

Lecture 2

Wednesday, January 12, 2022 10:05 AM

Adm'l

① HW # due Feb 2nd

② NI DA today.

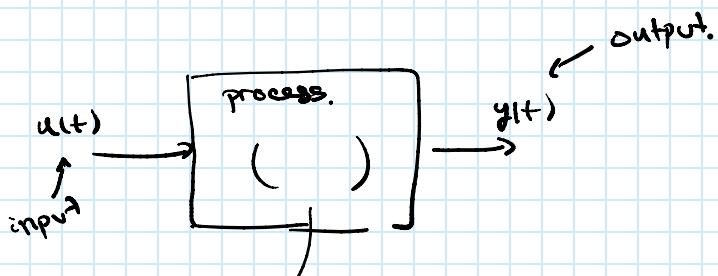
Objectives

- ① Overview of parameter estimation
- ② Random variables and probability / density funcs.
- ③ Formulate student's t-test as a parameter estimation problem.

Overview of parameter estimation => "

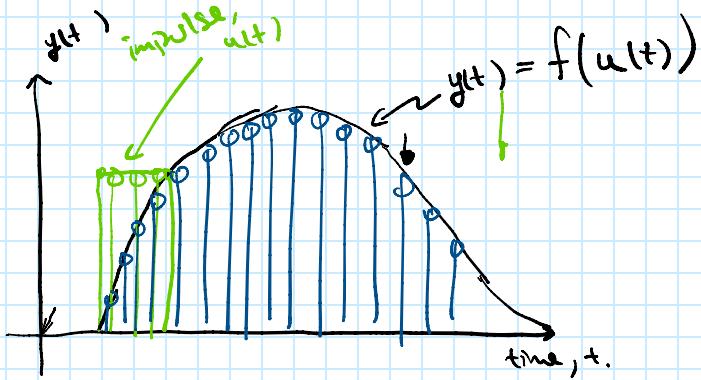
system identification"

- Goals of model of parameter estimation.
 - mathematical model to predict future behaviors
 - Ask if two pieces of data define distinct processes.
 - Extract processes or signatures from the data that are non-obvious.
 - discerning fetal ECG signals
 - eliminating artifacts from noisy signals.
 - genes related to disease
 - many others.
- Consider a deterministic process



- Car responds to accelerator

- Car responds to accelerator
- robot arm responds to motor
- immune cell response to a pathogen.



- Finite impulse response model:

$$y(t) = b_0 u(t-1) + b_1 u(t-2) + \dots$$

↑
parameters
to be identified

$$\Rightarrow y(t) = \varphi^T(t) \theta \quad \leftarrow \text{deterministic}$$

where

$$\theta = [b_0 \ b_1 \ b_2 \ \dots]^T$$

$$\varphi(t) = [u(t-1) \ u(t-2) \ \dots]^T$$

- Noise corrupted:

$$\hat{y}(t) = \varphi^T(t) \theta + e(t)$$

noise.
measurement noise,
biological.
wear.

- We can estimate parameters, θ , by using $u(t)$, $y(t)$.

$$V(\theta) = \frac{1}{N} \sum_{t=1}^N \left[(y(t) - \hat{y}(t))^2 \right]$$

↑ cost function ↓ actual outputs ↓ modeled outputs

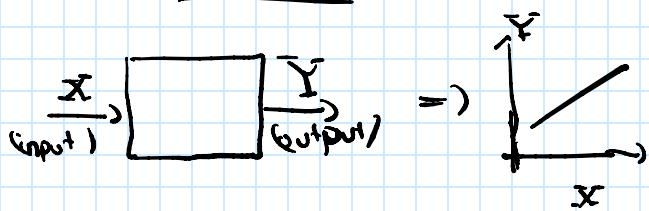
Random variables & probability Density Functions.

- Deterministic vs. Random

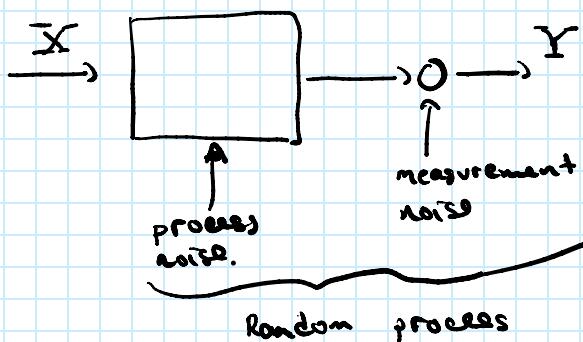
Focus.

- Deterministic vs. Random processes.

Deterministic



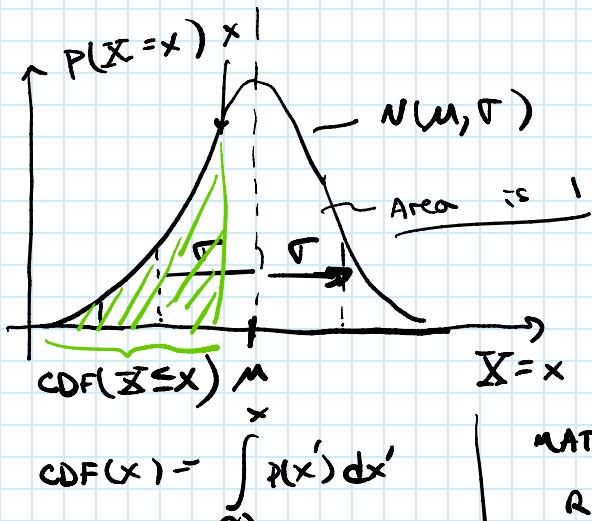
Random process



- In real systems, we need to understand the properties of noise to estimate system parameters.

Random variables.

- A random variable is a funcn. that maps every point in sample space onto the the real number line:



← we frequently assume this type of noise

$$p(X=x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2} \left(\frac{x-M}{\sigma}\right)^2}$$

MATLAB:
R : $cdf(x)$
 $ccdf(x)$.

$$\text{CDF}(x) = \int_{-\infty}^x p(x') dx' \quad | \quad \begin{array}{l} \text{MATLAB:} \\ R : \end{array} \quad \begin{array}{l} \text{ccdf}(x) \\ \text{ecdf}(x). \end{array}$$

- $E[X] = \int_{-\infty}^{\infty} x \cdot p(x) dx$ (continuous)

or

$$E[X] = \sum p_i x_i$$
 (discrete)

- $\text{Var}[X] = E[\underbrace{x - E[X]}_{\text{deviation from mean.}}]^2$

$$\leftarrow E[X^2] - 2E[X]E[X] + (E[X])^2$$

- $\text{std}(x) = \sqrt{\text{Var}(x)}$

- statistic independence.

→ consider two random vars, X, Y : statistically independent.

$$P_{XY}(x,y) = P_X(x) P_Y(y)$$

- conditional probability density:

$$P_{X|Y} = p(x \text{ given } y) = \frac{P_{XY}(x,y)}{P_Y(y)}$$

- If $X \nmid Y$ are independent, then

$$P_{X|Y} = P_X(x)$$

- Correlation

The expectation of the product of 2 random variables, $X \nmid Y$ is called "correlation":

$$E[XY] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy P_{XY}(x,y) dx dy$$

- If independent: $E[XY] = E[X]E[Y]$

- Note: correlation = 0 does not imply independence.

- Note: correlation = 0 does not imply independence.

- orthogonality:

X & Y are said to be orthogonal if correlation is zero: $E[XY] = 0$.

- covariance:

$$\text{cov}(X, Y) = E[(X - \mu_X)(Y - \mu_Y)]$$

