

Name: Solutions

## Homework Week # 10

Rotational Dynamics  
Due Tues 10/29/19

### Reading

C&J Physics:	Tues – Ch. 9: 1-4	Thurs – Ch. 9: 4-7
OS Coll Phys:	Tues – Ch. 9: 1-6	Thurs – Ch. 10

### Problems

Problem 1.	9.1
Problem 2.	9.2
Problem 3.	9.7
Problem 4.	9.12
Problem 5.	9.18
Problem 6.	9.32
Problem 7.	9.33
Problem 8.	9.33 (use the parallel-axis theorem)
Problem 9.	9.49 (treat each mass as a point mass)
Problem 10.	9.59 (hint: $I_{tot} = I_1 + I_2$ )

Prob. 1 9.1

2/15

Rolling w/o slipping means  $\tau$  from  
static friction balances  $\tau$  from  
car engine.

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$$\tau_s = r f_s = \tau_{\text{eng}} = 295 \text{ N}\cdot\text{m}$$

$$\text{for } r = 0.350 \text{ m.}$$

$$r f_s = \tau$$

$$f_s = \frac{\tau}{r} = \frac{295 \text{ N}\cdot\text{m}}{0.350 \text{ m}}$$

$$f_s = 843 \text{ N}$$

Prob. 2 a.2

3/15

Two torques are accomplished  
with equal force, but different  
radii. What's the ratio of the  
two torques?  $r_1 = 0.19m, r_2 = 0.25m$

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$$\text{Goal: } \frac{\tau_2}{\tau_1} = \frac{r_2 F_2}{r_1 F_1} \quad \text{when } F_1 = F_2$$

$$\frac{\tau_2}{\tau_1} = \frac{r_2 \cancel{F}}{r_1 \cancel{F}} \quad (\text{use given info})$$

$$\frac{\tau_2}{\tau_1} = \frac{r_2}{r_1}$$

$$= \left( \frac{0.25m}{0.19m} \right)$$

(plug in #'s)

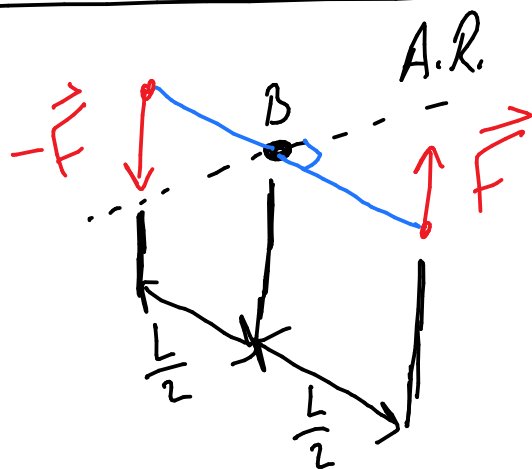
$$\boxed{\frac{\tau_2}{\tau_1} = 1.32}$$

4/15

Prob. 3 9.7

Find the torque for a given force "couple".

"couple" not on exam



$$\tau = LF$$

CCW(+) rotation

Both forces in the shown couple produce CCW torques with magnitude  $\tau = (\frac{L}{2})(F)$ .

$$\tau = \tau_F + \tau_{-F}$$

$$\tau = 2\left(\frac{L}{2}\right)F$$

$$\tau = LF$$

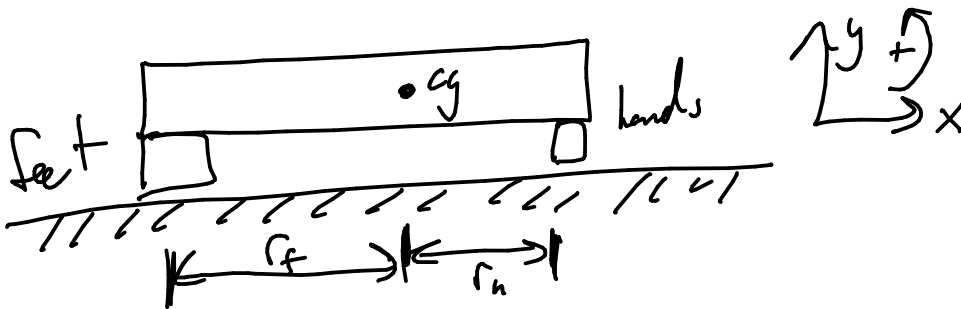
$\tau = LF$  for application at A, B, or C because applying the same couple means doing whatever is necessary to get exactly the same torque.

