

## Rohan Chitnis

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Education	<p><b>Massachusetts Institute of Technology, Cambridge, MA</b> PhD in Computer Science, May 2021 (expected).</p> <p><b>University of California, Berkeley, Berkeley, CA</b> <b>Graduated with Highest Honors (GPA in top 3%). GPA: 3.951 / 4.0.</b> Bachelor of Science in Electrical Engineering and Computer Sciences, May 2016. Relevant Coursework: Advanced Robotics, Machine Learning, Deep Reinforcement Learning, Artificial Intelligence, Computer Vision, Optimization, Graphics, Computational Geometry, Image Processing, Probability and Random Processes, Algorithms, Data Structures.</p>
Research Experience	<p><b>UC Berkeley Robot Learning Lab</b> (Adviser: Pieter Abbeel) 02/2013 - 05/2016</p> <ul style="list-style-type: none"><li>Performed work in (hierarchical) combined task and motion planning for execution of long-horizon tasks.</li><li>Integrated reinforcement learning to improve existing approaches.</li><li>Lead coordinator of lab outreach program, providing tours to visitors of varied ages.</li></ul> <p><b>UC Berkeley Oscii Lab</b> (Adviser: John DeNero) 04/2015 - 05/2016</p> <ul style="list-style-type: none"><li>Conducted research in Natural Language Processing.</li><li>Worked on improving performance of neural machine translation, which uses a recurrent neural network with an attention mechanism for machine translation, by introducing novel Huffman code compression techniques.</li></ul>
Publications	<p><b>Sequential Quadratic Programming for Task Plan Optimization</b> Dylan Hadfield-Menell, Christopher Lin, <b>Rohan Chitnis</b>, Stuart Russell, Pieter Abbeel. Proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2016.</p> <p><b>Guided Search for Task and Motion Plans Using Learned Heuristics</b> <b>Rohan Chitnis</b>, Dylan Hadfield-Menell, Abhishek Gupta, Siddharth Srivastava, Pieter Abbeel. Proceedings of the IEEE International Conference on Robotics and Automation (ICRA), 2016.</p> <p><b>Learning an Interface to Improve Efficiency in Combined Task and Motion Planning</b> <b>Rohan Chitnis</b>, Dylan Hadfield-Menell, Siddharth Srivastava, Abhishek Gupta, Pieter Abbeel. Proceedings of the IROS Workshop on Machine Learning in Planning and Control of Robot Motion (MLPC), 2015.</p> <p><b>Variable-Length Word Encodings for Neural Translation Models</b> <b>Rohan Chitnis</b>, John DeNero. Proceedings of the Conference on Empirical Methods in Natural Language Processing (EMNLP), 2015.</p> <p><b>Modular Task and Motion Planning in Belief Space</b> Dylan Hadfield-Menell, Edward Groshev, <b>Rohan Chitnis</b>, Pieter Abbeel. Proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2015.</p> <p><b>Combined Task and Motion Planning Through an Extensible Planner-Independent Interface Layer</b> Siddharth Srivastava, Eugene Fang, Lorenzo Riano, <b>Rohan Chitnis</b>, Stuart Russell, Pieter Abbeel. Proceedings of the IEEE International Conference on Robotics and Automation (ICRA), 2014.</p>
Honors/Awards	<p><b>NSF GRFP Fellow, 2016. Awarded NDSEG Fellowship (declined).</b></p> <p><b>Hertz Fellowship Finalist, 2016.</b> One of 40 finalists for the Hertz Fellowship, a highly reputable fellowship for student researchers in the physical, biological, and engineering sciences.</p>

**Runner-up for the Computing Research Association (CRA) Outstanding Undergraduate Researcher Award (Male, PhD-granting institution), 2016.** Highly prestigious award recognizing North American undergraduate students who show outstanding research potential in a field of computing.

**Sole recipient of the EECS Mark D. Weiser Excellence in Computing Scholarship, 2015.** Merit-based scholarship awarded to one student in the Berkeley EECS department each year for excellence in research.

**Member of the EECS Honors Degree Program, concentration in Mathematics.** Honors program with 20-30 students. Requirements include research and extended studies in concentration outside EECS.

**UC Berkeley Outstanding Graduate Student Instructor (OGSI) Award recipient, 2015.** Awarded to top 10% of Teaching Assistants across the university each year.

**UC Berkeley Regents' and Chancellor's Scholar.** Merit-based scholarship awarded to top 1.5% of applicants to UC Berkeley each year.

**National Merit Scholar.** Merit-based scholarship awarded to high-achieving high school students for partial college tuition payment.

**Teaching**

**CS189: Introduction to Machine Learning.** Spring 2016.

**CS188: Introduction to Artificial Intelligence.** Fall 2015.

**CS61A: Structure and Interpretation of Computer Programs.** Spring 2015, Spring 2014, Summer 2013.

**CS61C: Great Ideas in Computer Architecture.** Fall 2014.

**Industry**

**Airbnb Inc., San Francisco, CA** (Software Engineering Intern) 06/2016 - Present

- Improving machine learning models used by the Search Ranking team.

**eBay Inc., San Jose, CA** (Software Engineering Intern) 05/2014 - 08/2014

- Developed an end-to-end pipeline involving data querying and machine learning to build a classification model for checkout transactions, used in determining whether to offer buyers the option to place items on hold.
- Collected data using Hadoop MapReduce under the Apache Pig framework.
- Model achieved 85% accuracy on noisy data sets, using AdaBoost with a decision tree.

**Technical Skills**

**Fluency in:** Python, Java, Scala, C, C++, Scheme, LaTeX.

**Software:** Unix/Linux, Robot Operating System (ROS), OpenCV, MongoDB, Apache Pig, Apache Spark, Hadoop MapReduce, scikit-learn, scikit-image.