



GP INOP	DME (ISZ) (NM)	10	8	6	4	2																																																														
	ALT (m)	1062	855	649	442	235																																																														
<div><div>TL 3600 TA 3000 3300(QNH≥1031hPa) 2700(QNH≤979hPa)</div><div>MISSED APPROACH Climb up to 200, turn LEFT, fly to PEK at 600, join the holding pattern, contact ATC.</div><div><div><div>IF AA520 D16.4 ISZ D16.5SZY</div><div>FAF GP INOP D11.3 ISZ</div><div>GP INOP D5.5 ISZ 600(571)</div><div>MAPt GP INOP D0.7 ISZ ISZ</div></div><div><div>1200(1171)</div><div>1050</div><div>500</div><div>MDA</div><div>RDH=15</div></div><div><div>30.2km</div><div>20.7</div><div>10.0</div><div>0.95</div><div>0</div></div></div></div>																																																																				
<table><tr><td></td><td>A</td><td>B</td><td>C</td><td>D</td></tr><tr><td>ILS/DME</td><td>DA(H) RVR/VIS</td><td colspan="3">89(60) 550/800</td></tr><tr><td>GP INOP</td><td>MDA(H) RVR/VIS</td><td colspan="3">170(142) 1700/1700</td></tr><tr><td>CIRCLING</td><td>MDA(H) VIS</td><td>210(175) 2500</td><td>265(230) 3200</td><td>265(230) 3600</td></tr></table>						A	B	C	D	ILS/DME	DA(H) RVR/VIS	89(60) 550/800			GP INOP	MDA(H) RVR/VIS	170(142) 1700/1700			CIRCLING	MDA(H) VIS	210(175) 2500	265(230) 3200	265(230) 3600	<table><tr><td colspan="8">FAF-MAPt(GP INOP) 19.75km</td></tr><tr><td>GS in</td><td>kt</td><td>80</td><td>100</td><td>120</td><td>140</td><td>160</td><td>180</td></tr><tr><td></td><td>km/h</td><td>150</td><td>185</td><td>220</td><td>260</td><td>295</td><td>335</td></tr><tr><td>Time</td><td>min:sec</td><td>8:00</td><td>6:24</td><td>5:20</td><td>4:34</td><td>4:00</td><td>3:33</td></tr><tr><td>Rate of descent</td><td>m/s</td><td>2.3</td><td>2.9</td><td>3.4</td><td>4.0</td><td>4.6</td><td>5.2</td></tr></table>				FAF-MAPt(GP INOP) 19.75km								GS in	kt	80	100	120	140	160	180		km/h	150	185	220	260	295	335	Time	min:sec	8:00	6:24	5:20	4:34	4:00	3:33	Rate of descent	m/s	2.3	2.9	3.4	4.0	4.6	5.2
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Changes: Landing minima, add speed limit.																																																																				