

Q 1) Difference btw DFS & BFS - write applications of both algorithm

BFS

DFS

12) Breadth First Search
uses queue

Depth First Search
uses stack

Suitable when destination is
close to start node.

Suitable when destination is
far from source.

Not suitable for decision making
trees used in games & puzzles

DFS is more suitable for games or puzzle
problems.

Siblings visited before children

Siblings visited after children

Requires more memory

Less memory.

No concept of backtracking.

Recursive algo that uses backtracking

Applications -

BFS -> Bipartite graph and shortest path, peer to peer networking,
crawlers in search engine & GPS navigation system.

DFS -> acyclic graph, topological order, scheduling problems, sudoku puzzle

15	18	19	2018	2019
↓	↓	↓	↓	↓
20	7	10	11	12

Q. Which data structure are used to implement BFS & DFS and how

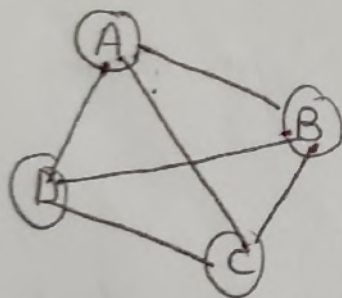
For BFS we use queue

For DFS we use a stack

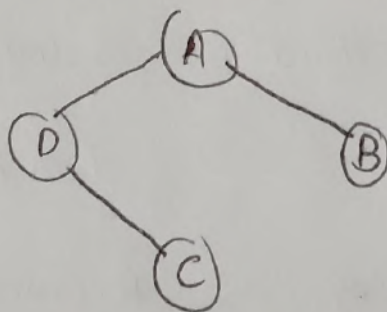
Q. What do you mean by sparse and dense graphs. Which representation of graph is better for sparse & dense graph?

Dense graph is where no. of edges is close to maximal no. of edges.

Sparse graph has less no. of edges.



Dense



sparse

For sparse graph we use adjacency list.

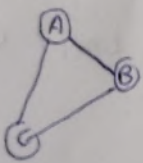
For dense graph we use adjacency matrix

How do we detect a cycle in a graph using BFS & DFS

For detecting a cycle in graph using BFS, we use Kahn's algorithm for Topological sorting

Steps involved are:

- 1) Compute in-degree (no. of incoming edges) for each of vertex present in graph & initialise no. of visited nodes as 0.
- 2) Pick all vertices with in-degree as 0 & add them in queue.
- 3) Remove a vertex from queue and then:
 - 1) $++$ visited nodes
 - 2) Decrease in-degree by 1 for all its neighbouring nodes
 - 3) If in-degree of neighbouring nodes is reduced to zero then add to queue.
- 4) Repeat 3) until queue is empty.
- 5) If count of visited nodes is not equal to no. of nodes in graph, then cycle, otherwise not.



A \rightarrow 2
B \rightarrow 2
C \rightarrow 2

To use DFS for the same,

DFS for a connected graph produces a tree. There is a cycle in a graph if there is a back edge present in graph. A back edge is an edge that is from a node to itself (self-loop) or one of its ancestors in the tree produced by DFS. For a disconnected graph, I get DFS forest as output. To detect cycle, check for a cycle in individual trees by checking back edges. To detect a back edge, keep track of vertices currently in recursion track for DFS traversal. If a vertex is reached that is already in recursion stack, then there is a cycle.

Q. What do you mean by disjoint set data structure? Explain 3 operations along with examples which can be performed on disjoint sets?

A disjoint set is a data structure that keeps track of set of elements partitioned into several disjoint subsets. In other words, a disjoint set is a group of sets where no item can be in more than one set.

3 operations

Find Implemented^{by} recursively traversing parent array until we hit a node who is parent to itself.

```
int find(int i)
```

```
{ if (parent[i] == i)
```

```
    { return i;
```

```
    } else { return find(parent[i]);
```

```
    }
```

ion \rightarrow Takes 2 elements as input and find representative of their set.
 ing the find operation & finally put other one of the tree under root
 of other tree, effectively merging the trees & sets.

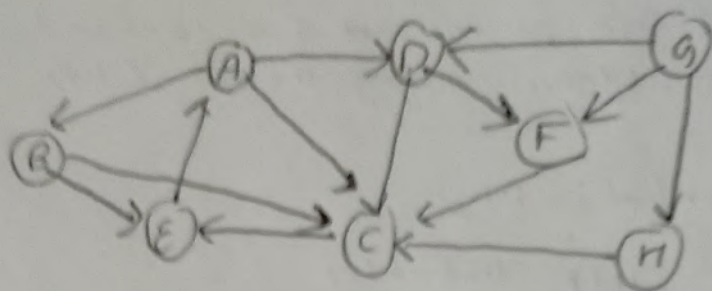
```
void union (int i, int j)
{
    int irep = this.find(i)
    int jrep = this.find(j)
    this.parent[irep] = jrep;
}
```

Union by Rank \rightarrow We need a new array rank[]. Size of array same
 as parent array. If i is representative of set, rank[i] is height of
 tree. We need to minimize height of tree. If we are
 uniting 2 trees, we call them left & right. Then it all depends
 on the rank of left & right. If rank of left is less than right then it
 has to move left under right & vice versa.

