

Phys 111
R 10/24/19

Lect. 18 Problem Solving (Scratch Work)

Look over the slides for more
information about the problems
and the problem-solving thought
process.

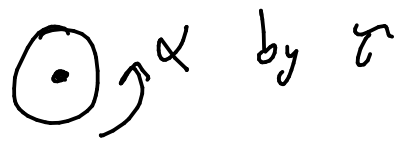
Ex. 1 C & J 9.32Find I given τ and α Using $\tau_{\text{net}} = I\alpha$

$$\tau = 15.0 \text{ N}\cdot\text{m}$$

$$\alpha = 5.00 \frac{\text{rad}}{\text{s}^2}$$



or

Since $\tau = I\alpha$ then

$$I = \frac{\tau}{\alpha}$$

$$\left(\text{also } \alpha = \frac{\tau}{I} \right)$$

$$I = \frac{(15.0)}{(5.00)} \frac{\text{N}\cdot\text{m}}{\frac{\text{rad}}{\text{s}^2}}$$

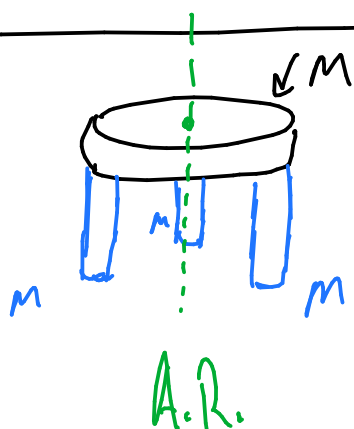
$$I = 3.0 \text{ kg}\cdot\text{m}^2$$

note

$$N = \frac{\text{kg}\cdot\text{m}}{\text{s}^2}$$

Ex. 2 C&J

Find the total I for an object with 4 distinct pieces of mass. $M = 1.4 \text{ kg}$, $m = 0.18 \text{ kg}$, $r = 0.18 \text{ m}$

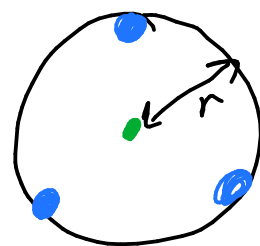


Bottom



View

• recall parallel-axis
comment from class •



$$I = \sum I = \sum (\text{fraction}) m r^2$$

$$I = I_{\text{disk}} + I_m + I_m + I_m$$

$$I = \left(\frac{1}{2} M r^2 \right) + 3(m r^2)$$

$$I = 0.040 \text{ kg} \cdot \text{m}^2$$

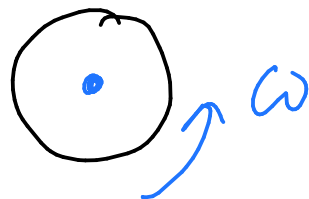
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Ex 3

How fast must a solid cylinder be spinning (ω) to store $[RKE =] 1.2 \times 10^9 \text{ J}$ of energy if it has a mass of $m = 15.0 \text{ kg}$ and a radius of $r = 0.40 \text{ m}$?



Top
→
View



$$I_{\text{disk}} = I_{\text{cyl}} = \frac{1}{2} m r^2 \quad \& \quad RKE = \frac{1}{2} I \omega^2$$

Therefore

$$2 RKE = I \omega^2$$

$$\omega^2 = \frac{2 RKE}{I}$$

$$\omega = \sqrt{\frac{2 RKE}{I}}$$

$$\omega = \sqrt{\frac{2(1.2 \times 10^9 \text{ J})}{(15.0 \text{ kg} \cdot \text{m}^2)}} \approx \boxed{4.5 \times 10^4 \frac{\text{rad}}{\text{s}}}$$

Ex 4 ^{1/2} 9.59

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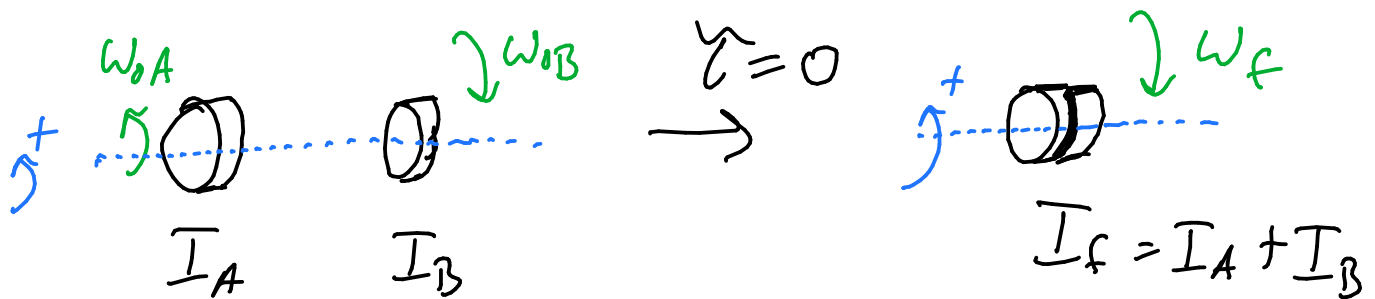
Two disks are rotated and then connected together without adding any extra angular momentum. Solve for the unknown moment of inertia I_B .

