Master Presentation Marius Hobbhahn

Start: 14:30

Fast Predictive Uncertainty for Classification with Bayesian Deep Networks

> Marius Hobbhahn 30 June 2020

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Motivation

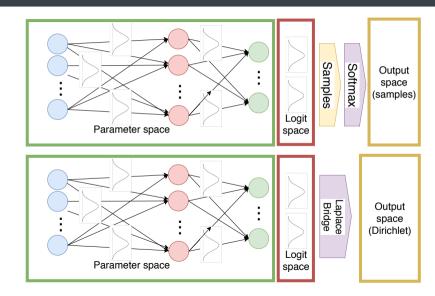
Why do we need fast uncertainty in neural networks?

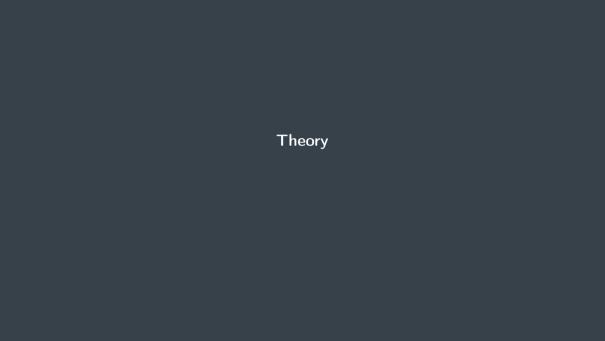
- * safety-critical applications e.g. self-driving cars
- + trade-off between accuracy and speed
- + out-of-distribution detection



Context

What's our new contribution?





Let \mathbf{x} be an n-dimensional continuous random variable with joint density function $p_{\mathbf{x}}$. If $\mathbf{y} = g(\mathbf{x})$, where g is a differentiable function, then \mathbf{y} has density $p_{\mathbf{y}}$:

$$p_{\mathbf{y}}(\mathbf{y}) = p_{\mathbf{x}} \left(g^{-1}(\mathbf{y}) \right) \left| \det \left[\frac{dg^{-1}(\mathbf{y})}{d\mathbf{y}} \right] \right|$$
 (1)

where the differential is the Jacobian of the inverse of g evaluated at \mathbf{y} .

+

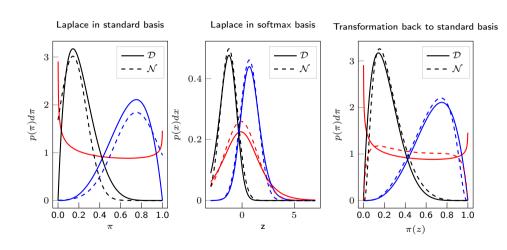
$$Dir(\boldsymbol{\pi}|\boldsymbol{\alpha}) := \frac{1}{B(\alpha)} \prod_{k=1}^{K} \pi_k^{\alpha_k - 1}$$
 (2)

+

$$\pi_k(\mathbf{z}) := \frac{\exp(z_k)}{\sum_{l=1}^K \exp(z_l)},\tag{3}$$

+

$$\operatorname{Dir}_{\mathbf{z}}(\boldsymbol{\pi}(\mathbf{z})|\boldsymbol{\alpha}) := \frac{1}{B(\alpha)} \prod_{k=1}^{K} \pi_k(\mathbf{z})^{\alpha_k}, \qquad (4)$$



$$\alpha_k = \frac{1}{\Sigma_{kk}} \left(1 - \frac{2}{K} + \frac{e^{\mu_k}}{K^2} \sum_{l}^{K} e^{-\mu_l} \right)$$
 (5)

$$\mu_k = \log \alpha_k - \frac{1}{K} \sum_{l=1}^K \log \alpha_l \tag{6}$$

$$\Sigma_{kl} = \delta_{kl} \frac{1}{\alpha_k} - \frac{1}{K} \left[\frac{1}{\alpha_k} + \frac{1}{\alpha_l} - \frac{1}{K} \sum_{u=1}^K \frac{1}{\alpha_u} \right]$$
 (7)

