

SOLVING THE MILD-SLOPE AND HELMHOLTZ EQUATIONS USING THE VIRTUAL ELEMENT METHOD (VEM), DEALING WITH HIGH ORDER ROBIN BOUNDARY CONDITION

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Abstract

The numerical solution of the Mild-slope equation (MSE) is crucial in various fields, including coastal engineering, oceanography, and offshore structure design. In this article, we present a novel approach utilizing the Virtual Element Method (VEM) for the numerical solution of the MSE. The VEM offers significant advantages over traditional finite element methods, particularly in handling complex geometries and irregular meshes. We first look at the implementation and validation of the model in the presence of Robin boundary conditions. We then apply the results to the calculation of eigenmodes for the port of Cherbourg.

Keywords. Mild-slope equation, Helmholtz equation, Virtual Element Method, computational fluid dynamics, validation, Finite Element Methods, Numerical Analysis, Complex Geometries, Irregular Meshes, Robin Boundary Condition, Coastal Engineering.

1 Introduction

Nowadays, coastal modeling has become a major challenge in the face of climate change. Coastal-related topics have become very numerous, including ocean modeling (large-scale), port modeling and numerous other topics such as morphodynamics. In this study, we are particularly interested in port modeling through the equation models developed by Helmholtz (1868) and Berkhoff (1972). These two equation models can be used in coastal modeling to calculate wave agitation inside a harbor. The Helmholtz (1868) equation is a very classical equation, which can be used in various fields such as electromagnetics or acoustics. In our study, it is used for flat sea bottoms, while the Berkhoff (1972) equation, also known as the Mild-Slope equation, is used for variable bottoms with a maximum slope of 1/3 (Booij 1983). In this study, we have chosen to solve these equations using the virtual element method (Beirão da Veiga et al. 2014) MATHIAS, tu peux ajouter qq's autres refs importantes stp. This method has the advantage of i) being a high-order finite element method, which enables wave phenomena to be accurately captured, where simple finite elements have difficulty capturing them RORO, tu peux ajouter des références pour ce que tu disais, que sur des méthodes FEM simple, même en raffinement, on arrivait pas à capturer tous les phénomènes ondulatoires., ii) handle polyhedral meshes as well as non-conforming meshes, enabling simple refinement in certain areas. Although a few studies have already dealt with the Helmholtz (1868) problem in virtual elements (Perugia et al. 2016; Mascotto et al. 2019), none of them has had any concrete application in the coastal sector. In this study, we will first express the modeling of the problem. Next, we will explain the virtual element strategy for approximating this problem. Finally, we'll look at a particular boundary condition, the Robin condition. After validating our model, we will apply it to the calculation of eigenvalues for the port of Cherbourg.

(Cook et al. 2021)

Vous pouvez étoffer un peu, c'est un draft.

2 Model Problem

In this section, we consider the wave problem described in figure 1.

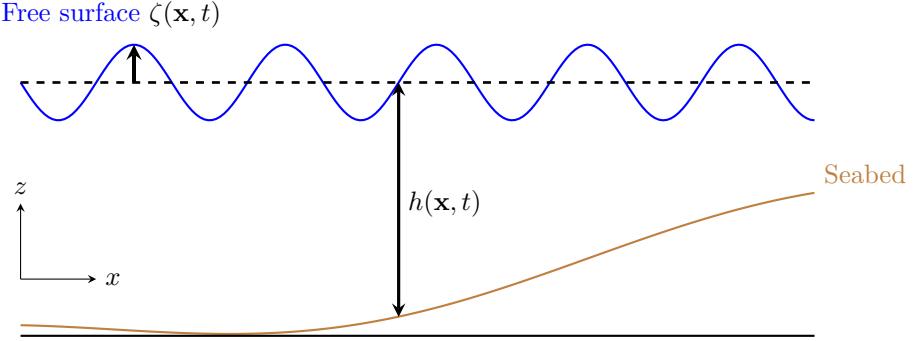


Figure 1: Sketch of a free surface elevation ζ in the (x, z) -plane.

with ζ the free surface defined by $\zeta(\mathbf{x}, t) = \Re\{\eta(x, y) e^{-i\omega t}\}$, η a complex-valued amplitude of ζ , $\omega = 2\pi/T_0$ the angular frequency, T_0 the wave period and h the depth.

The amplitude η can be split into its incident and reflective part,

$$\eta = \eta_I + \eta_R.$$

We thus have,

$$\eta_I(\mathbf{x}, t) = a_I(\mathbf{x})e^{-i\omega t} \quad \text{and} \quad \eta_R(\mathbf{x}, t) = a_R(\mathbf{x})e^{-i\omega t}$$

with the incident wave amplitude defined by,

$$a_I(\mathbf{x}) = a_{\max} e^{-i\mathbf{k}\mathbf{x}} \quad \text{with} \quad \mathbf{k} = k(\cos(\theta), \sin(\theta))^T,$$

with θ the incident wave angle, a_{\max} the maximum wave amplitude.