5/15

Prob. 4 9.12  
1/2

Known position of  $cg$  and that both hands exert equal force ( $2N_h$ ) and same for feet ( $2N_f$ ) find each normal force if  $W = 584\text{N}$ ,  $r_h = 0.410\text{m}$ , and  $r_f = 0.840\text{m}$ .

Mechanical equilibrium:  $\sum \vec{F} = 0$   
 $\sum \vec{\tau} = 0$



$$\sum F = 2N_h + 2N_f - W = 0$$

$$\sum \tau = \tau_h - \tau_f = 0$$

$$\tau = rF$$

$$\longrightarrow (2N_h)r_h - (2N_f)r_f = 0$$

means  $2N_f = \frac{r_h}{r_f} (2N_h)$

(sub into forces)

Prob. 4 2/2

6/15

$$\Sigma F = 0 \rightarrow 2N_h + \frac{r_h}{r_f} (2N_h) = W$$

$$\left(1 + \frac{r_h}{r_f}\right) (2N_h) = W$$

$$2N_h = \frac{W}{1 + \frac{r_h}{r_f}}$$

recall:  $2N_f = \frac{r_h}{r_f} (2N_h)$

$$r_h = 0.410\text{m}, r_f = 0.840\text{m}, W = 584\text{N}$$

Using #15

$$2N_h = 392\text{N}$$

$$2N_f = 192\text{N}$$

So

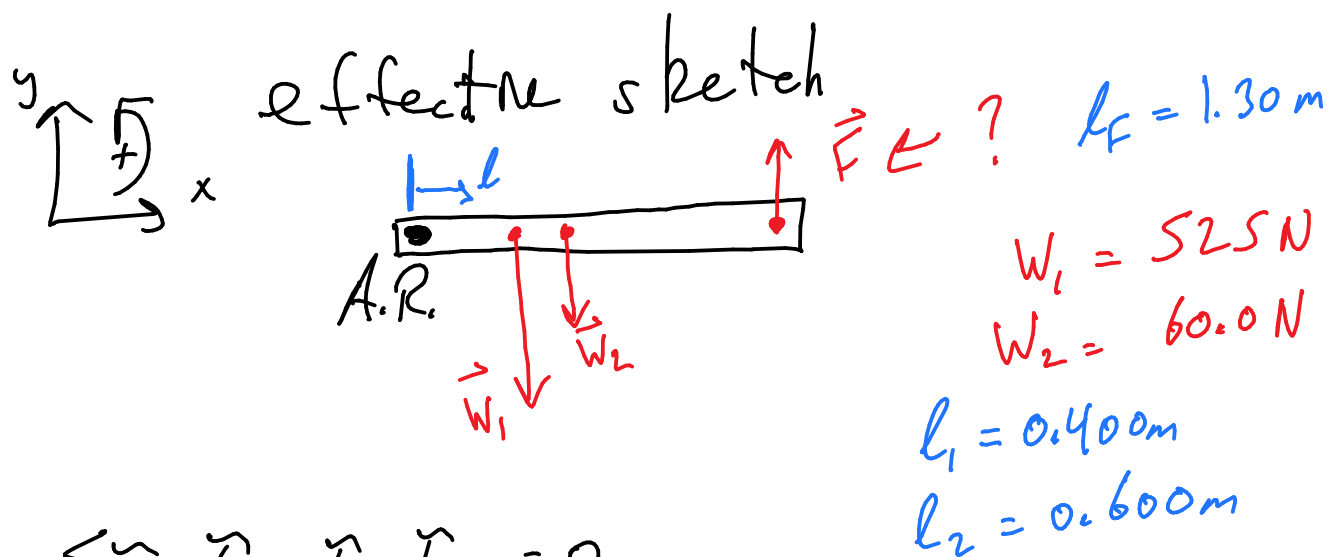
$N_h = 196\text{N}$	$N_f = 96\text{N}$
each hand $\uparrow$	each foot $\uparrow$

Prob. 5 1/2 9.18

7/15

For 2 designs use  $\sum \vec{\tau} = 0$   
to determine force applied by  
a person when 2 weights are  
equal, but one lever arm is changed.

