

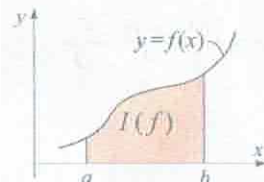
# MCEN3030 COMPUTATIONAL METHODS

## CHAPTER 9 NUMERICAL INTEGRATION

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### Background

- Engineering measurements require the calculation of both derivatives and integrals:
- Analytical integration can be difficult
- Same code can be used for many functions
- Numerical integration is related to solving ODE's



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### Example

Measuring the volumetric flow across a pipe using a Pitot tube:

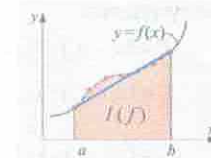


- Formula:  $Q = \int_A v dA = \int v(r) \cdot dA$
- Approximation:

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### Numerical Integration Approaches

- First approach consist on using the end points to approximate the integral to a trapezoid



- Closed vs Open Methods

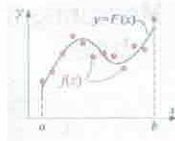


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## Initial Approaches

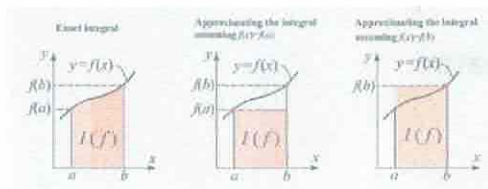
### ■ Newton-Cotes Integration: Closed Method

- Data is fitted into a curve (function), which is easy to integrate: polynomial



### ■ Rectangle Method: Closed Method

- Assume a constant value for the function:



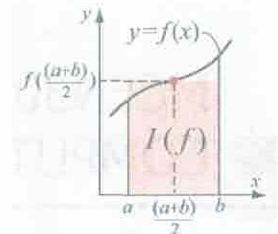
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## Mid Point Methods

### ■ Midpoint Method: Open Method

- Instead of the extreme points, the midpoint is used to calculate the integral

$$I = \int_a^b f(x) dx \approx \int_a^b f\left(\frac{a+b}{2}\right) dx = f\left(\frac{a+b}{2}\right) \int_a^b dx$$



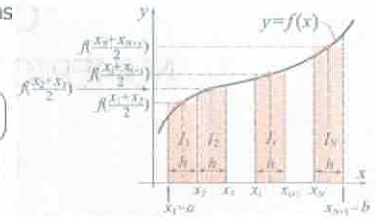
### ■ Composite Midpoint Method

- Domain is again divided into N sections

$$I_1 \approx (x_2 - x_1) f\left(\frac{x_1 + x_2}{2}\right) = h \cdot f\left(\frac{x_1 + x_2}{2}\right)$$

$$I_N \approx (x_{N+1} - x_N) f\left(\frac{x_N + x_{N+1}}{2}\right) = h \cdot f\left(\frac{x_N + x_{N+1}}{2}\right)$$

$$\Rightarrow I = \int_a^b f(x) dx \approx \sum_{i=1}^N I_i = \sum_{i=1}^N h \cdot f\left(\frac{x_i + x_{i+1}}{2}\right)$$

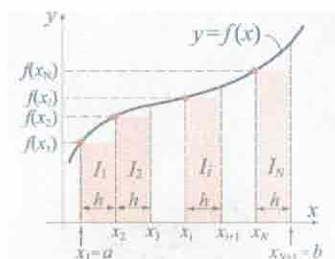


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## Rectangle Method

### ■ Composite Rectangle Method:

- The domain [a, b] is divided into N intervals: (N+1) points
- Each integral is calculated on every interval



$$I_1 \approx (x_2 - x_1) f(x_1) = h \cdot f(x_1)$$

$$I_2 \approx (x_3 - x_2) f(x_2) = h \cdot f(x_2)$$

$$\vdots$$

$$I_N \approx (x_{N+1} - x_N) f(x_N) = h \cdot f(x_N)$$

- More exact than the rectangle method
- More exact as the number of intervals increases