The amplitude of the reflected wave a_R is obtained by solving the Helmholtz (1868) equation, in the case of a flat bottom,

$$\begin{cases} \Delta a + k^2 a = 0, & \text{in } \Omega, \\ a = a_I, & \text{in } \Gamma_{\text{in}}, \\ \frac{\partial a}{\partial n} + ik a = 0, & \text{in } \Gamma_{\text{out}}, \\ a = -\gamma a_I & \text{in } \Gamma_D. \end{cases} \quad (1)$$

with $\gamma \in [0, 1]$ the reflection coefficient, k the wave number: solution of the dispersion relation at order 1 (equation (2)) from linear theory (Airy 1845),

$$\omega^2 = g k \tanh(kh) \quad \text{with} \quad \omega = \frac{2\pi}{T_0}. \quad (2)$$

The amplitude of the reflected wave a_R can also be obtained by solving the Mild-Slope equation (Berkhoff 1972), in the case of a variable bottom,

$$\left\{ \begin{array}{ll} \nabla(C_p C_g \nabla a) + k^2 C_p C_g a = 0, & \text{in } \Omega, \\ a = a_I, & \text{in } \Gamma_{\text{in}}, \\ \frac{\partial a}{\partial n} + ik a = 0, & \text{in } \Gamma_{\text{out}}, \\ a = -\gamma a_I & \text{in } \Gamma_{\text{D}}. \end{array} \right. \quad (3)$$

with

$$C_p = \frac{\omega}{k} \quad \text{and} \quad C_g = \frac{1}{2} C_p \left[1 + kh \frac{1 - \tanh^2(kh)}{\tanh(kh)} \right]. \quad (4)$$

The choice of boundary conditions will be explained in the application section 4.

Remarks:

- In practice, k is obtained simply by using the Guo (2002) approximation.
- Assuming constant depth within the port and $C_g = C_p/2$ (as in shallow water) and noting that $C_p = \omega/k = Cte$, equation (3) can be simplified to yield the Helmholtz (1868) equation.

3 Solving Equations Using the Virtual Element Method

In this section, we develop the variational formulation of the problem and briefly recall the formalism of virtual elements to solve the problem.

Eventuellement à completer.

3.1 Variational formulation

We decompose this subsection into two parts, one expressing the variational formulation for the Helmholtz (1868) equation (1) and another for that of the Mild-Slope equation (3).

3.1.1 The Helmholtz Equation

We consider the Helmholtz (1868) equation (1) and thus the following variational formulation:

$$\left\{ \begin{array}{l} \text{find } u \in V = H_0^1(\Omega) \text{ such that} \\ a(u, v) = 0 \quad \forall v \in V, \end{array} \right. \quad (5)$$

where,

$$\begin{aligned} a(u, v) &= \int_{\Omega} \Delta u v + k^2 \int_{\Omega} u v + k^2 \int_{\Gamma_{\text{out}}} \frac{\partial u}{\partial n} v \\ &= \int_{\Omega} \Delta u v + k^2 \int_{\Omega} u v - ik \int_{\Gamma_{\text{out}}} u v \end{aligned} \quad . \quad (6)$$

We build a discrete problem in following form:

$$\begin{cases} \text{find } u_h \in V_h \subset V \text{ such that} \\ a(u_h, v_h) = 0 \quad \forall v \in V, \end{cases} \quad (7)$$

where $V_h \subset V$ is a finite dimensional space and $a_h(\cdot, \cdot) : V_h \times V_h \rightarrow \mathbb{R}$ is a discrete bilinear form approximating the continuous form $a(\cdot, \cdot)$.

We thus have the discrete form:

$$\begin{aligned} a_h(u_h, v_h) &= \sum_{E \in \Omega_h} \left[\int_E \Delta u_h v_h + \int_E k^2 u_h v_h \right], \\ &\stackrel{\substack{\text{green} \\ \partial u / \partial n = -ik u}}{=} \sum_{E \in \Omega_h} \left[- \int_E \nabla u_h \nabla v_h + \int_E u_h v_h - \mathbb{1}_{\Gamma_{\text{out}} \subset E} i \int_{\Gamma_{\text{out}}} k u_h v_h \right]. \end{aligned} \quad (8)$$

with $\mathbb{1}_{\Gamma_{\text{out}} \subset E}$ the indicator function and $u = u + u_D$ and u_D is the lifting of $-\gamma a_I$ or a_I (depending on the border).

3.1.2 The Mild-Slope Equation

Now, we consider the [Berkhoff \(1972\)](#) equation (3) and thus the following variational formulation:

$$\begin{cases} \text{find } u \in V = H_0^1(\Omega) \text{ such that} \\ a(u, v) = 0 \quad \forall v \in V, \end{cases} \quad (9)$$

where,

$$a(u, v) = \int_{\Omega} \nabla(C_p C_g \nabla u v) + \int_{\Omega} k^2 C_p C_g u v \quad . \quad (10)$$

We build a discrete problem in following form:

$$\begin{cases} \text{find } u_h \in V_h \subset V \text{ such that} \\ a(u_h, v_h) = 0 \quad \forall v \in V, \end{cases} \quad (11)$$

where $V_h \subset V$ is a finite dimensional space and $a_h(\cdot, \cdot) : V_h \times V_h \rightarrow \mathbb{R}$ is a discrete bilinear form approximating the continuous form $a(\cdot, \cdot)$.

We thus have the discrete form:

$$\begin{aligned}
a_h(u_h, v_h) &= \sum_{E \in \Omega_h} \left[\int_E \nabla(C_p C_g \nabla u_h v_h) + \int_E k^2 C_p C_g u_h v_h \right], \\
&\stackrel{1/E \int_E C_p C_g = \mathcal{A}_E}{\approx} \sum_{E \in \Omega_h} \left[\mathcal{A}_E \int_E (\Delta u_h v_h) + \mathcal{B}_E \int_E u_h v_h \right], \\
&\stackrel{\partial u / \partial n = -ik u}{=} \sum_{E \in \Omega_h} \left[-\mathcal{A}_E \int_E \nabla u_h \nabla v_h + \mathcal{B}_E \int_E u_h v_h - \mathbb{1}_{\Gamma_{\text{out}} \subset E} i \mathcal{A}_E \int_{\Gamma_{\text{out}}} k u_h v_h \right].
\end{aligned} \tag{12}$$

with $\mathbb{1}_{\Gamma_{\text{out}} \subset E}$ the indicator function and $u = u + u_D$ and u_D is the lifting of $-\gamma a_I$ or a_I (depending on the border).

