Pin	Name	Value	Mode = 0 - Positioning
24	DOUT0	24 V 100 mA	Ready for operation output (high active)
25	DOUT2	24 V 100 mA	Output freely programmable – Default: Start ack (low active)

Table 6.2 Pin allocation: I/O interface [X1]

	Pin	Name	Value	Mode = 1 - Jog mode
	1	AGND	0 V	Screen for analogue signals
	2	DIN12	24 V	Mode switch “1” = Jog mode
	3	DIN10		Jog + (high active)
	4	+VREF	+10 V ±4%	Reference output for setpoint potentiometer
	5	Unassigned		
☑	6	GND24		Reference potential for digital inputs and outputs
	7	DIN1		Record selection 1 (high active)
	8	DIN3		Record selection 3 (high active)
☑	9	DIN5		Controller enable (high active)
☑	10	DIN7		Limit switch 1
	11	DIN9		Mode switch "0"
	12	DOUT1	24 V 100 mA	Output freely programmable - default motion complete (high active)
	13	DOUT3	24 V 100 mA	Output freely programmable - default error (low active)
	14	AGND	0 V	Reference potential for the analogue signals
☑	15	DIN13		Stop input (low active)
	16	DIN11		Jog – (high active)
	17	AMON0	0...10 V ±4%	Analogue monitor output 0
☑	18	+ 24 V	24 V 100 mA	24 V supply carried out Voeding vanuit de controller
	19	DIN0		Record selection 0 (high active)
	20	DIN2		Record selection 2 (high active)
☑	21	DIN4		End stage enable (high active)
☑	22	DIN6		Limit switch 0 Uitbedraden naar home sensor
	23	DIN8		Teach (high active)
	24	DOUT0	24 V 100 mA	Ready for operation output (high active)
	25	DOUT2	24 V 100 mA	Teach ack

Table 6.3 Pin allocation: I/O interface [X1]

Pin	Name	Value	Mode = 2 - Record linking
1	AGND	0 V	Screen for analogue signals
2	DIN12		Mode switch “0”
3	DIN10		Next 1
4	+VREF	+10 V ±4%	Reference output for setpoint potentiometer