Intoint 3 - Geometrie I

se afle izometria q = SA ° SR ° Sc.

$$S_{A}: \begin{pmatrix} 3 \\ 3 \end{pmatrix} = -\begin{pmatrix} 3 \\ 3 \end{pmatrix} + 2\begin{pmatrix} 1 \\ 0 \end{pmatrix} = -3 + 2$$

$$S_B$$
: $\binom{\mathcal{X}}{\mathcal{Y}} = -\binom{\mathcal{X}}{\mathcal{Y}} + 2\binom{3}{3} \iff S_B$: $\binom{\mathcal{X}}{\mathcal{Y}} = -\mathcal{X} + 6$

$$S_{c}: \begin{pmatrix} \mathcal{X}' \\ \mathcal{J}' \end{pmatrix} = -\begin{pmatrix} \mathcal{X} \\ \mathcal{J} \end{pmatrix} + 2\begin{pmatrix} \mathcal{A} \\ 2 \end{pmatrix} (=) S_{c}: \begin{pmatrix} \mathcal{X}' \\ \mathcal{J}' = -\mathcal{X} + 8 \end{pmatrix}$$

$$\frac{S_B}{\Rightarrow} \left(-(x+8)+6, -(y+4)+2 \right) = (x-2, y-2) \xrightarrow{S_A}$$

$$\xrightarrow{SA}$$
 $(-(x-2)+2, -(y-2)) = (-x+4, -y+2) =$

$$=-(x,y)+(4,2)=-(x,y)+2(2,1)$$

Aver
$$g = S_A \circ S_B \circ S_C = -(x, y) + 2(2, 1) = S_H, under$$

$$M(2, L)$$

$$g = (S_A \circ S_B \circ \mathcal{E})(x', y') = S_A(S_B(S_C(x', y')))$$

extra: Gasiti o dreapta invavianta în raport eu S_H, unde M(2,L).

(TEORIE) Doca MEd, aturci SM(d) = d.

Alegem d: x-2y=0, MEd.

-1-

Verificance: (d):
$$x - 2y = 0 \Rightarrow x = 2y$$

$$g(x,y) = g(2y,y) = (-2y+4, -y+2) = (2(-y+2), -y+2) \in d.$$

$$(x,y) = g(2y,y) = (-2y+4, -y+2) = (2(-y+2), -y+2) \in d.$$

$$(x,y) = g(2y,y) = (-2y+4, -y+2) = (2(-y+2), -y+2) \in d.$$

$$(x,y) = g(2y,y) = (-2y+4, -y+2) = (-2y+2) = (-2y+2)$$

Ex3) Fie f = In oS (glide reflection), is = (2,0), d: y=2. Ecuația lui f?? DII II, (9) 20 II mouh (d): 4-2=0=> 0=0, b=1,0=-2 $Sd_{s}\left(\frac{A_{i}}{A_{i}}\right) = \left(\frac{0}{7} - 1\right)\left(\frac{A}{A}\right) + \left(\frac{A}{0}\right) (=) Sd_{s}\left(\frac{A_{i}}{A_{i}} = -A+A\right)$ $\mathcal{I}_{\mathcal{Z}} = \mathcal{Z} \begin{cases} \mathcal{Z}' \\ \mathcal{Z}' \end{cases} = \begin{pmatrix} \mathcal{Z} \\ \mathcal{Z} \end{pmatrix} + \begin{pmatrix} \mathcal{Z} \\ \mathcal{Z} \end{pmatrix} = \begin{pmatrix} \mathcal{Z} \\ \mathcal{Z}' \end{cases} = \mathcal{Z}$ $f = \overline{J_{x}} \circ S_{d} = (x,y) \xrightarrow{S_{d}} (x,-y+u) \xrightarrow{J_{x}} (x+2,-y+u)$

 $= (x'-\lambda) + (5'h)$

(Ex4) a) Sã se socie ecuația lui Ro, 43.

b) So se determine $P_{0,\overline{N}_{2}}(d) = d'; (d): x+y+L=0$

c) Sã se sotie ecuação lui RH, N3, H(L, 1)

d) So se determine $R_{H,\overline{M}_3}(P) = P', H(1,1), P(3,3)$.

