Recorded at time: 31.956 odom Broadcaster: /gazebo Average rate: 19.816 Hz Most recent transform: 31.946 (0.010 sec old) Buffer length: 4.794 sec base_footprint Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Most recent transform: 32.454 (-0.498 sec old) Buffer length: 4.840 sec base_link Broadcaster: /robot_state_publisher Average rate: 35.208 Hz Most recent transform: 31.936 (0.020 sec old) Buffer length: 4.800 sec torso_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Average rate: 35.208 Hz Most recent transform: 32.454 (-0.498 sec old) Most recent transform: 31.936 (0.020 sec old) Buffer length: 4.840 sec Buffer length: 4.800 sec arm_link1 neck_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 35.208 Hz Average rate: 35.208 Hz Most recent transform: 31.936 (0.020 sec old) Most recent transform: 31.936 (0.020 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec arm_link2 head_link Broadcaster: /robot_state_publisher Average rate: 35.208 Hz Most recent transform: 31.936 (0.020 sec old) Buffer length: 4.800 sec arm_link3 Broadcaster: /robot_state_publisher Average rate: 35.208 Hz Most recent transform: 31.936 (0.020 sec old) Buffer length: 4.800 sec arm_link4 Broadcaster: /robot_state_publisher Average rate: 35.208 Hz Most recent transform: 31.936 (0.020 sec old) Buffer length: 4.800 sec arm_link5 Broadcaster: /robot_state_publisher Average rate: 35.208 Hz Most recent transform: 31.936 (0.020 sec old) Buffer length: 4.800 sec arm_link6 Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Most recent transform: 32.454 (-0.498 sec old) Buffer length: 4.840 sec

ee_link

view_frames Result