

#### Goal

- ☐ In Lab5, you will learn
  - How to read/write the memory.
  - → How to implement a simple image processing algorithm with a more complex FSM.





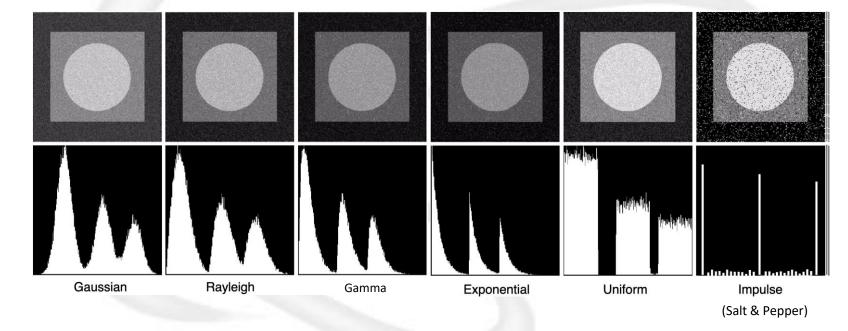
- Introduce to image filter
  - Mean filter (Only introduce)
  - Median filter (This Lab)
- Hardware description
  - Block diagram
  - I/O Information
  - Memory mapping
  - Flow in Lab5
- Criteria
  - Simulation Result
  - Grading policy
  - Requirement & file format



- Noise and Images
  - Principal sources of noise in digital images: during image acquisition, during image transmission.
  - Image acquisition: image sensor might produce noise because of environmental conditions or quality of sensing elements.
  - Image transmission: interference in the channel.



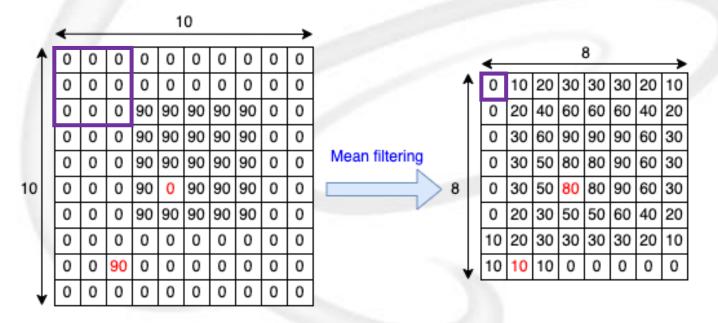
- Different types of image noise
  - Most common noise found in image processing: Gaussian noise, Rayleigh noise, Gamma noise, Exponential noise, Uniform noise, Impulse noise





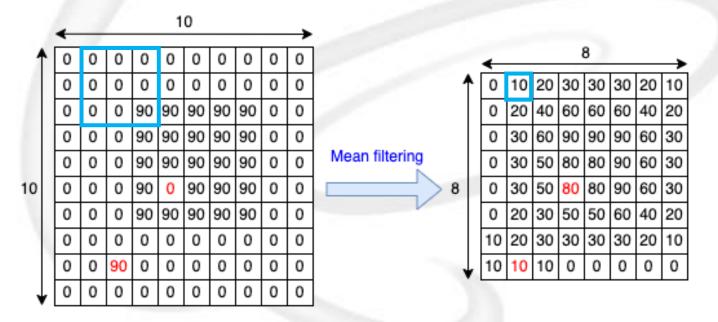


- ☐ Filtering to Remove Noise
  - → We can use spatial filters of different kinds to remove different kinds of noise
- Mean filter
  - → Taking the average of pixel values within a fixed region(ex:3X3 window)
  - This is implemented as the simple smoothing filter Blurs the image to remove noise





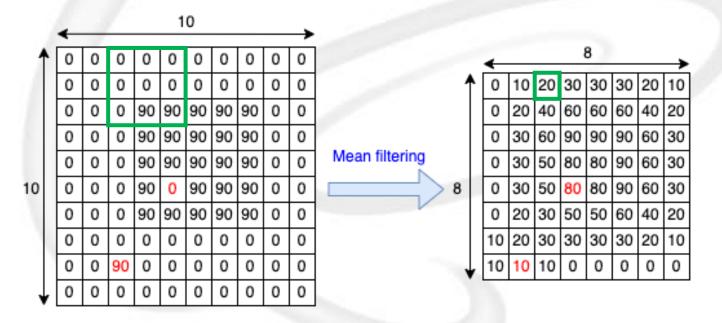
- ☐ Filtering to Remove Noise
  - → We can use spatial filters of different kinds to remove different kinds of noise
- Mean filter
  - → Taking the average of pixel values within a fixed region(ex:3X3 window)
  - This is implemented as the simple smoothing filter Blurs the image to remove noise





