Introduction to Machine Learning

Kernel Methods

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1 Kernel Methods

1.1 Extension to Non-Vector Data Examples

- What if $\mathbf{x} \notin \Re^D$?
- Does $\mathbf{w}^{\top}\mathbf{x}$ make sense?
- How to adapt?
 - 1. Extract features from **x**
 - 2. Is not always possible
- Sometimes it is easier/natural to compare two objects.
 - A similarity function or **kernel**
- Domain-defined measure of similarity

Example 1. Strings: Length of longest common subsequence, inverse of edit distance

 ${\it Example~2.~ \bf Multi-attribute~Categorical~ Vectors:~ \bf Number~of~ matching~ values}$

1.2 Kernel Regression

• Ridge regression estimate:

$$\mathbf{w} = (\lambda I_D + \mathbf{X}^{\mathsf{T}} \mathbf{X})^{-1} \mathbf{X}^{\mathsf{T}} \mathbf{y}$$

• Prediction at \mathbf{x}^* :

$$y^* = \mathbf{w}^{\mathsf{T}} \mathbf{x}^* = ((\lambda I_D + \mathbf{X}^{\mathsf{T}} \mathbf{X})^{-1} \mathbf{X}^{\mathsf{T}} \mathbf{y})^{\mathsf{T}} \mathbf{x}^*$$

- \bullet Still needs training and test examples as D length vectors
- Rearranging above (Sherman-Morrison-Woodbury formula or Matrix Inversion Lemma [See Murphy p120, Matrix Cookbook])

$$y^* = \mathbf{y}^{\top} (\lambda I_N + \mathbf{X} \mathbf{X}^{\top})^{-1} \mathbf{X} \mathbf{x}^*$$

2

The above mentioned "rearrangement" can be obtained using the *Matrix Inversion Lemma*, which in general term states for matrices **E,F,G,H**:

$$(E - FH^{-1}G)^{-1}FH^{-1} = E^{-1}F(H - GE^{-1}F)^{-1}$$

Setting $\mathbf{H} = \mathbf{I}$ and $\mathbf{E} = -a\mathbf{I}$, where a is a scalar value, we get:

$$(a\mathbf{I} + \mathbf{F}\mathbf{G})^{-1}\mathbf{F} = \mathbf{F}(a\mathbf{I} + \mathbf{G}\mathbf{F})^{-1}$$
(1)

Consider the prediction equation for ridge regression (we use the fact that $(\lambda \mathbf{I}_D + \mathbf{X}^{\top} \mathbf{X})$ is a square and symmetric matrix):

$$y^* = ((\lambda \mathbf{I}_D + \mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y})^\top \mathbf{x}^*$$

= $\mathbf{y}^\top \mathbf{X} (\lambda \mathbf{I}_D + \mathbf{X}^\top \mathbf{X})^{-1} \mathbf{x}^*$

Using the result in (1) with $a = \lambda$, $\mathbf{F} = \mathbf{X}$, and $\mathbf{X}^{\top} = \mathbf{G}$:

$$y^* = \mathbf{y}^{\mathsf{T}} (\lambda \mathbf{I}_N + \mathbf{X} \mathbf{X}^{\mathsf{T}})^{-1} \mathbf{X} \mathbf{x}^*$$

 $\mathbf{X}\mathbf{X}^{\mathsf{T}}$?

$$\mathbf{X}\mathbf{X}^{ op} = egin{pmatrix} \langle \mathbf{x}_1, \mathbf{x}_1
angle & \langle \mathbf{x}_1, \mathbf{x}_2
angle & \cdots & \langle \mathbf{x}_1, \mathbf{x}_N
angle \\ \langle \mathbf{x}_2, \mathbf{x}_1
angle & \langle \mathbf{x}_1, \mathbf{x}_2
angle & \cdots & \langle \mathbf{x}_2, \mathbf{x}_N
angle \\ dots & dots & \ddots & dots \\ \langle \mathbf{x}_N, \mathbf{x}_1
angle & \langle \mathbf{x}_N, \mathbf{x}_2
angle & \cdots & \langle \mathbf{x}_N, \mathbf{x}_N
angle \end{pmatrix}$$

