

I Ecuatii affine scalare

b) $t x' - x = t^2 e^t$

$$t \neq 0 \quad \text{pp } t > 0 \quad \therefore x' = t e^t + \frac{x}{t} \quad \Rightarrow \quad x' = \underbrace{\frac{1}{t}}_{\text{ac}} x + \underbrace{t e^t}_{\text{st.}}$$

$$\text{Ec. lim. asoc. } \bar{x}' = \frac{1}{t} \bar{x} \quad \Rightarrow \quad \bar{x}(t) = c e^{\int \frac{1}{t} dt} = c e^{lnt} = c t \quad c \in \mathbb{R}$$

Caut sol. de forma $x(t) = c(t) \cdot t$

$$x'(t) \text{ sol} \Rightarrow (c(t) \cdot t)' = x'(t)$$

$$c'(t) \cdot t + c(t) \cdot 1 = \frac{1}{t} c(t) \cdot t + t e^t.$$

$$c'(t)t = t e^t \quad | : t \neq 0$$

$$c'(t) = e^t \quad \Rightarrow \quad c(t) = e^t + k \quad k \in \mathbb{R}$$

$$\Rightarrow x_k(t) = (e^t + k) \cdot t \quad \text{inlocuim în } x$$

Verificare: $t x' = t((e^t + k) \cdot t)' =$
 $= t(e^t \cdot t + (e^t + k) \cdot 1) = e^t t^2 + e^t t + k t \quad \} \quad \checkmark$
 $x + t^2 e^t = (e^t + k) t + t^2 e^t = e^t t + k t + t^2 e^t \quad \}$

$$c) x' + \frac{2}{t} x = t^3 \quad \Rightarrow \quad x' = -\frac{2}{t} x + t^3$$

$$\text{Ec. lim. asoc. } \bar{x}' = -\frac{2}{t} \bar{x} \quad \Rightarrow \quad \bar{x}(t) = c \cdot e^{-\int \frac{2}{t} dt} = c e^{-2lnt} = c t^{-2} \quad c \in \mathbb{R}$$

Caut sol. de forma $x(t) = c(t) \cdot t^{-2}$

$$x'(t) \text{ sol} \Rightarrow (c(t) \cdot t^{-2})' = x'(t)$$

$$c'(t) \cdot t^{-2} - 2c(t) \cdot t^{-3} = -\frac{2}{t} \cdot c(t) \cdot t^{-2} + t^3$$

$$c'(t) \cdot t^{-2} = t^3 \quad | \cdot t^2$$

$$c'(t) = t^5 \quad \Rightarrow \quad c(t) = \frac{1}{6} t^6 + k \quad k \in \mathbb{R}$$

$$\Rightarrow x_k(t) = \left(\frac{1}{6} t^6 + k \right) \cdot t^{-2} = \frac{1}{6} t^4 + k t^{-2}$$

Veificare

$$\left\{ \begin{array}{l} x' + \frac{2}{t} x = \left(\frac{1}{6} t^4 + kt^{-2} \right)' + \frac{2}{t} \cdot \left(\frac{1}{6} t^4 + kt^{-2} \right) = \frac{2}{3} t^3 - 2kt^{-1} + \frac{1}{3} t^3 + 2kt^{-2} = t^3 \\ t^3 \end{array} \right.$$

✓

Ecuatii de tip Bernoulli

$$2. b) x' = -\frac{x}{t} + \frac{1}{t^2 x^2} \Leftrightarrow x' = -\frac{1}{t} x + \frac{1}{t^2} \cdot x^{-2}$$

$$\text{Ec. lin assoc. } \bar{x}' : a(t) \bar{x} = -\frac{1}{t} \bar{x} \Rightarrow \bar{x}(t) = c \cdot e^{-\int \frac{1}{t} dt} = ct^{-1} \text{ cu } k$$

Caut sol de forma $x(t) = c(t)t^{-1}$

$$x'(t) \text{ sol} \Rightarrow (c(t)t^{-1})' = x'(t)$$

$$c'(t) = b(t) e^{(t-1)A(t)} \cdot c^2(t)$$

$$c'(t) = \frac{1}{t^2} \cdot c^{-3} \ln t \cdot c^{-2}(t)$$

$$c'(t) = t^{-5} \cdot c^{-2}(t)$$

$$\frac{dc}{dt} = t^{-5} \cdot c^{-2}$$

$$dc \cdot c^2 = \frac{dt}{t^5} \rightarrow \int 2dc = \int t^{-5} dt \Leftrightarrow \frac{c^3(t)}{3} = -\frac{1}{4t^4} + k \Rightarrow$$

$$\Rightarrow c^3 = -\frac{3}{4t^4} \Rightarrow c_k(t) = -\frac{3}{4t^4} + k$$

$$x(t) = c(t)t^{-1} = \left(-\frac{3}{4t^4} + k \right) \cdot t^{-1} = -\frac{3}{4} \cdot t^{-5} + kt^{-2}$$

