

# Elliptic PDE

Fang-Hua Lin

Transcribed by Ron Wu

This is a graduate course, offered in fall 2013 at New York University. Course textbooks are *Elliptic Partial Differential Equations* by Han, Lin; *Elliptic Partial Differential Equations of Second Order* by Gilbarg, Trudinger; and *Fully Non-linear Elliptic Equations* by Caffarelli, Cabre. There would be no midterm or final. Textbooks used in PDE I & II may be good for review. They are *Partial Differential Equations* by Fritz John, and *Partial Differential Equations* by Evans.

## Contents

<b>1</b>	<b>Course Overview</b>	<b>3</b>
1.1	Basic Methods . . . . .	3
1.2	Classical Theories (1900 - 1955) . . . . .	4
1.3	More Recent Results (1955 - ) . . . . .	5
<b>2</b>	<b>Laplace Operators</b>	<b>8</b>
2.1	Mean-Value Properties . . . . .	8
2.2	Harnack Inequality . . . . .	10
2.3	Harmonic Measure . . . . .	11
2.4	Perron Methods . . . . .	13
2.5	Regular Point on $\partial\Omega$ for $\Delta$ . . . . .	15
2.6	Fundamental Solutions . . . . .	16
2.7	Maximum Principle on Unbounded Boundary . . . . .	17

<b>3</b>	<b>Classical Results</b>	<b>17</b>
3.1	Dini Continuous . . . . .	17
3.2	Unbounded Boundary . . . . .	20
3.3	Probability Measure . . . . .	21
3.4	Quasi-Open, Quasi-Continuous . . . . .	23
3.5	Serrin-Weinberger Method . . . . .	24
3.6	Maximum Principle . . . . .	27
3.7	Moving Plane Method . . . . .	29
<b>4</b>	<b>Modern Results</b>	<b>31</b>
4.1	Krylov-Safonov Theorem . . . . .	31
4.2	Calderon-Zygmund Lemma . . . . .	31
4.3	Continuity Method . . . . .	31
4.4	Lax-Milgram . . . . .	31
4.5	DeGiorgi Theory . . . . .	31
4.6	John-Nirenberg Estimate . . . . .	31
4.7	Morrey-Stampacchia Theory . . . . .	31
<b>5</b>	<b>More Recent Developments</b>	<b>31</b>

# 1 Course Overview

## 1.1 Basic Methods

Elliptic PDE is when  $a_{ij}$  positive definite, it has two forms: Divergence Form v.s. non Divergence Form.

### Divergence Form

$$\partial_{x_i}(a_{ij}(x)u_{x_j}) = f$$

one uses *Variational Method*, or *Energy Method*.

Assume (1)  $a_{ij}(x) \in L^\infty$  (2)  $a_{ij}(x)\xi_i\xi_j \geq \lambda|\xi|^2$   $\xi \in \mathbb{R}^n$ , then in Hilbert space, solution exists always in integral form (often involve integration by parts). More recently result (1960s) we will study include *De Giorgi-Nash-Moser* gives Holder continuous.

More specifically one can use *Dirichlet Principle*. That is if

$$\Delta u = 0$$

then  $u$  is the energy minimizer,

$$\min \int |\nabla u|^2 dx$$

### Non-Divergence Form

$$a_{ij}(x)u_{x_i x_j} + b_i(x)u_{x_i} + c(x)u = f$$

Assume (1) symmetric  $a_{ij} = a_{ji}$  (2) uniformly elliptic  $\Lambda I \geq (a_{ij}) \geq \lambda I$ .

one uses *Maximum principle for Hopf-Type or Alexandroff-Type*, or uses *Viscosity Solutions*. All of them give  $C^\alpha$  regularities. More recently (1980s) *Krylov-Safonov* show more general result, no smooth/continuity assumptions on  $a_{ij}$ , give  $u \in C^\alpha(\bar{\Omega})$ .

### Affine Invariant

The theorems mentioned above are stated in Balls  $B_R$  in  $\mathbb{R}^n$ .

For example, pde

$$\det(u_{ij}) = 1, \quad (u_{ij}) > 0$$

In 2-D, this equals to

$$u_{xx}u_{yy} - u_{xy}^2 = 1$$

then  $u(x)$  is a solution, implies  $u(Ax + b)$  is a solution  $\det(A) = 1$ , more specifically, this means the solution is invariant under rotation, and scalaring, i.e. *Affine Invariant*. That is  $R \in O(n)$ ,  $u \rightarrow u(Rx + a)$  or  $u \rightarrow u(\lambda x)$ .

Instead of working with Balls, we can also use *convex* set.

**Theorem 1.** (*John's Lemma*) Let  $\Omega$  be a convex body in  $\mathbb{R}^n$ , then there is an affine transformation  $T : x \rightarrow Ax + b$   $\det(A) = 1$  such that

$$B_R^n \subseteq T(\Omega) \subseteq B_{c(n)R}^n$$

Note 2. where  $c(n) = \sqrt{n}$  (?)

## 1.2 Classical Theories (1900 - 1955)

Review Function Theory, Geometric Function Theory (conformal Mapping)

Cauchy Integral

$$f(z) = \frac{1}{2\pi i} \oint_{\partial\Omega} \frac{f(\xi)}{\xi - z} d\xi \implies f^n(z) = \frac{1}{2\pi i} \oint_{\partial\Omega} \frac{f^n(\xi)}{\xi - z} d\xi$$

so

$$|f(z)| \leq \max |f(\xi)| \left( \frac{l(\partial\Omega)}{2\pi \text{dist}(z, \xi)} \right)^{1/n} \leq_{n \rightarrow \infty} \max |f(\xi)|$$

## Maximum Principle

$$a_{ij}(x)u_{x_i x_j} = 0$$

in  $\Omega$ , then  $\forall x \in \Omega$

$$|u(x)| \leq \max_{y \in \partial\Omega} |u(y)|$$

Notice this is *no* correct for vector functions  $u = (u^1, u^2, \dots, u^n)$

$$Lu = 0 \iff a_{\alpha\beta}^{ij} u_{x_i x_j}^\beta = 0 \text{ in } \Omega, \alpha = 1, 2, \dots, n$$

then

$$\sup_{x \in \Omega} |u(x)| \not\leq \sup_{y \in \partial\Omega} |u(y)|$$

## Gradient Estimate

$$f^{(n)}(z) = \frac{c(n)}{2\pi i} \oint_{\partial\Omega} \frac{f(\xi)}{(\xi - z)^{n+1}} d\xi$$

Looking for an integral representation for the solution. Things involved are *Power Series* (Analyticity), *Unique Continuation*, *Liouville Theorem* (local estimate). 1950s Power Series for non-linear pde developed.

**Theorem 3.** (*Hopf Theorem 2-D case*)

$$a_{ij}(x)u_{x_i x_j} = 0$$

in  $\mathbb{R}^2$ ,  $(a_{ij}) > 0$ . If  $u = o(|x|)$  as  $|x| \rightarrow \infty$ , then  $u(x) = \text{constant}$ .

## Singularities

Is it *removable* or not? Other involves *Fundamental Solutions*, *eigenvalues* & *eigenfunctions*.

For example

$$\begin{cases} \Delta u^\lambda + \lambda u = 0 & \text{in } \Omega \\ u^\lambda = 0 & \text{on } \partial\Omega \end{cases}$$

we require the solution to be normalized

$$\int_{\Omega} |u^\lambda|^2 dx = 1$$

choose a probability measure  $\mu_\lambda = |u^\lambda|^2 dx$ , let  $\mu_\lambda \rightharpoonup \mu$ .

Questions (1) What's the support of  $\mu$ ? (2) Do we have to take subsequence to make the weak convergence to work?

## Potential Theory

More of these are in Harmonic Analysis.

## 1.3 More Recent Results (1955 - )

### DeGiorgi-Moser-Nash

Late 1950's DeGiorgi-Moser-Nash developed  $C^\alpha$  regularity for  $(a_{ij}(x)u_{x_j})_{x_i} = 0$ . This solves *Quasilinear* Elliptic PDEs. The problem is motivated by Hilbert's 19th Problem: "whether the solutions of regular problems in the calculus of variations are always analytic." More improved results see Serrin, Trudinger.

## Krylov-Safonov

1980's Krylov-Safonov showed

$$a_{ij}(x)u_{x_i x_j} = 0 \implies u \in C^\alpha$$

with no smooth assumption on  $a_{ij}$ . This problem is motivated by solving  $F(D^2u) = 0$ .

Example

$$\begin{cases} F(D^2u) = 0 \\ u|_{\partial\Omega} = g \end{cases}$$

is uniformly elliptic at  $u$  iff

$$\lambda |N| \leq F(M + N) \leq \Lambda |N|$$

or

$$\lambda I \leq \left( \frac{\partial F}{\partial M_{ij}} \right) \leq \Lambda I$$

where  $M \in S_{n \times n}$ ,  $N \in S_{n \times n}^+$ .

Now

$$0 = \partial_l F(D^2u) = F_{ij}(D^2u) D_{ij}^2 u_l = 0$$

Let  $a_{ij}(x) = F_{ij}(D^2u)$  uniformly elliptic, let  $V = u_l$  so

$$a_{ij}(x)v = 0$$

By Krylov-Safonov

$$\begin{aligned} \implies D^2 u_l &\in C^\alpha(\Omega) \\ \implies u &\in C^{1,\alpha} \end{aligned}$$

In addition, if  $F$  is concave, then  $u \in C^{2,\beta}(\Omega)$ ,  $\beta > 0$  by Evans, Krylov, Caffarelli.