Remark: Unlike the discrete formulation of the homogeneous Helmholtz (1868) equation (8), the discrete formulation of the Mild-Slope equation (12) assumes that k^2 and $C_p C_g$ are constant for each cell in the mesh.

3.2 Dofs

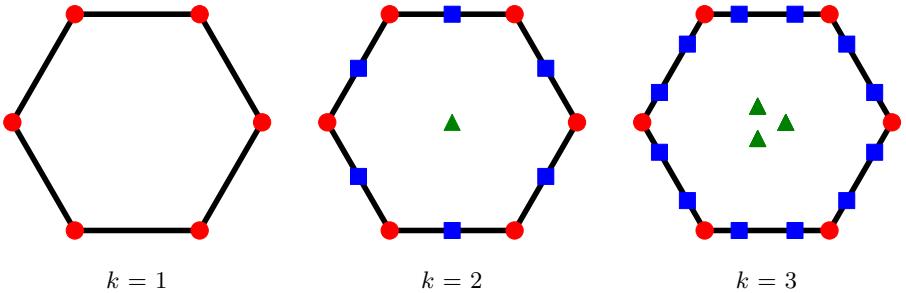


Figure 2: 2D element with ● : Summits dofs, ■ : Edges dofs, ▲ : Inner dofs.

Let Ω_h be a simple polygonal mesh on Ω . This can be any decomposition of Ω in non overlapping polygons E with straight faces. The space V_h will be defined element-wise, by introducing

- local spaces $V_{h|E}$;
- the associated local degrees of freedom.

For all $E \in \Omega_h$:

$$\begin{aligned}
V_{h|E} &= \left\{ v_h \in H_0^1(\Omega) \cap C^0(\partial E) : v_h|_{\partial E} \in \mathbb{P}_k(E), \Delta v_h \in \mathbb{P}_k(E) \right. \\
&\quad \left. (\Pi_k^\nabla v_h - v_h, p)_{0,E} = 0, \forall p \in \mathbb{P}_k(E)/\mathbb{P}_{k-2}(E) \right\}
\end{aligned} \tag{13}$$

where $\mathbb{P}_k(E)/P_{k-2}(E)$ is the subspace of $\mathbb{P}_k(E)$ of the polynomials that are orthogonal in the sense of L^2 to $\mathbb{P}_{k-2}(E)$, or, alternatively, the polynomials of degree $k-1$ and k .

- the functions $V_{h|E}$ are continuous (and known) on ∂E ;
- the functions $V_{h|E}$ are unknown on E !

1. Mesh Decomposition: We consider a polytopal decomposition $\{T_h\}_h$ of the domain Ω which is regular—that is, there exists $\rho \in (0, 1)$, independent of h , such that every element $E \in T_h$ is star-shaped with respect to a ball of radius $\geq \rho h_E$, with h_E the diameter of E .

2. Local Projections: We denote by $\Pi_k^{\nabla, E} : H^1(E) \rightarrow \mathbb{P}_k(E)$ and $\Pi_k^{0, E} : L^2(E) \rightarrow \mathbb{P}_k(E)$ the usual local elliptic projection and local L^2 -projection respectively onto the space of polynomials of degree at most k .

3. Virtual Space: We define the local virtual space by

$$V_h^E = \left\{ v_h \in H_0^1(\Omega) \cap C^0(\partial E) : v_h|_{\partial E} \in \mathbb{P}_k(E), \Delta v_h \in \mathbb{P}_k(E) \right. \\ \left. (\Pi_k^{\nabla} v_h - v_h, p)_{0,E} = 0, \forall p \in \mathbb{P}_k(E)/\mathbb{P}_{k-2}(E) \right\}$$

where $\mathbb{P}_k(E)/P_{k-2}(E)$ is the subspace of $\mathbb{P}_k(E)$ of the polynomials that are orthogonal in the sense of L^2 to $\mathbb{P}_{k-2}(E)$, or, alternatively, the polynomials of degree $k-1$ and k .

3. DDL

4. Base:

$$m_{\alpha_1, \alpha_2} = \left(\frac{x - x_D}{h_D} \right)^{\alpha_1} \cdot \left(\frac{y - y_D}{h_D} \right)^{\alpha_2}$$

Soit $V = \{v \in H^1(\Omega), v|_{\Gamma_D} = 0\}$.

$$\int_{\Omega} \Delta u v + \int_{\Omega} k^2 u v = 0, \quad \forall v \in V.$$

En appliquant la formule de Green, on a :

$$-\int_{\Omega} \nabla u \nabla v + \int_{\Gamma_{Inf}} \frac{\partial u}{\partial n} v + k^2 \int_{\Omega} u v = 0, \quad \forall v \in V.$$

$$-\int_{\Omega} \nabla u \nabla v - ik \int_{\Gamma_{Inf}} u v + k^2 \int_{\Omega} u v = 0, \quad \forall v \in V.$$

3.3 Robin Boundary Condition

Nous allons construire la matrice $B = (\int_{\partial\Omega} \alpha(\Phi_j(x, y), \Phi_i(x, y))_{i,j})$ en parcourant les éléments frontières du bord. Ces éléments sont des segments joignant 2 points consécutifs du bord. La fonction de base Φ_i attachée au sommet i du bord, restreinte à l'élément de bord est une fonction \mathbb{P}_k du bord.

