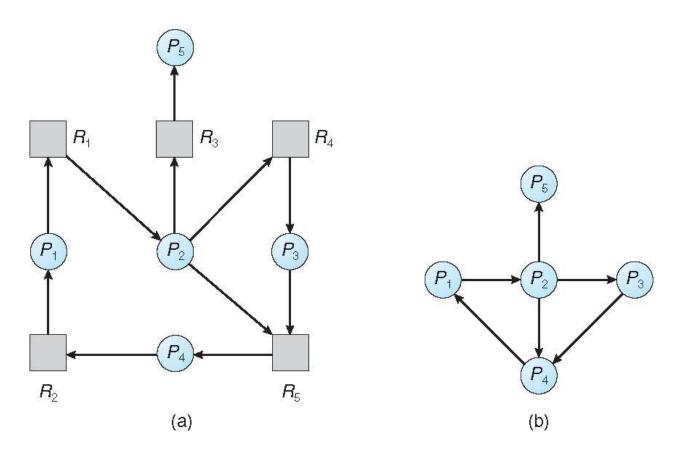
Adjacency Matrix Representation:

	A	B	C	D
A	0	1	0	0
B	0	0	1	0
C	0	0	0	1
D	1	0	0 1 0 0	0





Resource-Allocation Graph and Wait-for Graph



Resource-Allocation Graph

Corresponding wait-for graph





Several Instances of a Resource Type

- **Available**: A vector of length **m** indicates the number of available resources of each type
- **Allocation**: An **n** x **m** matrix defines the number of resources of each type currently allocated to each process
- Request: An n x m matrix indicates the current request of each process. If Request [i][j] = k, then process P_i is requesting k more instances of resource type R_j.

Algorithm requires an order of $O(m \times n^2)$ operations to detect whether the system is in deadlocked state

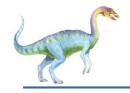




Detection-Algorithm Usage

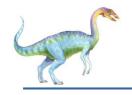
- When, and how often, to invoke depends on:
 - How often a deadlock is likely to occur?
 - How many processes will need to be rolled back?
 - one for each disjoint cycle
- If detection algorithm is invoked arbitrarily, there may be many cycles in the resource graph and so we would not be able to tell which of the many deadlocked processes "caused" the deadlock.
 - The algorithm can see the "traffic jam" (the cycle), but it can't point to a single process that caused it.





Recovery from Deadlock: Process Termination

- Abort ALL deadlocked processes
- Abort ONE process at a time until the deadlock cycle is eliminated
- In which order should we choose to abort?
 - 1. **Priority** of the process
 - 2. **How long** process has computed, and how much longer to completion
 - Resources the process has used
 - Resources process needs to complete
 - How many processes will need to be terminated
 - 6. Is process interactive or batch?
 - Interactive processes require continuous interaction with the user, and they need to respond quickly.
 - Batch processes execute without the need for user interaction and typically handle tasks that don't require real-time responses.



Recovery from Deadlock: Resource Preemption

- **Selecting a victim** minimize cost
- Rollback return to some safe state, restart process for that state
- Starvation same process may always be picked as victim, include number of rollback in cost factor



End of Chapter 8