## Regularity Theory (Linear)

$$\begin{cases} a_{ij}(x)u_{x_i x_j} = f(x) & \text{in } \Omega \subseteq \mathbb{R}^n \\ u|_{\partial\Omega} = 0 \\ \Lambda I \geq (a_{ij}(x)) \geq \lambda I \end{cases}$$

(i)  $a_{ij}(x) \in C^\alpha(\bar{\Omega})$  Hölder continuous ( $1 > \alpha > 0$ )  $\implies \|u\|_{C^{\alpha+2}(\bar{\Omega})} \leq c(n, \alpha, \lambda, \Lambda, \|a_{ij}\|_{C^\alpha}) \|f\|_{C^\alpha(\bar{\Omega})}$ .

This is called *Schauder Estimate*. See Trudinger Chap 6.

(ii)  $a_{ij}(x) \in C^0(\bar{\Omega}) \implies a_{ij} \in VMO$ .

This was proved by C. B. Morrey, L. Nirenberg. Furthermore Calderon-Zygmund, showed

$$a_{ij}(x) \in C^0(\bar{\Omega}) \implies \|u\|_{W^{2,p}(\Omega)} \leq c(n, \alpha, \lambda, \Lambda, \|a_{ij}\|_{C^\alpha}) \|f\|_{L^p(\Omega)}$$

$\forall 1 < p < \infty$ , then by Sobolev invariant, we got  $u \in C^{1-\alpha} \forall 0 < \alpha < 1$ .

Recall  $f \in VMO$  (*vanishing mean oscillation*) if

(a)  $f \in BMO$  (*bounded mean oscillation*) i.e.

$$\oint_{B_r} |f - \bar{f}_{B_r}| dx \leq C, \forall B_r \in \Omega$$

(b)

$$\lim_{r \rightarrow 0} \frac{1}{r^n} \int_{B_r} \left| f(x) - \oint_{B_r} f \right| \rightarrow 0$$

uniformly for  $x \in \Omega$ .

**Theorem 4.** *If  $f \in W^{1,n}(\Omega)$ ,  $\dim \Omega = n$ , then  $f \in VMO$ .*

*Proof.* By Poincare inequality

$$\oint_{B_r} |f - \bar{f}_{B_r}|^n \leq c(n) \int_{B_r} |\nabla f|^n dx \rightarrow 0$$

as  $r \rightarrow 0$

□

The reverse version of the theorem goes like

$\forall p \in (1, \infty)$ ,  $\exists \delta_p = \delta_p(n, \lambda, \Lambda)$  st if

$$\limsup_{r \rightarrow 0^+} \oint_{B_r(x)} |a_{ij}(y) - (a_{ij})_{B_r}| \leq \delta_p$$

uniformly  $x \in \Omega$ , then

$$u \in W^{2,p}(\Omega)$$

## Divergent Type

$$\begin{cases} \partial_{x_i}(a^{ij}(x)u_{x_i}) = f \\ u|_{\partial\Omega} = 0 \end{cases}$$

(1) Assume  $a^{ij} \in C^\alpha$ ,  $u \in C^{1,\alpha}$  if  $f \in L^p$ ,  $\alpha = 1 - n/p(\alpha)$  by G. Stampacchia, M. Giaquinta, E. Giusti in later 1970's.

(2)  $a^{ij} \in C^0 \implies u \in W^{1,p} \forall 1 < p < \infty$ ,  $f \in L^n$

(3)  $a^{ij} \in VMO \implies u \in W^{1,p}$  or  $a^{ij} \in \text{small BMO norm} \implies u \in W^{1,p_0}$ .

(4)  $\partial_{x_i}(a^{ij}(x)u_{x_i}) = f \implies u \in C^\alpha$  for some optimal  $\alpha = \alpha(n, \lambda, \Lambda) > 0$

## 2-D Cases

Non-Divergent case

Worked by Morrey, Nirenberg

$$a_{ij}(x)u_{x_i x_j} = 0$$

in  $C^{1,\alpha}$ , then  $(\nabla u) = (u_x, u_y)$  the map  $\Omega \rightarrow \mathbb{R}^2$  is quasi-conformal.

Divergent case

Worked by Ahlfors, Courant, Bernstein  $Du \in C^\alpha \implies u \in C^\alpha$ .

## 2 Laplace Operators

**Definition 5.** A function  $u \in C^2$  is harmonic if  $\Delta u = 0$  in  $\Omega$ .

But most of the discussion below will only assume  $\Delta u = 0$  in  $\Omega$ , not  $u \in C^2$ .

### 2.1 Mean-Value Properties

**Definition 6.** Let  $u \in L^1(\Omega)$ , we say  $u$  satisfies mean-value property if

$$u(x) = \frac{1}{|B_r|} \int_{B_r(x)} u(y) dy$$

for a.e.  $x \in \Omega$ , for any  $r > 0$ , s.t.  $B_r(x) \subset \Omega$ .



This definition is equivalent to

$$u(x) = \frac{1}{|\partial B_r|} \int_{\partial B_r(x)} u(y) dS_y$$

**Theorem 7.** *If  $u$  satisfies the mean-value property, then  $u$  is smooth.*

(For proof, see Lin Theorem 1.8) Basic idea, let  $\phi(r) \in C_0^1(B_r)$  with  $\int_{B_1} \phi(r) dr = 1$ , let  $p_\varepsilon(x) = \frac{1}{\varepsilon^n} \phi(\frac{x}{\varepsilon})$ , one can show

$$p_\varepsilon * u(x) = u_\varepsilon(x) \in C^\infty$$

and

$$u_\varepsilon(x) \equiv u(x), \forall \varepsilon > 0$$

**Theorem 8.** *If  $u \in C^2(\Omega)$  and  $\Delta u = 0$ , then  $u$  satisfies the mean value property.*

That is because

$$0 = \int_{B_r(x)} \Delta u(y) dy = \int_{\partial B_r(x)} \frac{\partial u}{\partial \nu} dS_y = r^{n-1} \frac{\partial}{\partial \nu} \int_{\partial B_r(x)} u(y).$$

**Theorem 9.** *If  $u$  satisfies mean-value property, then  $u$  satisfies the maximum principle,*

$$\max_{\Omega} u \leq \max_{\partial \Omega} u$$

*If  $u(x_0) = \max_{\Omega} u$ ,  $x_0 \in \Omega \implies u \equiv \text{constant}$  in a connected component of  $\Omega$  that contains  $x_0$ .*

**Theorem 10.** *Let  $u$  be a distribution, then  $\Delta u$  is also a distribution.*

*Proof.* By Wyl Theorem,  $\Delta u = 0$  in  $\mathcal{D}' \iff u$  is smooth and  $\Delta u = 0$  point wise. That  $\Delta u = 0$  in  $\mathcal{D}'$  implies

$$\Delta \rho_\varepsilon * u = \rho_\varepsilon * \Delta u = 0$$

So  $u_\varepsilon = \rho_\varepsilon * u$  is harmonic and  $u_\varepsilon \rightarrow u$  as  $\varepsilon \rightarrow 0$ , we have

$$u_\varepsilon \xrightarrow{C_{loc}^{2,\alpha}(\Omega)} u$$

Thus  $\Delta u = 0$  in  $C^2$  sense. □

Now we study Gradient Estimate for harmonic functions  $\Delta u = 0$  in  $B_1$ ,  $\Delta u_{x_i} = 0$ , by mean-value property

$$\begin{aligned} u_{x_i}(x_0) &= \frac{1}{|B_r|} \int_{B_r(x_0)} u_{x_i} dx_i \\ &= \frac{1}{|B_r|} \int_{\partial B_r(x_0)} u \nu_i dS_y \end{aligned}$$

**Theorem 11.** (*Gradient Estimate*) Given  $u$  above,

$$|u_{x_i}(x_0)| \leq \frac{|\partial B_r(x_0)|}{|B_r|} \int_{\partial B_r(x_0)} |u| = \frac{c_n}{r} \int_{\partial B_r(x_0)} |u|, \forall r$$

Moreover if  $u \geq 0$  in  $\Omega$

$$|\nabla u|(x_0) \leq \frac{c_n}{r} \int_{\partial B_r(x_0)} u \leq \frac{c_n}{r} u(x_0)$$

The last line is equal to

$$|\nabla \log u|(x_0) \leq \frac{c_n}{r}$$

**Theorem 12.**

$$\begin{cases} \Delta u = 0 & \text{in } B_R(0) \\ u|_{\partial B_R} = \phi \end{cases}$$

is solvable if  $\phi \in C^0(\partial B_R)$ , and Poisson Formula

$$u(x) = c_n \int_{\partial B_R} \frac{R^2 - |x|^2}{|x - y|^n} \phi(y) dS_y$$

## 2.2 Harnack Inequality

Use Poisson Formula, Gradient Estimate, and Mean-Value property, one can get Harnack Inequality, which states

**Theorem 13.** Let  $u \geq 0$  be s.t.  $\Delta u = 0$  in  $\Omega$  then

$$u(x) \leq c(K, \Omega) u(y)$$

for all  $x, y \in K \Subset \Omega$ .

