

# Data Representation - HW 3

## 1. On Circulant Matrices

a.) First well show what is the effect of applying  $J$  to a vector

$$\begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = v \in \mathbb{R}^n$$

$$\Rightarrow J \cdot v = \begin{bmatrix} 0 & \dots & 0 & 1 \\ 1 & 0 & \dots & 0 \\ 0 & 1 & \ddots & \vdots \\ 0 & \ddots & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} v_n \\ v_1 \\ v_2 \\ \vdots \\ v_{n-1} \end{bmatrix} \Rightarrow \text{applying } J \text{ to any column vector}$$

simply cyclic shifts of its content 1 spot "downward,"

So  $J^K = J^{K-1} \cdot J$  will be the same as shifting all of  $J$ 's columns <sup>cyclicly</sup>  $K-1$  slots down

In particular,  $J^n = J^{n-1} \cdot J$  will be cyclic  $n-1$  shifts down which is nothing but one shift upwards, so we will get the Identity matrix (since  $J$  is  $I$  when each column is shifted down once)

$$\Rightarrow J^n = I$$

I] cont.

b) Let  $\lambda \in \mathbb{R}$  be an Eigenvalue of  $J$  w.r.t. and  $\vec{v} \in \mathbb{R}^n$  be a corresponding eigenvector

By definition

$$\Rightarrow J \cdot \vec{v} = \begin{bmatrix} V_n \\ V_1 \\ \vdots \\ V_{n-1} \end{bmatrix} \stackrel{(1)}{=} \lambda \begin{bmatrix} V_1 \\ V_2 \\ \vdots \\ V_n \end{bmatrix} \Rightarrow \text{we get} \quad \begin{cases} V_1 = \lambda V_2 \\ V_2 = \lambda V_3 \\ \vdots \\ V_n = \lambda V_1 \end{cases}$$

if we choose  $V_1 = 0$  we get  $V = 0 \Rightarrow V_1 \neq 0$  which

Therefore we can choose  $V \in \mathbb{R}^n$  s.t.  $V_2 = 1$  (as  $V_1 \neq 0$  and eigenvectors are up to scalar multiplication)

$$\Rightarrow \text{we get } V_1 = \lambda, V_2 = \lambda^2, \dots, V_{n-1} = \lambda^{n-1}, \boxed{V_n = \lambda^n = 1}$$

$\Rightarrow$  all  $\lambda \in \mathbb{R}$  that s.t.  $\lambda^n = 1$   $\lambda$  can be an Eigenvalue of  $J$

and there are exactly  $n$  such complex numbers:  $e^{\frac{2\pi i k}{n}}$  for  $k=0, 1, \dots, n-1$

and since it is easy to see that



$\Rightarrow J$  has exactly  $n$  eigenvalues  $\Rightarrow \lambda_k = e^{\frac{2\pi i k}{n}}, k=0, 1, \dots, n-1$ .  
(by definition, all  $\lambda$  that fulfills the reqd equation is an eigenvalue)

1] cont.

$\frac{2\pi ik}{n}$

C.) as seen in (b.), we got that  $\pi_k = e^{\frac{2\pi i k}{n}}$ ,  $k=0, \dots, n-1$  are  $J$ 's eigenvalues, but we've also got from the calculations the corresponding eigenvectors!

$$V_k = \begin{bmatrix} 1 \\ \pi_1 \\ \pi_2 \\ \vdots \\ \pi_{n-1} \\ \pi_n \end{bmatrix} \Rightarrow \text{we get that } J \text{ is diagonalizable}$$

with  $P = \begin{bmatrix} 1 & 1 & 1 \\ V_1 & V_2 & \cdots & V_n \\ 1 & 1 & 1 \end{bmatrix}$

Moreover we can see that  $P$  is made of the Fourier vector which as we know are orthogonal

so after normalization we get that  $U = \frac{1}{\sqrt{n}} P$  is a unitary Basis which diagonalize  $J$ !  $U^* J U = \begin{bmatrix} \pi_0 & & & \\ & \pi_1 & & \\ & & \ddots & \\ & & & \pi_{n-1} \end{bmatrix}$