Veificare: $x' = \left(-\frac{3}{4} \cdot t^{-5} + kt^{-2} \right)' = -\frac{3}{4} \cdot (-5) \cdot t^{-6} - kt^{-3} = 5 \cdot \frac{3}{4} t^{-6} - kt^{-3}$

$$= \frac{-\frac{3}{4} \cdot t^{-5} + kt^{-2}}{t} + 8 \cdot \frac{3}{4} t^{-6} - 2kt^{-3}$$

$$= x + t^{-2} \left(\frac{9}{2} t^{-4} - 2k \right)$$

$$\frac{1}{t^2 x^2} = \frac{1}{t^2 \left(\frac{9}{4} t^{-10} - \frac{3}{2} t^{-6} + k^2 \cdot t^{-2} \right)}$$

$$= \frac{4}{9} \cdot t^{-8} - \frac{3}{2} t^{-4} + k^2$$

c) $x' = x \cos t + x^2 \cos t$

Ec. lin. assoc. $\bar{x}' = \cos t \cdot \bar{x} \Rightarrow \bar{x}(t) = C \cdot e^{\int \cos t dt} = C e^{\sin t}$

Cant sol. de forma $x(t) = C t / e^{\sin t}$

$$x(-) - \text{sol} \Rightarrow c'(t) = b(t) \cdot e^{(\alpha-1)\sin t} \cdot c^2(t)$$

$$c'(t) = \cos t \cdot e^{\sin t} \cdot c^2(t)$$

$$\frac{dc}{dt} = \cos t \cdot e^{\sin t} \cdot c^2$$

$$dc \cdot c^{-2} = \cos t \cdot e^{\sin t} dt \Rightarrow \int c^{-2} dc = \int \cos t \cdot e^{\sin t} dt$$

$$\Rightarrow -c^{-1} = e^{\sin t} + k \Rightarrow C_k(t) = (-e^{\sin t} - k)^{-1}$$

$$x(t) = C(t) \cdot e^{\sin t} \Rightarrow x_k(t) = (-e^{\sin t} - k)^{-1}.$$

$$\left\{ \begin{array}{l} x'_k(t) = \frac{e^{\sin t} \cos t}{(-e^{\sin t} - k)^2} \cdot \frac{e^{\sin t} + k}{\cos t} \\ x \cos t + x^2 \cos t = \frac{\cos t}{-e^{\sin t} - k} + \frac{\cos t}{(e^{\sin t} + k)^2} = \frac{e^{\sin t} \cos t + (k+1) \cos t}{(e^{\sin t} + k)^2} \end{array} \right.$$

Problema Cauchy:

$$x'' = x' \ln x' \quad x(0) = 0 \quad x'(0) = 1$$

S.V. $y = x' \rightarrow y' = y \ln y$

$$\frac{dy}{dt} = y \ln y \Rightarrow \frac{1}{y \ln y} dy = dt \Rightarrow \int \frac{1}{y \ln y} dy = \int dt \Rightarrow$$
$$\Rightarrow \ln(\ln y) = t + c \Rightarrow \ln y = e^{t+c} \Rightarrow y = e^{e^{t+c}} = e^{e^t \cdot e^c} = e^{k \cdot e^t}$$

Rezervim S.V: $e^{k \cdot e^t} = x'$

Stim că $\begin{cases} x(0) = 0 \\ x'(0) = 1 \end{cases} \Rightarrow \begin{cases} e^{k \cdot e^0} = 1 \\ e^{k \cdot e^0} = 1 \end{cases} \Rightarrow e^{k \cdot 1} = 1 \Rightarrow e^k = 1 \Rightarrow k = 0$

$$\begin{cases} x = t + c \\ x(0) = 0 \end{cases} \Rightarrow 0 + c = 0 \Rightarrow c = 0 \Rightarrow x(t) = t$$

Local lipschitz în rap. cu a doua variabilă

$$x' = 2e^{-t} + \ln(1+x^2)$$

$$f(t, x) - f(t, y) = 2e^{-t} + \ln(1+x^2) - 2e^{-t} - \ln(1+y^2) = \ln \frac{1+x^2}{1+y^2}$$

Vrem $\ln \frac{1+x^2}{1+y^2} \leq L(x-y)$

$$\lim_{y \rightarrow x} \frac{\ln(1+x^2) - \ln(1+y^2)}{|x-y|} \leq L$$
$$\frac{2x}{1+x^2} \leq L$$

