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## TEAM PRESENTATION

# Assignment Review

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The Med Fleet Project uses a fleet of drones to prioritize and synchronize the delivery of medical supplies in a disaster zone.

Requests for assistance are sent to the application from a mobile app.

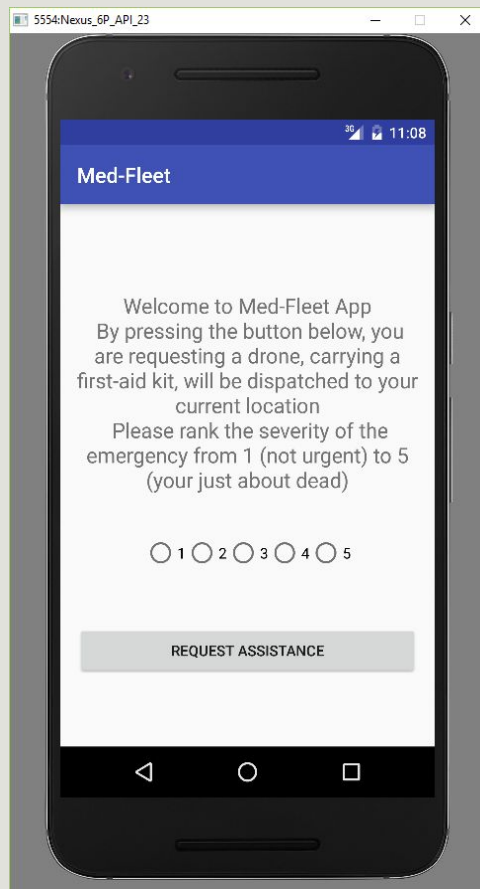
# Architecture Review

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(Peikang Animation)

# Mobile App/Ticket Demo

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# Field Tests

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[Video Link](#)

# Med-Fleet Monitor

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Web Application shows real time status of Drones and Missions utilizing google maps, javascript ajax.

<http://www.med-fleet-monitor.co.nf/home.html>

# Ground Station and DroneKit API

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- **Ground Station responsibilities:**
  - Receive missions from Mission Control.
  - Connect and send commands to drones; *DroneKit API*.
- **Testing:**
  - Static testing.
  - Simulator: Software in the Loop (SITL) and MavProxy.
  - Iris Plus.
- **Easy to use “Ready to Fly (RTF)”:**
  - Automatically connect to drones and the system.



# Future Sprints

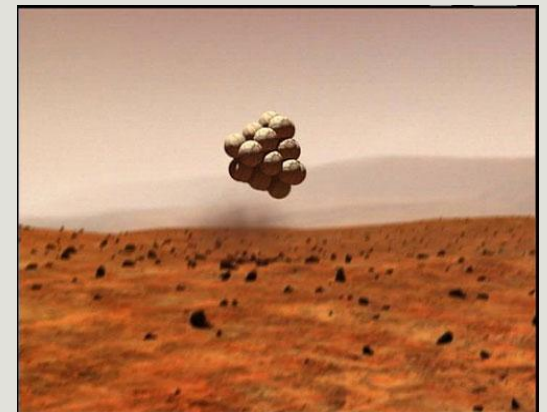
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**1- Add multiple drones to project.**