1] cont.

d.) we can use what we learned about  $J^K$  in (a.) to find such a polynomial expression:

$$P(A) + \text{that } J^k = h_0 + h_1 \cdot J + h_2 \cdot J^2 + \dots + h_{n-1} \cdot J^{n-1} + h_n \cdot J^n$$

$$\Rightarrow P(A) = h_0 \cdot A + h_1 \cdot A^2 + \dots + h_{n-1} \cdot A^{n-1} + h_n \cdot A^n$$

$$\Rightarrow \text{we get } P(J) = h_0 \cdot J + h_1 \cdot J^2 + \dots + h_{n-1} \cdot J^{n-1} + h_n \cdot J^n = H.$$

c.) From Kly-Hamilton we get that  $\forall j, j \in \mathbb{N}$ ,  $P(\pi_j)$ , s.t.  $\pi_j$  is an eigenvalue of  $J$  is an eigenvalue of  $P(J) = H$ , with the same eigenvectors!

$$\Rightarrow \pi_{H,j} = P(\pi_j) = P(e^{\frac{2\pi i j}{n}}) = h_0 + h_1 \cdot e^{\frac{-2\pi i j}{n}} + h_2 \cdot e^{\frac{-2\pi i j \cdot 2}{n}} + \dots + h_{n-1} \cdot e^{\frac{-2\pi i j \cdot (n-1)}{n}}$$

$$\text{with } V_{KH} = V_n = \begin{bmatrix} \pi_0 \\ \pi_1 \\ \vdots \\ \pi_{n-1} \end{bmatrix}$$

$\Rightarrow H$  is diagonalizable by the same unitary matrix  $U = \frac{1}{\sqrt{n}} \begin{bmatrix} 1 & 1 & \dots & 1 \end{bmatrix} \begin{bmatrix} \pi_0 & \pi_1 & \dots & \pi_{n-1} \end{bmatrix}$

with eigenvalues as computed above  $(P(V))^{-1} \sum_{k=0}^{n-1} h_k \pi_k \pi_j^{k+1}$

$$P(\pi_j) = \sum_{k=0}^{n-1} h_k \cdot e^{\frac{+2\pi i k \cdot j}{n}}$$

1] cont.

g.) as we've shown, we know  $W H W^* = \Delta$

since  $W, W^*$  are symmetric we get (and  $\Delta$  is diagonal so also symmetric)

$$(W H W^*)^T = \Delta^T \Rightarrow W^* H^T W = \Delta$$

now we'll multiply both sides by  $W^*$  from the right and since  $W W^* = I$  we get,

$$W^* H^T = \Delta W^* \Rightarrow \underbrace{\begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \lambda_1 & & & \\ \vdots & \lambda_1^2 & \lambda_2 & & \\ & \vdots & & \ddots & \\ 1 & \lambda_1^n & \dots & \lambda_{n-1} & 1 \end{bmatrix}}_{W^*} \begin{bmatrix} h_0 \\ h_1 \\ \vdots \\ h_{n-1} \end{bmatrix} = \Delta \begin{bmatrix} \pi_0 \\ \pi_1 \\ \vdots \\ \pi_{n-1} \end{bmatrix} \cdot \underbrace{\begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \lambda_1 & & & \\ \vdots & \lambda_1^2 & \lambda_2 & & \\ & \vdots & & \ddots & \\ 1 & \lambda_1^n & \dots & \lambda_{n-1} & 1 \end{bmatrix}}_{W}$$

from rules of matrix multiplication we get that the multiplication of  $W^*$  by the first column of  $H^T$  is equal to the first column in the resulting matrix, which is nothing but the  $\Delta$  matrix multiplied by the first column of  $W$  which is only ones

$$\Rightarrow W^* \begin{bmatrix} h_0 \\ h_1 \\ \vdots \\ h_{n-1} \end{bmatrix} = \begin{bmatrix} \pi_0 \\ \pi_1 \\ \vdots \\ \pi_{n-1} \end{bmatrix} \circ \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} = \begin{bmatrix} \pi_0 \\ \pi_1 \\ \vdots \\ \pi_{n-1} \end{bmatrix} \quad \blacksquare$$

1] cont.