Note that solve for left  
design and when solving for right  
design, one lever arm is set to zero.



$$\sum \vec{\tau} = \vec{\tau}_F - \vec{\tau}_1 - \vec{\tau}_2 = 0$$

$$\vec{\tau} = l F$$

$$\vec{\tau}_F = \vec{\tau}_1 + \vec{\tau}_2$$

8/15

Prob. 5 2/2

$$\frac{l_F F}{l_F} = \frac{l_1 W_1 + l_2 W_2}{l_F}$$

$$F = \frac{l_1 W_1 + l_2 W_2}{l_F}$$

$$l_F = 1.30 \text{ m}$$

$$(a) l_1 = 0.400 \text{ m}$$

$$l_2 = 0.600 \text{ m}$$

$$W_1 = 52.5 \text{ N}$$

$$W_2 = 60.0 \text{ N}$$

(b) same except  
 $l_1 = 0$ .

$$(a) F = 189 \text{ N}$$

$$(b) F = 28.0 \text{ N}$$



Prob. 6 9.32

Given  $\tau$  and  $\alpha$ , find  $I$

$$\tau = 10.0 \text{ N}\cdot\text{m}, \alpha = 8.00 \frac{\text{rad}}{\text{s}^2}$$

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$$\sum \tau = \tau_{\text{net}} = I\alpha$$

$$I = \frac{\tau}{\alpha}$$

$$I = \frac{10.0 \text{ N}\cdot\text{m}}{8.00 \frac{\text{rad}}{\text{s}^2}}$$

$$I = 1.25 \text{ kg}\cdot\text{m}^2$$

10/15

Prob. 7 a.33

Calculate total  $I$  if disk  
and 3 compact masses at end of disk

$M_{\text{disk}} = 1.2 \text{ kg}$ ,  $r_{\text{disk}} = 0.16 \text{ m}$  + 3 masses

$m = 0.15 \text{ kg}$  at  $r = r_{\text{disk}}$ .

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$$I_{\text{tot}} = I_{\text{disk}} + 3 I_m$$

$$I = \frac{1}{2} M_d r^2 + 3 m r^2$$

$$= \left( \frac{1}{2} M_d + 3m \right) r^2$$

$$I = \left( \frac{1}{2} (1.2) + 3(0.15) \right) (0.16)^2 \text{ kg} \cdot \text{m}^2$$

$$I = 2.7 \times 10^{-2} \text{ kg} \cdot \text{m}^2$$

Prob. 8 9.34

11/15

Find  $\alpha$  given  $\tau$  and  $I$ .

$$\tau = 1.8 \text{ N}\cdot\text{m}, I = 0.22 \text{ kg}\cdot\text{m}^2$$

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$$\sum \tau = I\alpha$$

$$\alpha = \frac{\sum \tau}{I}$$

$$\alpha = \frac{1.8 \text{ N}\cdot\text{m}}{0.22 \text{ kg}\cdot\text{m}^2}$$

$$\alpha = 8.2 \frac{\text{rad}}{\text{s}^2}$$

Prob. 9 9.49  
1/2

12/15

Three compact/point masses rotate about the same axis with the same angular velocity  $\omega = 5.00 \frac{\text{rad}}{\text{s}}$ , but different masses and radii.

$$m_1 = 6.00 \text{ kg}, r_1 = 2.00 \text{ m}$$

$$m_2 = 4.00 \text{ kg}, r_2 = 1.50 \text{ m}$$

$$m_3 = 3.00 \text{ kg}, r_3 = 3.00 \text{ m}$$

same  $\omega$ ,  
different  
 $m, r$

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(a) Calculate each tangential speed. ( $v = r\omega$ )

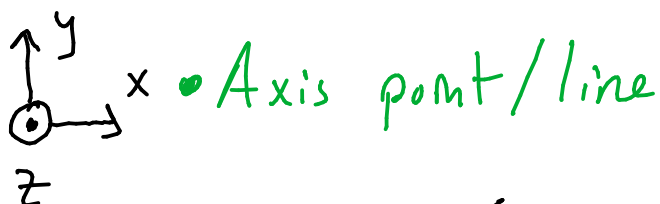
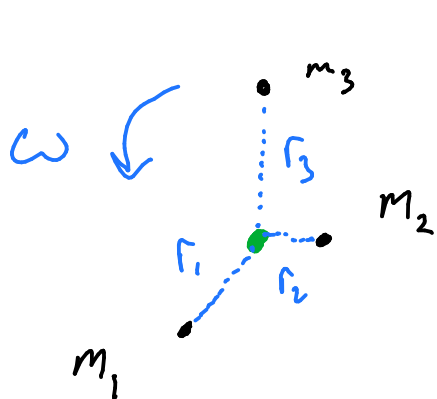
$$V_1 = 10.0 \frac{\text{m}}{\text{s}}, V_2 = 7.5 \frac{\text{m}}{\text{s}}, V_3 = 15.0 \frac{\text{m}}{\text{s}}$$