Les éléments du bord sont de longueur $\lambda(e)$. Pour un élément de référence de la forme $[\xi_0, \xi_0 + \lambda]$ entre deux points V_0 et V_1 .

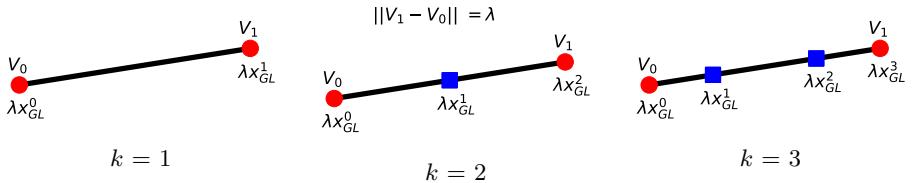


Figure 3: 1D element $[\xi_0, \xi_0 + \lambda]$ representation with ● : Summits dofs, ■ : Edges dofs.

La matrice élémentaire associée à ce terme de Robin est de la forme

$$elb = \left(\int_0^\lambda \alpha_*(\xi_0 + \xi) \varphi_j(\xi) \varphi_i(\xi) d\xi \right)_{1 \leq i, j \leq k+1}, \quad (14)$$

avec $\alpha_*(\xi_0 + \xi) = \alpha(V_0|_x + \xi t_x, V_0|_y + \xi t_y)$ et \vec{t} est le vecteur unitaire orienté de V_0 à V_1 . Pour $i, j \in \llbracket 0, k \rrbracket$:

$$\varphi_i(\lambda x_{GL}^j) = \delta_j^i,$$

avec x_{GL}^j le $j - i$ ème point de quadrature de Gauss-Lobatto sur $[0, 1]$. On trouve les φ_i aisément avec les polynômes de Lagrange comme suivant:

$$\begin{aligned} \varphi_i(\xi) &= \sum_{j=0}^k \delta_j^i \left(\prod_{l=0, l \neq j}^k \frac{\xi - \lambda x_{GL}^l}{\lambda x_{GL}^j - \lambda x_{GL}^l} \right) \\ &= \frac{1}{\lambda^k} \prod_{l=0, l \neq i}^k \frac{\xi - \lambda x_{GL}^l}{x_{GL}^i - x_{GL}^l} \end{aligned}$$

Remark:

$$\begin{aligned}
& \left(\int_0^\lambda \alpha_*(\xi_0 + \xi) \varphi_j(\xi) \varphi_i(\xi) d\xi \right)_{0 \leq i, j \leq k} \\
&=_{\alpha_* = \alpha = cte} \left(\frac{\alpha}{\lambda^{2k}} \int_0^\lambda \left[\prod_{l=0, l \neq i}^k \frac{\xi - \lambda x_{\text{GL}}^l}{x_{\text{GL}}^i - x_{\text{GL}}^l} \prod_{l=0, l \neq i}^k \frac{\xi - \lambda x_{\text{GL}}^l}{x_{\text{GL}}^j - x_{\text{GL}}^l} \right] d\xi \right)_{0 \leq i, j \leq k} \\
&=_{\substack{\xi = \lambda \xi' \\ d\xi = \lambda d\xi'}} \left(\frac{\alpha}{\lambda^{2k}} \int_0^1 \left[\prod_{l=0, l \neq i}^k \frac{\lambda \xi' - \lambda x_{\text{GL}}^l}{x_{\text{GL}}^i - x_{\text{GL}}^l} \prod_{l=0, l \neq i}^k \frac{\lambda \xi' - \lambda x_{\text{GL}}^l}{x_{\text{GL}}^j - x_{\text{GL}}^l} \right] \lambda d\xi' \right)_{0 \leq i, j \leq k} \\
&= \left(\frac{\alpha}{\lambda^{2k}} \int_0^1 \left[\prod_{l=0, l \neq i}^k \lambda \frac{\xi' - x_{\text{GL}}^l}{x_{\text{GL}}^i - x_{\text{GL}}^l} \prod_{l=0, l \neq i}^k \lambda \frac{\xi' - x_{\text{GL}}^l}{x_{\text{GL}}^j - x_{\text{GL}}^l} \right] \lambda d\xi' \right)_{0 \leq i, j \leq k} \\
&= \left(\alpha \lambda \int_0^1 \left[\prod_{l=0, l \neq i}^k \frac{\xi' - x_{\text{GL}}^l}{x_{\text{GL}}^i - x_{\text{GL}}^l} \prod_{l=0, l \neq i}^k \frac{\xi' - x_{\text{GL}}^l}{x_{\text{GL}}^j - x_{\text{GL}}^l} \right] d\xi' \right)_{0 \leq i, j \leq k} \\
&= \alpha \lambda \left(\int_0^1 \tilde{\varphi}_j(\xi) \tilde{\varphi}_i(\xi) d\xi \right)_{0 \leq i, j \leq k}
\end{aligned} \tag{15}$$

with $\tilde{\varphi}_i$ the polynomials for a unit element $[\xi_0, \xi_0 + 1]$

Et par exemple pour $k = 1$, $\varphi_1(\xi) = \frac{\lambda - \xi}{\lambda}$, $\varphi_2(\xi) = \frac{\xi}{\lambda}$.