$c$  depends on the ratio of the size of  $\Omega$  and  $\text{dist}(K, \Omega)$ . We can check this by a special case

If  $\Delta u = 0$  in  $B_R$  and  $u \geq 0$  in  $B_R$ ,

$$\begin{cases} u(x) \leq c_n u(y) \\ x, y \in B_{R/2} \end{cases}$$

let

$$P(x, y) = c_n \frac{R^2 - |x|^2}{|x - y|^2}$$

$x$  in  $B_R$  and  $y \in \partial B_R$ , choose  $r$  s.t.  $|x| < r < R$ , then

$$c_n \frac{R - r}{(R + r)^{n-1}} \leq P(x, y) \leq c_n \frac{R^2 - r^2}{(R - r)^n} = c_n \frac{R + r}{(R - r)^{n-1}}$$

$c_n \frac{R - r}{(R + r)^{n-1}}$  gives the optimal constant. That is because for fixed  $y \in \partial B_R$

$$\begin{cases} \Delta_x P(x, y) = 0 & \text{in } B_R \\ P(x, y)|_{x=\partial B_R} \equiv \delta_y \end{cases}$$

One can also see that for fixed  $y \in \partial B_R$ ,  $\{P(x, y)\} = H_+$ , the set of positive harmonic function on  $B_R$ , forms a *positive cone* in  $C(B_R)$ . Here  $K$  = extreme points of  $H_+$ .

## 2.3 Harmonic Measure

Let  $h \geq 0$ ,  $\Delta h = 0$  in  $B_R$ ,

$$h = \int_K \phi_y d\mu(y)$$

We say  $u$  satisfies the *Martin boundary*, if  $u > 0$ , and

$$\Delta u - c^2 u = 0$$

or

$$\Delta u + \vec{b} \cdot \vec{\nabla} u + c(x)u = 0$$

in  $\mathbb{R}^n$ . Let

$$\begin{cases} \Delta u = 0 & \text{in } \Omega \\ u = \phi & \text{on } \partial\Omega \end{cases}$$

$\phi \in C(\partial\Omega)$ ,  $\Omega$  open and bounded. let  $x_0 \in \Omega$ , then for all  $\phi \in C(\partial\Omega)$ , the map  $l$

$$\phi \xrightarrow{l} u_\phi(x_0)$$

is linear and positive representation,

$$l(\phi) = u_\phi(x_0) = \int_{\partial\Omega} dw_{x_0}(y)$$

$\{w_{x_0}(y)\}$  probability measure on  $\partial\Omega$ .

The support of  $w_{x_0}(\cdot)$ ,  $K$ , is a subset of  $\partial\Omega$ . For  $x_1, x_2 \in K \Subset \Omega$ , ( $K$  compact) one has

$$w_{x_1} \leq cw_{x_2} \leq c^2 w_{x_1}$$

where  $c = c(K)$ .

When  $n = 2$ , the *Hausdorff dimension* of  $K$  is 1. This is due to T. Wolff.

$$\eta(r) = r \log(\log(\log r))$$

When  $n \geq 3$ , the *Hausdorff dimension* of  $K \leq n - \varepsilon(n)$ . This is due to J. Bourgain.

More facts:  $\exists \Omega$  s.t. *Hausdorff dimension* of  $K > n - 1$ . And the following

**Theorem 14.** (*Dahlberg's theorem*) *If  $\Omega$  is Lipschitz, then  $w_{x_0}$  is an  $A_p$  weight.*

C. Kenig studied harmonic measure on Lipschitz domains, his main result

**Theorem 15.** *For  $1 < p \leq 2 + \delta$*

$$\left( \int_E w^p \right)^{1/p} \leq c_p \int_E w$$

Let us now consider distribution function. let

$$Lu = \frac{\partial}{\partial x_i} (a_{ij}(x) u_{x_j}) = 0$$

$(a_{ij}(x))$  positive definite, and  $\lambda |\xi|^2 \leq a_{ij}(x) \xi_i \xi_j \leq \Lambda |\xi|^2$ . Since

$$\Delta \frac{c_n}{r^{n-2}} = -\delta_0$$

consider  $G(x, y)$

$$LG = -\delta_x$$

and

$$E_r(x) = \{y \in \mathbb{R}^n : G(y, x) \geq r^{2-n}\}$$

Let  $Lu = 0$ , then

$$\begin{aligned} u(x) &= \int_{E_r} (GLu - uLG) \\ &= \int_{\partial E_r} (GA \nabla u \cdot \nu - u(A \nabla G) \cdot \nu) ds \\ &\geq r^{2-n} \int_{\partial E_r} A \nabla u \cdot \nu + \int_{\partial E_r} u(A |\nu|) |\nabla G| \\ &= r^{2-n} \int_{E_r} Lu + \int_{\partial E_r} u(A |\nu|) |\nabla G| \\ &= \int_{\partial E_r} Au(y) |\nabla G| dS_y \end{aligned}$$

**Exercise 16.** Find mean-value formula for

$$\Delta u + c^2 u = 0$$

$$\Delta u - c^2 u = 0$$

**Exercise 17.** Consider the region  $\Omega$  in  $\mathbb{R}^2$  is bounded by  $x, y$  axes and a line  $y = -ax + b$ ,  $a, b > 0$ . Solve  $\Delta u = 0$  in  $\Omega$  with the boundary conditions  $u = 0$  on  $y$  axis and  $\frac{\partial u}{\partial y} = 0$  on the other two edges. Show that

$$u = cx, \quad c \in \mathbb{R}$$

are all solutions. Generalize this problem to n-dim.

## 2.4 Perron Methods

We solve

$$\begin{cases} \Delta u = 0 & \text{in } \Omega \\ u = \phi \in C(\partial\Omega) \end{cases}$$

Let  $S_\phi = \{v | v \text{ is subharmonic in } \Omega \text{ and } v \leq \phi \text{ on } \partial\Omega\}$ .

**Definition 18.**  $v \in C(\Omega)$  is called subharmonic if  $v \leq u$  in  $B_r(x_0) \subset \Omega$ .

Here  $\Delta u = 0$  in  $B_r(x_0)$ ,  $u|_{\partial B_r(x_0)} = v|_{\partial B_r(x_0)}$ . These are equivalent to  $v(x_0) \leq \int_{B_r(x_0)} v(y) dy$ .

**Theorem 19.** (i)  $S_\phi \neq \emptyset$ ,  $v = \min_{\partial\Omega} \phi \equiv m \in S_\phi$ .

(ii)  $u_\phi(x) = \sup_{v \in S_\phi} v(x)$  is well-defined, and it is  $\leq M \equiv \max_{\partial\Omega} \phi$ .

**Theorem 20.**  $u_\phi$  is harmonic in  $\Omega$ ,  $u_\phi \leq \phi(x) \forall x \in \partial\Omega$ .

*Proof.* Take  $x_0 \in \Omega$ ,  $B_r(x_0) \subset \Omega$ ,  $\exists v_i \in S_\phi$  s.t.  $v_i(x_0) \rightarrow u_\phi(x_0)$ .

Let  $\tilde{v}_i = \begin{cases} w_i & \text{in } \overline{B_r(x_0)} \\ v_i & \text{outside } B_r(x_0) \end{cases}$ , then  $\begin{cases} \Delta w_i = 0 & \text{in } B_r(x_0) \\ w_i = v_i & \text{on } \partial B_r(x_0) \end{cases}$ . More

$$v_i \leq \tilde{v}_i \implies \tilde{v}_i(x_0) \rightarrow u_\phi(x_0)$$

and

$$m \leq w_i \leq M$$

implies  $v \in S_\phi$ ,  $m \in S_\phi$  and  $\max(v, m) \in S_\phi$ . Thus

$$w_i \xrightarrow{C_{loc}^{2,\alpha}} w \quad \text{in } B_r(x_0)$$

with  $\Delta w = 0$ . Next  $u_\phi \equiv w$  on  $B_r(x_0)$ . Let  $x_1 \in B_r(x_0)$   $\exists \bar{v}_i \in S_\phi$  s.t.  $\bar{v}_i(x_1) \rightarrow u_\phi(x_1)$ . And  $\Delta \bar{w}_i = 0$  in  $B_r(x_0)$

$$\bar{w}_i = \begin{cases} \max(\tilde{v}_i, \bar{v}_i) & \in S_\phi \\ \max(\tilde{v}_i, \bar{v}_i)|_{\partial B_r} \end{cases}$$

So  $\bar{w}_i$  is harmonic and  $\bar{w}_i \rightarrow \bar{w}$  is harmonic in  $B_r(x_0)$ ,  $\bar{w} \geq w$  in  $B_r(x_0)$ . Combining  $\bar{w}(x_0) \geq w(x_0) = u_\phi(x_0)$  and  $\bar{w}(x_0) \leq u_\phi(x_0)$ ,  $\bar{w} \equiv w \implies w(x_1) = u_\phi(x_1) \forall x_1 \in B_r(x_0)$ .

Now we show  $u_\phi(x_0) = \phi(x_0)$  for any  $x_0 \in \partial\Omega$ .

**Definition**  $x_0 \in \partial\Omega$ ,  $B_{x_0}(x)$  is called a barrier function for  $\Delta$  at  $x_0$  if  $B_{x_0}(x) \in C(\Omega)$ ,  $\Delta B_{x_0}(x) = 0$  and  $B_{x_0}(x_0) = 0$  and  $B_{x_0}(x) < 0 \forall x \in \partial\Omega$ .