Q.E.D. let  $H_1, H_2 \in \mathbb{R}^{n \times n}$ , s.t.  $g_{l_1}, g_{l_2}$  are circulant.  
I'll show  $H_1 \cdot H_2 = H_2 \cdot H_1$ .

as we've shown, all circulant matrices are uniformly  
diagonalizable by  $W = DFT$

$$\Rightarrow H_1 \cdot H_2 = W \Delta_1 \underbrace{W^* \cdot W \Delta_2}_{I} W^* = W \Delta_1 \Delta_2 W^*$$

$\Delta_1, \Delta_2$   
are diagonal =  $W \Delta_2 \Delta_1 W^* = W \Delta_2 \underbrace{W^* W}_{I} \Delta_1 W^* = H_2 \cdot H_1$   
so they  
commute

$\Rightarrow$  all circulant matrices commute.

now we'll show that  $H_1 \cdot H_2$  is circulant (and in other words,  
that circulant matrices are closed to multiplication)

as seen in (d.) we can build in the exact same way a  
polynomial expression for each of the matrices  $P_1, P_2$  s.t.  $P_i(J) = H_i$ ,

and  $P_2(J) = H_2$

$$\Rightarrow H_1 \cdot H_2 = P_1(J) \cdot P_2(J) = \sum_{k=0}^{n-1} h_{1,k} \cdot J^k \cdot \sum_{j=0}^{n-1} h_{2,j} \cdot J^j$$
$$= \sum_{k=0}^{n-1} \sum_{j=0}^{n-1} h_{1,k} \cdot h_{2,j} \cdot J^{k+j} = (\star)$$

$\Rightarrow$  as we've seen before for any  $\alpha \in \mathbb{N}$ ,  $J^\alpha$  is a circulant matrix  
and since circulant matrices are closed to addition:

$$\left( \begin{bmatrix} A_0 & A_1 & \dots & A_{n-1} \\ A_1 & A_2 & \dots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ A_{n-1} & \dots & \dots & A_n \end{bmatrix} + \begin{bmatrix} B_0 & B_1 & \dots & B_{n-1} \\ B_1 & B_2 & \dots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ B_{n-1} & \dots & \dots & B_n \end{bmatrix} = \begin{bmatrix} A_0 + B_0 & A_1 + B_1 & \dots & A_{n-1} + B_{n-1} \\ A_1 + B_1 & A_2 + B_2 & \dots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ A_{n-1} + B_{n-1} & \dots & \dots & A_n + B_n \end{bmatrix} \text{ is a circulant matrix} \right)$$

$\Rightarrow$  we get  $(\star)$  is circulant  $\Rightarrow H_1 \cdot H_2$  is circulant.



1] cont.

j) First, we can write the convolution of  $x \otimes y$

in matrix form by building a circulant matrix

$X$  s.t. its first row (which fully defines it) is  $x$  and multiplying  $y$  by its transpose

$$\Rightarrow x \otimes y = X^T$$

$$\Rightarrow Z = x \otimes y = X^T_y \Rightarrow \text{DFT}(Z) =$$

$$\Rightarrow \text{DFT} \circ Z = WZ = W X^T_y = W X^T W^* W y \stackrel{(1)}{=} \underbrace{W^* X W}_{I} \cdot W y \stackrel{(2)}{=} \underbrace{W_x \otimes W_y}_{\square}$$

(1) ~~W X^T W^\*~~ subtracted

(2) well show  $W X^T W^* = W^* X W$ :

$X^T$  is circulant  $\Rightarrow W$  diagonalize her

$\Rightarrow W^* X W$  is diagonal  $\Rightarrow (W^* X W)^T = W^* X W$   $\Rightarrow$  symmetric

$\Rightarrow W^* X W = (W^* X W)^T = W^T X^T W^{*T} = W X^T W^*$  ( $W, W^*$  are symmetric).

