

SYLABUS – teoria grafów:

1. Basic concepts: graphs, paths and cycles, complete and bipartite graphs
2. Matchings: Hall's Marriage theorem and its variations
3. Forbidden subgraphs: complete bipartite and r -partite subgraphs, chromatic numbers, Turán's theorem, asymptotic behaviour of edge density, Erdős-Stone theorem
4. Hamiltonian cycles (Dirac's Theorem), Eulerian circuits
5. Connectivity: connected and k -connected graphs, Menger's theorem
6. Ramsey theory: edge colourings of graphs, Ramsey's theorem and its variations, asymptotic bounds on Ramsey numbers
7. Planar graphs and colourings: statements of Kuratowski's and Four Colour theorems, proof of Five Colour theorem, graphs on other surfaces and Euler characteristics, chromatic polynomial, edge colourings and Vizing's theorem
8. Random graphs: further asymptotic bounds on Ramsey numbers, Zarankiewicz numbers and their bounds, graphs of large first and high chromatic number, complete subgraphs in random graphs.
9. Algebraic methods: adjacency matrix and its eigenvalues, strongly regular graphs, Moore graphs and their existence.

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1 Basic concepts of graph theory

1.1 Graphs

Graph ($G = (V, E)$) - a structure made up of vertices (V) that are connected in pairs with edges (E).

Multigraph - a graph where two vertices are allowed to have more than one edge connecting them.

If a vertex is allowed to be connected to itself, then the graph is called a **graph with loops** and the edge that connects the vertex to itself is known as a **loop**.

Adjacency relation - is the symmetric relation of pairings between vertices of an undirected graph. It is used to construct an adjacency matrix that is another form of representing graphs.



$$\begin{matrix} & 1 & 2 & 3 \\ \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \end{matrix}$$

Directed graph is a graph in which edges have orientation. Here, the set of edges contains ordered pairs of vertices. However, this definition does not allow multiple edges between two vertices. To fix this problem, we introduce another object, ϕ , that is a mapping of edges to ordered pairs of vertices. To avoid confusion, we call such graph a directed multigraph ($G = (V, E, \phi)$).

Mixed graph is a graph that allows both directed and undirected edges.

Weighted graph is a graph in which each edge has a value assigned to it.

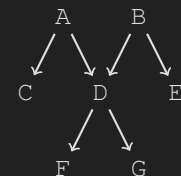
Oriented graph is a directed graph where each edge has a set orientation, that is if an edge $\langle x, y \rangle$ exists, there cannot be an edge $\langle y, x \rangle$.

Regular graph is a graph in which each vertex has the same number of neighbours (degree).

Complete graph is a graph where every pair of vertices is connected with an edge.

Tree is a graph in which any two vertices are connected by exactly one path.

Polytree is a graph whose underlying graph is a tree. For example on the right is a polytree in which subgraph (A, D, F, G) is a tree.



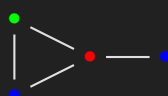
1.2 Paths

A pair of vertices x, y is **connected** if there can be found a collection of edges so that they have connected ends and going through them leads from x to y and vice versa. Such a collection is called a **path**.

A graph is **connected** if each two vertices are connected. A stronger condition, each two vertices are connected with directed edges, makes a graph **strongly connected**.

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Chromatic number - the smallest number of colors needed to color a graph so that every two vertices of an edge have different colors. For example the following graph has chromatic number 3:



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Bipartite graph is a simple graph where vertex set can be partitioned into two sets. Alternatively, it is a graph with chromatic number 2.

Planar graph is a graph that can be drawn on a plane so that no two edges intersect.