If at  $x_0 \in \Omega$  s.t. such  $B_{x_0}(x)$  exists, then  $u_\phi(x_0) = \phi(x_0)$ . (see theorem 22 below)  $\square$

### Lecture 3 (9/25/13)

#### Summary of Perron's Method

For  $\Delta u = 0$  in  $\Omega \subseteq \mathbb{R}^n$  (bounded, open),  $u|_{\partial\Omega} = \phi \in C(\partial\Omega)$ , Perron method is based on

- (a) Maximum Principle (comparison principle)
- (b) Solvability of the problem on a ball  $B$ .

$S_\phi = \{v \in C(\bar{\Omega}) : v \text{ subharmonic in } \Omega \text{ \& } v \leq \phi \text{ on } \partial\Omega\}$  then (i)  $S_\phi \neq \emptyset$   
(ii)  $u_\phi(x) = \sup_{v \in S_\phi} v(x)$ ,  $x \in \Omega$  is the solution.

## 2.5 Regular Point on $\partial\Omega$ for $\Delta$

**Definition 21.**  $x_0$  is called regular point of  $\Delta$  if  $\exists B_{x_0}(x)$  continuous in  $B_R(x_0) \cap \bar{\Omega}$  s.t.  $B_{x_0}(x_0) = 0$ ,  $\Delta B_{x_0}(x) \geq 0$  and  $B_{x_0} < 0 \ \forall x \in \partial\Omega$ .

**Theorem 22.**  $x$  is regular  $\implies u_\phi(x_0) = \phi(x_0)$ .

*Proof.*  $m \equiv \inf_{\partial\Omega} \phi \leq u_\phi \leq M \equiv \sup_{\partial\Omega} \phi$ ,  $\forall x \in B_R(x_0) \cap \Omega$ ,  $\forall \varepsilon > 0$ ,  $\exists K(R, m, M, \varepsilon)$ , s.t.

$$\phi(x_0) - \varepsilon + KB_{x_0} \leq u_\phi(x) \leq \phi(x_0) + \varepsilon - KB_{x_0}(x)$$

$$\lim_{x \rightarrow x_0} u_\phi(x) = \phi(x_0)$$

$$B_{x_0}(x) \leq -c_\delta < 0, \text{ on } B_\delta^c(x_0) \cap \partial\Omega$$

then Maximum principle implies the conclusion.  $\square$

**Example 23.** If  $\Omega$  has an exterior cone at  $x_0 \in \partial\Omega$ , with angle  $\theta_0 \in (0, \pi)$ , use conformal mapping, one can show

$$-B_{x_0}(x) = r^{1+\alpha} \sin\left(\frac{\theta}{\theta_0} \pi\right)$$

$\alpha = \alpha(\theta_0) > 0$ , and  $\Delta B_{x_0}(x) = 0$  in  $\Omega$ ,  $B_{x_0}(x_0) = 0$ , and  $B_{x_0} \leq 0$ .

**Theorem 24.** (*Wiener Criterion*) If  $x_0 \in \partial\Omega$ , then  $x_0$  is regular for  $\Delta \iff$

$$\int_0^{r_0} \frac{c_{x_0}(\rho)}{\rho^{n-1}} d\rho = \infty.$$

where  $c_{x_0}(\rho) = \text{capacity of } \Omega^c \cap B_\rho(x_0)$ .

**Definition 25.** Let  $E$  be compact in  $\mathbb{R}^n$ , then

$$\begin{aligned} \text{cap}(E) &= \int_{\mathbb{R}^n} |\nabla u|^2 dx \\ &= \inf \left\{ \int_{\mathbb{R}^n} |\nabla v|^2 dx, v \in H_0^1(\mathbb{R}^n), v \geq 1 \text{ on } E \right\} \end{aligned}$$

**Example 26.** Capacity on  $B_{r_0}$

$$u(r) = \begin{cases} 1 & r < r_0 \\ \left(\frac{r_0}{r}\right)^{n-2} & r > r_0 \end{cases}$$

This is close related to Bernstein Method (1930's).

**Theorem 27.** (Bernstein)  $\Delta u = 0$  in  $B_1$ , then  $|\nabla u(0)| \leq c(n) \max_{B_1(0)} |u|$ .

*Proof.*

$$\Delta(|\nabla u|^2(x)) = 2|\text{Hess } u|^2 = 2 \sum_{ij} u_{x_i x_j}^2 \geq 0$$

implies

$$|\nabla u|^2(0) \leq \sup_{\partial B_1(0)} |\nabla u(x)|^2$$

$\forall \phi \in C_0^\infty(B_1)$  s.t.  $\phi = 1$  for  $0 < x < 1/2$ ,  $\phi = 0$  for  $x > 1$ , then by  $\Delta u^2 = 2|\nabla u|^2$ ,

$$\Delta(\phi^2 |\nabla u|^2 + M_\phi u^2)^{1/2} \geq 0$$

this shows that  $(\phi^2 |\nabla u|^2 + M_\phi u^2)^{1/2}$  is subharmonic, then

$$|\nabla u|^2(0) \leq (\phi^2 |\nabla u|^2 + M_\phi u^2)(0) \leq \sup_{\partial B_1} (\phi^2 |\nabla u|^2 + M_\phi u^2) = M_\phi \sup_{\partial B_1} (u^2)$$

since  $\phi|_{\partial B_1} = 0$ . □

H.F. Weinberger, Shing-Tung Yau showed  $\Delta_M u = 0$ .

## 2.6 Fundamental Solutions

We use  $\Delta u = 0$  in  $B_1$ ,  $\Delta \frac{1}{|x|^{n-2}} = -c(n)\delta_0$ .

**Proposition 28.** Let  $u(x)$  be a harmonic function in  $B_1 \setminus \{0\}$ . Suppose  $u(x) = o(|x|^{2-n})$ , as  $|x| \rightarrow 0$ , then  $u(x)$  can be defined at  $x = 0$  in a way  $\Delta u = 0$  in  $B_1$ .

For proof see Lin Theorem 1.28.

The following two theorems also deal with *Riemann removable singularity*.

**Theorem 29.**  $f(z)$  is holomorphic on  $B_1 \setminus \{0\}$  and if  $|f(z)| \leq M$  or  $|f(z)| \leq o(\frac{1}{|z|})$ , as  $z \rightarrow 0$ , then  $f^*(z)$  is holomorphic in  $B_1$ .

**Theorem 30.**  $u(z)$  harmonic in  $B^2 \setminus \{0\}$  and if  $u(z) = o(|\log |z||)$ , then  $u$  is harmonic in  $B(0)$ .



*Proof.* Solve

$$\begin{cases} \Delta h = 0 & \text{in } B_1 \\ h|_{\partial B_1} = u \end{cases}$$

then  $u - h = v$  is harmonic in  $B_1 \setminus \{0\}$ , and  $v(x) = o(|x|^{2-n})$ , as  $|x| \rightarrow 0^+$ .  
 $v|_{\partial B_1} = 0$ .

That is

$$-\varepsilon |x|^{2-n} \leq v(x) \leq \varepsilon |x|^{2-n}$$

$\forall \varepsilon \in (0, 1)$  and  $x \in B_1 \setminus \{0\}$ , then let  $\varepsilon \rightarrow 0^+$ , we get the desire results.  $\square$

## 2.7 Maximum Principle on Unbounded Boundary

Suppose we want to do

$$\Delta u = 0$$

in  $B_1^c = \{x \in \mathbb{R}^n : |x| > 1\}$  with  $u|_{\partial B_1} = 0$ .

$u = 0$  is a solution and  $u = 1 - |x|^{2-n}$  is also a solution, and we require solution to be  $u(x) \rightarrow 0$ , as  $|x| \rightarrow \infty$ , by *involution*.

## 3 Classical Results

We now begin to study general elliptic pde operators.

### 3.1 Dini Continuous

**Example 31.**  $Lu = a_{ij}(x)u_{x_i x_j} = 0$ ,  $\lambda |\xi|^2 \leq a_{ij}(x)\xi_i \xi_j \leq \Lambda |\xi|^2$ ,  
 $\forall x, \xi \in \mathbb{R}^n$ .

Consider

$$a_{ij}(x) = \delta_{ij} + g(r) \frac{x_i x_j}{r^2}$$

then

$$\Delta u = u_{rr} + \frac{n-1}{r} u_r + \frac{1}{r^2} \Delta_\theta u$$

and

$$\frac{u_{rr}}{u_r} = \frac{1-n}{(g(r)+1)r}$$

So

$$u(r) = \int_0^r \exp \left[ \int^\gamma \frac{1-n}{g(\rho)} \frac{d\rho}{\rho} \right] d\gamma$$

and

$$\lambda = \min(1, 1+g) \quad \Lambda = \max(1, 1+g).$$

If  $n = 2$ ,  $g(r) = -\frac{2}{2+\log r}$ ,  $0 < r < e^{-2}$ , then this  $g(r)$  is continuous and  $g(0) = 0$ , but not Hölder i.e.

$$|g(x) - g(y)| \leq C |x - y|^\alpha$$

for some  $C, \alpha$ .  $g$  is also not *Dini continuous*. i.e.

$$\int_0^1 \frac{w_g(r)}{r} dr = \infty$$

where the *modulus of continuity* of  $g$ ,  $w_g(r) = \sup_{d(x,y) \leq r} d(g(x), g(y)) \sim 1/\log r$ .

