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|   CSE 421/521   |
| PROJECT 1: THREADS |
|   DESIGN DOCUMENT   |
+-----+
```

---- GROUP ----

>> Fill in the names and email addresses of your group members.

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---- PRELIMINARIES ----

>> If you have any preliminary comments on your submission, notes for the
>> TAs, or extra credit, please give them here.

>> Please cite any offline or online sources you consulted while
>> preparing your submission, other than the Pintos documentation, course
>> text, lecture notes, and course staff.

<http://stuartharrell.com/blog/2016/12/16/efficient-alarm-clock/>

ALARM CLOCK

---- DATA STRUCTURES ----

>> A1: Copy here the declaration of each new or changed ``struct'` or
>> ``struct'` member, global or static variable, ``typedef'`, or
>> enumeration. Identify the purpose of each in 25 words or less.

Add Global Variable in timer.c file home/pintos/src/devices

```
static struct list waiting_list /*keeps a track of sleeping process*/
```

Use variable `int64_t ticks` in thread.h to track the number of ticks a process is sleeping and let variable `make_thread_wake_up` try to wake up the thread after the end of sleeping process.

---- ALGORITHMS ----

>> A2: Briefly describe what happens in a call to `timer_sleep()`,
>> including the effects of the timer interrupt handler.

In `timer_sleep()` function

- Check for timer ticks > 0.
- Calculate the ticks value using `int64_t ticks`.
- Put/Add the current thread to the `list_of_sleeping_threads`. Add it in the sorted order such that the first element can be woken up as soon as the ticks end for sleep.
- Block the thread if above not true.

In Timer interrupt handler

a) Find the first element thread.
b) Calculate if the thread tick <= global tick, and if true remove thread from list_of_sleeping_threads and also unblock it. Continue this process i.e. a) & b) till list_of_sleeping_threads are empty and are woken up when ready and sent forward to the next process step.
c) Put a test to see if the current thread is of the highest priority in the list_of_sleeping_threads.

>> A3: What steps are taken to minimize the amount of time spent in
>> the timer interrupt handler?

Maintaining the accuracy of the sorting of the threads, this will minimize the time of each thread in the interrupt handler so that the iteration process won't take place often.

---- SYNCHRONIZATION ----

>> A4: How are race conditions avoided when multiple threads call
>> timer_sleep() simultaneously?

>> A5: How are race conditions avoided when a timer interrupt occurs
>> during a call to timer_sleep()?

---- RATIONALE ----

>> A6: Why did you choose this design? In what ways is it superior to
>> another design you considered?

PRIORITY SCHEDULING

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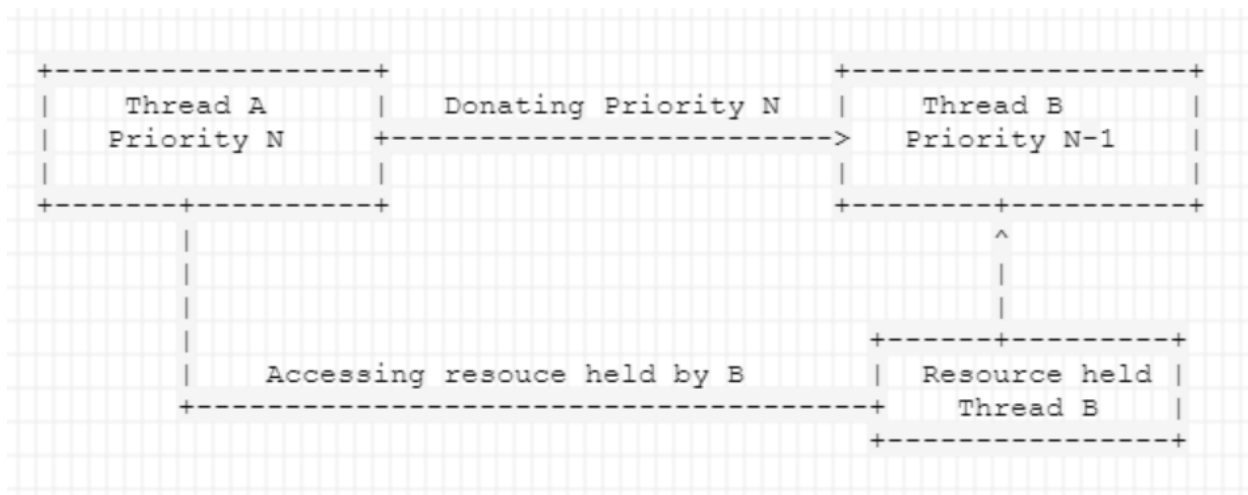
---- DATA STRUCTURES ----

>> B1: Copy here the declaration of each new or changed 'struct' or
>> 'struct' member, global or static variable, 'typedef', or
>> enumeration. Identify the purpose of each in 25 words or less.

Added in threads.c