⇒ fct. diferențială $\Rightarrow L \leq 1$

PB. sol. maximală Cauchy ~easy version

$$\varphi(\cdot, \tilde{t}): I(\tilde{t}) \subset \mathbb{R} \rightarrow \mathbb{R} \quad \tilde{t} \in \mathbb{R}$$

$$x' = x^2 - x \cos t + \sin t + 1 \quad x(\tilde{t}) = 0$$

$$\Delta_2 \varphi(t, 0) = ?$$

Fie $\varphi(\cdot, \cdot, \cdot): D_\varphi \rightarrow \mathbb{R}$ curentul maximal C^1

$$\varphi(t, \tilde{t}) = \varphi(t, \tilde{t}, 0) \quad | \frac{\partial}{\partial \tilde{t}}$$

$$x'' = 2x - \cos t$$

$$\tilde{t} = 0 \rightarrow \Delta_2 \varphi(t, 0) = \Delta_2 \varphi(t, 0, 0) \text{ am buat } \tilde{t} = 0 \text{ mai sus}$$

$$t \rightarrow \Delta_2 \varphi(t, 0, 0) \text{ adă: } \underbrace{y' = \Delta_2 \varphi(t, \varphi(t, 0, 0)) y}_{y(0) = -\varphi(0, 0)}$$

$$\Delta_2 \varphi(t, x) = 2x - \cos t$$

$$\varphi(t, 0, 0) = \varphi(t, 0) = t \sin t$$

$$\Rightarrow y' = (2t \sin t - \cos t) y \quad y(0) = -\varphi(0, 0) = -(0 - 0 \cdot \cos 0 + \sin 0 + 1) = -1$$

$$y(t) = C \int (2t \sin t - \cos t) dt = C e^{-2t \sin t} (\cos t) - \sin t$$

$$\Rightarrow y(t) = C \cdot \frac{1}{\cos^2 t} e^{-2t \sin t} \quad \left. \begin{array}{l} \\ \end{array} \right\} \Rightarrow C \cdot \frac{1}{\cos^2 0} e^{-2 \sin 0} = -1$$

$$y(0) = -1$$

$$\Rightarrow y(t) = -\frac{e^{-2t \sin t}}{\cos^2 t} = -\frac{1}{\cos^2 t e^{2t \sin t}}$$

dim teorie

$$= C e^{-2t \sin t} (\cos t) - \sin t$$

$$C \cdot \frac{1}{1} \cdot e^0 = -1 \Rightarrow C = -1$$

Pb. sol maximală Cauchy ~ exam mode

$$f(\cdot, \lambda) : I(\lambda) \subseteq \mathbb{R} \rightarrow \mathbb{R}, \lambda \in \mathbb{R}$$

$$x' = x^2 + \frac{x}{t} + \lambda(x^2 + 1) \quad x(\lambda + 1) = \lambda - 1 \quad \circ$$

$$\Delta_2 \Psi(t, 0) = ?$$

$$f(t, x, \lambda) = x^2 + \frac{x}{t} + \lambda(x^2 + 1) \quad f(\cdot, \cdot, \cdot) : \underbrace{\mathbb{R}^* \times \mathbb{R} \times \mathbb{R}}_{\text{domeniu}} \rightarrow \mathbb{R} \quad \text{f cont } C^1$$

Fie $\alpha_f(\cdot, \cdot, \cdot, \cdot) : D_f \rightarrow \mathbb{R}$ curentul maximal parametrizat c'

$$\Psi(t, \lambda) = \alpha_f(t, \lambda+1, \lambda-1, \lambda) \mid \frac{\partial}{\partial \lambda} \rightarrow$$

$$\begin{cases} x' = f(t, x, \lambda) \\ x(\lambda+1) = \frac{\lambda-1}{3} \end{cases} \sim \text{dim ip } \circ$$

$$\Rightarrow \Delta_2 \Psi(t, \lambda) = \Delta_2 \alpha_f(t, \lambda+1, \lambda-1, \lambda) + \Delta_3 \alpha_f(t, \lambda+1, \lambda-1, \lambda) + \Delta_4 \alpha_f(t, \lambda+1, \lambda-1, \lambda)$$

Nă numim $\Psi(t, 0)$ deci buârnă $\lambda = 0$

$$\Delta_2 \Psi(t, 0) = \Delta_2 \alpha_f(t, 1, -1, 0) + \Delta_3 \alpha_f(t, 1, -1, 0) + \Delta_4 \alpha_f(t, 1, -1, 0)$$

$$\bullet t \mapsto \Delta_2 \alpha_f(t, -1, 1, 0) \text{ sol } \begin{cases} y' = \Delta_2 \alpha_f(t, \alpha_f(t, 1, -1, 0), 0) \\ y(1) = -\alpha_f(1, -1, 0) = -(1 - 1 + 0) = 0 \end{cases}$$

$$\bullet t \mapsto \Delta_3 \alpha_f(t, -1, 1, 0) \text{ sol matriceală } \begin{cases} y' = \Delta_2 f(t, \alpha_f(t, 1, -1, 0), 0) \\ y(1) = J_4 \end{cases}$$