Recall

$$f(r) = a + \frac{b}{\log r}$$

is not Dini continuous.

Things go wrong when  $u$  is not Dini continuous.

- (a) Extended Maximum Principle is not true.
- (b) No positive fundamental solution. (No positive solution  $v(x)$  in neighborhood of 0 s.t.  $v(x) \rightarrow +\infty$ , as  $x \rightarrow 0$ .)
- (c) Removable singularity theorem is also not true.
- (d) If  $a_{ij} \in C^\alpha(\text{Dini})$ , then exists fundamental solution.

**Example 32.**  $n = 2$ , let  $g(r) = \frac{2}{\log r - 2} \implies u = (\log \frac{1}{r})^3$ . So existence of positive solution  $v(x)$  near  $r = 0$ , s.t.  $v(x) \rightarrow +\infty$  as  $|x| \rightarrow 0$ . It is not like  $\log 1/r$ .

**Example 33.**  $n > 2$ , let  $g(r) = -\frac{1}{1+(n-1)\ln r}$ , then  $u(r) = \frac{r^{2-n}}{\log r}(1+\varepsilon(r))$ , where  $\varepsilon(r) \rightarrow 0$  as  $r \rightarrow 0^+$ .  $u(r) = o(r^{2-n})$ .  $u(x) \neq O(|x|^{2-n+\delta})$  for any  $\delta > 0$ .

**Example 34.**  $n > 2$ , let  $g(r) = \frac{(n-2)\ln r - 2}{\ln r + 2}$ ,  $r > 0$ ,  $g(0) = n - 2$ , so  $\frac{1-n}{1+g(r)} = -1 - \frac{2}{\ln r} \implies u(r) = a + b/\ln r$ .

The following theorem is very important. See paper “On isolated singularities of solutions of second order elliptic differential equations” (1953-Acta Math) by D. Gilbarg, James Serrin.

**Theorem 35.** *If  $(a_{ij})$  is Dini at  $r = 0$ , and if  $u$  is a non-constant solution of  $Lu = a_{ij}(x)u_{x_i x_j} \geq 0$  in  $\{0 < r \leq r_0\}$ . Let  $M = \max_{|x|=r_0} u$  and if  $u(x) = \begin{cases} o(\ln r) & n = 2 \\ o(r^{2-n}) & n \geq 3 \end{cases}$ , then  $u(x) < M$  in  $\{r : 0 < r < r_0\}$ . More  $\overline{\lim}_{|x| \rightarrow 0^+} u(x) < M$ .*

**Corollary 36.** *(of theorem 35) If  $(a_{ij})$  are continuous at  $r = 0$  and  $u$  is as above. If  $u(x) = O(|x|^{2-n+\delta})$ ,  $\delta > 0$ , then conclusion of theorem 35 is true.*

*Proof.* (Corollary 36) Let  $g = r^{2-n}$ ,  $h = r^{2-n+\delta'} = g^{1-r}$ .  $0 < \delta' < \delta$ ,  $r = \delta'/(n-2)$ . Calculate, we find

$$Lh \leq \varepsilon_1(r)r^{-n}$$

and

$$a_{ij}g_{x_i}g_{x_j} \geq (n-2)^2(1-\varepsilon_2(r))r^{2-2n}$$

we need

$$\varepsilon_1 - r(n-2)^2(1-\varepsilon_2) \leq 0$$

$0 < r < r_1$ . Consider  $v(x) = u - \varepsilon h - M$ , then apply Maximum principle, we got  $v < 0$  in  $\{0 < r < r_1\}$

$$\therefore u \leq M \text{ in } \{0 < r < r_1\}.$$

□

Now we give a sketch of proof of theorem 35.

*Proof.* Let

$$h(x) = h(r) = \int_0^g \exp K(r + \int_0^r \phi(s) \frac{ds}{s}) dg$$

where  $\phi(s)$  = modulo of continuity of  $a_{ij}$ . and let  $g = r^{2-n}$ .

*Remark 37.* if  $a_{ij}(x)$  is Holder, then  $h = g(1 + Kr^\alpha)$

Therefore

$$Lh \leq 0$$

□

Lecture 4  
(10/2/13)

Summary

Assume  $Lu = a_{ij}(x)u_{x_i x_j} = 0$ ,  $|a_{ij}(x) - \delta_{ij}| \ll c(\delta_1)$

(i)  $a_{ij} \in C^0(B_{r_0})$ ,  $L(r^{2-n+\delta_1}) \leq 0$  on  $B_{r_1}$ , then  $h > 0$ ,  $\Delta h = 0 \implies \Delta h^\alpha \leq 0$  for  $0 \leq \alpha < 1$ .

$Lu = 0$  in  $\{0 < |x| < r_0\}$  and  $u(x) = o(|x|^{2-n+\delta}) \implies \lim_{x \rightarrow 0} |u(x)| \leq M = \sup_{\partial B_{r_0}} |u(x)|$ . This is because  $x = 0$  is removable singularity.

(ii)  $a_{ij} \in \text{Holder (Dini)}$ ,  $h(r) = r^{2-n}(1 + Kr^\alpha)$ ,  $Lh \leq 0$  in  $B_{r_0} \implies u(x) = o(|x|^{n-2})$ ,  $x = 0$  is removable singularity.

$$\overline{\lim}_{x \rightarrow 0} |u(x)| \leq M = \sup_{\partial B_{r_0}} |u(x)|$$

and

$$Lu = 0 \quad \text{in } \{0 < |x| < r_0\}.$$

### 3.2 Unbounded Boundary

We first take  $u(x)$  which is bounded on one-side.

**Theorem 38.** Assume  $u(x) \geq -M$ , then  $\lim_{x \rightarrow 0} u(x) = +\infty$ , or finite, both exists.

*Proof.*  $\underline{\lim}_{x \rightarrow 0} u(x) = u_0 \geq -M$ , consider  $v_\varepsilon(x) = u(x) - v_0 + \varepsilon$ ,  $\forall \varepsilon > 0$ .  $\underline{\lim}_{x \rightarrow 0} v_\varepsilon(x) = \varepsilon > 0$ . By Harnack inequality,

$$\sup_{|x|=r} v(x) \leq \inf_{|r|=r} v(x) \cdot c_*$$

(since the value at each ball is comparable.)

$$\sup_{|x|=r} v_\varepsilon \leq \inf_{|r|=r} v(x) \cdot c_* \rightarrow c_* \varepsilon,$$

as  $r \rightarrow 0$ . If  $u_0 < \infty$ ,

$$\lim_{|x| \rightarrow 0} \sup v_\varepsilon \leq c_* \varepsilon$$

□

$$\therefore \overline{\lim}_{x \rightarrow 0} v(x) = u_0$$

**Theorem 39.** *If  $u \in H^1(B_1)$ ,  $E \subset \bar{B}_1$  closed,  $\Delta u = 0$  in  $B_1 \setminus E$ , then  $\Delta u = 0$  in  $B_1$  if  $Cap(E) = 0$ .*

*Proof.*  $Cap(E) = \min\{\int_{\mathbb{R}^n} |\nabla u|^2 : v \in H_0^1(\mathbb{R}^n), v \geq 1 \text{ on } E\}$ , and

$$\begin{cases} -\Delta v_E = \mu_E \geq 0 \\ v_E = 1 \end{cases} \quad \text{on } E$$

$$v_E(\infty) = 0, \quad Cap(E) = \int_{\mathbb{R}^n} |\nabla v_E|^2 dx = \int_{\mathbb{R}^n} (-\Delta v_E \cdot v_E) dx = \int_{\mathbb{R}^n} \mu_E v_E$$

$$v_E(x) = c(n) \int_{\mathbb{R}^n} \frac{d\mu_E(y)}{|x-y|^{n-2}} = c(n) \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} \frac{d\mu_E(x) d\mu_E(y)}{|x-y|^{n-2}}$$

That  $cap(E) = 0$  gives  $\exists \{v_i\} \in C_0^\infty(\mathbb{R}^n)$  s.t.  $v_i \geq 1$  on  $E$ ,  $0 \leq v_i \leq 1$  in  $B_1$

$$\int_{\mathbb{R}^n} |\nabla v_i|^2 dx \rightarrow 0$$

$$\Delta u = 0 \text{ in } B_1. \quad \forall \phi \in C_0^\infty(B_1),$$

$$0 = \int_{B_1} \phi(1 - v_i) \Delta u$$

$\phi v_i \xrightarrow{H^1} 0$ , so

$$\int_{B_1} \phi v_i \Delta u \rightarrow 0$$

as  $i \rightarrow \infty$ .  $\Delta u \in H^{-1}$ , hence

$$0 = \int_{B_1} \phi \Delta u$$

□

### 3.3 Probability Measure

**Definition 40.** Given a *Radon measure*  $\mu$  on  $\mathbb{R}^n$  (with point separated), we define

$t$ -potential of  $\mu$ ,

$$\phi_t = \int \frac{d\mu(y)}{|x-y|^t}.$$

$t$ -energy of  $\mu$ ,

$$I_t(\mu) = \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} \frac{d\mu_t(x)d\mu_t(y)}{|x-y|^t}.$$