(b) Calculate  $KE = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 + \frac{1}{2} m_3 v_3^2$

$$KE = 750 \text{ J}$$

Prob. 9 2/2

(c) Calculate  $I$  for the whole system.



$$I = \sum m r^2$$

each mass is a pt. mass.

$$I = m_1 r_1^2 + m_2 r_2^2 + m_3 r_3^2$$

$$I = (24.0 + 9.00 + 27.0) \text{ kg} \cdot \text{m}^2$$

$$I = 60.0 \text{ kg} \cdot \text{m}^2$$

(d) Calculate  $RKE = \frac{1}{2} I \omega^2$

$$RKE = \frac{1}{2} (60.0 \text{ kg} \cdot \text{m}^2) \left( 5.00 \frac{\text{rad}}{\text{s}} \right)^2$$

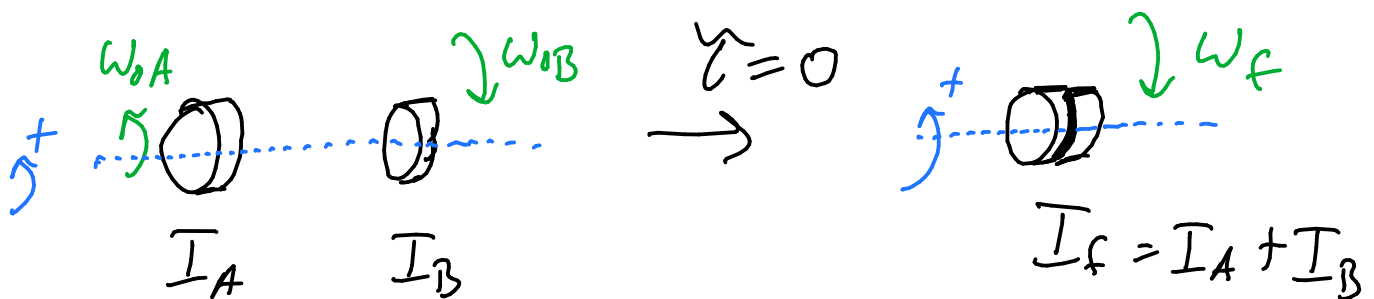
$$RKE = 750 \text{ J} = KE \checkmark$$

Prob. 10  $\frac{1}{2}$  9.59

Two disks are rotated and then connected together without adding any extra angular momentum. Solve for the unknown moment of inertia  $I_B$ .

$$\begin{aligned} \omega_A = \omega_{0A} &= +7.2 \text{ rad/s} & I_A &= 3.4 \text{ kg}\cdot\text{m}^2 \\ \omega_B = \omega_{0B} &= -9.8 \text{ rad/s} & \omega_f &= -2.4 \text{ rad/s} \end{aligned}$$


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Conservation:  $L_0 = L_f$  ;  $L = I\omega$

Thus,  $L_{0A} + L_{0B} = L_f$

Specific to this problem  $\Rightarrow$

$$I_A \omega_A + I_B \omega_B = (I_A + I_B) \omega_f$$

Prob. 10 2/2

$$I_A \omega_A + I_B \omega_B = (I_A + I_B) \omega_f$$

Now to rewrite/solve for  $I_B$ . (No zeros)

$$I_A \omega_A + I_B \omega_B = I_A \omega_f + I_B \omega_f$$

$$I_B \omega_B - I_B \omega_f = I_A \omega_f - I_A \omega_A$$

$$I_B (\omega_B - \omega_f) = I_A (\omega_f - \omega_A)$$

$$I_B = \frac{I_A (\omega_f - \omega_A)}{(\omega_B - \omega_f)} \quad \begin{array}{l} \text{form ready} \\ \text{for \#5.} \end{array}$$

$$I_B = \frac{(3.4 \text{ kg}\cdot\text{m}^2)(-7.2 - 2.4) \frac{\text{rad}}{\text{s}}}{(-9.8 + (+2.4)) \frac{\text{rad}}{\text{s}}} = \frac{+(3.4)(9.6)}{+(7.4)} \text{ kg}\cdot\text{m}^2$$

$$I_B = 4.4 \text{ kg}\cdot\text{m}^2$$