

GM8724S009

Lo-Cog® DC Servo Gearmotor



Assembly Data	Symbol	Units	Value	
Reference Voltage	Е	V	12	
No-Load Speed	S _{NL}	rpm (rad/s)	720	(75.4)
Continuous Torque (Max.) ¹	T _C	oz-in (N-m)	15	(1.0E-01)
Peak Torque (Stall) ²	T_{PK}	oz-in (N-m)	42	(3.0E-01)
Weight	W_{M}	oz (g)	11.2	(316)
Motor Data				
Torque Constant	K_T	oz-in/A (N-m/A)	3.09	(2.18E-02)
Back-EMF Constant	K _E	V/krpm (V/rad/s)	2.29	(2.18E-02)
Resistance	R_T	Ω	4.33	
Inductance	L	mH	2.34	
No-Load Current	I _{NL}	Α	0.18	
Peak Current (Stall) ²	Ι _Ρ	Α	2.77	
Motor Constant	K_{M}	oz-in/√W (N-m/√W)	1.49	(1.05E-02)
Friction Torque	T_F	oz-in (N-m)	0.35	(2.5E-03)
Rotor Inertia	J_M	oz-in-s ² (kg-m ²)	2.3E-04	(1.6E-06)
Electrical Time Constant	$ au_{E}$	ms	0.54	
Mechanical Time Constant	τ_{M}	ms	14.7	
Viscous Damping	D	oz-in/krpm (N-m-s)	0.020	(1.4E-06)
Damping Constant	K_D	oz-in/krpm (N-m-s)	1.6	(1.1E-04)
Maximum Winding Temperature	θ_{MAX}	°F (°C)	311	(155)
Thermal Impedance	R_{TH}	°F/watt (°C/watt)	70.5	(21.4)
Thermal Time Constant	$ au_{TH}$	min	10.7	
Gearbox Data				
Reduction Ratio			6.3	
Efficiency ³			0.95	
Maximum Allowable Torque		oz-in (N-m)	100	(0.71)
Encoder Data				
Channels			3	
Resolution		CPR	500	

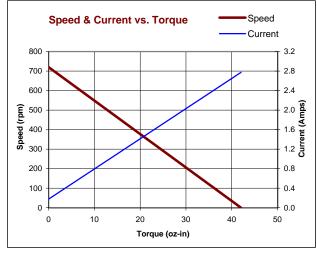
^{1 -} Specified at max. winding temperature at 25°C ambient without heat sink. 2 - Theoretical values supplied for reference only.

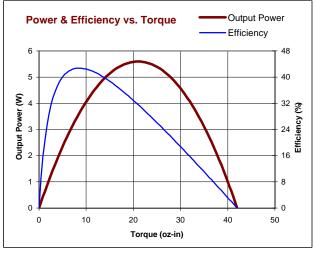
Included Features

2-Pole Stator
Ceramic Magnets
Heavy-Guage Steel Housing
7-Slot Armature
Silicon Steel Laminations
Stainless Steel Shaft
Copper-Graphite Brushes
Diamond Turned Commutator
Motor Ball Bearings
Output Ball Bearing
Standard Gears

Customization Options

Alternate Winding
Sleeve or Ball Bearings
Modified Output Shaft
Custom Cable Assembly
Special Brushes
EMI/RFI Suppression
Alternate Gear Material
Special Lubricant
Optional Encoder
Fail-Safe Brake





All values are nominal. Specifications subject to change without notice. Graphs are shown for reference only.

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^{3 -} Effective gearbox efficiency for this unit improved by use of ball bearings

