



National Science Foundation
WHERE DISCOVERIES BEGIN



Robots and Sensors for the Human Well-being (ROSE-HUB)

Meeting: Thursday February 6, 2025

Meeting Location: Virtual via Zoom Meeting

Link: <https://umn.zoom.us/j/3945673601>

Meeting ID: 394 567 3601

Agenda

(All times are in Central Time)

Thursday February 6, 2025

1:00 PM Agenda, Mr. Mike Bazakos, Managing Director

1:05 Welcome, Dr. Nikolaos Papanikolopoulos, Director of the Minnesota Robotics Institute (MnRI) at the University of Minnesota

1:15 Center Update

10 mins – NSF Update, Dr. Mohan Kumar, National Science Foundation PD

10 mins – Center Highlights, Dr. Vassilios Morellas, Center Director

10 mins - The Industrial View, Dr. Vibhor Bageshwar, IAB chair (Honeywell)

1:45 Proposal Presentations and IAB Evaluations (online) [*]

5 mins – Introduction to the “Airtable” Evaluation System – Mr. Haoyi Shi

30 mins (3 projects) - University of Minnesota

UMN1: Federated Learning for Traffic Flow Predictions

(PI: Maria Gini, Presenter: Ebaso Temesgen)

UMN2: Truck Parking Detection Deployment and Maintenance: Phase II

(PIs: V. Morellas, T. Morris and N. Papanikolopoulos, Presenter: Ted Morris)

UMN3: Development of Individualized, Autonomous Interaction Using Nao, Socially-Assistive Robot, for Aging Population

(PIs: Vassilios Morellas and Haoyi Shi, Presenter: Felix Su)

2:15 30 mins (3 projects) - Worcester Polytechnic Institute

WPI1: Tele-Robotic System for Waste Disposal

(PI: Jane Li, Presenter: Nikita Boguslavskii)

WPI2: Wire Inspect Autonomous Thin Wire and Line Inspection

(PI: Nitin Sanket, Presenters: Manoj Velmurugan and Kushagra Srivastav)

WPI3: Robotic Bird Deterrent

(PI: Greg Lewin, Presenter: Nikesh Walling)

2:45 IAB Feedback/Discussion - Dr. Vibhor Bageshwar, IAB chair/ALL

3:00 Adjourn

[*] Online project evaluation by IAB
<https://airtable.com/shrh6CWRqYmOpr0RY>

Online project for PI and Faculty
<https://airtable.com/shrTflyubNF43Bfzk>

Please check out the new website of ROSE-HUB: <https://rose-hub-iucrc.github.io>