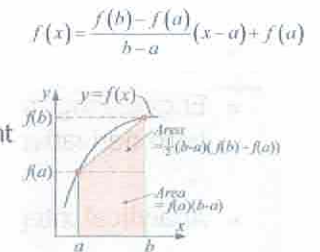
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## Trapezoidal Method

### ■ Closed Method

- A linear approximation is used to represent the function:

$$I = \int_a^b f(x) dx \approx \int_a^b \left[ \frac{f(b) - f(a)}{b - a} (x - a) + f(a) \right] dx$$

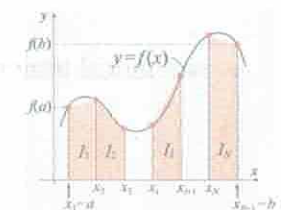


### ■ Composite Trapezoidal Method

$$I_1 \approx \left[ \frac{f(x_1) + f(x_2)}{2} \right] (x_2 - x_1) = \left[ \frac{f(x_1) + f(x_2)}{2} \right] h$$

$$\vdots$$

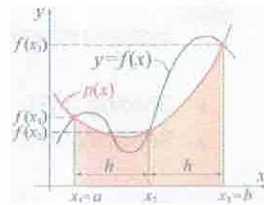
$$I_N \approx \left[ \frac{f(x_N) + f(x_{N+1})}{2} \right] (x_{N+1} - x_N) = \left[ \frac{f(x_N) + f(x_{N+1})}{2} \right] h$$



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## Simpson's Methods

- This technique approximates the function to higher order polynomial instead of a line
- Quadratic function: 1/3 method
  - 3 points needed:  $x_1, x_2, x_3$   $f(x_1), f(x_2), f(x_3)$
  - Newton's Polynomial:



$$p(x) = \alpha + \beta(x-x_1) + \gamma(x-x_1)(x-x_2)$$

$$\Rightarrow p(x) = f(x_1) + \left[ \frac{f(x_2) - f(x_1)}{h} \right] (x-x_1) + \left[ \frac{f(x_3) - 2f(x_2) + f(x_1)}{2h^2} \right] (x-x_1)(x-x_2) \quad h = \frac{b-a}{2}$$

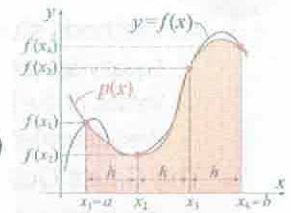
$$\Rightarrow I = \int_a^b f(x) dx \approx \int_a^b p(x) dx = \int_a^b [\alpha + \beta(x-x_1) + \gamma(x-x_1)(x-x_2)] dx$$

$$\Rightarrow I \approx \alpha \int_a^b dx + \beta \int_a^b (x-x_1) dx + \gamma \int_a^b (x-x_1)(x-x_2) dx$$

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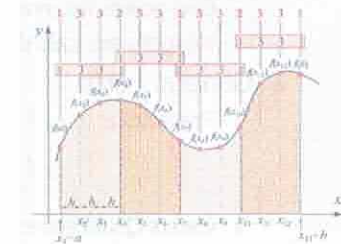
## 3/8 Simpson's Methods

- Cubic function: 3/8 method
    - Four points are needed: equally spaced  $x_1, x_2, x_3, x_4$   $f(x_1), f(x_2), f(x_3), f(x_4)$
- $$p(x) = \alpha + \beta(x-x_1) + \gamma(x-x_1)(x-x_2) + \delta(x-x_1)(x-x_2)(x-x_3)$$
- $$I = \int_a^b f(x) dx \approx \frac{3}{8} h [f(a) + 3f(x_2) + 3f(x_3) + f(b)]$$



- Composite 3/8 methods:
  - N has to be a multiple of 3

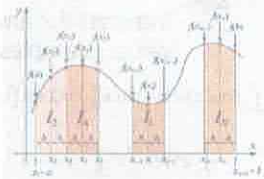
$$I \approx \sum_{i=1,4,7,\dots} \frac{3}{8} h [f(x_i) + 3f(x_{i+1}) + 3f(x_{i+2}) + f(x_{i+3})]$$