$$\bullet t \mapsto \Delta_4 \alpha_f(t, -1, 1, 0) \text{ sol: } \begin{cases} z' = \Delta_2 \alpha_f(t, \alpha_f(t, 1, -1, 0), 0)z + \Delta_3 \alpha_f(t, \alpha_f(t, 1, -1, 0), 0) \\ z(1) = 0 \end{cases}$$

$$\Delta_2 \alpha_f(t, x, \lambda) = 2x + \frac{1}{t} + 2x\lambda = 2x(\lambda + 1) + \frac{1}{t} \quad \frac{\partial f}{\partial x}$$

$$\Delta_3 \alpha_f(t, x, \lambda) = x^2 + 1 \quad \frac{\partial f}{\partial x}$$

$\alpha_f(t, 1, -1, 0) = ?$ înlocuim în ecuația cu $\lambda = 0$

$$x' = x^2 + \frac{x}{t} + O(x^2 + 1) = x^2 + \frac{x}{t} \quad \text{ec. Bernoulli}$$

$$\begin{aligned} x(\lambda+1) &= \lambda-1 \\ \lambda &= 0 \end{aligned} \quad \left. \begin{array}{l} x(1) = -1 \end{array} \right\}$$

Bägåm la calculator $x(t) = -\frac{2t}{t^2+1} = d_2(t, 1, -1, 0)$

$$\left. \begin{array}{l} y' = D_2 f(t, d_2(t, 1, -1, 0), 0) y = D_2 f(t, -\frac{2t}{t^2+1}, 0) y \\ D_2 f(t, x, \lambda) = 2x(\lambda+1) + \frac{1}{t} \end{array} \right\} \Rightarrow$$

$$\Rightarrow y' = \left(\frac{-4t}{t^2+1} (0+1) + \frac{1}{t} \right) \cdot y = \frac{t^2 - 4t^2 + 1}{t(t^2+1)} \cdot y = \frac{1 - 3t^2}{t(t^2+1)} \cdot y \quad \text{er. lin. scalar}$$

$$y(t) = c \cdot e^{\int \frac{1-3t^2}{t^2+t} dt} = c \cdot e^{4nt - 2 \ln(t^2+1)} = c \cdot \frac{e^{4nt}}{e^{2 \ln(t^2+1)}} = c \cdot \frac{t}{(t^2+1)^2} \quad c \in \mathbb{R}$$

$$y(1) = 0 \Rightarrow c \cdot \frac{1}{4} = 0 \Rightarrow c = 0 \Rightarrow y(t) = 0$$

$$\left. \begin{array}{l} y'(t) = c \cdot \frac{t}{(t^2+1)^2} \\ y(1) = 1 \end{array} \right\} \Rightarrow \frac{c}{4} = 1 \Rightarrow c = 4 \Rightarrow y(t) = \frac{4t}{(t^2+1)^2}$$

$$\left. \begin{array}{l} D_3 f(t, d_2(t, 1, -1, 0), 0) = D_3 f(t, -\frac{2t}{t^2+1}, 0) \\ D_3 f(t, x, \lambda) = x^2 + 1 \end{array} \right\} = \frac{4t^2}{(t^2+1)^2} + 1$$

$$\left. \begin{array}{l} z' = \frac{1-3t^2}{t(t^2+1)} \cdot z + \frac{4t^2}{(t^2+1)^2} + 1 \\ z(1) = 0 \end{array} \right\} \stackrel{\text{Wolfram}}{\Rightarrow} z(t) = \frac{t(t^4 + 12t^2 + 4 \ln t - 13)}{4(t^2+1)^2}$$

$$\begin{aligned} D_2 \varphi(t, 0) &= D_2 d_2(t, 1, -1, 0) + D_3 d_2(t, 1, -1, 0) + D_4 d_2(t, 1, -1, 0) \\ &= 0 + \frac{4t}{(t^2+1)^2} + \frac{t(t^4 + 12t^2 + 4 \ln t - 13)}{4(t^2+1)^2} = \end{aligned}$$

$$= \frac{t(16 + t^4 + 12t^2 + 4 \ln t - 13)}{4(t^2+1)^2}$$

$$= \frac{t(t^4 + 12t^2 + 4 \ln t + 3)}{4(t^2+1)^2}$$

PB sol. maximală Cauchy

$$x' = x^3 + tx \quad x(0) = \underline{3}$$

$\Delta_2 \Psi(t, 0) = ?$

$\varphi(t, \xi) : I(\emptyset) \subset \mathbb{R} \rightarrow \mathbb{R}$ sol max a pb

$$\varphi(t, x) = x^3 + tx \quad \varphi(\cdot, \cdot) : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$$

