

# Lecture 3: Bayes + LVM/FA

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# Why Bayes For FA and SEM?

- lavaan is quick, easy, seamless, well documented
- you certainly don't need me here to show you how to use it
- And Bayes FA/SEM
  - not quick
  - not easy
  - not seamless
  - not well documented

# Why Bayes For FA and SEM

1. Fixes Heywood cases.
  - Variances are negative
  - Correlations are bigger than 1.0 or negative

# Why Bayes For FA and SEM

2. Most of our data are not cute little matrices  $\mathbf{Y}_{[I \times J]}$
3. Preprocessing the data to make  $\mathbf{Y}$ 
  - could be simple, like aggregation
  - could be complicated, like deriving a drift rate in a diffusion model
  - resulting  $\mathbf{Y}$  in real data is often too noisy to support FA/SEM
4. Needed: a fully integrated approach where FA affects preprocessing and preprocessing affects FA.
5. Enter Bayes

## Bayes For Cute Little Score Matrices

Here is our data set:

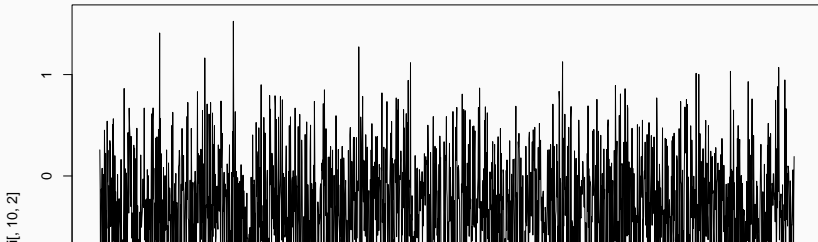
```
set.seed(123)
I=200
J=8
D=2
lambda=matrix(nrow=J,ncol=D)
lambda[,1]=seq(1,0,length=J)
lambda[,2]=seq(0,1,length=J)
Sigma=crossprod(t(lambda))+diag(rep(1^2,J))
y=rmvnorm(I,rep(0,J),Sigma)
```

## Your turn

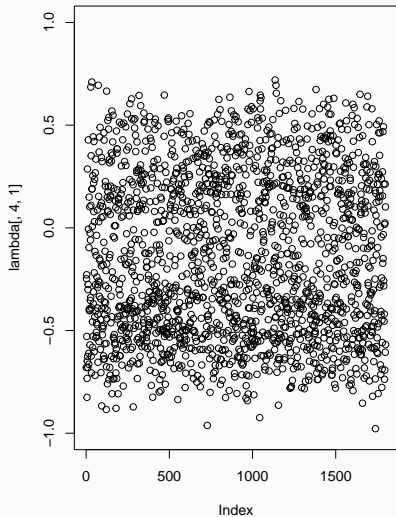
- Program up a Bayes sampler in JAGS or stan (I will do JAGS) for recovering  $\lambda$
- Use the conditional formulation
  - write out the model
  - implement it in JAGS or stan
  - run it and see if you can document issues
- When I program up all Gibbs steps, I get a lot of autocorrelation.

# My turn

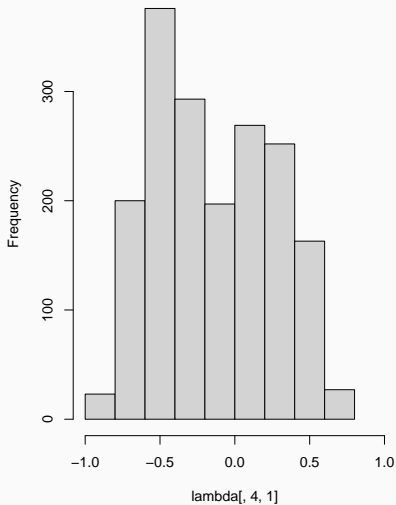
```
## Compiling model graph
##   Resolving undeclared variables
##   Allocating nodes
## Graph information:
##   Observed stochastic nodes: 1600
##   Unobserved stochastic nodes: 432
##   Total graph size: 7056
##
## Initializing model
```



# Lambda [4,1]



Histogram of  $\lambda[4, 1]$





# Rotations!

- each iteration is corresponding to a different rotation.
- what to do?
- old way, fix loading to lower triangle

## Lower Triangle for 3 Factors

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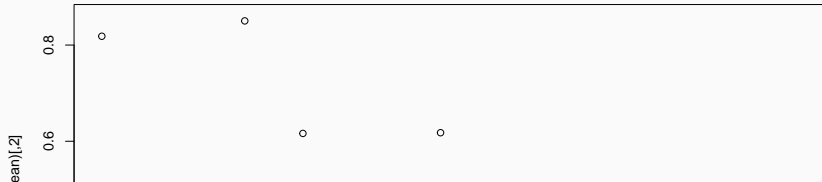
|   |   |   |
|---|---|---|
| + | 0 | 0 |
| * | + | 0 |
| * | * | + |
| * | * | * |
| * | * | * |
| * | * | * |
| * | * | * |
| * | * | * |

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## Your Turn

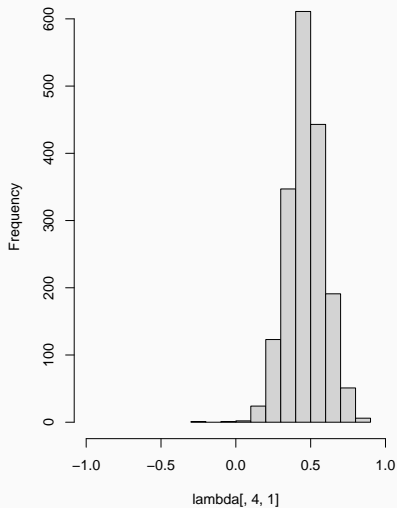
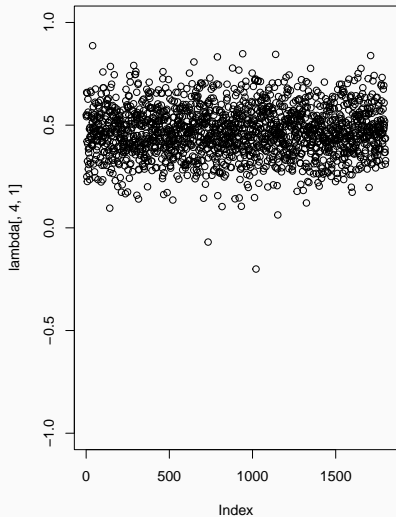
Adapt your code for lower triangle.

```
## Compiling model graph
##   Resolving undeclared variables
##   Allocating nodes
## Graph information:
##   Observed stochastic nodes: 1600
##   Unobserved stochastic nodes: 432
##   Total graph size: 7103
##
## Initializing model
```



# Lower Triangle

Histogram of `lambda[, 4, 1]`



## Post-Sampling Rotations

- Very new approach
- Align each iteration to a common rotation after the fact.
- Papastamoulis, P., & Ntzoufras, I. (2022). On the identifiability of Bayesian factor analytic models. *Statistics and Computing*, 32(2), 23. doi:10.1007/s11222-022-10084-4
- Poworoznek, E., Ferrari, F., & Dunson, D. (2021, July 29). Efficiently resolving rotational ambiguity in Bayesian matrix sampling with matching. Retrieved November 21, 2023, from <http://arxiv.org/abs/2107.13783>