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## Simpson's Methods

- Composite Simpson's 1/3 method
  - Use N several subintervals: different N equations
  - Each quadratic equation will involve two intervals
  - Number of intervals must be an even number
- The case for same width is shown:  $h = \frac{b-a}{N}$



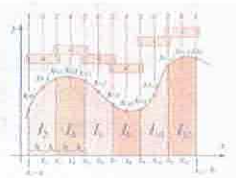
$$\Rightarrow I = \int_a^b f(x) dx = \int_{x_{0,1}}^{x_{1,2}} f(x) dx + \int_{x_{1,2}}^{x_{2,3}} f(x) dx + \dots + \int_{x_{N-1,1}}^{x_{N,2}} f(x) dx + \dots + \int_{x_{N,1}}^{x_{N+1,2}} f(x) dx$$

$$\Rightarrow I = \sum_{i=2,4,6,\dots}^N \int_{x_{i-1,1}}^{x_{i,2}} f(x) dx \approx \sum_{i=2,4,6,\dots}^N \int_{x_{i-1,1}}^{x_{i,2}} p(x) dx \Rightarrow I \approx \sum_{i=2,4,6,\dots}^N \frac{h}{3} [f(x_{i-1,1}) + 4f(x_i) + f(x_{i+1,2})]$$

$$I \approx \frac{h}{3} \left[ \sum_{i=2,4,6,\dots}^N f(x_{i-1,1}) + 4 \sum_{i=2,4,6,\dots}^N f(x_i) + \sum_{i=2,4,6,\dots}^N f(x_{i+1,2}) \right]$$

$$I \approx \frac{h}{3} \left[ \sum_{i=1,3,5,\dots}^{N-1} f(x_i) + 4 \sum_{i=2,4,6,\dots}^N f(x_i) + \sum_{i=3,5,7,\dots}^{N+1} f(x_i) \right]$$

$$I \approx \frac{h}{3} \left[ f(x_1) + \sum_{i=3,5,\dots}^{N-1} f(x_i) + 4 \sum_{i=2,4,6,\dots}^N f(x_i) + \sum_{i=3,5,7,\dots}^{N+1} f(x_i) + f(x_{N+1,2}) \right]$$



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## Summary Table

### Single Methods

Integration Method	Values of the function used in evaluating the integral.
Rectangle Equation (7.2)	$f(a)$ or $f(b)$ (Either one of the endpoints.)
Midpoint Equation (7.5)	$f((a+b)/2)$ (The middle point.)
Trapezoidal Equation (7.9)	$f(a)$ and $f(b)$ (Both endpoints.)
Simpson's 1/3 Equation (7.16)	$f(a)$ , $f(b)$ , and $f((a+b)/2)$ (Both endpoints and the middle point.)
Simpson's 3/8 Equation (7.20)	$f(a)$ , $f(b)$ , $f(a + \frac{1}{3}(a+b))$ , and $f(a + \frac{2}{3}(a+b))$ (Both endpoints and two points that divide the interval into three equal-width subintervals.)

- Composite Methods include several intervals

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## Gauss Quadrature

- All methods studied previously use:
  - Equally spaced points
  - Values of the function at those points.
  - Predetermined constant weights
- The Gauss Quadrature Method:
  - Points are not equally spaced
  - End points are not included
  - Weights are calculated to minimize the error
- General Form
  - Previously:  $I = \int_a^b f(x) dx \approx f(a) \cdot (b-a)$
  - $I = \int_a^b f(x) dx \approx \frac{b-a}{3} \left[ f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right]$
  - Gauss Quadrature:

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## Gauss Quadrature

- System reduces to:
  - Dividing IV/II:
  - Replacing in (III): , from (I):
  - Taking the positive root:
  - Choosing  $x_1$  to be symmetrically opposite to  $x_2$  :
  - Replacing in (II):  $C_1(-1/\sqrt{3}) = -C_2(1/\sqrt{3}) \Rightarrow C_1 = C_2 \Rightarrow C_1 = C_2 = 1$
  - Finally:
- Previous 2-term expression will calculate the exact integral for the 4 functions presented:  $f(x) = 1, x, x^2, x^3$