Pour le cas particulier où $\alpha = cte$, l'intégrale (14) revient à intégrer un polynôme de degrés $2k$. En évaluant celle-ci par $k + 2$ points de GL (car exacte à $2n - 3$), on obtient l'intégrale exacte.

Nous allons construire également le second membre SMB qui provient des termes de bord inhomogènes:

$$SMB_i = \int_{\partial\Omega} b(x, y) \Phi_i(x, y).$$

Ce terme est non trivialement nul si le sommet i appartient à $\partial\Omega = \Gamma_b \cup \Gamma_t \cup \Gamma_l \cup \Gamma_r$. Pour un élément de référence de la forme $[\xi_0, \xi_0 + \delta]$, le vecteur élémentaire associé à ce terme inhomogène est de la forme

$$vecb = \left(\int_0^\lambda b_*(\xi_0 + \xi) \varphi_i(\xi) d\xi \right)_{1 \leq i \leq k+1},$$

avec $\varphi_1(\xi) = \frac{\delta - \xi}{\delta}$, $\varphi_2(\xi) = \frac{\xi}{\delta}$ et $\beta_*(\xi_0 + \xi)$ coïncide avec $\beta_*(\xi_0 + \xi) = \beta(V_0|_x + \xi t_x, V_0|_y + \xi t_y)$ et \vec{t} est le vecteur unitaire orienté de V_0 à V_1 . Également, cette intégrale pourra être intégrée par GL.

3.4 Numerical Validation

In this section, we check the validity of our model. Thus, we compare our model with a manufactured analytical solution (see appendix A). We there-

fore consider the [Helmholtz \(1868\)](#) equation with mixed Dirichlet and Robin boundary conditions, below equation (16).

$$\begin{cases} \Delta u + k^2 u = f(x, y) & , \quad \text{in } \Omega, \\ u = u_{\text{exact}} & , \quad \text{on } \Gamma_2 \cup \Gamma_3 \cup \Gamma_4, \\ \frac{\partial u}{\partial n} + i k u = g(x, y) & , \quad \text{on } \Gamma_1, \end{cases} \quad \begin{array}{c} \Gamma_3 \\ \square \\ \Omega \\ \Gamma_4 \\ \Gamma_2 \\ \Gamma_1 \end{array} \quad (16)$$

For this analytical case, we take the geometry of a unit square and link it with regular triangles, irregular triangles, irregular quadrilaterals and polygons. To generate these meshes, we use the Gmsh ([Geuzaine et al. 2009](#)) and PyPoly-Mesher ([Abedi-Shahri 2024](#); [Talischi et al. 2012](#)). We perform calculations from order 1 to order 5 on maximum cell diameters h from 0.05 to 0.7 m. We then compute the L^2 error for each calculation. The results are shown in figure 4.

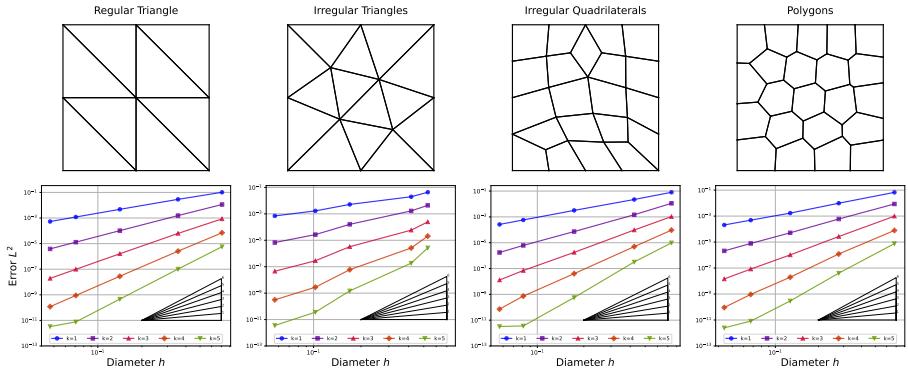


Figure 4: Convergence of order $\mathcal{O}(h^{k+1})$.

We find the expected superconvergence of order $\mathcal{O}(h^{k+1})$.

Remarks: For a validation with the Mild-Slope equation, the order would have been less good, given the approximation we have made per cell.

4 Application and Discussion

In this section, we apply the solution of the Helmholtz and Mild-Slope equations to a coastal engineering problem. We take the case of the port of Cherbourg in France and calculate the associated wave fields under certain conditions. First, we select our study site, as shown in figure 5 (left). Next, we break down the contour into 3 different boundaries (figure 5 (center)): Γ_{in} the harbour entrance, Γ_{out} the harbour exit and Γ_D the port walls. Finally, we assign the correct boundary condition to these edges (figure 5 (right)).