N(x0190)

$$\begin{array}{lll} & \mathcal{R}_{0,\overline{1}|3} & \mathcal{R}_{1} = A(\overline{1}|3) \, \mathcal{R}_{2} = \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{Y}_{1} \end{pmatrix} = \begin{pmatrix} \cos \overline{1}|3 & -\sin \overline{1}|3 \, \mathcal{X}_{2} \\ \sin \overline{1}|3 & \cos \overline{1}|3 \, \mathcal{X}_{3} \end{pmatrix} = \\ & = \begin{pmatrix} 1|2 & -\sqrt{3}|2 \, \mathcal{X}_{2} \\ \sqrt{3}|2 & 1|2 \end{pmatrix} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{2} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{2} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{2} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{3} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{2} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{3} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{2} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{3} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{2} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{3} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{2} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{3} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{2} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{3} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{3} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{2} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{3} \end{pmatrix} \stackrel{(a)}{=} \begin{pmatrix} \mathcal{X}_{1} \\ \mathcal{X}_{2} \end{pmatrix} \stackrel{(a)}{=}$$

b) Lin teorie stim că
$$A \cdot A^{T} = J_{A}$$
 (izometrii)

Apadoir, aveu că $A^{T} = A^{T}$, cāci $A \cdot A^{T} = J_{A}$.

Noi aveu: $X' = A(T_{A})X \iff A^{T}(T_{A})X' = A^{T}(T_{A})A(T_{A})X$

$$A^{T}(T_{A})X' = X$$

Ellew someth

$$X = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1/2 & \sqrt{3}/2 \\ -\sqrt{3}/2 & 1/2 \end{pmatrix} \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} x \\ y' \end{pmatrix} \begin{pmatrix} x \\ y' \end{pmatrix} \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} x \\ y' \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$(d'): \left(\frac{2}{L} \cancel{x}' + \frac{2}{L^3} \cancel{y}'\right) + \left(\frac{2}{L^3} \cancel{x}' + \frac{1}{L} \cancel{y}'\right) + 1 = 0 \cdot 2$$

$$(d'): \quad \mathcal{X}' + \sqrt{3} y' + (-\sqrt{3} x') + y' + \lambda = 0$$

$$(d')$$
: $(1-\sqrt{3})x' + (1+\sqrt{3})y' + 2 = 0$.

$$R_{H,\overline{W}3} \circ \left(\frac{\mathcal{X}^{1}}{Y^{1}} \right) = \left(\frac{\cos \overline{u}}{3} - \sin \overline{u} \right) \left(\frac{\mathcal{X}^{-1}}{Y^{-1}} \right) + \left(\frac{1}{1} \right)$$

$$R_{1} = \frac{1}{2} (x - 1) + \frac{$$

$$\mathcal{R}_{H,\overline{M}_{2}}(\mathfrak{P}) = P'\left(\frac{1}{2}(3-1) - \frac{3}{2}(3-1) + 1; \frac{3}{2}(3-1) + \frac{1}{2}(3-1) + 1\right) =$$

$$= P'\left(\frac{1}{2}\cdot 2 - \frac{13}{2}\cdot 2 + 1; \frac{13}{2}\cdot 2 + 1\right) =$$

Fie punctele
$$A(1,0)$$
, $B = R_{0,2\overline{0}/3}(A)$ is $C = R_{0,2\overline{0}/3}(B)$.
So se determine $R_{0,\overline{1}/2}(\Delta ABC) = \Delta A'B'C'$.

504;

$$R_{0,2\overline{u}/3}: X' = A\left(\frac{2\overline{u}}{3}\right)X \iff \left(\frac{2}{3}\right) = \begin{pmatrix} \cos 2\overline{u}/3 & -\sin 2\overline{u}/3 \\ \sin 2\overline{u}/3 & \cos 2\overline{u}/3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$(=) \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} -1/2 & -1/3/2 \\ \sqrt{3}/2 & -1/2 \end{pmatrix} \begin{pmatrix} x \\ y' \end{pmatrix} = \begin{pmatrix} 3/2 & -\frac{1}{2}x - \frac{1}{2}x \\ \sqrt{3}/2 & -\frac{1}{2}x \end{pmatrix}$$

$$R_{0,2\sqrt{3}}(A) = B = \left(-\frac{1}{2} \cdot 1 - \frac{\sqrt{3}}{2} \cdot 0; \frac{\sqrt{3}}{2} \cdot 1 - \frac{1}{2} \cdot 0\right) = \left(-\frac{1}{2}; \frac{\sqrt{3}}{2}\right)$$

