lecture 10

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
|---------------|-----|-----|------|----|-----|----|-----|------|-------|
| | RXC | TXC | UDRE | FE | DOR | PE | U2X | МРСМ | UCSRA |
| Read/Write | R | R/W | R | R | R | R | R/W | R/W | |
| Initial Value | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | |

| Bit 7 – RXC: USART Receive Complete — | if we have no data, then set 0 if we have some data, then set 1 |
|--|--|
| Bit 6 – TXC: USART Transmit Complete – | if it's in default state, means no data transmit, set 0 if when data transfer complete, then set 1 |
| Bit 5 – UDRE: USART Data Register Empty – | If UDRE is 0, the buffer is empty, and therefore ready to be written if data buffer has already completed data reciving then, it becomes 1 |
| Bit 4 – FE: Frame Error | FE is 1, when 'stop bit' is recieved or writing the buffer default 0. |
| Bit 3 – DOR: Data OverRun | DOR is 1, if data buffer is full default 0 |
| Bit 2 – PE: Parity Error | PE is 1, if parity error is occured in char bit. default 0 |
| Bit 1 – U2X: Double the USART Transmission Speed | U2X is 1, if operation is asynchronous default 0, when operation is Sync. |

Writing this bit to one will reduce the divisor of the baud rate divider from 16 to 8 effectively doubling the transfer rate for asynchronous communication.

go to baud rate section for better understanding

Bit 0 – MPCM: Multi-processor Communication Mode

if MPCM is 1, enables the Multi-processor Communication mode default 0