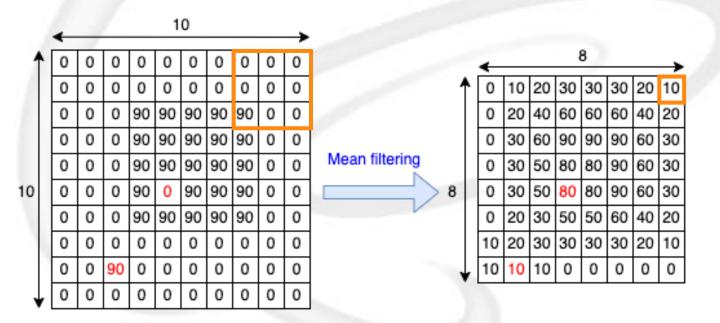


- ☐ Filtering to Remove Noise
  - → We can use spatial filters of different kinds to remove different kinds of noise
- Mean filter
  - → Taking the average of pixel values within a fixed region(ex:3X3 window)
  - This is implemented as the simple smoothing filter Blurs the image to remove noise





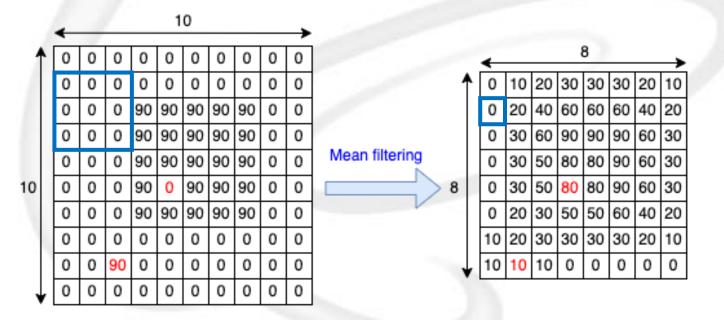
- Filtering to Remove Noise
  - → We can use spatial filters of different kinds to remove different kinds of noise
- Mean filter
  - → Taking the average of pixel values within a fixed region(ex:3X3 window)
  - This is implemented as the simple smoothing filter Blurs the image to remove noise







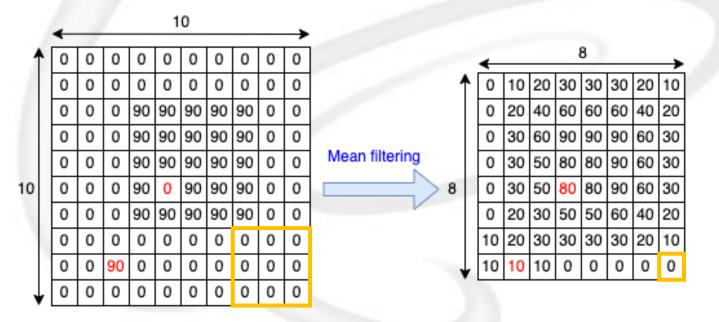
- Filtering to Remove Noise
  - → We can use spatial filters of different kinds to remove different kinds of noise
- Mean filter
  - → Taking the average of pixel values within a fixed region(ex:3X3 window)
  - This is implemented as the simple smoothing filter Blurs the image to remove noise







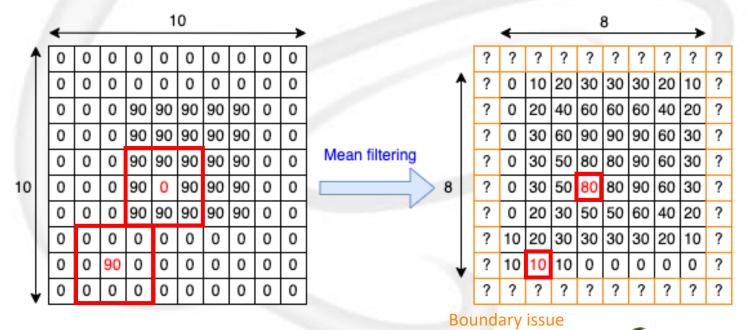
- ☐ Filtering to Remove Noise
  - → We can use spatial filters of different kinds to remove different kinds of noise
- Mean filter
  - → Taking the average of pixel values within a fixed region(ex:3X3 window)
  - This is implemented as the simple smoothing filter Blurs the image to remove noise







- ☐ Filtering to Remove Noise
  - → We can use spatial filters of different kinds to remove different kinds of noise
- Mean filter
  - → Taking the average of pixel values within a fixed region(ex:3X3 window)
  - This is implemented as the simple smoothing filter Blurs the image to remove noise