Teorema lui Picard-Lindelöf: $\Delta_\varphi \rightarrow \mathbb{R}$ curentul maximal parametrizat

$$\Psi(t, \xi) = \Delta_\varphi(t, 0, \xi) \quad | \frac{\partial}{\partial \xi}$$

$$\Delta_2 \Psi(t, \xi) = \Delta_3 \Delta_\varphi(t, 0, \xi)$$

$$\underline{3} = 0 \Rightarrow \Delta_2 \Psi(t, 0) = \Delta_3 \Delta_\varphi(t, 0, 0)$$

$$\Delta_3 \Delta_\varphi(t, 0, 0) \text{ sol a ec} \Rightarrow \begin{cases} y' = \Delta_2 \varphi(t, \Delta_\varphi(t, 0, 0)) \cdot y \\ y(0) = 1 \end{cases}$$

$$\Delta_2 \varphi(t, x) = 3x^2 + t$$

$$\Delta_\varphi(t, 0, 0) = ?$$

$$x' = x^3 + tx \quad x(0) = 0 \quad \text{ec. Bernoulli}$$

$$\text{Ec. lin ord. } \bar{x}' = t\bar{x} \Rightarrow \bar{x}(t) = C e^{\frac{t^2}{2}}$$

$$\begin{aligned} x(t) &= C(t) e^{\frac{t^2}{2}} \\ x(0) &= 0 \end{aligned} \Rightarrow C(0) = 0 \Rightarrow$$

$$x' = (C(t) \cdot e^{\frac{t^2}{2}})' = x'(t) \quad (\Leftarrow)$$

$$\Rightarrow C(t) \cdot e^{\frac{t^2}{2}} + C'(t) e^{\frac{t^2}{2}} = C(t)^3 e^{\frac{3t^2}{2}} + t C(t) e^{\frac{t^2}{2}}$$

$$\Rightarrow C'(t) = C^3(t) e^{t^2}$$

$$\frac{dc}{dt} = C^3 e^{t^2}$$

$$\stackrel{!}{=} C^3 = 0 \Rightarrow C(t) = 0 \Rightarrow x(t) = 0 \quad \text{OK}$$

$$\stackrel{!}{=} \frac{dc}{c^3} = dt e^{t^2} \Rightarrow \int \frac{1}{c^3} dc = \int e^{t^2} dt \Rightarrow -\frac{1}{c^2} = \int e^{t^2} dt + k \quad \text{OK}$$

$$\Rightarrow \Delta_\varphi(t, 0, 0) = 0 \Rightarrow \begin{cases} y' = ty \Rightarrow \frac{dy}{dt} = ty \\ y(0) = 1 \end{cases}$$

$$\begin{aligned} \dot{y} &= 0 \text{ ab} \\ \Rightarrow \int y' dt &= t dt \Rightarrow \ln y = \frac{t^2}{2} + k \Rightarrow y = e^{\frac{t^2}{2} + k} \\ y(0) &= 1 \Rightarrow e^k = 1 \Rightarrow k = 0 \Rightarrow y(t) = e^{\frac{t^2}{2}} \\ \Rightarrow D_2 \Psi(t, 0) &= e^{\frac{t^2}{2}} \end{aligned}$$

Fr. sol. maximal à Cauchy

$$x' = x^2 + \lambda t x^3 - x \quad x(0) = N$$

$$D_2 \Psi(t, 0) = ?$$

$$\varphi(t, x, \lambda) = x^2 + \lambda t x^3 - x$$

& $\varphi(\cdot, \cdot, \cdot)$ current maximal solution

$$\varphi(t, \lambda) = d \varphi(t, 0, (\lambda, \lambda))$$

$$\lambda = 0 \rightarrow D_2 \varphi(t, 0) = D_3 \varphi(t, 0, (0, 0)) + D_4 \varphi(t, 0, (0, 0))$$

$$\begin{cases} y' = D_2 \varphi(t, d \varphi(t, 0, (0, 0)), 0) y \\ y(0) = -\varphi(0, 0, 0) = 0 \end{cases}$$

$$D_2 \varphi(t, x, \lambda) = 2x + 3\lambda x^2 - 1$$

$$D_3 \varphi(t, x, \lambda) = t x^3$$

$$D_4 \varphi(t, 0, (0, 0)) = ? \quad x' = x^2 - x \quad x(0) = 1 \quad \int -1 dt = c(t) e^{-t}$$

$$x(t) = c(t) e^{-t} \quad |(1)'$$

$$c(t) e^{-t} - \cancel{c(t) e^{-t}} = c^2(t) e^{-2t} - c(t) e^{-t}$$

$$\Rightarrow c'(t) = c^2(t) e^{-t}$$

$$\frac{dc}{dt} = c^2 e^{-t} \Leftrightarrow \int c^{-2} dc = - \int e^{-t} dt \Leftrightarrow -\frac{1}{c} = -e^{-t} + k$$