```
static struct list donor_thread_list /*Keep track of donor threads*/
```

>> B2: Explain the data structure used to track priority donation.
>> Use ASCII art to diagram a nested donation. (Alternately, submit a
>> .png file.)



----- ALGORITHMS -----

>> B3: How do you ensure that the highest priority thread waiting for
>> a lock, semaphore, or condition variable wakes up first?

- Once the executing thread has completed execution using the locked resource, it calls `cond_wait()` to release the lock and waits for some other piece of code to call condition.
- This will call `cond_signal()` if there was any thread waiting for the resource it reacquires the lock makes a call to `cond_broadcast()` to wake up that thread which has the highest priority.

>> B4: Describe the sequence of events when a call to `lock_acquire()`
>> causes a priority donation. How is nested donation handled?

Priority Donation: Consider two threads,

Thread A	High Priority
Thread B	Low Priority

Step 1-

Thread A has higher priority, and is scheduled for execution in the CPU.

Step 2-

Thread A needs some resource to continue its execution, but the resource is held by a low priority Thread B which is either in the `ready_list` or `waiting_list`.

Step 3-

To allow Thread A to continue execution, a call to `lock_acquire()` will donate the priority of Thread A to Thread B by calling `thread_set_priority()` for a given `TIME_SLICE`. During this time Thread A is placed in `donor_thread_list`.

Step 4-

Thread B executes in the CPU and releases the lock on the resource it held by calling `lock_release()`.

Step 5-

Thread A is popped out of `donor_thread_list` and is scheduled to execute in the CPU.

Nested Donation: Consider more than 2 threads, where thread c holds a resource required by a higher priority thread b which holds a resource required by another higher priority thread a.

Thread A donates priority(N) → B donates priority(N) → C now holds priority(N)

Execution: C executes → B executes → A executes

>> B5: Describe the sequence of events when lock_release() is called
>> on a lock that a higher-priority thread is waiting for.

Considering a simple priority donation scenario,

Step 1-

Thread B executes in the CPU and releases the lock on the resource held by calling lock_release() which calls lock_held_by_current_thread() to reset the value of the lock.

Step 2-

If

Thread B has completed execution then its status is updated and it exits the scheduler.

Else

The priority of Thread B is updated and then placed on the ready or wait list.

---- SYNCHRONIZATION ----

>> B6: Describe a potential race in thread_set_priority() and explain
>> how your implementation avoids it. Can you use a lock to avoid
>> this race?

There can be multiple donations from different threads (with calls to thread_set_priority()), in which multiple priorities are donated to a single thread. This scenario causes a potential race condition.

---- RATIONALE ----

>> B7: Why did you choose this design? In what ways is it superior to
>> another design you considered?

This design provides a solution for the priority inversion problem, using ready list, wait list and donor list makes it easy to schedule the threads from high to low priority.

ADVANCED SCHEDULER

---- DATA STRUCTURES ----

>> C1: Copy here the declaration of each new or changed 'struct' or
>> 'struct' member, global or static variable, 'typedef', or
>> enumeration. Identify the purpose of each in 25 words or less.

Added in thread.h

```
int nice; /*The nice value for each thread*/
```

```
int recent_cpu; /*CPU time received by each thread*/
```

Added in thread.c

```
int load_avg; /*Average threads ready to run over the past minute*/
```

Added fixed-point.h /*Contains the fixed-point arithmetic operations*/

---- ALGORITHMS ----

>> C2: Suppose threads A, B, and C have nice values 0, 1, and 2. Each
>> has a recent_cpu value of 0. Fill in the table below showing the
>> scheduling decision and the priority and recent_cpu values for each
>> thread after each given number of timer ticks:

timer ticks	recent_cpu			priority			thread to run
	A	B	C	A	B	C	
0	0	0	0	63	61	59	A
4	4	0	0	62	61	59	A
8	8	0	0	61	61	59	B
12	8	4	0	61	60	59	A
16	12	4	0	60	60	59	B
20	12	8	0	60	59	59	A
24	16	8	0	59	59	59	C
28	16	8	4	59	59	58	B
32	16	12	4	59	58	58	A
36	20	12	4	58	58	58	C

>> C3: Did any ambiguities in the scheduler specification make values
>> in the table uncertain? If so, what rule did you use to resolve
>> them? Does this match the behavior of your scheduler?

When the priority of two or more threads is the same, at that time which thread should run is not certain. And thus causes ambiguity. To resolve this ambiguity, we have used the 'Round Robin' scheduling to decide the next thread to run. This is behavior matches the behavior of our scheduler.

>> C4: How is the way you divided the cost of scheduling between code
>> inside and outside interrupt context likely to affect performance?

Most of the coding has to be done inside the interrupt context, this would have an negative impact of the performance of the Operating System. The resetting of the values can be done outside the interrupt context.

---- RATIONALE ----

>> C5: Briefly critique your design, pointing out advantages and
>> disadvantages in your design choices. If you were to have extra
>> time to work on this part of the project, how might you choose to
>> refine or improve your design?

The design is using round robin scheduling for the processes with the same priority. The priority scheduling can lead to starvation of the lower priority scheduling hence we have also calculated the aging of the processes.

>> C6: The assignment explains arithmetic for fixed-point math in
>> detail, but it leaves it open to you to implement it. Why did you
>> decide to implement it the way you did? If you created an
>> abstraction layer for fixed-point math, that is, an abstract data
>> type and/or a set of functions or macros to manipulate fixed-point
>> numbers, why did you do so? If not, why not?

Fixed point arithmetic is needed to convert the recent_cpu and load_avg of a thread into integers as they are real numbers and pintos does not support floating point arithmetic in the kernel. We are implementing the arithmetic for fixed-point in a separate file fixed-point.h.

SURVEY QUESTIONS

Answering these questions is **optional**, but it will help us improve the course in future quarters. Feel free to tell us anything you want--these questions are just to spur your thoughts. You may also choose to respond anonymously in the course evaluations at the end of the quarter.

>> In your opinion, was this assignment, or any one of the three problems
>> in it, too easy or too hard? Did it take too long or too little time?

>> Did you find that working on a particular part of the assignment gave
>> you greater insight into some aspect of OS design?

>> Is there some particular fact or hint we should give students in
>> future quarters to help them solve the problems? Conversely, did you
>> find any of our guidance to be misleading?

>> Do you have any suggestions for the TAs to more effectively assist
>> students, either for future quarters or the remaining projects?

>> Any other comments?