Port location

The Helmholtz or Mild-Slope equation:

$$\left\{ \begin{array}{ll} \nabla(\mathbf{C}_p \mathbf{C}_g \nabla a) + k^2 \mathbf{C}_p \mathbf{C}_g a = 0, & \text{in } \Omega, \\ a = a_I, & \text{in } \Gamma_{\text{in}}, \\ \frac{\partial a}{\partial n} + ik a = 0, & \text{in } \Gamma_{\text{out}}, \\ a = -\gamma a_I, & \text{in } \Gamma_D. \end{array} \right.$$

Port boundary

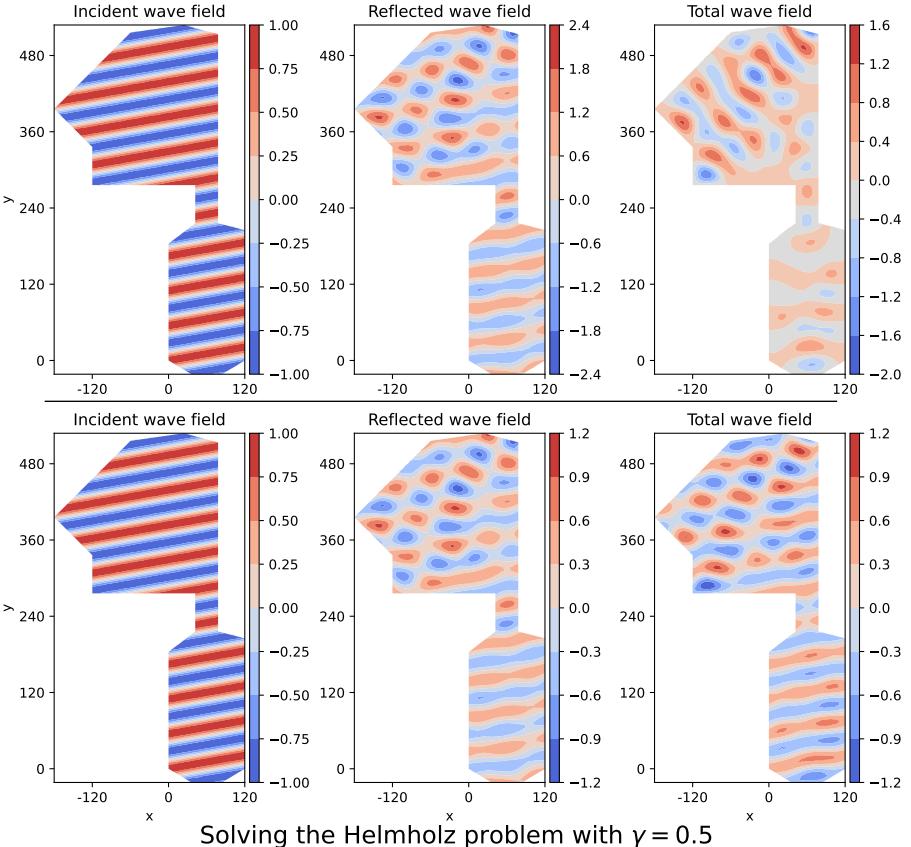
Figure 5: Configuration of our study of the port of Cherbourg

The Γ_{in} boundary condition is modeled by an inhomogeneous Dirichlet condition taking the incident field as argument. The Γ_{out} boundary condition is modeled by a Robin condition allowing the wave to exit without disturbing other wave fields. More information on this condition in Appendix B. The Γ_D boundary condition is modeled by an inhomogeneous Dirichlet condition with a reflection coefficient γ . First, we'll look at the importance of this reflection coefficient in the section 4.1. Then, we will compare the results obtained using the Helmholtz equation and the Mild-Slope equation, in section 4.2. Finally, we will compare the results with different orders of the virtual element method, in section 4.3.

4.1 Sensitivity of the γ reflection coefficient

In this section, we look at the influence of the harbor wall reflection coefficient γ on wave fields. We compare reflected and total wave fields for two different reflection coefficients, $\gamma = 1$ (figure 6 (top)) and $\gamma = 0.5$ (figure 6 (bottom)). For this study, we generate an incident wave field entering the harbour at 280° with a maximum amplitude $a_{\max} = 1$ m and a wave period $T_0 = 8$ s. This incident field can be seen in figure 6 (left). The results of this study are shown in figure 6 with i) on the left, the incident field ii) in the middle, the reflected field (solution of the Helmholtz equation) iii) on the right, the total field.

Solving the Helmholtz problem with $\gamma = 1$



Solving the Helmholtz problem with $\gamma = 0.5$

Figure 6: Comparison of wave fields for the two reflection coefficients $\gamma = 1$ (top) and $\gamma = 0.5$ (bottom). Problem condition: $\alpha = 280^\circ$, $a_{\max} = 1$ m and $T_0 = 8$ s.

The results in figure 6 show that by halving the reflection coefficient γ , the reflected wave field is also halved. This results in a totally different total wave field (incident + reflected), so that the harbour's eigenmodes are no longer located in exactly the same places for the two configurations. It is therefore very important to calibrate this reflection condition correctly.

Ajouter note sur le fait que tous les murs renvoient la même condition de bord alors que c'est peut-être pas vrai partout ?

4.2 Sensibilité de la pente, Helmholtz vs Berkhoff

In this section, we'll look at the influence of the harbor wall reflection coefficient γ on wave fields. For this study, we generate an incident wave field entering the harbour at 280° with a maximum amplitude $a_{\max} = 2$ m and a wave period $T_0 = 8$ s. This incident field can be seen in figure 7 (left).