 Xx^* ?

$$\mathbf{X}\mathbf{x}^* = egin{pmatrix} \left\langle \mathbf{x}_1, \mathbf{x}^*
ight
angle \\ \left\langle \mathbf{x}_2, \mathbf{x}^*
ight
angle \\ dots \\ \left\langle \mathbf{x}_N, \mathbf{x}^*
ight
angle \end{pmatrix}$$

 \bullet Consider a set of P functions that can be applied on input example **x**

$$\boldsymbol{\phi} = \{\phi_1, \phi_2, \dots, \phi_P\}$$

$$\mathbf{\Phi} = \begin{pmatrix} \phi_1(\mathbf{x}_1) & \phi_2(\mathbf{x}_1) & \cdots & \phi_P(\mathbf{x}_1) \\ \phi_1(\mathbf{x}_2) & \phi_2(\mathbf{x}_2) & \cdots & \phi_P(\mathbf{x}_2) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_1(\mathbf{x}_N) & \phi_2(\mathbf{x}_N) & \cdots & \phi_P(\mathbf{x}_N) \end{pmatrix}$$

3

• Prediction:

$$y^* = \mathbf{y}^{\top} (\lambda \mathbf{I}_N + \mathbf{\Phi} \mathbf{\Phi}^{\top})^{-1} \mathbf{\Phi} \boldsymbol{\phi}(\mathbf{x}^*)$$

• Each entry in $\Phi\Phi^{\top}$ is $\langle \phi(\mathbf{x}), \phi(\mathbf{x}') \rangle$

We have already seen one such non-linear transformation in which one attribute is expanded to $\{1, x, x^2, x^3, \dots, x^d\}$.

2 Kernel Trick

- Replace dot product $\langle \mathbf{x}_i, \mathbf{x}_i \rangle$ with a function $k(\mathbf{x}_i, \mathbf{x}_i)$
- Replace XX^{\top} with K

$$K[i][j] = k(\mathbf{x}_i, \mathbf{x}_j)$$

- K Gram Matrix
- \bullet k kernel function
 - Similarity between two data objects

Kernel Regression

$$y^* = \mathbf{y}^{\top} (\lambda \mathbf{I}_N + \mathbf{K})^{-1} k(\mathbf{X}, \mathbf{x}^*)$$

2.1 Choosing Kernel Functions

• Already know the simplest kernel function:

$$k(\mathbf{x}_i, \mathbf{x}_j) = \mathbf{x}_i^{\mathsf{T}} \mathbf{x}_j$$

Approach 1: Start with basis functions

$$k(\mathbf{x}_i, \mathbf{x}_j) = \boldsymbol{\phi}(\mathbf{x}_i)^{\top} \boldsymbol{\phi}(\mathbf{x}_j)$$

Approach 2: Direct design (good for non-vector inputs)

- Measure similarity between \mathbf{x}_i and \mathbf{x}_j
- Should follow Mercer's Condition

- Kernel/Gram matrix must be positive semi-definite
- \bullet k should be symmetric

For instance, consider the following kernel function for two-dimensional inputs, $(\mathbf{x} = (x_1, x_2))$:

$$\begin{array}{rcl} k(\mathbf{x}, \mathbf{z}) & = & (\mathbf{x}^{\top} \mathbf{z})^2 \\ & = & x_1^2 z_1^2 + 2 x_1 z_1 x_2 z_2 + x_2^2 z_2^2 \\ & = & (x_1^2, \sqrt{2} x_1 x_2, x_2^2)^{\top} (x_z^2, \sqrt{2} z_1 z_2, z_2^2) \\ & = & \boldsymbol{\phi}(\mathbf{x})^{\top} \boldsymbol{\phi}(\mathbf{z}) \end{array}$$

where the feature mapping $\phi(\mathbf{x})$ is defined as:

$$\phi(\mathbf{x}) = (x_1^2, \sqrt{2}x_1x_2, x_2^2)^{\top}$$

2.2 Constructing New Kernels Using Building Blocks

$$k(\mathbf{x}_i, \mathbf{x}_j) = ck_1(\mathbf{x}_i, \mathbf{x}_j)$$

$$k(\mathbf{x}_i, \mathbf{x}_j) = f(\mathbf{x})k_1(\mathbf{x}_i, \mathbf{x}_j)f(\mathbf{x}_j)$$