Given compact set  $E$ , we define

$$C_t(E) = \sup_{\mu} \left\{ \frac{1}{I_t(\mu)} : \mu \text{ is a probability measure on } E \right\}$$

One can check that the notion in the proof of theorem 39,

$$v_E(x) = c(n) \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} \frac{d\mu_E(x)d\mu_E(y)}{|x-y|^{n-2}}$$

$$\begin{aligned} \mu_E(E) &= \int_E d\mu_E(x) \\ &= \int_E v_E(x) d\mu_E(x) \\ &= c(n) I_{n-2}(\mu_E) \\ \tilde{\mu} &= \frac{\mu_E}{c(n) I_{n-2}(\mu_E)} \end{aligned}$$

is probability measure.

$$I_{n-2}(\tilde{\mu}) = \frac{1}{c^*(\mu) I_{n-2}(\mu_E)}.$$

**Theorem 41.** *Let  $\mu$  be a probability measure, let*

$$E_0 = \left\{ x : \lim_{r \rightarrow 0} \frac{\mu(B(x, r))}{r^t} > 0 \right\}$$

*then  $I_t(\mu) < \infty \implies \mu(E_0) = 0$ .*

*Proof.*  $I_t(\mu) < \infty \implies \phi_t(x) < \infty$  for  $\mu$  a.e.  $x$ . If at  $x_0$   $\phi_t < \infty$ , i.e.  $\int \frac{d\mu(y)}{|x_0-y|^t} < \infty$

$$\therefore \frac{\mu(B(x, r))}{r^t} \rightarrow 0$$

as  $r \rightarrow 0^+$ . □

**Proposition 42.** *(i) if  $H^t(E) < \infty$ , then  $C_t(E) = 0$ . (ii) if  $C_t(E) = 0$ , then  $H^s(E) = 0 \forall s > t$ .*

*Proof.* Let  $\mu$  be a probability measure.  $H^t(E) \geq H^t(E \setminus E_0)$ , note  $\forall \varepsilon > 0$ ,  $E \setminus E_0$  can be finitely covered by balls  $B_1(x)$ , such that

$$\frac{\mu(B_r(x))}{r^t} < \varepsilon \implies r^t > \frac{\mu(B_r(x))}{\varepsilon}$$

Conversely  $H^t(E \setminus E_0) \geq \frac{1}{\varepsilon} \mu(E \setminus E_0) = \frac{\mu(E)}{\varepsilon} = \frac{1}{\varepsilon} \implies H^t(E) = \infty$ . If  $C_t(E) > 0$ , then  $\exists \mu$  s.t.  $I_t(\mu) < \infty$ .  $\square$

**Corollary 43.** *If  $E \subset B_1$  closed and  $H^{n-2}(E) < \infty$ , then  $E$  is removable for any  $H^1$  solution of  $\Delta u = 0$  in  $B_1 \setminus E$ .*

### 3.4 Quasi-Open, Quasi-Continuous

**Definition 44.** A set  $E \subseteq \mathbb{R}^n$  (Borel) is called Quasi-open if  $\forall \varepsilon > 0$ ,  $\exists O_\varepsilon$  open set s.t.

$$\text{cap}(O_\varepsilon \Delta E) < \varepsilon.$$

**Definition 45.**  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is called Quasi-continuous if  $\forall \varepsilon > 0$ ,  $\exists f_\varepsilon$  continuous  $f_\varepsilon : \mathbb{R}^n \rightarrow \mathbb{R}$  s.t.

$$\text{cap}\{x : f_\varepsilon(x) \neq f(x)\} < \varepsilon.$$

**Theorem 46.** (Federer-Ziemer) *If  $f \in H^1(\mathbb{R}^n)$ , then  $f$  is Quasi-continuous.*

**Definition 47.** We define  $E_n \Rightarrow E$  (bounded sets)  $\subseteq \Omega$  to mean that if

we solve  $\begin{cases} -\Delta u_{E_n} = f, & f \in H^{-1} \\ u_{E_n} = 0 & \text{on } \Omega \setminus E_n \end{cases}$ , then

$$u_{E_n} \xrightarrow{H^1} u_E \text{ s.t. } \begin{cases} -\Delta u_E = f \\ u_E = 0 & \text{on } \Omega \setminus E \end{cases}$$

**Definition 48.** We define  $E_i \xrightarrow{*} E$  to mean that if we solve  $\begin{cases} -\Delta u_i = 1 \\ u_i = 0 & \text{on } \Omega \setminus E_i \end{cases}$ , then

$$u_i(x) \xrightarrow{H^1} w(x) \text{ where } E = \{x | w(x) > 0\}$$

Clearly if  $w(x) = u_E(x)$ , then  $E_i \xrightarrow{*} E$ . If  $E_n \Rightarrow E$ ,  $\lambda_i(E_i) \rightarrow \lambda(E)$ .

*Remark 49.*  $\exists Lu = a_{ij}(x)u_{x_i x_j} = 0$  in  $B_{r_0} \setminus \{0\}$  uniformly elliptic,  $a_{ij} \in C^w(B_{r_0} \setminus \{0\})$ .  $\exists u^*(x)$  solution of  $LU = 0$  in  $B_{r_0} \setminus \{0\}$  s.t.  $u^*|_{\partial B} = 1$ ,  $u^*(0) = 0$ ,  $u^*(x)$  Holder.

### 3.5 Serrin-Weinberger Method

The following theorem is applied to divergence form

$$Lu = \partial_{x_i}(a_{ij}(x)u_{x_j}) = 0$$

in  $B_{r_0} \setminus \{0\}$ ,  $\lambda |\xi|^2 \leq a_{ij}(x)\xi_i\xi_j \leq \Lambda |\xi|^2$ .

**Theorem 50.** (*Littman-Stampacchia-Weinberger*)  $\exists G(x) \geq 0$ ,  $LG(x) = -\delta(x)$ ,  $G(x) \cong |x|^{2-n}$ ,  $\nabla G \in L^{\frac{n}{n-1}}$ ,  $G \in L^{\frac{n}{n-1}-\varepsilon}$ ,  $\forall \varepsilon > 0$ ,  $G \in \text{Holder}$  in  $\mathbb{R}^n \setminus \{0\}$ , and  $G \in H_{loc}^1(\mathbb{R}^n \setminus \{0\})$  and

$$c|x|^{2-n} \leq G(x) \leq C|x|^{2-n}$$

**Lemma 51.** If  $Lu = 0$  in  $B_{r_0} \setminus \{0\}$  &  $u(x) = o(|x|^{2-n})$ , then  $u(x) = aG(x) + w(x)$ , where  $a$  is a constant,  $Lw(x) = 0$  in  $B_{r_0}$  and  $w \in \text{Holder}$  in  $B_{r_0}$ .

*Proof.* (See Serrin)  $\begin{cases} Lv = 0 & \text{in } B_{r_0} \\ v = G & \text{on } \partial B_{r_0} \end{cases}$ . let  $g = G - v$  in  $B_{r_0}$ . Since  $u(x) = o(|x|^{2-n})$ , let  $u^*(x) = u(x) - w(x)$ ,  $u^*|_{\partial B_{r_0}} = 0$ , one need to show  $u^*(x) = ag$ . We have  $u^*(x) = O(|x|^{2-n}) = O(g)$ ,  $u^*|_{\partial B_{r_0}} = 0 \implies u^*(x) \leq Mg(x)$  for large  $M$ .

Let  $a = \inf\{M \in \mathbb{R}, u^*(x) \leq Mg(x) \text{ for } x \in B_{r_0} \setminus \{0\}\}$ , one wants to show  $0 \leq ag(x) - u^*(x) = 0$ , that is to show

$$\lim_{|x| \rightarrow 0} \frac{ag(x) - u^*(x)}{|x|^{n-2}} = 0$$

suppose that  $\lim_{|x| \rightarrow 0} \frac{ag(x) - u^*(x)}{|x|^{n-2}} \geq \varepsilon_0 > 0$ , then by Maximum principle

$$ag(x) - u^*(x) \geq \frac{\varepsilon_0}{c}g(x) \quad \text{for } 0 < |x| < r_0$$

then

$$ag(x) - u^*(x) \leq \varepsilon g(x) \quad \forall \varepsilon > 0, 0 < |x| < r_0$$

let  $\varepsilon \rightarrow 0$ ,

$$ag(x) - u^*(x) \leq 0$$

□



**Theorem 52.** (Serrin-Weinberger) Consider  $Lu = 0$  in  $B_R^c = \{|x| > R\}$ ,

$$m(\sigma) = \inf_{\partial B_\sigma} u \quad M(\sigma) = \sup_{\partial B_\sigma} u$$

Either  $u(x) \rightarrow u_\infty$  as  $x \rightarrow \infty$ ; or else  $M(\sigma) \geq A\sigma^\alpha$ ,  $m(\delta) \leq -A\sigma^\alpha$ , for some  $A > 0$  and  $\alpha = \alpha(n, \lambda, \Lambda)$ . More  $u_\infty$  is finite if  $n \geq 3$ .

Note 53.  $Lu = 0$  in  $\mathbb{R}^n$ .  $M(\sigma) \uparrow$ ,  $m(\sigma) \downarrow$ , Moser showed  $M(\sigma) - m(\sigma) \geq A\sigma^\alpha$ .

