

Rohan Chitnis

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Education	<p>University of California, Berkeley, Berkeley, CA</p> <p>GPA: 3.951</p> <p>Bachelor of Science in Electrical Engineering and Computer Sciences, May 2016.</p> <p>Relevant Coursework: Advanced Robotics, Machine Learning, Deep Reinforcement Learning, Artificial Intelligence, Computer Vision, Optimization, Graphics, Computational Geometry, Image Processing, Probability and Random Processes, Algorithms, Data Structures.</p>
Experience	<p>UC Berkeley Robot Learning Lab (Adviser: Pieter Abbeel) 02/2013 - Present</p> <ul style="list-style-type: none">• Perform work in (hierarchical) combined task and motion planning for execution of long-horizon tasks.• Integrating reinforcement learning to improve existing approaches.• Lead coordinator of lab outreach program, providing tours to visitors of varied ages. <p>UC Berkeley Oscii Lab (Adviser: John DeNero) 04/2015 - Present</p> <ul style="list-style-type: none">• Conduct research in Natural Language Processing.• Working on improving performance of neural machine translation, which uses a recurrent neural network with an attention mechanism for machine translation, by introducing novel Huffman code compression techniques. <p>eBay Inc., San Jose, CA (Software Engineering Intern) 05/2014 - 08/2014</p> <ul style="list-style-type: none">• Developed an end-to-end pipeline involving data querying and machine learning to build a classification model for checkout transactions, used in determining whether to offer buyers the option to place items on hold.• Collected data using Hadoop MapReduce under the Apache Pig framework.• Model achieved 85% accuracy on noisy data sets, using adaptive boosting with a decision tree classifier.
Publications	<p>Guided Search for Task and Motion Plans Using Learned Heuristics. Rohan Chitnis, Dylan Hadfield-Menell, Abhishek Gupta, Siddharth Srivastava, Pieter Abbeel. Proceedings of the IEEE International Conference on Robotics and Automation (ICRA), 2016.</p> <p>Learning an Interface to Improve Efficiency in Combined Task and Motion Planning. Rohan Chitnis, Dylan Hadfield-Menell, Siddharth Srivastava, Abhishek Gupta, Pieter Abbeel. Proceedings of the IROS Workshop on Machine Learning in Planning and Control of Robot Motion (MLPC), 2015.</p> <p>Variable-Length Word Encodings for Neural Translation Models. Rohan Chitnis, John DeNero. Proceedings of the Conference on Empirical Methods in Natural Language Processing (EMNLP), 2015.</p> <p>Modular Task and Motion Planning in Belief Space. Dylan Hadfield-Menell, Edward Groshev, Rohan Chitnis, Pieter Abbeel. Proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2015.</p> <p>Combined Task and Motion Planning Through an Extensible Planner-Independent Interface Layer. Siddharth Srivastava, Eugene Fang, Lorenzo Riano, Rohan Chitnis, Stuart Russell, Pieter Abbeel. Proceedings of the IEEE International Conference on Robotics and Automation (ICRA), 2014.</p>
Honors/ Awards	<p>Runner-up for the CRA Outstanding Undergraduate Male Researcher Award, 2016.</p> <p>Sole recipient of the EECS Mark D. Weiser Excellence in Computing Scholarship, 2015.</p> <p>Member of the EECS Honors Degree Program.</p> <p>UC Berkeley Outstanding Graduate Student Instructor (OGSI) Award recipient, 2015.</p> <p>UC Berkeley Regents' and Chancellor's Scholar.</p> <p>National Merit Scholar.</p>
Technical Skills	<p>Fluency in: Python, Java, C, C++, Scheme, LaTeX.</p> <p>Software: Unix/Linux, Robot Operating System (ROS), OpenCV, MongoDB, Apache Pig, Apache Spark, Hadoop MapReduce, scikit-learn, scikit-image.</p>