$$R_{0,2M/3}(B) = C = \left(-\frac{1}{2} \cdot \left(-\frac{1}{2}\right) - \frac{\sqrt{3}}{2} \cdot \frac{\sqrt{3}}{2} \cdot \left(-\frac{1}{2}\right) - \frac{1}{2} \cdot \frac{\sqrt{3}}{2}\right) = \left(\frac{1}{4} - \frac{3}{4} \cdot \frac{1}{2} - \frac{\sqrt{3}}{4} - \frac{\sqrt{3}}{4}\right) = \left(-\frac{1}{2} \cdot -\frac{\sqrt{3}}{2}\right)$$

$$A(L_{1}O), B\left(-\frac{1}{2}, \frac{12}{2}\right), C\left(-\frac{1}{2}, -\frac{12}{2}\right)$$

$$P_{0}|_{1}|_{2} (ABC) = AA'B'C'$$

$$P_{0}|_{1}|_{2} (ABC) = A'B'C'$$

$$P_{0}|_{1}|_{2} (ABC) = B'C''$$

$$P_{0}|_{1}|_{2} (ABC) = B'C''$$

$$P_{0}|_{1}|_{2} (ABC) = B'''$$

$$P_{0}|_{2} (ABC) = B'''$$

$$P_{0}|_{2} (ABC) = B'''$$

$$P_{0}|_{2} (ABC) = B'$$

Ext. Fie $f: \mathcal{E}_2 \to \mathcal{E}_2$ o transformate geométrica de ecuatie $\chi' = A\chi + \chi_0$.

$$A = \begin{pmatrix} 7/25 & -24/25 \\ 24/25 & 7/25 \end{pmatrix}, \chi_0 = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

- a) Aratati ca q este o izometrie.
- b) Precizati speta, multimea de punde fixe si tipul

a) f este izometrie dacă A este matrice ortogenală, adică $A \cdot A^T = A^T \cdot A = J_2$.

$$A^{T} = \begin{pmatrix} +/25 & +24/25 \\ 24/25 & +/25 \end{pmatrix} = A \cdot A^{T} = \begin{pmatrix} \frac{7}{25} & -24/25 \\ 24/25 & +/25 \end{pmatrix} \begin{pmatrix} \frac{7}{25} & \frac{7}{25} \\ \frac{7}{25} & \frac{7}{25} \end{pmatrix} = \begin{pmatrix} \frac{49}{25^{2}} + \frac{576}{25^{2}} & \frac{7\cdot 24}{25^{2}} - \frac{34\cdot 7}{25^{2}} \\ \frac{24\cdot 7}{25^{2}} - \frac{24\cdot 7}{25^{2}} & \frac{7\cdot 24}{25^{2}} + \frac{49}{25^{2}} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = J_{2}.$$

beci, A.AT = I2 => & izonetrie.

$$det A = \begin{vmatrix} \frac{7}{25} & -\frac{24}{25} \\ \frac{24}{25} & \frac{7}{25} \end{vmatrix} = \frac{49}{625} + \frac{576}{625} = \frac{625}{625} = 1 \Rightarrow Appeta 1.$$

Punte fixe: X = AX + Xo (=> (I2-A)X = Xo

$$\begin{pmatrix}
\frac{18}{25} & \frac{24}{25} \\
-\frac{24}{25} & \frac{18}{25}
\end{pmatrix}
\begin{pmatrix}
\cancel{3}
\end{pmatrix} = \begin{pmatrix}
2 \\
\cancel{3}
\end{pmatrix}$$

$$\det B = \begin{vmatrix} 18/25 & 24/25 \\ -24/25 & 18/25 \end{vmatrix} = \frac{324 + 576}{625} = \frac{900}{625} = \frac{36}{25} \neq 0 \Rightarrow$$

=> sistemul are solutie unica => are un singur pot fix

4 este o rotatie.

$$\Delta_{x} = \begin{vmatrix} 2 & \frac{24}{25} \\ 0 & \frac{18}{25} \end{vmatrix} = \frac{36}{25} \Rightarrow x = \frac{0x}{\Delta} = \frac{36}{25} \Rightarrow x = \frac{1}{25} \Rightarrow x = \frac{1}{25$$

=> M(1, 4) puret fix.