

Noise

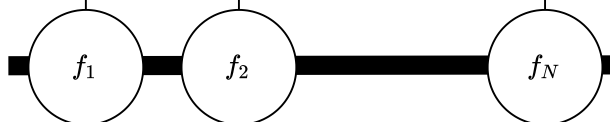


Observation



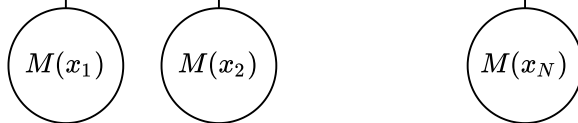
Observed:  $y - space$

Gaussian Field



Latent:  $f - space$

Transformed



Latent:  $u - space$

Input



Observed:  $x - space$