Minimum of Rastrigin Function by Particles Swarm Optimization (DEAP)

From Wikipedia, the free encyclopedia (https://en.wikipedia.org/wiki/Rastrigin_function)

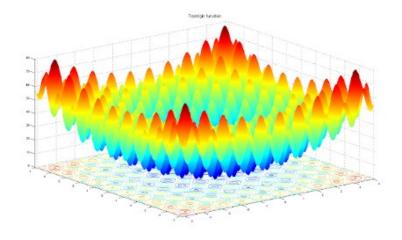
In mathematical optimization, the **Rastrigin function** is a non-convex function used as a performance test problem for optimization algorithms. It is a typical example of non-linear multimodal function. It was first proposed by Rastrigin as a 2-dimensional function and has been generalized by Mühlenbein et al. Finding the minimum of this function is a fairly difficult problem due to its large search space and its large number of local minima.

On an n-dimensional domain it is defined by:

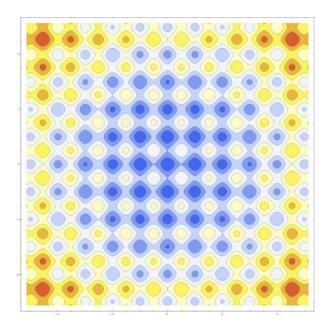
$$f(\mathbf{x}) = An + \sum_{i=1}^n \left[x_i^2 - A \cos(2\pi x_i)
ight]$$

where A = 10 and $x(i) \in [-5.12, 5.12]$. It has a global minimum at x = 0 where f(x) = 0

Rastrigin function of two variables in 3D



Rastrigin function Contour



In this brief notebook we are addressing the **Rastrigin function of two variables minimum problem** by a **Particles Swarm Optimization** implementation using the python library <u>DEAP (Distributed Evolutionary Algorithms in Python)</u> (https://github.com/DEAP) with a Swarm of 100 Particles and 1000 Generations.

```
In [1]: # Libraries import
        import operator
        import random
        import numpy as np
        import time
        from deap import base, creator, tools
In [2]: # Function definition
        c = np.zeros((1,1))
        def Rastrigin(x):
            fitness = 10*len(x)
            for i in range(len(x)):
                fitness += x[i]**2-(10*np.cos(2*np.pi*x[i]))
            c[0] = fitness
            return c
In [3]: # Fitness and Particles
        creator.create("FitnessMin", base.Fitness, weights=(-1.0,))
        creator.create("Particle", list, fitness = creator.FitnessMin, speed= list, smin=None, s
        max= None, best=None)
In [4]: # Definition of Particles generation function
        def generate(size,pmin,pmax,smin,smax):
            part = creator.Particle(random.uniform(pmin,pmax) for in range(size))
            part.speed = [random.uniform(smin,smax) for in range(size)]
            part.smin = smin
            part.smax = smax
            return part
In [5]: # Definition of Particles update function
        def updateParticle(part,best,phi1,phi2):
            u1 = (random.uniform(0,phi1) for _ in range(len(part)))
            u2 = (random.uniform(0,phi2) for in range(len(part)))
            v u1 = map(operator.mul, u1, map(operator.sub, part.best, part))
            v u2 = map(operator.mul, u2, map(operator.sub,best, part))
            part.speed = list(map(operator.add,part.speed, map(operator.add, v u1,v u2)))
            for i, speed in enumerate (part.speed):
                if speed< part.smin:</pre>
                    part.speed[i]=part.smin
                elif speed > part.smax:
                    part.speed[i] = part.smax
            part[:] = list(map(operator.add,part,part.speed))
In [6]: # Toolbox and its objects registration
        toolbox = base.Toolbox()
        toolbox.register("particle", generate, size =2 , pmin = -6 , pmax = 6, smin =-3 , sm
        toolbox.register("population", tools.initRepeat, list, toolbox.particle)
        toolbox.register("update", updateParticle, phi1 = 2.0 ,phi2=2.0)
        toolbox.register("evaluate", Rastrigin)
```

```
In [7]: # Main function
        def main():
           pop = toolbox.population(n=100)
           logbook = tools.Logbook()
           logbook.header = ["gen", "evals"]
           GEN = 1000 #Number of Particles Generations
           best = None
           start t=time.time()
           for g in range(GEN):
               for part in pop:
                   part.fitness.values = toolbox.evaluate(part)
                   if not part.best or part.best.fitness < part.fitness:</pre>
                       part.best = creator.Particle(part)
                       part.best.fitness.values = part.fitness.values
                   if not best or best.fitness <part.fitness:</pre>
                       best = creator.Particle(part)
                       best.fitness.values = part.fitness.values
               for part in pop:
                   toolbox.update(part,best)
               stats = tools.Statistics(lambda ind:ind.fitness.values)
               stats.register("Min", np.min)
               logbook.record(gen= g, evals = len(pop), **stats.compile(pop))
               #Minimum Research Loop Visualization
               #print("Generation e Particles Number =", logbook.stream)
               \#print("X, Y = \$s \ , \ Rastrigin \ Minimum \ \$s" \ \$(best, best.fitness))
           end t=time.time()
           print("\n----")
           print("Rastrigin Function Minimum Determination")
           print("-----\n")
           print("[X,Y] = ",best)
           print("Best Fitness (Rastrigin Minimum) = ", str(best.fitness)[7:-3])
           print("Elapsed Time (seconds):", end t-start t)
           return pop , logbook, best, stats
In [8]: # Code execution
        if __name__ == "__main__":
           main()
        _____
       Rastrigin Function Minimum Determination
        [X,Y] = [-0.0027465187213622233, 0.0016474240374112492]
       Best Fitness (Rastrigin Minimum) = [0.00203494]
       Elapsed Time (seconds): 3.296771764755249
In [ ]:
```

4 di 4