**2- Options for delivery: land or drop.**

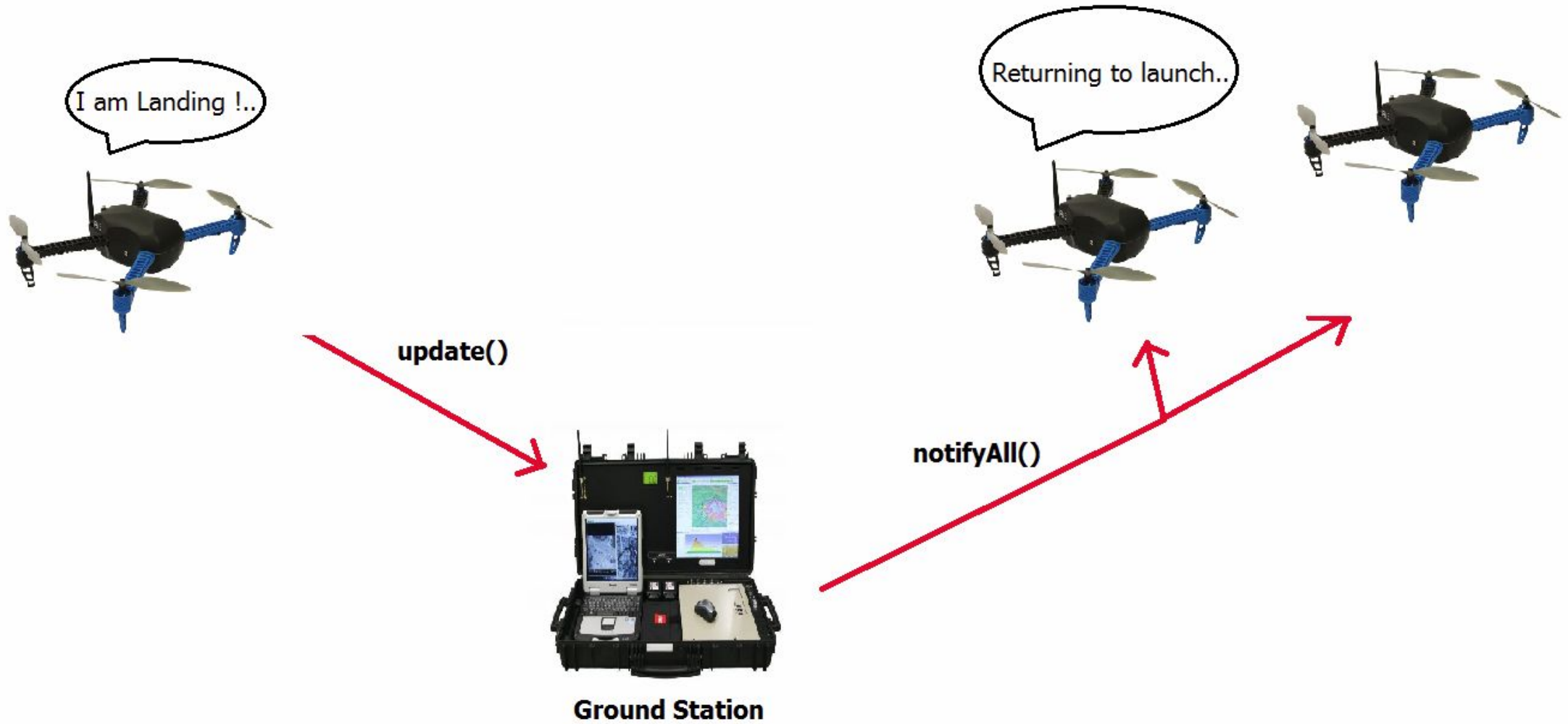
**3- Managing air traffic.**

- Assign each drone to fly in a different altitude.
- Add an observer to Ground Station.





# MFGS Observer



# FMECA

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- Drones and Emergency Situations make Med-Fleet a Safety Critical Project
- Through our FMECA we discovered our Safety Limitations could be broken down into three main categories:
  - **Hardware Issues**
  - **Software Issues**
  - **Regulatory Issues**
- Dissecting the intricacies that each issue grouping can create and how they affect another is essential to the success of our project.
- The impact on the customer could be Fatal!

# FMECA

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## Hardware Issues

- Due to Safety Critical nature of project, resources need to be stable and fully tested to assure proper functionality.
- All Servers need to provide constant uptime when missions are deployed
- In case of emergency, tested failovers need to be in place
- All servers need to have Monitoring Agents running at all times to alert team of both immediate issues and potential problems
- Drones need to be examined and tested after every day deployed to ensure they are still functioning properly