$$\Rightarrow c(t) = \frac{1}{e^{-t} + k} \Rightarrow x(t) = \frac{e^{-t}}{e^{-t} + k}$$

$$\lambda(0) = 1 \Rightarrow k = 0 \quad x(t) = d_f(t, 0, (0, 0)) = 1$$

$$\begin{cases} y' = D_2 f(t, 1, 0) = (2 \cdot 1 + 3 \cdot 0 \cdot t \cdot 1 - 1)y = y \Rightarrow y(t) = C_1 e^t \\ y(0) = 0 \Rightarrow y(t) = 0 \end{cases}$$

$$\begin{cases} z' = D_2 f(t, 1, 0) \cdot 2 + D_3 f(t, 1, 0) = 2 + t \Rightarrow z(t) = C_1 e^t - t - 1 \\ z(0) = 0 \Rightarrow C_1 = 1 \Rightarrow z(t) = e^t - t - 1 \end{cases}$$

$$\Rightarrow D_2 \Psi(t, 0) = y(t) + z(t) = 0 + e^t - t - 1 = e^t - t - 1$$

Pb. sol. maximală Cauchy

$$x' = x^2 + \lambda t x - \lambda \quad x(0) = 0$$

$$\Delta_2 \varphi(t, 0) = ?$$

$$f(t, x, \lambda) = x^2 + \lambda t x - \lambda$$

$$\varphi(t, \lambda) = \Delta_2 f(t, 0, \lambda, \lambda) \quad \text{~curvențul maximal}$$

$$\lambda = 0 \Rightarrow f(t, 0) = \Delta_2 f(t, 0, 0, 0)$$

$$\begin{cases} y' = \Delta_2 f(t, \Delta_2 f(t, 0, 0, 0), 0) \cdot y \\ y(0) = -\underline{f(0, 0, 0)} = 0 \end{cases}$$

$$\begin{cases} z' = \Delta_2 f(t, \Delta_2 f(t, 0, 0, 0), 0) \cdot z + \Delta_3 f(t, \Delta_2 f(t, 0, 0, 0), 0) \\ z(0) = 0 \end{cases}$$

$$\Delta_2 f(t, x, \lambda) = 2x + \lambda t \quad \text{~dériv f după } x$$

$$\Delta_3 f(t, x, \lambda) = tx - 1 \quad \text{~dériv f după } \lambda$$

$$\Delta_2 f(t, 0, 0, 0) = ?$$

înlocuim $\lambda = 0$ în ec: $x' = x^2 + 0tx + 0 \Rightarrow x' = x^2$

$$\text{Wofram} \Rightarrow x(t) = \frac{1}{c-t}$$

$$x(0) = 0 \Rightarrow \frac{1}{c} = 0 \quad \text{dx} \Rightarrow x(t) \equiv 0 \Rightarrow \Delta_2 f(t, 0, 0, 0) = 0 \quad (\text{OK})$$

$$\begin{cases} y' = \Delta_2 f(t, 0, 0) \cdot y = 2 \cdot 0 + 0 \cdot t = 0 \\ y(0) = 0 \end{cases} \Rightarrow y(t) = 0$$

$$\begin{cases} z' = \Delta_2 f(t, 0, 0) \cdot z + \Delta_3 f(t, 0, 0) = 2 \cdot 0 + 0t)z + t \cdot 0 - 1 = -1 \\ z(0) = 0 \end{cases}$$

$$\Rightarrow z(t) = -t$$

$$\Delta_2 \varphi(t, 0) = y(t) + z(t) = 0 - t = -t$$

Pb. parametrizare

$$(p-q)(x-y) + \frac{p^2}{2} - z = 0, \quad y=1, z = \frac{(x-1)^2}{2}$$

este:

$$x(t, \sigma) = 1 + (\sigma-1)e^{2t}, y(t, \sigma) = 1 + (\sigma-1)e^t - (\sigma-1)e^{2t}, z(t, \sigma) = \frac{(\sigma-1)^2 e^{2t}}{2}$$

$$\varphi = \frac{\partial z}{\partial x}(x, y)$$

$$\varrho = \frac{\partial z}{\partial y}(x, y)$$

$$F(x, y, z, (\varphi, \varrho)) = (\varphi - \varrho)(x - y) + \frac{\varrho^2}{2} - z = 0$$

$$\begin{cases} x = \underbrace{\sigma}_{\text{1}} & \alpha(\sigma) = \begin{pmatrix} \sigma \\ 1 \end{pmatrix} \\ y = 1 & \\ z = \frac{(\sigma-1)^2}{2} & \varphi(\sigma) = \frac{(\sigma-1)^2}{2} \end{cases}$$