$$k(\mathbf{x}_i, \mathbf{x}_j) = q(k_1(\mathbf{x}_i, \mathbf{x}_j)) \ q \text{ is a polynomial}$$

$$k(\mathbf{x}_i, \mathbf{x}_j) = exp(k_1(\mathbf{x}_i, \mathbf{x}_j))$$

$$k(\mathbf{x}_i, \mathbf{x}_j) = k_1(\mathbf{x}_i, \mathbf{x}_j) + k_2(\mathbf{x}_i, \mathbf{x}_j)$$

$$k(\mathbf{x}_i, \mathbf{x}_j) = k_1(\mathbf{x}_i, \mathbf{x}_j)k_2(\mathbf{x}_i, \mathbf{x}_j)$$

3 Kernels

• Radial Basis Function or Gaussian Kernel

$$k(\mathbf{x}_i, \mathbf{x}_j) = exp\left(-\frac{1}{2\sigma^2} \|\mathbf{x}_i - \mathbf{x}_j\|^2\right)$$

• Cosine Similarity

$$k(\mathbf{x}_i, \mathbf{x}_j) = \frac{\mathbf{x}_i^{\top} \mathbf{x}_j}{\|\mathbf{x}_i\| \|\mathbf{x}_j\|}$$

One can start with a Mercer kernel and show through the **Mercer's theo**rem how it can be expressed as an inner product. Since K is positive definite we can compute an eigenvector decomposition:

$$\mathbf{K} = \mathbf{U}^{\mathsf{T}} \mathbf{\Lambda} \mathbf{U}$$

Each element of K can be rewritten as:

$$\mathbf{K}_{ij} = (\mathbf{\Lambda}^{rac{1}{2}}\mathbf{U}_{:,i})^{ op}(\mathbf{\Lambda}^{rac{1}{2}}\mathbf{U}_{:,j})$$

Let $\phi(\mathbf{x}_i) = \mathbf{\Lambda}^{\frac{1}{2}} \mathbf{U}_{:,i}$. Then we can write:

$$\mathbf{K}_{ij} = \boldsymbol{\phi}(\mathbf{x}_i)^{\top} \boldsymbol{\phi}(\mathbf{x}_j)$$

3.1 RBF Kernel

$$k(\mathbf{x}_i, \mathbf{x}_j) = exp\left(-\frac{1}{2\sigma^2}||\mathbf{x}_i - \mathbf{x}_j||^2\right)$$

• Mapping inputs to an infinite dimensional space

Whenever presented with a "potential" kernel function, one needs to ensure that it is indeed a valid kernel. This can be done in two ways, one through functional analysis and second by decomposing the function into a valid combination of valid kernel functions. For instance, for the Gaussian kernel, one can note that:

$$||\mathbf{x}_i - \mathbf{x}_j||^2 = \mathbf{x}^\top \mathbf{x}_i + (\mathbf{x}_j)^\top \mathbf{x}_j - 2\mathbf{x}_i^\top \mathbf{x}_j$$

Which means that the Gaussian kernel function can be written as:

$$k(\mathbf{x}_i, \mathbf{x}_j) = exp(\frac{\mathbf{x}_i^{\top} \mathbf{x}_i}{2\sigma^2}) exp(\frac{\mathbf{x}_i^{\top} \mathbf{x}_j}{2\sigma^2}) exp(\frac{(\mathbf{x}_j)^{\top} \mathbf{x}_j}{2\sigma^2})$$

All three individual exponents are valid covariance functions and hence the product of these is also a valid covariance function.

