

# #1 - Detail of a spur gear

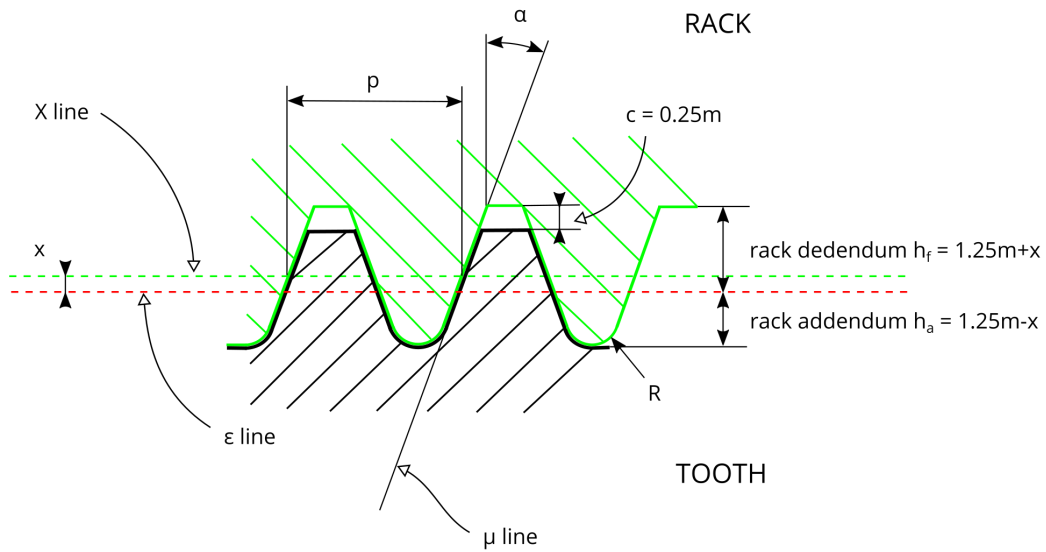
The diagram illustrates the geometry and stress distribution of a spur gear tooth. Key features include:

- Geometric Parameters:**
  - addendum diameter ( $d_a$ )
  - tooth addendum ( $t_a$ )
  - reference diameter ( $d$ )
  - tooth dedendum ( $t_f$ )
  - root diameter ( $d_f$ )
  - base diameter ( $d_b$ )
  - involute tooth limit diameter ( $d_{lim}$ )
- Points and Lines:**
  - point V (top of tooth)
  - point T (bottom of tooth)
  - points A (on the tooth profile)
  - X line (horizontal line through the tooth)
  - $\epsilon$  line (dashed line)
  - uniform resistance parabola (dashed curve)
- Forces and Angles:**
  - $F_{bn}$  (normal force)
  - $F_{bt}$  (tangential force)
  - $\alpha_1$  (pressure angle)
- Stress and Deformation:**
  - $h_{Fe}$  (elastic deformation)
  - $S$  (stress)
  - $S_{Fn}$  (normal stress)

## #2 - Involute schema to create the gear

Figure #3 represents the **rack cutter** used to generate the gear, as defined in ISO 53:1998.

### #3 - Rack tooth profile



In the following table there are a numerical example and some basic **formulas related to standard spur gears** valid if  $R/m = 0$  and  $x/m = 0$ .

Element	Formula	Example
number of teeth	$\frac{Z}{z}$	30
module	$\frac{m}{m}$	5 mm
pressure angle	$\frac{\alpha}{\alpha}$	20°
rack shift coefficient	$\frac{x/m}{x/m}$	0
coefficient of fillet radius of the rack cutter	$\frac{R/m}{R/m}$	0

static nominal torque	$\frac{C}{C}$	250 Nm
face width	$b$ $b$	10 mm
	$l_0 = \frac{d}{2} \cdot \sin^2(\alpha)$ $l_0 = d/2 \cdot \sin^2(\alpha)$	8.77 mm
	$\frac{y}{d/2} = \frac{2.5}{z} - \sin^2(\alpha)$ $y/d/2 = 2.5/z - \sin^2(\alpha)$	-0.0336
	$l = l_0 + y$ $l = l_0 + y$	6.25 mm
pitch	$p = m \cdot \pi$ $p = m \cdot \pi$	15.71 mm
reference diameter	$d = m \cdot z$ $d = m \cdot z$	150 mm
base diameter	$d_b = d \cdot \cos(\alpha)$ $d_b = d \cdot \cos(\alpha)$	140.95 mm
involute tooth limit diameter	$d_{lim} = 2 \cdot \sqrt{(r-l)^2 + \left(\frac{1}{\tan(\alpha)}\right)^2}$ $d_{lim} = 2 \cdot (r-l)^2 + (l \tan(\alpha))^2$	141.72 mm
root diameter	$d_f = d - 2 \cdot l$ $d_f = d - 2 \cdot l$	137.5 mm
addendum diameter	$d_t = d + 2 \cdot m$ $d_t = d + 2 \cdot m$	160 mm