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## Gauss Quadrature

- Basic Integral on domain  $[-1, 1]$ :  $\int_{-1}^1 f(x) dx \approx \sum_{i=1}^n C_i f(x_i)$
- Coefficients and Weights are calculated by enforcing the results for:  $f(x) = 1, x, x^2, x^3, \dots$
- Example:  $n=2$ 
  - 4 unknowns:  $x_1, x_2, C_1, C_2 \rightarrow 4$  equations
  - Procedure: Take first four functions:
    - First:  $\int_{-1}^1 (1) dx = C_1 \cdot 1 + C_2 \cdot 1 \Rightarrow x_1^0 = 2 = C_1 + C_2$
    - Second:  $\int_{-1}^1 x dx = C_1 x_1 + C_2 x_2 \Rightarrow \left[ \frac{x^2}{2} \right]_{-1}^1 = 0 = C_1 x_1 + C_2 x_2$
    - Third:  $\int_{-1}^1 x^2 dx = C_1 x_1^2 + C_2 x_2^2 \Rightarrow \left[ \frac{x^3}{3} \right]_{-1}^1 = \frac{2}{3} = C_1 x_1^2 + C_2 x_2^2$
    - Fourth:  $\int_{-1}^1 x^3 dx = C_1 x_1^3 + C_2 x_2^3 \Rightarrow \left[ \frac{x^4}{4} \right]_{-1}^1 = 0 = C_1 x_1^3 + C_2 x_2^3$

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## Gauss Quadrature

- Integrals for any other function will have an approximated value. Examples:
  - $\int_{-1}^1 \cos(x) dx = [\sin x]_{-1}^1 = 2 \sin(1) = 1.683 \Rightarrow$
  - $\int_{-1}^1 e^x dx = [e^x]_{-1}^1 = e^1 - e^{-1} = 2.350 \Rightarrow$
  - $\int_{-1}^1 x^4 dx = \left[ \frac{x^5}{5} \right]_{-1}^1 = \frac{1^5}{5} - \frac{-1^5}{5} = 0.4 \Rightarrow$
  - $\int_{-1}^1 x^8 dx = \left[ \frac{x^9}{9} \right]_{-1}^1 = \frac{1^9}{9} - \frac{-1^9}{9} = 0.222 \Rightarrow$
- Accuracy can be improved by increasing the number of terms:
  - 3 terms  $\rightarrow$  6 unknowns: Use 6 functions:  $f(x) = 1, x, x^2, x^3, x^4, x^5$
  - 4 terms  $\rightarrow$  8 unknowns: Use 8 functions: ...

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## Gauss Quadrature: General Case

- Simple Integral:  $\int_{-1}^1 f(x) dx \approx \sum_{i=1}^2 C_i f(x_i)$
- General Integral:  $I = \int_a^b f(x) dx$
- Changing variable:  $x \rightarrow t$  }  $x = mt + p$
- Then:

$$I = \int_a^b f(x) dx = \int_{-1}^1 f\left(\frac{1}{2}[t(b-a) + b + a]\right) \frac{1}{2}(b-a) dt$$

$$\int_a^b f(x) dx = \frac{1}{2}(b-a) \int_{-1}^1 f\left(\frac{1}{2}[t(b-a) + b + a]\right) dt$$

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## Improper Integrals

- Not all integrals are continuous:
  - Check for discontinuity points in the function domain
- Integral may have singularities
  - Numerical Integration must be performed by dividing the whole domain into several domains
  - Limit of integrations may need to be approximated
  - Consider changing variables to avoid singularities
- Unbounded Limits
  - Numerical integrations is possible if the integral converges
  - Number of intervals is increased until variation becomes small

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## Matlab Commands

- `quad(function,a,b)`
  - Function and limits are needed within a tolerance of  $10^{-6}$
  - Tolerance is specified for the case: `quad(function,a,b,tol)`
  - Modified Simpson's Method is used
- `trapz(x,y)`
  - Data is entered as two column vectors
  - Trapezoid method is used
- `dblquad`
  - Used for double integrals

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