# 向量化计算

## 代码

```
import numpy as np
from numpy import int64
def bilinear_interp_vectorized(a: np.ndarray, b: np.ndarray) -> np.ndarray:
                 This is the vectorized implementation of bilinear interpolation.
                  - a is a ND array with shape [N, H1, W1, C], dtype = int64
                  - b is a ND array with shape [N, H2, W2, 2], dtype = float64
                   - return a ND array with shape [N, H2, W2, C], dtype = int64
         # get axis size from ndarray shape
         N, H1, W1, C = a.shape
         N1, H2, W2, \underline{\phantom{A}} = b.shape
         assert N == N1
         # TODO: Implement vectorized bilinear interpolation
         res = np.empty((N, H2, W2, C), dtype=int64)
         padding = np.empty((N, H2, W2, 2))
         padding[:, :, :, :] = b
        xy = np.array(np.meshgrid(np.arange(H2), np.arange(W2)), dtype=np.float32)
         x = xy[0].flatten().astype(np.int)
         y = xy[1].flatten().astype(np.int)
         index = padding[:, x, y, :]
         clip_index = np.floor(index).astype(np.int)
         clip\_index = clip\_index.reshape((-1, 2))
         index = index.reshape((-1, 2))
         a = a.reshape((-1, C))
         _xy = index - clip_index
         n = np.array(np.meshgrid(np.arange(W2*H2), np.arange(N)), dtype=np.int32)
         n = n[1].flatten().astype(np.int)
         result = (1-_xy[:, 0, None]) * (1-_xy[:, 1, None]) * a[clip_index[:, 0]*w1 +
clip_index[:, 1] + n[:]*W1*H1, :] + \
                             _xy[:, 0, None] * (1 - _xy[:, 1, None]) * a[(clip_index[:, 0]+1)*w1
+ clip_index[:, 1] + n[:]*W1*H1, :] + \
                              (1-_xy[:, 0, None]) * _xy[:, 1, None] * a[clip_index[:, 0]*W1 +
(clip\_index[:, 1]+1) + n[:]*W1*H1, :] + 
                             xy[:, 0, None] * xy[:, 1, None] * a[(clip_index[:, 0]+1)*W1 + a[(clip_index[:, 0]+1)
(clip_index[:, 1]+1) + n[:]*W1*H1, :]
         res[:, :, :] = result.reshape((N1, W2, H2, -1)).transpose(0, 2, 1, 3)
         return res
```

首先,先利用meshgrid生成三维的矩阵坐标xy,利用xy[0] xy[1]遍历b数组中XY轴的坐标,获得每个点的值,再对值做向下取整得到该位置对应的a数组中的值的坐标;然后将数组全部reshape成二维的,方便检索;之后做batchsize的向量化,生成值为00..00111...11...22...22...33...33...44...55...66...77形状的数组,代表不同的batchsize,在检索下标时乘上W1和H1就能区分不同的Batch size;最后通过reshape,转成正确的形状进行输出。

### 正确性和加速比

试验次数	加速比
1	68.66
2	49.64
3	39.59
4	47.50
5	49.94

#### 平均加速比为51.066

### 实验截图:

```
F:\Anaconda\python.exe "E:/Grade Three/ShortSemester/HPC101/lab2/starter_code/main.py"
Generating Data...
Executing Baseline Implementation...
Finished in 207.66153836250305s
Executing Vectorized Implementation...
(7372800, 2)
(8, 720, 1280, 4)
Finished in 3.024407386779785s
[PASSED] Results are identical.
Speed Up 68.66189365567219x

Process finished with exit code 0
```

```
F:\Anaconda\python.exe "E:/Grade Three/ShortSemester/HPC101/lab2/starter_code/main.py"
Generating Data...
Executing Baseline Implementation...
Finished in 214.23999643325806s
Executing Vectorized Implementation...
(7372800, 2)
(8, 720, 1280, 4)
Finished in 4.3159403800964355s
[PASSED] Results are identical.
Speed Up 49.63923909172978x
```

```
F:\Anaconda\python.exe "E:/Grade Three/ShortSemester/HPC101/lab2/starter_code/main.py"
Generating Data...
Executing Baseline Implementation...
Finished in 158.15961718559265s
Executing Vectorized Implementation...
(7372800, 2)
(8, 720, 1280, 4)
Finished in 3.9944911003112793s
[PASSED] Results are identical.
Speed Up 39.59443473869994x
```

```
F:\Anaconda\python.exe "E:/Grade Three/ShortSemester/HPC101/lab2/starter_code/main.py"
Generating Data...

Executing Baseline Implementation...
Finished in 146.1722469329834s

Executing Vectorized Implementation...
Finished in 3.0772807598114014s

[PASSED] Results are identical.

Speed Up 47.500458470335325x
```

```
F:\Anaconda\python.exe "E:/Grade Three/ShortSemester/HPC101/lab2/starter_code/main.py"
Generating Data...
Executing Baseline Implementation...
Finished in 155.85010290145874s
Executing Vectorized Implementation...
Finished in 3.1204781532287598s
[PASSED] Results are identical.
Speed Up 49.94430188213322x
```