On introduit un déferlement selon (Munk 1949)

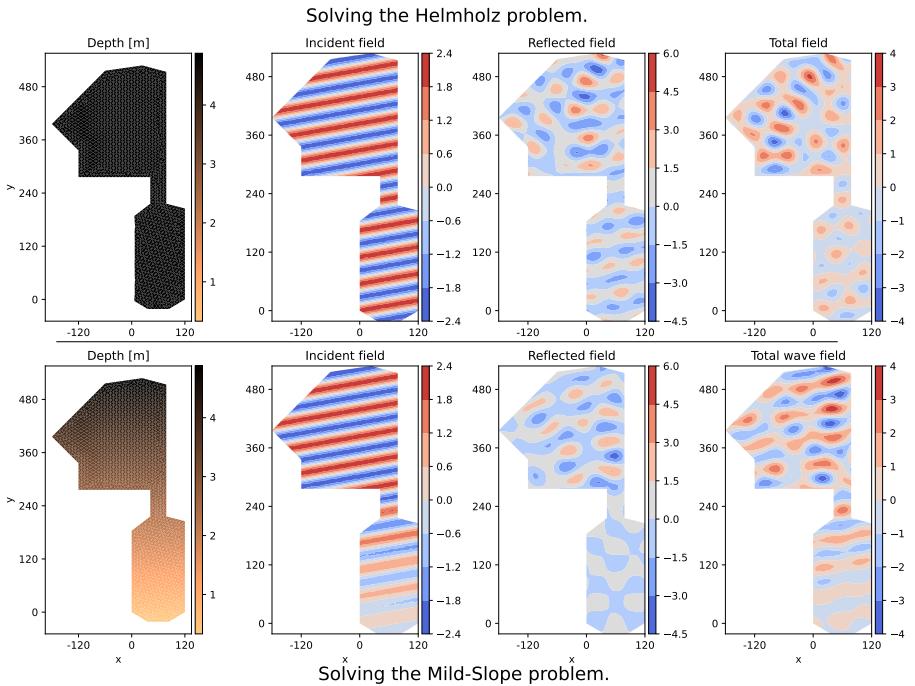


Figure 7: Comparison of wave fields for the two reflection coefficients $\gamma = 1$ (top) and $\gamma = 0.5$ (bottom). Problem condition: $\alpha = 280^\circ$, $a_{\max} = 2$ m and $T_0 = 8$ s.

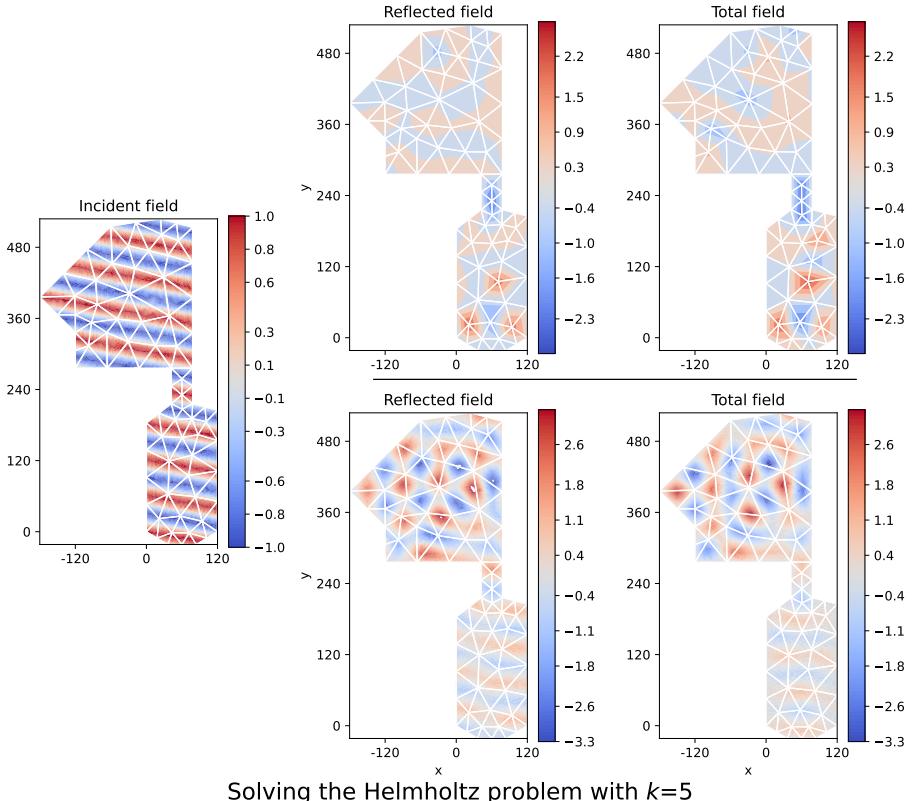
4.3 Application claquéée - Résultats avec différents k

In this section, we'll look at the influence of the harbor wall reflection coefficient γ on wave fields. For this study, we generate an incident wave field entering the harbour at 250° with a maximum amplitude $a_{\max} = 1$ m and a wave period $T_0 = 8$ s. This incident field can be seen in figure 8 (left).

5 Conclusion

On est content

Solving the Helmholtz problem with $k=1$



Solving the Helmholtz problem with $k=5$

Figure 8: Comparison of wave fields for the two reflection coefficients $\gamma = 1$ (top) and $\gamma = 0.5$ (bottom). Problem condition: $\alpha = 250^\circ$, $a_{\max} = 1$ m and $T_0 = 8$ s.

6 Declarations

6.1 Availability of data and material

All data, models, and code generated or used during the study are available on request.

6.2 Conflict of interest

The authors declare that they have no conflict of interest.

6.3 Acknowledgements

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Appendix

A Manufactured analytical solution

The solution to the equation 16 problem has been produced using the following functions:

$$\begin{aligned} u_{\text{exact}}(x, y) &= (x + y) \cdot (1 + i) + \exp(x^2 + iy^2), \\ f(x, y) &= -((2x)^2 + (2iy)^2 + 2(1+i)) \cdot \exp(x^2 + iy^2) + k^2 \cdot u_{\text{exact}}(x, y), \\ g(x, y) &= (1+i) + (2iy) \cdot \exp(x^2 + iy^2) + ik \cdot u_{\text{exact}}(x, y). \end{aligned} \quad (\text{A1})$$

This produces the complex analytical solution that can be seen below in figure A1.