$$\omega_A = \omega_{0A} = +7.2 \text{ rad/s}$$

$$I_A = 3.4 \text{ kg}\cdot\text{m}^2$$

$$\omega_B = \omega_{0B} = -9.8 \text{ rad/s}$$

$$\omega_f = -2.4 \text{ rad/s}$$



$$\text{Conservation: } L_0 = L_f \quad ; \quad L = I\omega$$

$$\text{Thus, } L_{0A} + L_{0B} = L_f$$

Specific to this problem \Rightarrow

$$I_A \omega_A + I_B \omega_B = (I_A + I_B) \omega_f$$

Ex 4 _{2/2} $I_A \omega_A + I_B \omega_B = (I_A + I_B) \omega_f$

Now to rewrite/solve for I_B . (No zeros)

$$I_A \omega_A + I_B \omega_B = I_A \omega_f + I_B \omega_f$$

$$I_B \omega_B - I_B \omega_f = I_A \omega_f - I_A \omega_A$$

$$I_B (\omega_B - \omega_f) = I_A (\omega_f - \omega_A)$$

$$I_B = \frac{I_A (\omega_f - \omega_A)}{(\omega_B - \omega_f)} \quad \text{form ready for \#15.}$$

$$I_B = \frac{(3.4 \text{ kg}\cdot\text{m}^2) (-7.2 - 2.4) \frac{\text{rad}}{\text{s}}}{(-9.8 + (+2.4)) \frac{\text{rad}}{\text{s}}} = \frac{+(3.4)(9.6)}{+(7.4)} \text{ kg}\cdot\text{m}^2$$

$$I_B = 4.4 \text{ kg}\cdot\text{m}^2$$

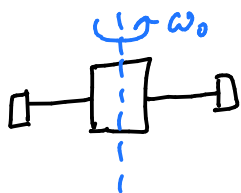
Ex 5 Ch. 9 Example 15

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Figure skater changes their moment of inertia with only internal torques.

I 's rotational energy conserved too.

Initial I_0, ω_0



$$\vec{\tau} = 0$$
$$I < I_0$$

Final I, ω



$$\vec{\tau} = 0$$

$$\rightarrow$$

$$L_0 = L_f$$

$I_0 \omega_0 = I \omega$ means if $I = \frac{1}{2} I_0$ then $\omega = 2\omega_0$.

Using $RKE_0 = \frac{1}{2} I_0 \omega_0^2$ and $RKE_f = \frac{1}{2} I \omega^2$

$$RKE_f = \frac{1}{2} \left(\frac{1}{2} I_0 \right) (2\omega_0)^2$$

$$RKE_f = \frac{1}{2} \left(\frac{1}{2} I_0 \omega_0^2 \right) (4)$$

$$RKE_f = 2 \left(\frac{1}{2} I_0 \omega_0^2 \right) > RKE_0$$

Think: The person had to use chemical/food potential energy to speed up.

Ex. 6 1/2

Three compact/point masses rotate about the same axis with the same angular velocity $\omega = 5.00 \frac{\text{rad}}{\text{s}}$, but different masses and radii.

$$m_1 = 6.00 \text{ kg}, r_1 = 2.00 \text{ m}$$

$$m_2 = 4.00 \text{ kg}, r_2 = 1.50 \text{ m}$$

$$m_3 = 3.00 \text{ kg}, r_3 = 3.00 \text{ m}$$

same ω ,
different
 m, r

(a) Calculate each tangential speed. ($v = r\omega$)

$$v_1 = 10.0 \frac{\text{m}}{\text{s}}, v_2 = 7.5 \frac{\text{m}}{\text{s}}, v_3 = 15.0 \frac{\text{m}}{\text{s}}$$

(b) Calculate $KE = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 + \frac{1}{2} m_3 v_3^2$

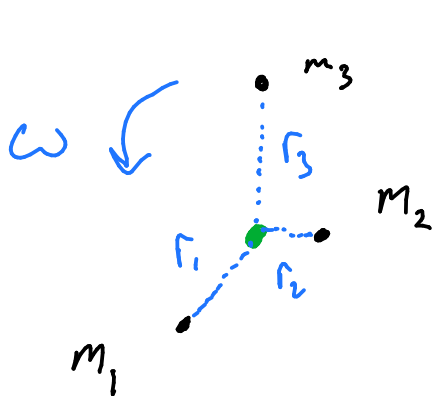
$$KE = 750 \text{ J}$$

Ex. 6 2/2

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(c) Calculate System.

I for the whole



Axis point/line

$$I = \sum m r^2$$

each mass is a pt. mass.

$$I = m_1 r_1^2 + m_2 r_2^2 + m_3 r_3^2$$

$$I = (24.0 + 9.00 + 27.0) \text{ kg} \cdot \text{m}^2$$

$$I = 60.0 \text{ kg} \cdot \text{m}^2$$

(d) Calculate $RKE = \frac{1}{2} I \omega^2$

$$RKE = \frac{1}{2} (60.0 \text{ kg} \cdot \text{m}^2) \left(5.00 \frac{\text{rad}}{\text{s}} \right)^2$$

$$RKE = 750 \text{ J} = KE \checkmark$$