

Task 0 – Pollinator Bee

Read Me

This task is divided into two parts:

- Software Installation
- WhyCon Task

Please find the following folders within the folder that contains this Read Me file.

- First Folder is **Installation Instructions**
 - Please find the following files in this folder
 - [ROS_Kinetic_Installation.pdf](#)
 - [V-REP_Installation_Instructions.pdf](#)
 - [V-REP_ROS_Interface_Installation_Instructions.pdf](#)
 - Open the file [ROS_Kinetic_Installation.pdf](#) and follow the instructions to install the Robotics Operating System on your Linux machine
 - Open the file [V-REP_Installation_Instructions.pdf](#) and follow the instructions to install the Virtual Robot Experimentation Platform on your Linux machine
 - Open the file [V-REP_ROS_Interface_Installation_Instructions.pdf](#) and follow the instructions to install the V-REP-ROS Interface package on your Linux machine
- Second folder is **Task**
 - Please find the following files in this folder
 - Files:
 - [Problem Statement.pdf](#)
 - [task0_pb.ttt](#)
 - Open the file [Problem Statement.pdf](#) and follow the instructions to implement the task.
- Third folder is **Tutorials**
 - Please find the following folder/file in this folder
 - Folder:
 - [Python](#)
 - Files:
 - [Creating a Workspace and Learning ROS.pdf](#)
 - [Introduction to ROS.pdf](#)
 - [Introduction to V-REP.pdf](#)
 - [Linux Tutorials.pdf](#)
 - [Understanding WhyCon.pdf](#)
 - [Understanding World.pdf](#)
 - Open the [Introduction to ROS.pdf](#) and follow the instructions to understand ROS.
 - Open the [Creating a Workspace and Learning ROS.pdf](#) to get a head-start in using ROS and creating your first package.
 - Open [Introduction to V-REP.pdf](#) to understand and learn V-REP.
 - Open the [Linux Tutorials.pdf](#) and follow the instructions to learn the basics of Linux.
 - Open the [Python folder](#) to brush up your basics on Python.
 - Open the [Understanding WhyCon.pdf](#) file to learn about the WhyCon fiducial marker
 - Open the [Understanding World.pdf](#) to learn about the V-REP scene provided to you