# FMECA

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## Software Issues

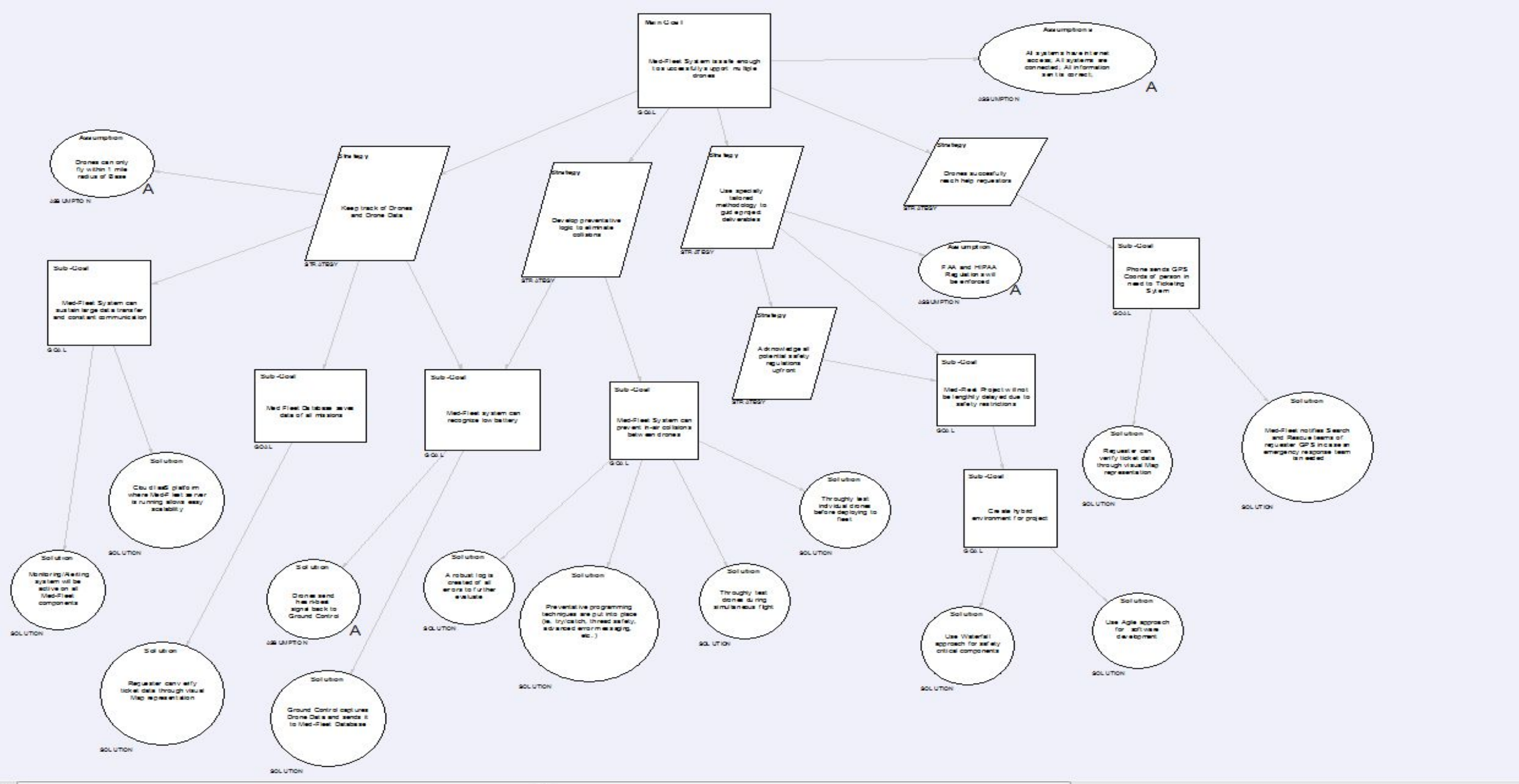
- Software plays a vital role in all aspects of the Med Fleet system.
- Software controls where the drones are deployed to, it is vital that this logic is being properly calculated.
  - Otherwise Drones could crash or get lost and requesters will be without medicine
- Software also handles the communication between all of the Med-Fleet servers, app, website, and drones.
  - The collection of all these components utilizing different technologies and software is what allows the Med-Fleet system to work.
    - With such a dependence on software, proper testing is a necessity!

# FMECA

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## **Regulatory Issues**

- Very Strict Regulations could hold back progress due to oversight by organizations such as HIPAA and FAA.
- Through proper planning and foresight discovered in FMECA document, project is able to navigate around such hurdles.
- One of the biggest discoveries was the idea to essentially partition project into two sectors:
  - One part is Regulatory and Planning branch
  - Other part is Development branch
  - These two different branches require different processes to achieve success within their respective domain
  - Regulatory and Planning works better under a more waterfall approach, as it has mandatory approval processes that must be attended to
  - Development Branch works better with an Agile Methodology, once dev work is approved by the proper regulatory committees, a true Dev Sprint can begin.



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