*Proof.* If  $u$  is bounded on one-side, then  $\lim_{|x| \rightarrow \infty} u(x) = u_0$  exists (finite if  $n \geq 3$ ).  $\exists G(x)$  fundamental solution s.t.

$$\begin{cases} L(C - G) = 0 & \text{in } B_R^c \\ C - G|_{\partial B_R} = 0 \end{cases}$$

Since  $Lv = 0$  in  $B_R^c$ ,  $v \geq 0$  in  $B_R^c$ , and  $v(x) \rightarrow \infty$  as  $|x| \rightarrow \infty$ .  $C - G \leq \varepsilon v$ ,  $\forall \varepsilon > 0$ . So the fundamental solution goes to  $C$ , hence  $u$  is not bounded on neither side.

By maximum principle  $M(\sigma) = \max_{|x|=\sigma} u(x)$  can have at most one relative maximum;  $m(\sigma) = \min_{|x|=\sigma} u(x)$  can have at most one relative minimum. And  $M(\sigma) \rightarrow \infty$ ,  $m(\sigma) \rightarrow -\infty$ , as  $\sigma \rightarrow \infty$ . So  $\exists \sigma_0$  s.t. for  $\sigma \in [\sigma_0, \infty)$ ,  $M(\sigma) \uparrow \infty$ ,  $M(\sigma) \geq 0$  and  $m(\sigma) \downarrow -\infty$ ,  $m(\sigma) \leq 0$ .

Let  $A_\sigma = \{\frac{\sigma}{2} < |x| < 2\sigma\}$ , then

$$0 \leq M(2\sigma) - u(x), \quad 0 \leq u(x) - m(2\sigma), \quad \text{on } A_\sigma$$

$$\therefore M(\sigma) - m(2\sigma) \leq c(m(\sigma) - m(2\sigma))$$

Apply Harnack inequality of Moser on  $|x| = \sigma \implies$

$$M(2\sigma) - m(\sigma) \leq c(M(2\sigma) - M(\sigma))$$

Combining the two,

$$M(\sigma) - m(2\sigma) + M(2\sigma) - m(\sigma) \leq c(M(2\sigma) - m(2\sigma)) - c(M(\sigma) - m(\sigma))$$

Or

$$(M(\sigma) - m(\sigma)) \leq \frac{c-1}{c+1} (M(2\sigma) - m(2\sigma))$$

That gives

$$M(\sigma) - m(\sigma) \geq A\delta^\alpha, \quad \sigma \geq 2\sigma_0$$

Lecture 5  
(10/9/13)

and

$$\begin{aligned}
M(2\sigma) - M(\sigma) &\geq \frac{1}{c} (M(2\sigma) - m(\sigma)) \\
&\geq \frac{1}{c} (M(\sigma) - m(\sigma)) \\
&\geq \frac{A}{c} \sigma^\alpha
\end{aligned}$$

Thus

$$\sup_{|x|=r} u(x) \geq Ar^\alpha$$

□

**Corollary 54.** *If  $Lu = 0$  in  $\{|x| > r_0\}$  and if either  $\overline{\lim} |x|^{-\alpha} u(x) \leq 0$  or  $\underline{\lim} |x|^{-\alpha} u(x) \geq 0$ , then  $\lim_{|x| \rightarrow \infty} u(x) = u_0$  is finite.*

**Theorem 55.** *If  $Lu = 0$  in  $\{0 < |x| \leq r_0\}$ ,  $\exists \delta = \delta(m, \lambda, \Lambda) > 0$  s.t. suppose either  $\overline{\lim} |x|^{2-n-\delta} u(x) \leq 0$  or  $\underline{\lim} |x|^{2-n-\delta} u(x) \geq 0$ , then  $u(x) = aG(x) + w(x)$ , where  $Lw(x) = 0$  and  $w(x)$  is regular solution.*

If  $\Delta u(x) = 0$  in  $|x| > 1$ , then

$$v(y) = \frac{u(\frac{y}{|y|^2})}{\frac{1}{|y|^{n-2}}} = |y|^{n-2} u(\frac{y}{|y|^2})$$

solves  $\Delta v(y) = 0$  in  $|y| < 1$ .

For more general elliptic operator, if  $a^{ij}(x)u_{x_i x_j} = 0$  in  $|x| < 1$ , define

$$v(y) = \frac{u(\frac{y}{|y|^2})}{G(y)}$$

to be solution of  $\tilde{L}v = 0$  in  $|y| > 1$ , where

$$\tilde{L} = \partial_{y_i}(\tilde{a}^{ij}(y)\partial_{y_j}), \tilde{a}^{ij}(y) = \frac{G^2(y)}{J(y)} a^{kj}(x) \frac{\partial y^i}{\partial x_i} \frac{\partial y^j}{\partial x_j}$$

$$c\lambda \leq (\tilde{a}^{ij}) \leq c\Lambda, \frac{\partial y^i}{\partial x_i} \sim \frac{1}{|x|^2}, J(y) \sim \frac{1}{|x|^{2n}}, G(y) \sim |x|^{2-n}$$

so

$$\tilde{a}^{ij}(y) \sim \frac{|x|^{2n}}{|x|^4} \left(|x|^{2-n}\right)^2$$

### 3.6 Maximum Principle

We now discuss two aspects of Maximum principle.

**Theorem 56.** (i) If  $a_{ij}(x)u_{x_i x_j} \geq 0$  in  $B_1$  and  $u \in C^2(B_1)$ , then

$$\sup_{x \in B_1} u(x) \leq \sup_{\partial B_1} u(x)$$

(ii) (Hopf boundary point lemma or strong Maximum principle) If

$$u(x_0) = \max_{x \in \bar{B}_1} u(x)$$

$u \in C^2$ , and  $u \neq \text{constant}$ , then

$$\frac{\partial u}{\partial \nu}(x_0) > 0.$$

Another version:  $u(x) < u(x_0) \ \forall x \in \bar{B}_1 \setminus \{x_0\}$ ,  $u \in C^0(\bar{B}_1) \cap C^2(B_1)$ , then

$$\frac{\partial u}{\partial \nu}(x_0) \geq c(n, \lambda, \Lambda) (u(x_0) - u(0))$$

*Proof.* Consider  $h(x) = e^{-\alpha|x|^2} - e^{-\alpha}$ ,  $h$  vanishes on boundary and  $\geq 0$  inside.

$$Lh = (4\alpha^2 a_{ij}(x)x_i x_j + o(\alpha))e^{-\alpha|x|^2}$$

$Lh > 0$  if  $|x| \geq 1/2$ ,  $0 \geq \alpha(n, \lambda, \Lambda)$

$$v = u(x) - u(x_0) + \varepsilon h(x) \leq 0$$

in  $\{1/2 < |x| < 1\}$ , implies

$$Lv \geq 0$$

in  $\{1/2 < |x| < 1\}$ , implies

$$v(x) \leq 0 \text{ in } \{\frac{1}{2} < |x| < 1\}, \ v(x_0) = 0$$

So

$$\frac{\partial v}{\partial \nu}(x_0) \geq 0$$

which gives

$$\frac{\partial u}{\partial \nu}(x_0) \geq -\varepsilon \frac{\partial h}{\partial \nu}(x_0) \geq \varepsilon \alpha > 0$$

How big is  $u(x_0) - u(x)$  on  $|x| = \frac{1}{2}$ ? Since

$$c(u(x) - u(x_0)) \leq u(x_0) - u(x) \leq c(u(x_0) - u(0))$$

we have

$$\begin{aligned} (u(x) - u(x_0)) &\sim (u(x_0) - u(0)) \sim \varepsilon \\ \therefore \frac{\partial u}{\partial \nu}(x_0) &\geq c(n, \lambda, \Lambda) (u(x_0) - u(0)) \end{aligned}$$

□

**Exercise 57.**  $Lu = 0$  in  $B_1$ . Show Hopf boundary point lemma  $\implies$  Holder of solution.

$M(R) = \max_{|x| \leq R} (u(x) - u(0))$ ,  $RM'(R) \geq c(n, \lambda, \Lambda)M(R)$  ( $R = 1$  by scaling),  $M(R) \geq 2^c M(R/2)$ , for  $0 \leq r < 1$ ,  $M(r) \leq M(1)r^c$ .

**Theorem 58.** (*Alexandroff Estimate or ABP-Estimate [Alexandroff–Bakelman–Pucci]*)  $a_{ij}(x)u_{x_i x_j}(x) \geq f(x) \in L^n(\Omega)$ ,  $u \in W^{2,n}(\Omega)$ ,  $u|_{\partial\Omega} \leq 0$ , then

$$\sup_{\Omega} u^+ \leq c(n)(\dim\Omega) \left( \int_{\Omega} \left| \frac{f^-}{A} \right|^n dx \right)^{1/2}$$

where  $A = \det^{1/n}(a_{ij}(x))$ .  $f = f^+ - f^-$ .

*Remark 59.* If  $(a_{ij}) \geq \lambda I$ ,  $A \geq \lambda$ .