(2) well show ~~W X^T W^\* = W^\* X W~~  $\Rightarrow W^* X W \cdot W y = \sqrt{n} W_x \otimes W_y$

\* as we've seen  $W^* X W$  diagonalizes  $X$ , therefore

it is a diagonal matrix where its values on the diag

is its eigenvalues, and since  $X$  is built using the  $\pi$

we know from (g.) that  $\sqrt{n} W x = \begin{bmatrix} \pi_{0,x} \\ \vdots \\ \pi_{n-1,x} \end{bmatrix}$  of  $X$

$$\Rightarrow W x = \frac{1}{\sqrt{n}} \begin{bmatrix} \pi_{0,x} \\ \vdots \\ \pi_{n-1,x} \end{bmatrix} \Rightarrow \pi_{i,x} = \frac{1}{\sqrt{n}} \pi_{i,x}$$

$$\Rightarrow \sqrt{n} W^* X W \cdot W y = \sqrt{n} \begin{bmatrix} \pi_{0,x} \\ \pi_{1,x} \\ \vdots \\ \pi_{n-1,x} \end{bmatrix} \cdot \begin{bmatrix} \pi_{0,y} \\ \pi_{1,y} \\ \vdots \\ \pi_{n-1,y} \end{bmatrix} = \begin{bmatrix} \pi_{0,x} \\ \vdots \\ \pi_{n-1,x} \end{bmatrix} \odot \begin{bmatrix} \pi_{0,y} \\ \pi_{1,y} \\ \vdots \\ \pi_{n-1,y} \end{bmatrix}$$

$$= W_x \odot W_y$$

## 2] Fourier Transform

a.) we are given  $\delta(t) * g(t) = h(t)$

we will show  $\delta(t-1) * g(t+1) = h(t)$ :

First we'll define two new functions:  $\tilde{f}(t) = \delta(t-1), \tilde{g}(t) = g(t+1)$

$$\begin{aligned} \Rightarrow \boxed{\delta(t-1) * g(t+1)} &= \tilde{f}(t) * \tilde{g}(t) = \int_{-\infty}^{\infty} \tilde{f}(\xi) \cdot \tilde{g}(t-\xi) \cdot d\xi \\ &= \int_{-\infty}^{\infty} \delta(\xi-1) \cdot g(t-(\xi-1)) \cdot d\xi = \int_{-\infty}^{\infty} \delta(\tau) \cdot g(t-\tau) \cdot d\tau \\ &\quad \left. \begin{array}{l} \text{Var change:} \\ \left\{ \begin{array}{l} \tau = \xi - 1, \\ \frac{d\tau}{d\xi} = 1 \Rightarrow d\tau = d\xi \end{array} \right. \end{array} \right\} \end{aligned}$$

conv  
definition  
 $= \delta(t) * g(t) = \boxed{h(t)}$

Another maybe easier way of showing this is by using the fact that  $T_f$  is LSI as shown in class

and by using:  $T_{-1}(T_{+1}(\varphi(t))) = T_{+1}(\varphi(t+1)) = \varphi(t)$

$\Rightarrow$  we'll define  $h_{T_{-1}}(t), h_{T_{+1}}(t)$  to be the impulse responses of  $T_{-1}, T_{+1}$

$$\Rightarrow \boxed{\delta(t) * g(t)} = T_{-1}(T_{+1}(\delta(t) * g(t))) = h_{T_{-1}}(t) * (h_{T_{+1}}(t) * (\delta(t) * g(t)))$$

$$\Leftarrow \text{(LSI commutativity)} \quad \text{(as seen in Lecture 7)} = h_{T_{-1}}(t) * (\delta(t) * (h_{T_{+1}}(t) * g(t)))$$

$$= (h_{T_{-1}}(t) * (\delta(t)) * (h_{T_{+1}}(t) * g(t))) = T_{-1}(\delta(t)) * T_{+1}(g(t))$$

$$= \boxed{\delta(t-1) * g(t+1)}$$

2] cont.

b] we need to show:  $\int_{-\infty}^{\infty} f(t) \cdot g(t) dt = \int_{-\infty}^{\infty} F(u) \cdot G(u) du$

where  $F(u), G(u)$  are the Fourier transforms of  $f(t), g(t)$ .