$$\begin{cases} F(\alpha(\sigma), \beta(\sigma), (\varphi, \varrho)) = 0 \\ (\varphi, \varrho) \Delta \alpha(\sigma) = \Delta \beta(\sigma) \end{cases}$$

$$\begin{cases} (\varphi - \varrho)(\sigma - 1) + \frac{\varrho^2}{2} - \frac{(\sigma-1)^2}{2} = 0 \\ (\varphi, \varrho) \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \left(\frac{(\sigma-1)^2}{2} \right)' = \left(\frac{\sigma^2 - 2\sigma + 1}{2} \right)' = \sigma - 1 \Rightarrow \varphi = \sigma - 1 \end{cases}$$

inlocuind $\varphi = \sigma - 1$ în ec 1:

$$\varrho(\sigma - 1) - \underbrace{\varrho(\sigma - 1)}_{\cancel{+ \frac{(\sigma-1)^2}{2} - \frac{(\sigma-1)^2}{2}}} = 0$$

$$(\sigma-1)^2 - \underbrace{\varrho(\sigma-1)}_{\cancel{+ \frac{(\sigma-1)^2}{2} - \frac{(\sigma-1)^2}{2}}} = 0$$

$$\varrho = \sigma - 1$$

$$\chi(\sigma) = \begin{pmatrix} \sigma-1 \\ \sigma-1 \end{pmatrix}$$

$$\left\{ \begin{array}{l} x' = \frac{\partial F}{\partial p} = x - y + p \\ y' = \frac{\partial F}{\partial q} = y - x \end{array} \right.$$

$$\left. \begin{aligned} z' &= p \cdot x' + q \cdot y' = px - py + p^2 + qy - qx \\ &= (p-q)x - (q-p)y + p^2 \\ &= (p-q)(x-y) + p^2 \end{aligned} \right\}$$

$$p' = -\frac{\partial F}{\partial x} - p \frac{\partial F}{\partial z} = q - p + p = q$$

$$q' = -\frac{\partial F}{\partial y} - q \frac{\partial F}{\partial z} = p - q + q = p$$

$$\begin{aligned} x(0) &= 0 \\ y(0) &= 1 \end{aligned}$$

$$x(t) = \begin{pmatrix} x(0) \\ y(0) \end{pmatrix}$$

$$z(0) = \frac{(0-1)^2}{2} = 3(0)$$

$$\left. \begin{aligned} p(0) &= 0-1 \\ q(0) &= 0-1 \end{aligned} \right\} x(t)$$

$$z(0) = 0-1$$

$$\left\{ \begin{array}{l} x' = x - y + p \\ y' = y - x \\ z' = (p-q)(x-y) + p^2 \\ p' = q \\ q' = p \end{array} \right. \quad \begin{aligned} x(0) &= 0 \\ y(0) &= 1 \\ z(0) &= \frac{(0-1)^2}{2} \\ p(0) &= 0-1 \\ q(0) &= 0-1 \end{aligned}$$

$$\left. \begin{aligned} p' &= q \\ q' &= p \end{aligned} \right\} \Rightarrow q'' = q \Rightarrow q'' - q = 0 \Rightarrow q(t) = c_1 e^t + c_2 e^{-t}$$

$$q(0) = 0-1 \Rightarrow c_1 e^0 + c_2 e^0 = 0-1 \Rightarrow c_1 + c_2 = 0-1$$

$$p(t) = q(t) = c_1 e^t - c_2 e^{-t}$$

$$p(0) = 0-1 \Rightarrow c_1 e^0 - c_2 e^0 = 0-1 \Rightarrow \underline{c_1 - c_2 = 0-1 \quad (+)}$$

$$2c_1 = 20-2 \Rightarrow c_1 = 0-1 \Rightarrow c_2 = 0$$

$$\Rightarrow \begin{cases} p(t) = (0-1) e^t \\ q(t) = (0-1) e^t \end{cases}$$

$$\begin{aligned}x' &= x - y + (\Gamma - 1)e^t \\y' &= y - \cancel{x}\end{aligned}\quad (+)$$

$$x' + y' = (\Gamma - 1)e^t \quad | \int$$

$$x + y = (\Gamma - 1)e^t + k$$

$$x(t) + y(t) = (\Gamma - 1)e^t + k$$

$$t=0 \Rightarrow x(0) + y(0) = (\Gamma - 1)e^0 + k$$

$$\Gamma + 1 = \Gamma - 1 + k \Rightarrow k = 2$$

$$x(t) = (\Gamma - 1)e^t - y(t) + 2$$

$$\begin{aligned}x' &= x - y + (\Gamma - 1)e^t \\&= x - \cancel{y} + (\Gamma - 1)e^t + 2 - 2\end{aligned}$$

