

# MATH3802

## Chapter 2: Stationary processes

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## Stochastic processes

- ▶ To get a model of a time series, we consider the  $X_t$  to be random variables. The collection  $\{X_t\}_{t \in \mathbb{N}}$  is called a *stochastic process*.

## Summary statistics

**Definition 2.1** For a stochastic process  $\{X_t\}$ , we use the following definitions:

**mean:**

$$\mu(t) = \mathbb{E}(X_t);$$

**variance:**

$$\sigma^2(t) = \text{var}(X_t);$$

**auto-covariance:**

$$\gamma(s, t) = \text{cov}(X_s, X_t) = \mathbb{E}[(X_s - \mu(s))(X_t - \mu(t))];$$

**auto-correlation:**

$$\rho(s, t) = \text{corr}(X_s, X_t) = \frac{\gamma(s, t)}{\sqrt{\sigma^2(s)\sigma^2(t)}}.$$

## Stationarity

**Definition 2.2 ((Strong) stationarity)** The stochastic process  $\{X_t\}$  is *stationary* if  $\{X_1, \dots, X_n\}$  and  $\{X_{1+k}, \dots, X_{n+k}\}$  have the same distribution for all  $k, n \in \mathbb{N}$ .

Remarks:

1. If  $\{X_t\}$  is stationary, then  $X_k$  has the same distribution as  $X_1$  for all  $k \in \mathbb{N}$ . In particular, if the first two moments are finite then  $\mu(t) = \mathbb{E}(X_t) = \mu$  and  $\sigma^2(t) = \text{var}(X_t) = \sigma^2$  for all  $t$ . Therefore, a process with trend or seasonal effects cannot be stationary.
2. For stationary processes, sometimes it is useful to consider  $t \in \mathbb{Z}$  instead of  $t \in \mathbb{N}$ .

## Weak Stationarity

**Definition 2.3 (Weak stationarity)** A stochastic process  $\{X_t\}$  is *weakly stationary* or *second order stationary* if

1.  $\mu(t)$  is constant, i.e.  $\mu(t) = \mu$  for all  $t$ ;
2.  $\gamma(s, t)$  only depends on the times  $t, s$  via the *lag*  $t - s$ , i.e.  $\gamma(s, t) = \gamma_{t-s}$ .

Note that  $\sigma^2(t) = \sigma^2 = \gamma_0$ .

## Examples

**Example 2.1 (White noise)** Let  $X_t \sim N(0, 1)$ , i.i.d. Then  $\mu(t) = 0$ ,  $\sigma^2(t) = 1$ ,  $\gamma(s, t) = 0$  for all  $s, t \in \mathbb{N}$ . Clearly  $\{X_t\}$  is weakly stationary.

Indeed, the collection  $\{X_{1+k}, \dots, X_{n+k}\}$  is an i.i.d. collection of  $N(0, 1)$  r.v.s for any shift  $k \in \mathbb{N}$ , so  $\{X_t\}$  is strongly stationary.

**Example 2.2 (Symmetric random walk)** Let  $X_0 = 0$  and

$X_t = \sum_{i=1}^t Z_i$  where  $Z_i$  takes values  $+1, -1$  with probability  $1/2$  each.

Then  $\mu(t) = \sum_{k=1}^t \mathbb{E}(Z_i) = 0$  but  $\sigma^2(t) = \sum_{k=1}^t \text{var}(Z_k) = t$ , which is not constant so  $\{X_t\}$  is neither weakly nor strongly stationary.

*Exercise: Show that  $\gamma(s, t) = s$  and  $\rho(s, t) = \sqrt{s/t}$ .*

## Remarks

1. Every stationary process is weakly stationary since, for all  $t$ ,

$$\begin{aligned}\mu(t) &= \mathbb{E}(X_t) = \mathbb{E}(X_1) \\ \gamma(t, t+k) &= \text{cov}(X_t, X_{t+k}) = \text{cov}(X_1, X_k).\end{aligned}$$

Therefore, both quantities are independent of  $t$ .

2. If  $\{X_t\}$  is weakly stationary,

$$\begin{aligned}\gamma_0 &= \text{cov}(X_t, X_t) = \text{var}(X_t) = \sigma^2 \quad \forall t \\ \gamma_k &= \text{cov}(X_t, X_{t+k}) = \text{cov}(X_{t+k}, X_t) = \gamma_{t-(t+k)} = \gamma_{-k},\end{aligned}$$

so it is enough to consider lags  $k \geq 0$ .

Also note that

$$\rho(s, t) = \frac{\gamma(s, t)}{\sqrt{\sigma^2(s)\sigma^2(t)}} = \frac{\gamma_{t-s}}{\sqrt{\gamma_0\gamma_0}} = \frac{\gamma_{t-s}}{\gamma_0} =: \rho_{t-s},$$

and hence  $\rho(t, t) = \rho_0 = 1$ .

**Definition 2.4 (Autocorrelation function)** The quantity  $\rho_k$  is called the *lag  $k$  autocorrelation*;  $\rho_k$  as a function of  $k$  is the *autocorrelation function (acf)*. A plot of  $\rho_k$  against  $k$  is called a *correlogram*

Note that, strictly speaking, it only makes sense to compute the acf for weakly stationary processes. However, we shall see that we can use the acf to diagnose whether a process is stationary or not.

## Estimation of $\mu, \gamma_k, \rho_k$

Normally we would estimate covariances by using

$$\text{cov}(X, Y) \approx \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})(Y_i - \bar{Y})$$

where  $X_i, Y_i$  are i.i.d. copies of  $X, Y$ . For a time series, we typically have only one *realisation*  $X_1, X_2, \dots, X_n$ , so we can't estimate  $\text{cov}(X_1, X_2)$  as above. However, if  $\{X_t\}$  is (weakly) stationary, we can use

$$\begin{aligned} \hat{\mu} &= \frac{1}{n} \sum_{i=1}^n X_i \approx \mu(X_t) \\ \hat{\gamma}_k &= \frac{1}{n-k} \sum_{i=1}^{n-k} (X_i - \hat{\mu})(X_{i+k} - \hat{\mu}) \approx \gamma_k \\ \hat{\rho}_k &= \hat{\gamma}_k / \hat{\gamma}_0. \end{aligned}$$