The Laplace Bridge

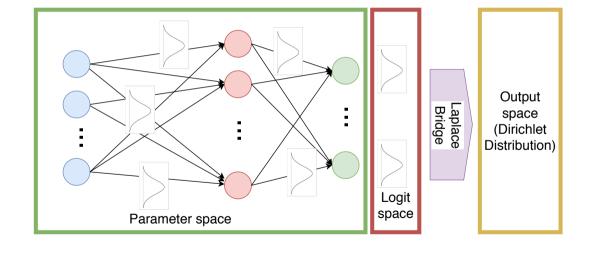
Summary



- + The Dirichlet in the inverse softmax basis approximates a Gaussian
- + Via the Laplace approximation in the transformed basis we can create a closed-form transformation $\alpha \to (\mu, \Sigma)$.
- + We can also construct an inverse of this transformation $(\mu,\Sigma) \to \alpha$
- In total, we have a fast way to transform between the parameters of a Dirichlet and a Gaussian

The Laplace Bridge

Application to Neural Networks

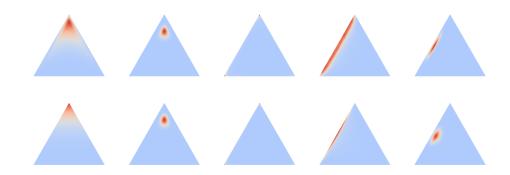


a



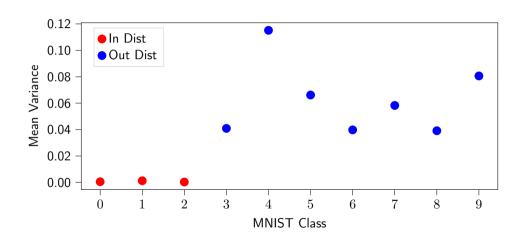
A sanity check

Samples from a 3D Gaussian + Softmax vs. Dirichlet



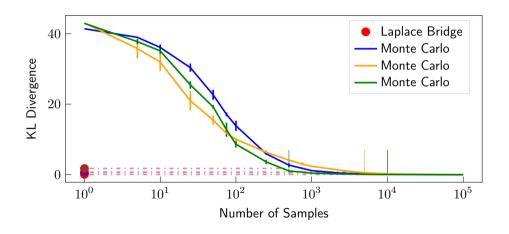
MNIST

Train on 0,1,2; test on 0-9



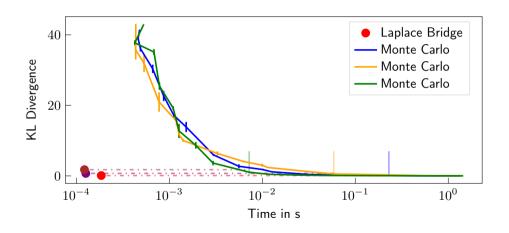
Speedtest - I

KL divergence vs. number of samples



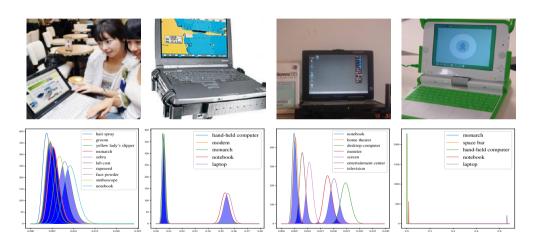
Speedtest - II

KL divergence vs. wall-clock time

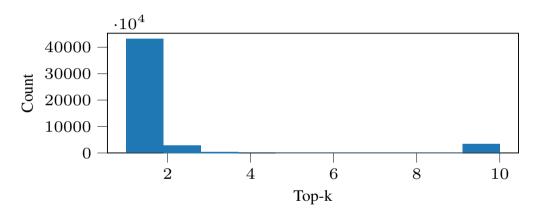


Imagenet

Using the properties of the Dirichlet - The marginal of a Dirichlet is a Dirichlet



We can use the overlap of the distributions to create an uncertainty-aware top-k ranking.



- + The original top-1 accuracy of DenseNet on ImageNet is 0.744 and top-5 accuracy is 0.919
- + The uncertainty-aware top-k accuracy is 0.797, where k is on average 1.688.