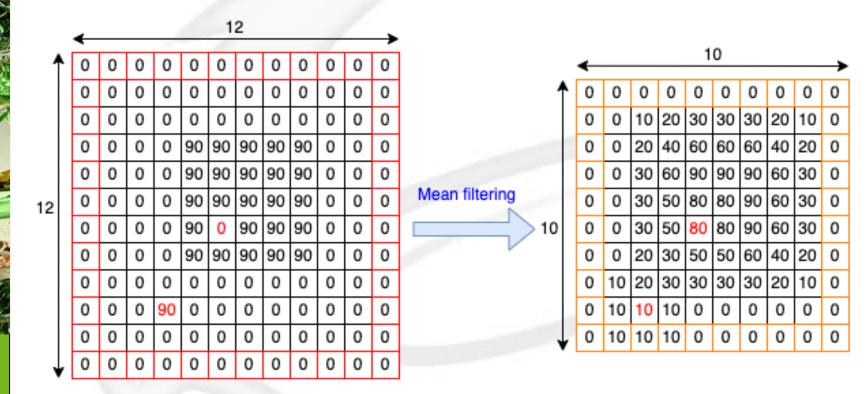




# LPHPLMB VLSI Design LAB

#### Introduce to image filter

- How to solve the boundary issue?
  - Padding (Zero padding)

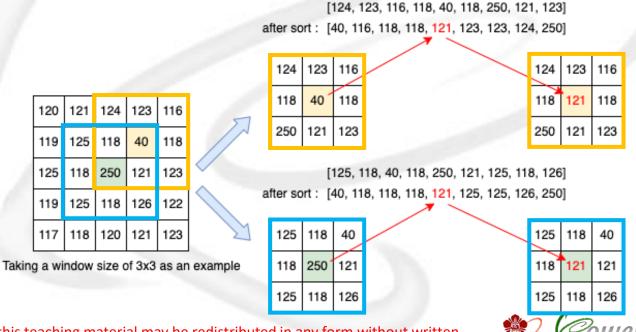


→ You need to do the zero padding in this Lab!



#### Median filter

- Find the median of all pixel values within a fixed range and replace the original central pixel value with this median value.
- → Excellent at noise removal, without the smoothing effects that can occur with other smoothing filters .
- Particularly good when salt and pepper noise is present.
- In Lab5, the window size is 3\*3.



No part of this teaching material may be redistributed in any form without written permission from Prof. Lih-Yih Chiou NCKU LPHP Lab, Taiwan

The effects of different spatial filters



The original image



Add salt-and-pepper



Mean filter( $3 \times 3$ )



Median filter(3 x 3)

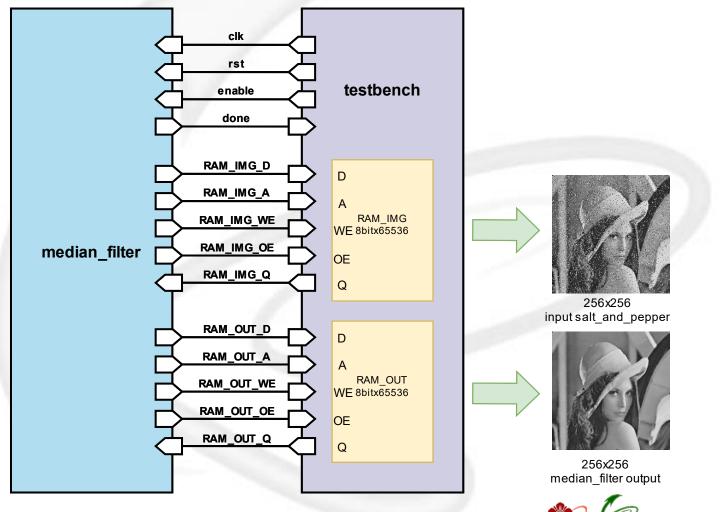




# LPHPLHE VLSI Design LAE

#### **Hardware description**

Block diagram





#### □ I/O Information

Signal	I/O	width	Desc.	
clk	I	1	positive-edged triggered	
rst	- 1	1	asynchronous positive-edged triggered	
enable	I	1	enable signal to start processing	
*_Q	I	8	8-bit data to be transmitted	
*_OE	0	1	Active high read enable signal	
*_WE	0	1	Active high write enable signal	
*_A	0	16	Address	
*_D	0	8	Data	
done	0	1	Finish signal	



■ Memory mapping(1/2)

Content in RAM\_IMG

fig[0]

fig[1]

fig[2]

fig[3]

fig[65533]

fig[65534]

fig[65535]

Storage format for input BMP

fig[0]	fig[255]
	•••
fig[65280]	fig[65535]





■ Memory mapping(2/2)

Content in RAM\_OUT

output[0]

output[1]

output[2]

output[3]

output[65533]

output[65534]

output[65535]

Storage format for output BMP

out[0]		out[255]
	300	
out[65280]	3	out[65535



- enable & done signal
  - → The enable signal will be pulled up to HIGH after reset, and will be maintained for only one cycle.