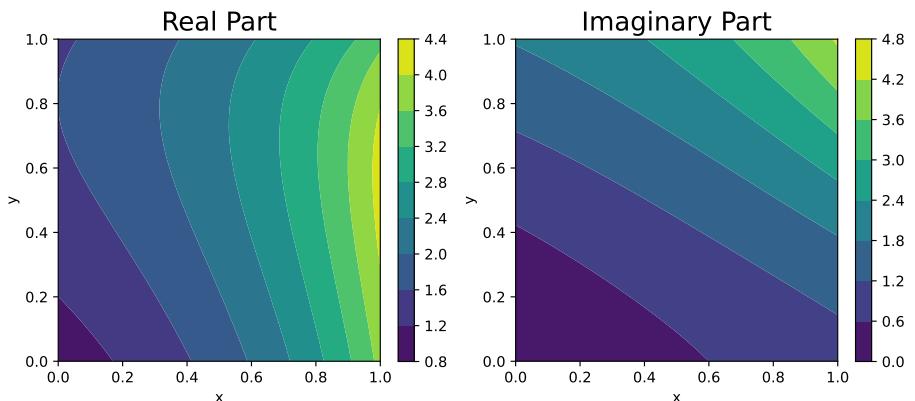


Figure A1: Real and Imaginary part of u_{exact} .

B Interest of a Robin condition

To show the interest of a Robin boundary condition in our problem, we look at the problem represented by figure B1. In this problem, we want to calculate the amplitude of reflected waves around an island. Thus, we have an incident wave arriving at 0° with an amplitude of 2 m and a period of 20 s. This wave is reflected on the boundary island Γ_D . On the other hand, the wave must be able to leave the domain freely via the boundary Γ_{inf} .

The reflected wave is calculated by the following Helmholtz (1868) equation and the wave leaving condition at infinity Γ_{inf} will be studied for a Robin (left) and zero Neumann (right) condition.

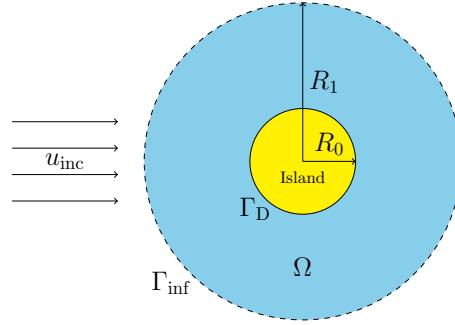
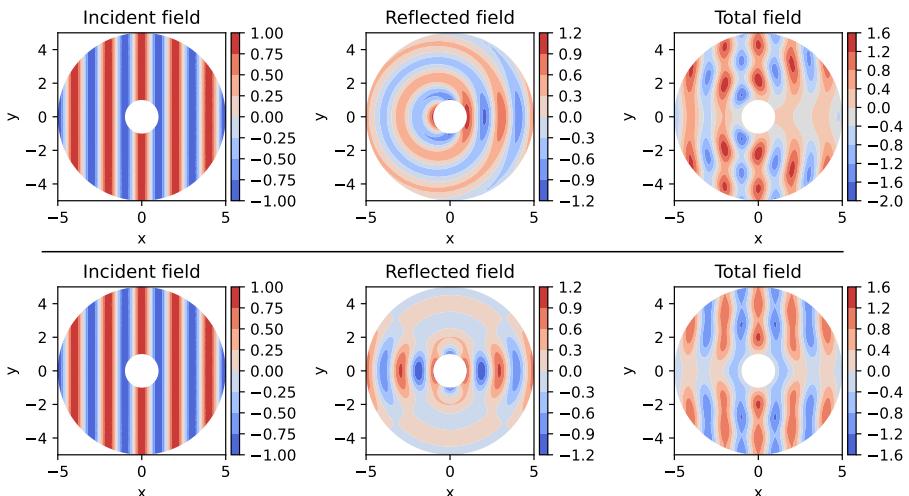


Figure B1: Sketch of the island reflection problem.

$$\left\{ \begin{array}{ll} \Delta u + k^2 u = 0 & , \quad \text{in } \Omega, \\ u = -u_{\text{inc}} & , \quad \text{on } \Gamma_D, \\ \frac{\partial u}{\partial n} + i k u = 0 & , \quad \text{on } \Gamma_{\text{Inf}}. \end{array} \right. \quad \text{or} \quad \left\{ \begin{array}{ll} \Delta u + k^2 u = 0 & , \quad \text{in } \Omega, \\ u = -u_{\text{inc}} & , \quad \text{on } \Gamma_D, \\ \frac{\partial u}{\partial n} = 0 & , \quad \text{on } \Gamma_{\text{Inf}}. \end{array} \right.$$

The results of this study are shown in figure B2. In this figure, it's clear that the wave reflected under Robin's condition (top) can leave freely, while the wave reflected under Neumann's condition (bottom) seems to be disturbed under this condition.

Solving the Helmholtz problem with a Robin condition on Γ_{inf}



Solving the Helmholtz problem with a Neuman condition on Γ_{inf}

Figure B2: Comparison of the results obtained on the island problem by solving the Helmholtz equation with a Robin condition (top) and a zero Neumann condition (bottom).

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