Out-of-distribution Detection

Looking at the numbers

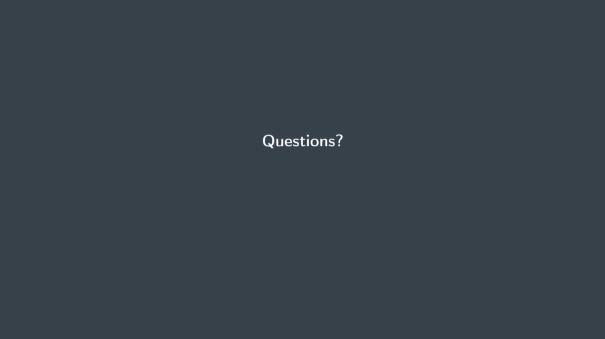
		Diag Sampling		Diag LB		KFAC Sampling		KFAC LB		Time in s ↓	
Train	Test	MMC ↓	AUROC ↑	MMC ↓	AUROC ↑	MMC↓	AUROC ↑	$MMC\downarrow$	AUROC ↑	Sampling	LB
MNIST	MNIST	0.942 ± 0.007	-	0.987 ± 0.000	-	l -	-	-	-	26.8	0.062
MNIST	FMNIST	0.397 ± 0.001	0.992 ± 0.000	0.363 ± 0.000	0.996 ± 0.000	-		-	-	26.8	0.062
MNIST	notMNIST	0.543 ± 0.000	0.960 ± 0.000	0.649 ± 0.000	0.961 ± 0.000	-		-	-	50.3	0.117
MNIST	KMNIST	0.513 ± 0.001	0.974 ± 0.000	0.637 ± 0.000	0.973 ± 0.000	-	-	-	-	26.9	0.062
CIFAR-10	CIFAR-10	0.948 ± 0.000	-	0.966 ± 0.000	-	0.857 ± 0.003	-	0.966 ± 0.000	-	6.58	0.017
CIFAR-10	CIFAR-100	0.708 ± 0.000	0.889 ± 0.000	0.742 ± 0.000	0.866 ± 0.000	0.562 ± 0.003	0.880 ± 0.012	0.741 ± 0.000	0.866 ± 0.000	6.59	0.016
CIFAR-10	SVHN	0.643 ± 0.000	0.933 ± 0.000	0.647 ± 0.000	0.934 ± 0.000	0.484 ± 0.004	0.939 ± 0.001	0.648 ± 0.003	0.934 ± 0.001	17.0	0.040
SVHN	SVHN	0.986 ± 0.000	-	0.993 ± 0.000	-	0.947 ± 0.002	-	0.993 ± 0.000	-	17.1	0.042
SVHN	CIFAR-100	0.595 ± 0.000	0.984 ± 0.000	0.526 ± 0.000	0.985 ± 0.000	0.460 ± 0.004	0.986 ± 0.001	0.527 ± 0.002	0.985 ± 0.000	6.62	0.017
SVHN	CIFAR-10	0.593 ± 0.000	0.984 ± 0.000	0.520 ± 0.000	0.987 ± 0.000	0.458 ± 0.004	0.986 ± 0.001	0.520 ± 0.002	0.987 ± 0.000	6.62	0.017
CIFAR-100	CIFAR-100	0.762 ± 0.000	-	0.590 ± 0.000	-	0.404 ± 0.000	-	0.593 ± 0.000	-	6.76	0.01
CIFAR-100	CIFAR-10	0.467 ± 0.000	0.788 ± 0.000	0.206 ± 0.000	0.791 ± 0.000	0.213 ± 0.000	0.788 ± 0.000	0.209 ± 0.000	0.791 ± 0.000	6.71	0.01
CIFAR-100	SVHN	0.461 ± 0.000	0.795 ± 0.000	0.170 ± 0.000	0.815 ± 0.000	0.180 ± 0.001	0.838 ± 0.001	0.173 ± 0.000	0.815 ± 0.000	17.3	0.04

- + The Laplace Bridge seems to be have better MMC and AUROC compared to sampling from a diagonal Gaussian approximation
- + The Laplace Bridge is as good as a KFAC approximation
- + The Laplace Bridge is around 400 times faster on average

Conclusions

What can or can't the Laplace Bridge achieve in the context of BNNs?

- + The Laplace Bridge improves an important part of Bayesian Neural Network inference for classification (fast & non-invasive)
- + The Dirichlet distribution has some additional interesting use cases (e.g. the top-k ranking)
- + It will not revolutionize BNNs; it is just one piece in the larger puzzle





The generalized Laplace Bridge

Looking at the larger pattern

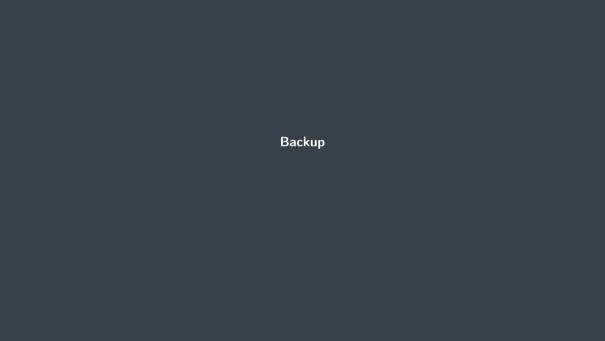
- + Similar "Bridges" can be found for all exponential families.
- + Develop a general theoretically grounded framework for the general Laplace Bridge
- + Compute KL-divergences in the different basis

The generalized Laplace Bridge

So what?