If ranks are equal, rank of result will always be one greater than
 rank of tree.

```
void union (int i, int j)
{
    int irep = this.find(i);
    int jrep = this.find(j);
    if (irep == jrep) return;
    irank = Rank[irep];
    jrank = Rank[jrep];
    if (irank < jrank)
        this.parent[irep] = jrep;
    else if (jrank < irank)
        this.parent[jrep] = irep;
    else {
        this.parent[irep] = jrep;
        Rank[jrep]++;
    }
}
```


Q. Run BFS & DFS on below graph



BFS

child or H D F C E A B

Parent

G G G H C E A

Path

G → H → C → E → A → B

DFS

G
D
H
F
G
E
A
B

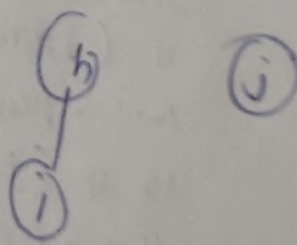
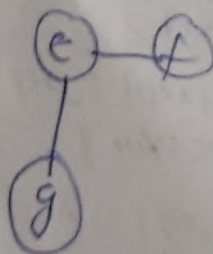
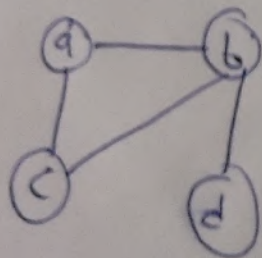
Nodes
visited

G
F
C
E
A
B

STACK

Path → G → F → C → E → A → B

Find no. of connected components and vertices in each component using disjoint set data structure



$V = \{a, b, c, d, e, f, g, h, i, j\}$

$E = \{a, b\}, \{a, c\}, \{b, c\}, \{b, d\}, \{c, f\}, \{e, g\}, \{h, i\}, \{j\}$

$(a, b) \quad \{a, b\} \quad \{c\} \quad \{d\} \quad \{e\} \quad \{f\} \quad \{g\} \quad \{h\} \quad \{i\} \quad \{j\}$

$(a, c) \quad \{a, b, c\} \quad \{d\} \quad \{e\} \quad \{f\} \quad \{g\} \quad \{h\} \quad \{i\} \quad \{j\}$

$(b, c) \quad \{a, b, c\} \quad \{d\} \quad \{e\} \quad \{f\} \quad \{g\} \quad \{h\} \quad \{i\} \quad \{j\}$

$(b, d) \quad \{a, b, c, d\} \quad \{e\} \quad \{f\} \quad \{g\} \quad \{h\} \quad \{i\} \quad \{j\}$

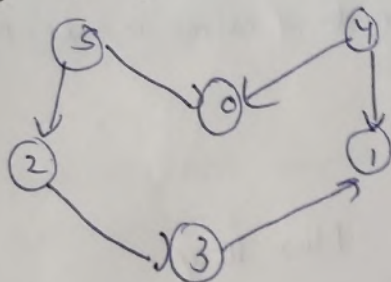
$(c, f) \quad \{a, b, c, d\} \quad \{e, f\} \quad \{g\} \quad \{h\} \quad \{i\} \quad \{j\}$

$(e, g) \quad \{a, b, c, d\} \quad \{e, f, g\} \quad \{h\} \quad \{i\} \quad \{j\}$

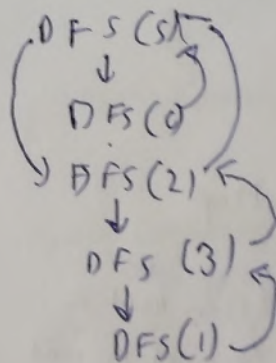
$(h, i) \quad \{a, b, c, d\} \quad \{e, f, g\} \quad \{h, i\} \quad \{j\}$

(3)

Apply topological sort & DFS on graph having vertices from 0-5



4
5
2
3
1
0



4 → 5 → 2 → 3 → 1 → 0

Heap can be used to implement priority queue.
Not a few graph algorithms where you

Yes heaps are used to implement priority queue.
It will take $O(\log N)$ time to insert & delete each element in priority queue.

Based on heap structure there are

- 1) Max Heap
- 2) Min Heap

Graph algorithms like Dijkstra's, Prim's used priority queue.

- 1) Dijkstra \rightarrow Priority queue is used to extract minimum
- 2) Prim's used to store keys of nodes & extract min key node at every step

Min Heap

Key present at root node must be less than or equal to keys present at all of its children

Min key element is present at root.

Uses ascending priority

Smallest element is popped first

Max heap

Key present at root node must be greater than or equal to keys present at all of its children

Max^{key} Element is present at root.

Uses descending priority

Largest element is popped first