First we'll define  $h(\xi) = f(\xi) * g(\xi) = \int_{-\infty}^{\infty} f(t) \cdot g(\xi - t) dt$

we'll notice 
$$h(0) = \int_{-\infty}^{\infty} f(t) \cdot g(-t) dt \quad (1)$$

Moreover, as we learned in the lectures, we can fully represent any function by projecting it to the Fourier family

$$\Rightarrow h(t) = \int_{-\infty}^{\infty} H(u) \cdot e^{2\pi i ut} du \text{ when } H(u) \text{ is the Fourier transform of } h(t).$$

$$\Rightarrow h(0) = \int_{-\infty}^{\infty} H(u) du \quad (2)$$

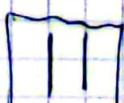
Now, let's find out who is  $H(u)$ .

First as we said before we can look at  $f(t), g(t)$  in their Fourier representations:

$$f(t) = \int_{-\infty}^{\infty} F(u) \cdot e^{2\pi i ut} du, \quad g(t) = \int_{-\infty}^{\infty} G(u) \cdot e^{-2\pi i ut} du$$

$$\begin{aligned} H(u) &= \int_{-\infty}^{\infty} f(t) \cdot g(t) \cdot e^{-2\pi i ut} dt \\ &= \int_{-\infty}^{\infty} \left( \int_{-\infty}^{\infty} F(s) \cdot e^{2\pi i us} ds \right) \cdot \left( \int_{-\infty}^{\infty} G(t) \cdot e^{-2\pi i ut} dt \right) e^{-2\pi i ut} dt \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} F(s) \cdot G(t) \cdot e^{2\pi i us} \cdot e^{-2\pi i ut} \cdot e^{-2\pi i ut} ds dt \end{aligned}$$

More in the next page



2] b. cont.

recap, from (2) we know  $h(0) = \int_{-\infty}^{\infty} H(u) du$

and from (1) we know  $h(0) = \int_{-\infty}^{\infty} f(t) \cdot g(-t) dt$

$\Rightarrow$  we need only to show  $\int_{-\infty}^{\infty} H(u) du = \int_{-\infty}^{\infty} F(u) G(u) du \quad (3)$

let us look at  $F(u) \cdot G(u)$

$$\boxed{F(u) \cdot G(u)} = \int_{-\infty}^{\infty} f(x) \cdot e^{-2\pi i ux} dx \cdot \int_{-\infty}^{\infty} g(y) \cdot e^{-2\pi i uy} dy$$
$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x) \cdot g(y) \cdot e^{-2\pi i u(x+y)} dy dx \quad \begin{array}{l} \text{change variable from } y \text{ to } z-x \\ y = z-x, \frac{dy}{dz} = -1 \Rightarrow dy = -dz \end{array}$$

$$\boxed{(3)} = \int_{-\infty}^{\infty} e^{-2\pi i ug} \cdot \underbrace{\int_{-\infty}^{\infty} f(x) \cdot g(z-x) dx}_{H(z)} dz = \int_{-\infty}^{\infty} e^{-2\pi i ug} \cdot h(z) dz$$
$$= \boxed{H(u)}$$

(\*) we also changed the order of integration from  $dz dx$  to  $dx dz$  (Fubini)

$\Rightarrow$  since we've shown  $H(u) = F(u) \cdot G(u)$  then we get (3) instantly

$$\boxed{\Rightarrow \int_{-\infty}^{\infty} F(u) \cdot G(u) du = \int_{-\infty}^{\infty} H(u) du = h(0) = \int_{-\infty}^{\infty} f(t) \cdot g(-t) dt}$$