Implications: (with a small error)

- + All exponential families can be transformed to Gaussians
- + All exponential families can be transformed to each other
- + All exponential families are conjugate priors for each other



$$p(c|x) = \mathcal{N}(x; f(x, w_{MAP}), J(x)^T H^{-1} J(x))$$
 (8)

- + $f(x; w_{\text{MAP}})$ is the network output induced by the MAP estimate w_{MAP} .
- + $J(x) = \frac{\partial f(x, w_{\text{MAP}})}{\partial w} \in \mathbb{R}^{K \times P}$ is the Jacobian of the network
- + $H_{ij} = \frac{\partial^2 \mathcal{L}(f(x), y)}{\partial w_i \partial w_j} \in \mathbb{R}^{P \times P}$ its Hessian.
- + K,P are the number of classes and parameters of the network respectively.

Proposition

Let $\mathrm{Dir}(\pi|\alpha)$ be obtained via the Laplace Bridge from a Gaussian distribution $\mathcal{N}(\mathbf{z}|\boldsymbol{\mu},\boldsymbol{\Sigma})$ over \mathbb{R}^K . Then, for each $k=1,\ldots,K$, letting $\alpha_{\neq k}:=\sum_{l\neq k}\alpha_l$, if

$$\alpha_k > \frac{1}{4} \left(\sqrt{9\alpha_{\neq k}^2 + 10\alpha_{\neq k} + 1} - \alpha_{\neq k} - 1 \right) ,$$

then the variance $\operatorname{Var}(\pi_k|\alpha)$ of the k-th component of π is increasing in Σ_{kk} .

Backup

Computing the Hessian

First, we consider the special case where π is confined to a I-1 dimensional subspace satisfying $\sum_i \pi_i = c$. In this subspace we can represent π by an I-1 dimensional vector $\mathbf a$ such that

$$\pi_i = a_i \quad i, ..., I - 1 \tag{9}$$

$$\pi_I = c - \sum_{i}^{I-1} a_i \tag{10}$$

and similarly we can represent z by an I-1 dimensional vector ϱ :

$$z_i = \varrho_i \quad i, ..., I - 1 \tag{11}$$

$$z_I = 1 - \sum_{i}^{I-1} \varrho_i \tag{12}$$

then we can find the density over ϱ (which is proportional to the required density over z) from the density over π (which is proportional to the given density over π) by finding the determinant of the $(I-1)\times (I-1)$ Jacobian ${\bf J}$ given by

$$J_{ik} = \frac{\partial \varrho_i}{\partial a_i} = \sum_{j}^{I} \frac{\partial z_i}{\partial \pi_j} \frac{\partial \pi_j}{\partial a_k}$$
 (13)

$$= \delta_{ik} \mathbf{z}_i - \mathbf{z}_i \mathbf{z}_k + \mathbf{z}_i \mathbf{z}_I = \mathbf{z}_i (\delta_{ik} - (\mathbf{z}_k - \mathbf{z}_I))$$
(14)

We define two additional I-1 dimensional helper vectors $\mathbf{z}_k^+ := \mathbf{z}_k - \mathbf{z}_I$ and $n_k := 1$, and use $\det(I - xy^T) = 1 - x \cdot y$ from linear algebra. It follows that

$$\det J = \prod_{i=1}^{I-1} \mathbf{z}_i \times \det[I - n\mathbf{z}^{+T}]$$
(15)

$$= \prod_{i=1}^{I-1} \mathbf{z}_i \times (1 - n \cdot \mathbf{z}^+) \tag{16}$$

$$= \prod_{i=1}^{I-1} \mathbf{z}_i \times \left(1 - \sum_k \mathbf{z}_k^+\right) = I \prod_{i=1}^{I} \mathbf{z}_i$$
 (17)