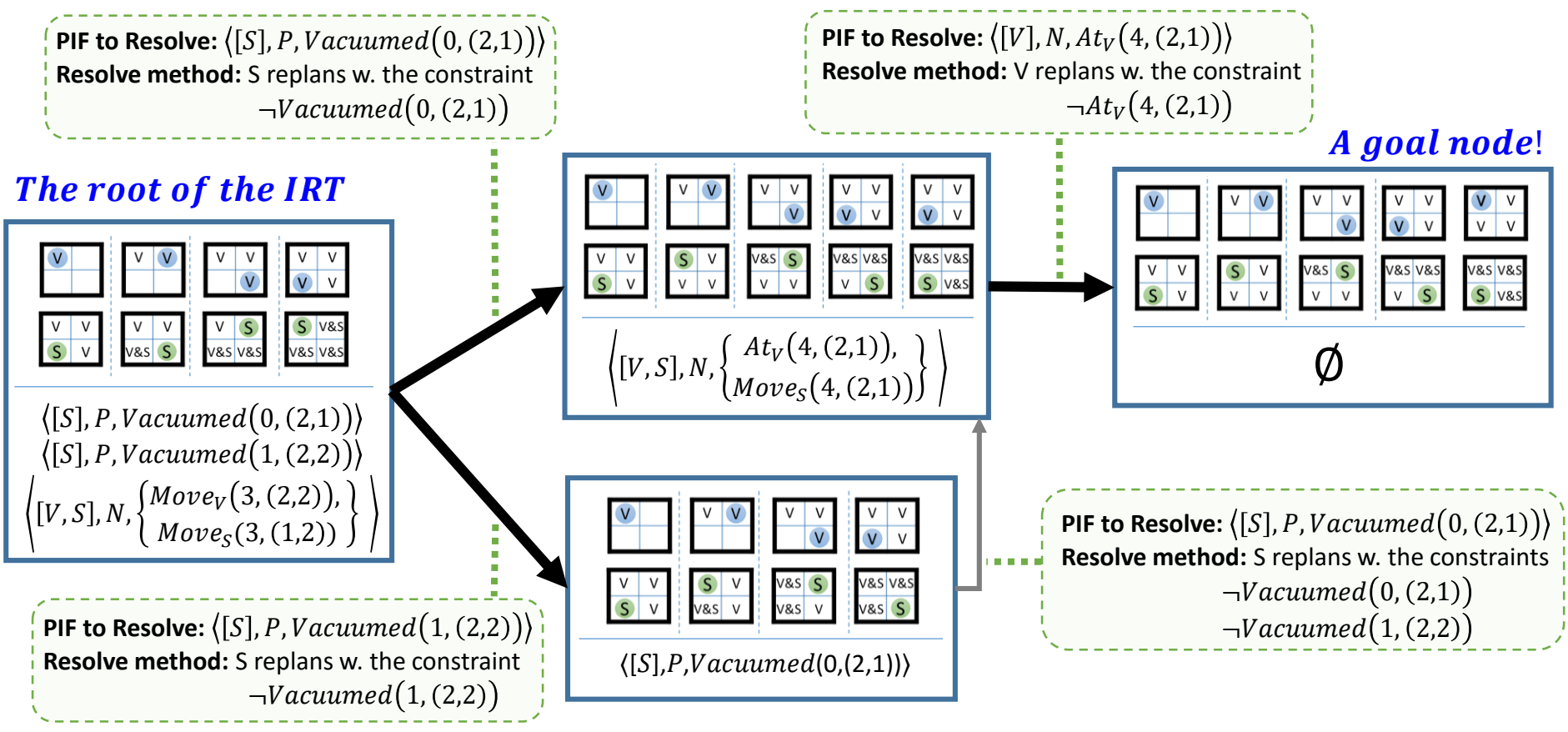
PIF to Resolve: ⟨[S], P, Vacuumed(0, (2,1))⟩
Resolve method: S replans w. the constraint
¬Vacuumed(0, (2,1))
PIF to Resolve: ⟨[V], N, At_V(4, (2,1))⟩
Resolve method: V replans w. the constraint
¬At_V(4, (2,1))
A goal node!
The root of the IRT
⟨[S], P, Vacuumed(0, (2,1))⟩
⟨[S], P, Vacuumed(1, (2,2))⟩
⟨[V, S], N, {Move_V(3, (2,2)), Move_S(3, (1,2))}⟩
⟨[V, S], N, {At_V(4, (2,1)), Move_S(4, (2,1))}⟩
∅
⟨[S], P, Vacuumed(0,(2,1))⟩
PIF to Resolve: ⟨[S], P, Vacuumed(1, (2,2))⟩
Resolve method: S replans w. the constraint
¬Vacuumed(1, (2,2))
PIF to Resolve: ⟨[S], P, Vacuumed(0, (2,1))⟩
Resolve method: S replans w. the constraints
¬Vacuumed(0, (2,1))
¬Vacuumed(1, (2,2))