3.2 Probabilistic Kernel Functions

• Allows using generative distributions in discriminative settings

ullet Uses class-independent probability distribution for input ${\bf x}$

$$k(\mathbf{x}_i, \mathbf{x}_j) = p(\mathbf{x}_i | \boldsymbol{\theta}) p(\mathbf{x}_j | \boldsymbol{\theta})$$

• Two inputs are more similar if both have high probabilities

Bayesian Kernel

$$k(\mathbf{x}_i, \mathbf{x}_j) = \int p(\mathbf{x}_i | \boldsymbol{\theta}) p(\mathbf{x}_j | \boldsymbol{\theta}) p(\boldsymbol{\theta}) d\boldsymbol{\theta}$$

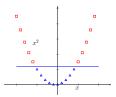
3.3 Kernels for Other Types of Data

- String Kernel
- Pyramid Kernels

4 More About Kernels

4.1 Motivation

- $x \in \Re$
- No linear separator
- Map $x \to \{x, x^2\}$
- Separable in 2D space







- $\mathbf{x} \in \Re^2$
- No linear separator
- Map $\mathbf{x} \to \{x_1^2, \sqrt{2}x_1x_2, x_2^2\}$
- A circle as the decision boundary

4.2 Gaussian Kernel

• The squared dot product kernel $(\mathbf{x_i}, \mathbf{x_j} \in \Re^2)$:

$$k(\mathbf{x_i}, \mathbf{x_j}) = \mathbf{x_i}^{\top} \mathbf{x_j} \triangleq \boldsymbol{\phi}(\mathbf{x_i})^{\top} \boldsymbol{\phi}(\mathbf{x_j})$$

$$\phi(\mathbf{x_i}) = \{x_{i1}^2, \sqrt{2}x_{i1}x_{i2}, x_{i2}^2\}$$

• What about the Gaussian kernel (radial basis function)?

$$k(\mathbf{x_i}, \mathbf{x_j}) = exp\left(-\frac{1}{2\sigma^2}||\mathbf{x}_i - \mathbf{x}_j||^2\right)$$

• Assume $\sigma = 1$ and $\mathbf{x} \in \Re$ (denoted as x)

$$\begin{array}{rcl} k(x_i,x_j) & = & exp(-x_i^2)exp(-x_j^2)exp(2x_ix_j) \\ & = & exp(-x_i^2)exp(-x_j^2)\sum_{k=0}^{\infty}\frac{2^kx_i^kx_j^k}{k!} \\ & = & \sum_{k=0}^{\infty}\left(\frac{2^{k/2}}{\sqrt{k!}}x_i^kexp(-x_i^2)\right)\left(\frac{2^{k/2}}{\sqrt{k!}}x_j^kexp(-x_j^2)\right) \end{array}$$

• Using Maclaurin Series Expansion

$$k(x_i, x_j) = \begin{pmatrix} 1 \\ 2^{1/2} x_i^1 exp(-x_i^2) \\ \frac{2^{2/2}}{2} x_i^2 exp(-x_i^2) \\ \vdots \end{pmatrix} \times \begin{pmatrix} 1 \\ 2^{1/2} x_j^1 exp(-x_j^2) \\ \frac{2^{2/2}}{2} x_j^2 exp(-x_j^2) \\ \vdots \\ \vdots \end{pmatrix}^\top$$

One can note above that since computing the Gaussian kernel is same as taking a dot product of two vectors of infinite length, it is equivalent to mapping the input features into an infinite dimensional space.

5 Kernel Machines

- We can use kernel function to *generate* new features
- \bullet Evaluate kernel function for each input and a set of K centroids

$$\phi(\mathbf{x}) = [k(\mathbf{x}, \boldsymbol{\mu}_1), k(\mathbf{x}, \boldsymbol{\mu}_2), \dots, k(\mathbf{x}, \boldsymbol{\mu}_K)]$$
$$y = \mathbf{w}^{\top} \phi(\mathbf{x}), \quad y \sim Ber(\mathbf{w}^{\top} \phi(\mathbf{x}))$$

- If k is a Gaussian kernel \Rightarrow Radial Basis Function Network (RBF)
- How to choose μ_i ?
 - Clustering
 - Random selection

5.1 Generalizing RBF

• Another option: Use every input example as a "centroid"

$$\phi(\mathbf{x}) = [k(\mathbf{x}, \mathbf{x}_1), k(\mathbf{x}, \mathbf{x}_2), \dots, k(\mathbf{x}, \mathbf{x}_N)]$$

References