$$= x + x - 2$$

$$= 2x - 2$$

$$\begin{aligned}x' = 2x - 2 \Rightarrow x &= ce^{2t} + 1 \\x(0) = \Gamma &\end{aligned}\quad \left. \right\} \Rightarrow c + 1 = \Gamma \Rightarrow c = \Gamma - 1$$

$$\Rightarrow x(t) = (\Gamma - 1)e^{2t} + 1$$

$$\begin{aligned}y(t) &= (\Gamma - 1)e^t + 2 - (\Gamma - 1)e^{2t} - 1 \\&= (\Gamma - 1)e^t - (\Gamma - 1)e^{2t} + 1\end{aligned}$$

$$z' = p - q(x - y) + p^2$$

$$\begin{aligned}&= \underbrace{((\Gamma - 1)e^t - (\Gamma - 1)e^t)}_0 ((\Gamma - 1)e^{2t} + 1 - (\Gamma - 1)e^t + (\Gamma - 1)e^{2t} - 1) + (\Gamma - 1)^2 e^{4t}\end{aligned}$$

$$= (\Gamma - 1)^2 e^{2t}$$

Pb parametrizare

$$2xy - pq - z = 0, \quad x = 1, z = y$$

este:

$$x(t, \sigma) = e^{-t}, \quad y(t, \sigma) = \sigma e^{-t}, \quad z(t, \sigma) = \sigma e^{-2t}$$

$$P = \frac{\partial^2}{\partial x^2} |x, y|$$

$$Q = \frac{\partial^2}{\partial y^2} |x, y|$$

$$F(|x, y|, z, (P, Q)) = 2xy - pq - z = 0$$

$$\begin{cases} x = 1 \\ y = \sigma \\ z = y = \sigma \end{cases} \quad \alpha(\tau) = \begin{pmatrix} 1 \\ \sigma \\ \sigma \end{pmatrix}$$

$$\begin{cases} F(x(\tau), y(\tau), (p, q)) = 0 \\ (p, q) D\alpha(\tau) = D\beta(\tau) \end{cases} \Rightarrow \begin{cases} 2 \cdot 1 \cdot \sigma - pq - \sigma = 0 \Leftrightarrow \sigma = pq \\ (p, q) \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 1 \Leftrightarrow q = 1 \end{cases}$$

in locum $q = 1$ în ec 1:

$$\begin{cases} \tau = p \\ \rightarrow \gamma(\tau) = \begin{pmatrix} \tau \\ 1 \end{pmatrix} \end{cases} \quad \text{rez. } \underbrace{\gamma}_{\text{gg.}}$$

$$\begin{cases} x' = \frac{\partial F}{\partial p} = -q & x(0) = 1 \\ y' = \frac{\partial F}{\partial q} = -p & y(0) = \sigma \\ z' = p \cdot x' + q \cdot y' = -pq - q \cdot p = -2pq & z(0) = \sigma \\ p' = -\frac{\partial F}{\partial x} - p \frac{\partial F}{\partial z} = -2y + p = p - 2y & p(0) = \sigma \\ q' = -\frac{\partial F}{\partial y} - q \cdot \frac{\partial F}{\partial z} = -2x + q = q - 2x & q(0) = 1 \end{cases}$$

$$x' = -q \quad |(1) \Rightarrow x'' = -q' \quad \left. \begin{array}{l} \\ \end{array} \right\} \Rightarrow -x'' = -x' - 2x$$

$$q' = q - 2x$$

$$\Rightarrow x(t) = C_1 e^{-t} + C_2 e^{2t}$$

$$x(0) = 1 \Rightarrow C_1 + C_2 = 1$$

$$q = -x' = C_1 e^{-t} - 2C_2 e^{2t}$$

$$q(0) = 1 \Rightarrow C_1 - 2C_2 = 1$$

$$\Rightarrow \begin{cases} x(t) = e^{-t} \\ q(t) = e^{-t} \end{cases}$$

$$\begin{matrix} q' = -p & |(1) \Rightarrow q'' = -p' \\ p = p - 2q & \end{matrix} \quad \left. \begin{array}{l} \\ \end{array} \right\} \Rightarrow q'' = q' + 2q$$

$$x(t) = C_1 e^{-t} + C_2 e^{2t}$$

$$q(0) = \sqrt{r} \Rightarrow C_1 + C_2 = \sqrt{r}$$

$$p = -q' = C_1 e^{-t} - 2C_2 e^{2t}$$

$$q(0) = \sqrt{r} \Rightarrow C_1 - 2C_2 = \sqrt{r}$$

$$\begin{cases} q(t) = \sqrt{r} e^{-t} \\ p(t) = \sqrt{r} e^{-t} \end{cases}$$

$$z' = -2pq = -2 \cdot \sqrt{r} e^{-t} \cdot e^{-t} = -2\sqrt{r} e^{-2t} \quad | \int$$

$$z = \sqrt{r} e^{-2t}$$