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# CSC 4444 Assignment 1

Goal based agent - seeks to achieve a goal that describes situations that are desirable

- Considers world after taking action
- Flexible to make decisions that can adjust to changes in situations

```
1. state ← UPDATE STATE(state, action, percept, model)
if GOAL-ACHIEVED(state, goal) then return null action
if plan is empty then
    plan ← PLAN(state, goal, model)
    action ← FIRST(plan)
    plan ← REST(plan)
return action
```

2.

a. State space - All potential city pairings within the country

b. initial state - All potential city pairings in the country

c. The most equidistant city between the individual starting points.

The series of smallest  $d(i, j)$  for both friends. Friend 1 & Friend 2 in the same city.

d. The actions simultaneously move each friend to a neighbouring city

e.  $d(i, j)$