→ When the testbench receives the done signal, it will start comparing the values inside RAM\_OUT.



#### **Flow in Lab5(1/2)**

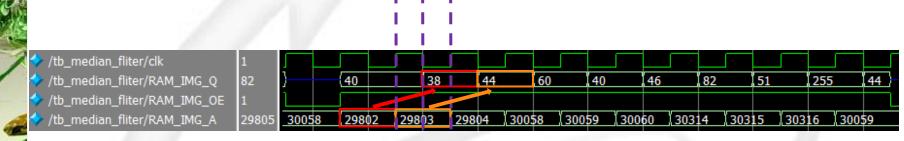
- ☐ Step1
  - → Read each address and its surrounding eight pixels sequentially from RAM.
- ☐ Step2
  - Utilize the sort module to sort the nine pixels and find the median.
- ☐ Step3
  - After finding the median, write it into the memory RAM\_OUT.
  - Repeat step1-step3 until the entire input image is processed.



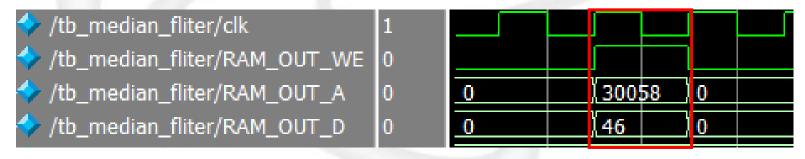


#### Flow in Lab5(2/2)

- The timing information for Read/Write SRAM
  - Read operation (delay one cycle)



- ✓ The memory will output values on the negative edge(T2), and you need to capture data on the positive edge(T3).
- Write operation





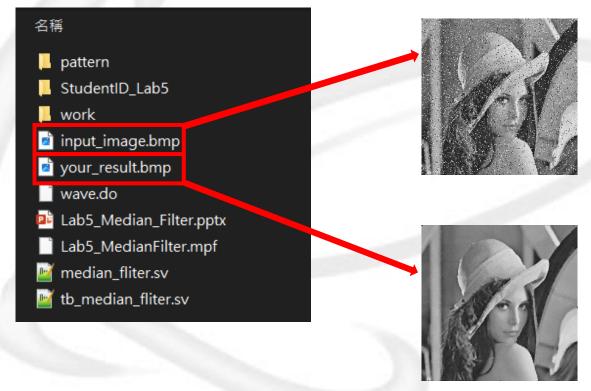
- Simulation result
  - Pass

Failed



#### Criteria

- Simulation result Visualization
  - → It will generate the input picture and your output result in a BMP file when your simulation is finished.





#### **Criteria**

- ☐ Grading policy(100%)
  - → Lab5
    - ◆ Simulation pass (90%)
    - ◆ Report (10%)







- You must finish median filter.v/.sv and pass all patterns
- For Lab5, you need to submit
  - median\_filter.v / median\_filter.sv
  - tb\_median\_fliter.sv
  - StudentID\_Lab5.pdf
- Deadline:2024/03/28 08:59 a.m. (No late submission)





#### Lab5 Requirement & file format

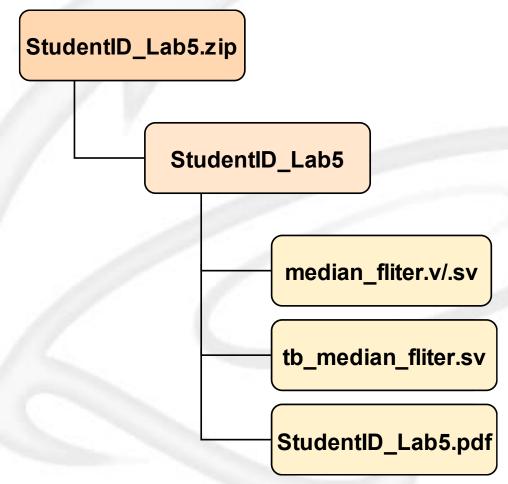
- Friendly reminder
  - → Please complete the assignment by your own, discussion with peers is recommended, but do not cheat.
  - → Warning! Any dishonesty found will result in zero grade.
  - → Warning! Any late submission will also receive zero.
  - → Warning! Please make sure that your code can be compiled in Modelsim, any dead body that we cannot compile will also receive zero.
  - → Warning! Please submit your work according to the specified file format, making sure not to include any unnecessary files. Any unnecessary file found, will lead to 10% deduction from the overall score.



## LPHPLMB VLSI Design LAB

#### **Lab5 Requirement & file format**

File format



### Thanks for listening