tooth addendum	$t_a = m$ $t_a = m$	5 mm
tooth dedendum	$t_f = 1.25 \cdot m$ $t_f = 1.25 \cdot m$	6.25 mm
circular reference tooth thickness	$s = \frac{m \cdot \pi}{2}$ $s = m \cdot \pi$	7.85 mm
	$z_{\min} = 1.25 \cdot \frac{2}{\sin^2(\alpha)}$ $z_{\min} = 1.25 \cdot 2 \sin^2(\alpha)$	22
rack addendum	$h_a = 1.25 \cdot m$ $h_a = 1.25 \cdot m$	6.25 mm
rack dedendum	$h_f = 1.25 \cdot m$ $h_f = 1.25 \cdot m$	6.25 mm
nominal load, normal to the line of contact	$F_{bn} = \frac{C}{d/2 \cdot \cos(\alpha)}$ $F_{bn} = C/d/2 \cdot \cos(\alpha)$	3547.26 N
	$\alpha_1$ $\alpha_1$	26.92°
nominal transverse load in plane of action	$F_{bt} = F_{bn} \cdot \cos(\alpha_1)$ $F_{bt} = F_{bn} \cdot \cos(\alpha_1)$	3162.85 N
tooth root chord at the critical section	$s_{Fn}$ $s_{Fn}$	9.74 mm
bending moment arm relevant to load application at the tooth tip	$h_{Fe}$ $h_{Fe}$	9.4 mm

tooth form factor - Lewis method	$Y_L = \frac{s_{Fn}^2}{6 \cdot h_{Fe} \cdot m}$ $Y_L = s_{Fn}^2 \cdot 6 \cdot h_{Fe} \cdot m$	0.3361
tooth root bending stress at point T	$\sigma_f = \frac{F_{bt}}{Y_L \cdot b \cdot m}$ $\sigma_f = F_{bt} Y_L \cdot b \cdot m$	188.21 N/mm <sup>2</sup>

## Gear ratio

The gear ratio  $\tau$  of a gear train is the ratio of the angular velocity of the input gear to the angular velocity of the output gear:

$$\tau = \frac{\omega_1}{\omega_2} = \frac{d_2}{d_1} = \frac{z_2}{z_1}$$

$$\tau = \omega_1 \omega_2 = d_2 d_1 = z_2 z_1$$

where

$\omega_1$  is the angular velocity of the input gear e  $\omega_2$  is the angular velocity of the output gear;  
 $d_1$  is the reference diameter of the input gear e  $d_2$  is the reference diameter of the output gear;  
 $z_1$  is the number of teeth of the input gear e  $z_2$  is the number of teeth of the output gear.

## Center distance

For a pinion and a wheel without correction ( $x/m = 0$ ) or in case of complementary correction (e.g. the pinion with a positive correction  $x/m = +0.5$  and the wheel with a negative correction  $x/m = -0.5$ ), the center distance  $i$  is calculated with the formula:

$$i = \frac{d_1}{2} + \frac{d_2}{2} = \frac{m \cdot (z_1 + z_2)}{2}$$

$$i = d_1^2 + d_2^2 = m \cdot (z_1 + z_2)^2$$

In case  $x_1 + x_2 \neq 0$   $x_1 + x_2 \neq 0$ , the center distance  $i'$  is different from  $i$  and may be calculated solving the following formulas:

$$\text{inv}(\alpha') = \frac{2 \cdot (x_1 + x_2) \cdot \tan(\alpha)}{m \cdot (z_1 + z_2)} + \text{inv}(\alpha)$$

$$\text{inv}(\alpha') = 2 \cdot (x_1 + x_2) \cdot \tan(\alpha) m \cdot (z_1 + z_2) + \text{inv}(\alpha)$$

$$i' = i \cdot \frac{\cos(\alpha)}{\cos(\alpha')}$$

$$i' = i \cdot \cos(\alpha) \cos(\alpha')$$

where  $\alpha'$  is the working pressure angle, different from the pressure angle  $\alpha$  of the rack cutter.

## Clearance

The pinion-wheel clearance  $c$  depends from the value of  $(x_1 + x_2)$  ( $x_1+x_2$ ) and may be calculated with the formula

$$c = m \cdot \left[ 0.25 - \frac{x_1 + x_2}{m} + \frac{z_1 + z_2}{2} \cdot \left( \frac{\cos(\alpha)}{\cos(\alpha')} - 1 \right) \right]$$
$$c = m \cdot [0.25 - x_1 + x_2 + \frac{z_1 + z_2}{2} \cdot (\cos(\alpha) \cos(\alpha') - 1)]$$

For gears with  $x_1 + x_2 = 0$   $x_1+x_2=0$ , the clearance is equal to  $0.25m$  (type A basic rack tooth profile - ISO 53:1998).