*Proof.* Let  $\Gamma_u(x)$  be the minimum concave function which vanishes on  $\partial\Omega$  and lies above  $u$ . So

$$M = \max \Gamma_u = \max u^+$$

Let  $d = \dim\Omega$ .

$$\text{Vol} \left( \frac{B_M^n(0)}{d} \right) = c(n) \left( \frac{M}{d} \right)^n$$

$D\Gamma_u(\Omega) = \{D\Gamma_u(x) : x \in \Omega\} \supseteq B_M^n(0)/d$ , any plane from  $u = \infty$  with slope  $\leq M/d$  will have to touch the graph  $\Gamma_u$  before it hits  $\partial\Omega$ , that implies

$$\begin{aligned} c(n) \left( \frac{M}{d} \right)^n &\leq |D\Gamma_u(\Omega)| \\ &\leq \int_{\Omega} |\det(\text{Hessian of } \Gamma_u)| dx \\ &\leq \int_{\Omega} |\det(D^2 u(x))| dx \\ &\leq \int_{\{(D^2 u) \leq 0\}} |\det(D^2 u(x))| dx \end{aligned}$$

here we used  $\det(\text{Hessian of } \Gamma_u) = J_{ac}(D\Gamma_u(\Omega))$  for Lipschitz map  $\Gamma_u$ .  
Moreover

$$-a_{ij}(x)u_{ij}(x) \leq -f(x) \leq f^-(x)$$

$$\begin{aligned} \det(A)\det(-D^2u) &= \det(A(-D^2u)) \\ &\leq c(n) [\text{tr}(A(-D^2u))]^n \\ &\leq c(n)f^n(x) \end{aligned}$$

on  $(D^2u \leq 0)$ , use  $\lambda_1\lambda_2\ldots\lambda_n \leq \left(\frac{\lambda_1+\ldots+\lambda_n}{n}\right)^n$ , we get

$$\begin{aligned} c(n) \left(\frac{M}{d}\right)^n &\leq \int_{\{D^2u \leq 0\}} |\det(D^2u(x))| dx \leq c(n) \int_{\Omega} \frac{(f^-)^n}{\det A} dx \\ \therefore \sup u^+ = M &\leq c(n) \dim \Omega \left( \int_{\Omega} \frac{(f^-)^n}{\det A} \right)^{1/n} \end{aligned}$$

□

We will apply Alexandroff estimate to get the following result

**Proposition 60.** (*small-volume maximum principle*) Let  $d = \dim \Omega$ ,  $\delta = \text{Vol} \Omega$ , and  $|c(x)| \leq M$ . If  $\Delta u + c(x)u = 0$  in  $\Omega$ ,  $u \leq 0$  on  $\partial\Omega$ , then  $\exists \delta_0 = \delta_0(n, M, d)$  s.t. if  $\delta \leq \delta_0$  then  $u(x) \leq 0$  in  $\Omega$ .

*Proof.*  $\sup u^+ \leq c(n)d \|(c(x)u)^+\|_{L^n(\Omega)} \leq c(n)dM \sup u^+ \delta^{1/n} \implies \sup u^+ = 0$ , if  $\delta^{1/n}c(n)dM < 1$ . □

### 3.7 Moving Plane Method

We borrow an idea from Geometry: Constant-mean-curvature surface in  $\mathbb{R}^3$  must be sphere by Alexandrov.

**Theorem 61.** If

$$\begin{cases} \Delta u + f(x) = 0 & \text{in } B_1 \\ u = 0 & \text{on } \partial B_1 \\ u > 0 & \text{in } B_1 \end{cases}$$

with  $f \in \text{Lip}$ , then  $u(x) = u(|x|)$ .

See Lin Lemma 2.35 gives a different version of the theorem.

**Lemma 62.** (Similar to Lin 2.35) Consider the plane  $T_\lambda = \{x_1 = \lambda\}$ ,  $0 \leq \lambda \leq 1$ , let  $\Sigma_\lambda = B_1 \cap \{x_1 > \lambda\}$  and  $\Sigma_\lambda^*$  = reflection of  $\Sigma_\lambda$  with respect to  $T_\lambda$ . Then

$$u(x^\lambda) \leq u(x)$$

$x \in \Sigma_\lambda^*$  for all  $0 \leq \lambda \leq 1$ , where  $x^\lambda = (2\lambda - x_1, x')$ .

Notice when  $\lambda = 0$ , the lemma says  $u(x_1, x') \leq u(-x_1, x')$ .

Idea of proof Lemma: Let  $w^\lambda = u(x^\lambda) - u(x)$ ,  $x \in \Sigma_\lambda^*$ , then  $w^\lambda = 0$  on  $T_\lambda$ ,  $w^\lambda < 0$  on  $\partial\Sigma_\lambda^* \setminus T_\lambda$  and

$$\Delta w^\lambda(x) + c^\lambda(x)w^\lambda(x) = 0$$

in  $\Sigma_\lambda^*$ , where  $|c^\lambda(x)| \leq L = \max|f'|$ , and  $c^\lambda(x)w^\lambda(x) = f(u^\lambda) - f(u)$ , where  $u^\lambda(x) = u(x^\lambda)$ .

*Proof.* (of Lemma 62) If  $1 - \delta_0 \leq \lambda \leq 1$  ( $\delta_0 > 0$  small),  $|\Sigma_\lambda^*| \leq c\delta_0$  and  $\dim\Sigma_\lambda \leq 2$ . By ABP-estimate,  $w^\lambda(x) \leq 0$ ,  $x \in \Sigma_\lambda^*$  and  $w^\lambda(x) < 0$  inside  $\Sigma_\lambda^*$ .

Since  $\sup_{\Sigma_\lambda^*} (w_+^\lambda) \leq c \dim |\Sigma_\lambda^*| \cdot \|c^\lambda w^\lambda\|_{L^n(\Sigma_\lambda^*)}$ ,

$$\sup w_+^\lambda \leq c \dim |\Sigma_\lambda^*| L \sup w_+^\lambda |\Sigma_\lambda^*|^{1/n}$$

$$\therefore \sup w_+^\lambda = 0$$

for  $\sup w_+^\lambda$  appears on both sides but  $c \dim |\Sigma_\lambda^*| |\Sigma_\lambda^*|^{1/n}$  is arbitrarily small.

Let  $\lambda_0 = \inf\{\lambda_* \in (0, 1) : w^\lambda(x) \leq 0 \forall \lambda \geq \lambda_*\}$ , if  $\lambda_0 = 0$  we are done, i.e.  $u(x_1, x') = u(-x_1, x')$ ,  $x_1 \geq 0$ . (choose all planes)

If  $\lambda_0 > 0$ , then  $u^{\lambda_0}(x) \leq u(x)$  on  $\Sigma_{\lambda_0}^*$ ,  $u(x) = u^{\lambda_0}(x)$  on  $T_{\lambda_0}$  and  $u^{\lambda_0}(x) \leq u(x)$  on  $\partial\Sigma_{\lambda_0}^* \setminus T_{\lambda_0}$ . By Hopf,

$$u^{\lambda_0}(x) < u(x)$$

inside  $\Sigma_{\lambda_0}^*$ , it implies  $w^{\lambda_0}(x) < 0$ , so  $w^{\lambda_0}(x)$  is continuous on  $\Sigma_{\lambda_0}^* \implies$

$$w^{\lambda_0}(x) \leq -\eta_0(K) < 0$$

on  $K \Subset \Sigma_{\lambda_0}^*$ . Choose  $K$  large s.t.  $|\Sigma_{\lambda_0}^* \setminus K| < \delta_0/2$  for  $\lambda_0 - \delta \leq \lambda < \lambda_0$  ( $\delta \ll \delta_0$ )

Consider  $w^\lambda(x)$  continuous in  $\lambda$  on  $\Sigma_{\lambda_0}^* \implies w^\lambda(x) \leq -\frac{\eta_0}{2} \forall x \in K$  and  $|\Sigma_\lambda^* \setminus K| < \delta_0$ . Consider  $w^\lambda$  on  $\Sigma_\lambda^* \setminus K$ ,  $w^\lambda \leq 0$  on  $\partial(\Sigma_\lambda^* \setminus K)$ ,

$$\Delta w^\lambda = -c^\lambda(x)w^\lambda$$

in  $\Sigma_\lambda^*$ . Then by ABP-estimate,

$$\begin{aligned} \sup_{\Sigma_\lambda^* \setminus K} |w_+^\lambda| &\leq c_0 2L |w_+^\lambda|_{L^n(\Sigma_\lambda^* \setminus K)} \\ &\leq 2c_0 L |\Sigma_\lambda^* \setminus K| \sup_{\Sigma_\lambda^* \setminus K} |w_+^\lambda| \\ &\leq 2c_0 L \delta_0^{1/n} \sup_{\Sigma_\lambda^* \setminus K} (w_+^\lambda) \end{aligned}$$

This gives

$$\sup_{\Sigma_\lambda^* \setminus K} (w_+^\lambda) = 0$$

□

One can use the same idea in the proof to show:  $M^2$  embedded in  $\mathbb{R}^3$  consider constant mean curvature  $H_M = \text{const} > 0 \implies M^2 \cong S^2$  standard sphere.

## 4 Modern Results

### 4.1 Krylov-Safonov Theorem

### 4.2 Calderon-Zygmund Lemma

### 4.3 Continuity Method

### 4.4 Lax-Milgram

### 4.5 DeGiorgi Theory

### 4.6 John-Nirenberg Estimate

### 4.7 Morrey-Stampacchia Theory

## 5 More Recent Developments